

# Jingtong(Stacy) Yue

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## EDUCATION

**Carnegie Mellon University (CMU)** Pittsburgh, PA  
*Master of Science in Computer Vision, School of Computer Science* Aug. 2025 – Dec. 2026

**Sichuan University** Chengdu, China  
*Bachelor of Engineering in Electronics and Information Engineering | GPA: 3.87/4.0* Sep. 2021 – Jun. 2025

## EXPERIENCE

**Undergraduate Research Assistant** Peking University & University of California, Merced  
*3D Detection for Autonomous Driving* May 2024 – Oct. 2024

- Conducted a systematic analysis on the **safety** and **stability** of radar-camera 3D object detection, benchmarking 4 key types of radar corruptions using scikit-learn, Numpy, and Pandas libraries
- Proposed RobuRCDet, a robust detector based on **Pytorch**, **mmcv** and **mmdetection3D** designed to handle adverse weather and radar corruption, achieving a **19.4%** improvement in NDS and a **25.7%** improvement in mAP
- Designed efficient 3D Gaussian Expanding algorithm and adaptive fusion modules to boost perception robustness in challenging weather conditions

**Artificial Intelligence Research Assistant** MMLab @ Nanyang Technological University  
*Video Generation Towards World Model* Feb. 2025 – Sep. 2025

- Engineered a **data pipeline** to parse and categorize **300+** research papers based on **diffusion models** and **auto-regressive models**, automating classification, and evaluation from video generation to world models
- Developed a benchmarking framework integrating 20+ evaluation detailed capabilities across 3 core capabilities, faithfulness, interactiveness, and planning, enabling systematic comparison of state-of-the-art models
- Maintained an **open-source repository (150+ stars)** widely used by the research community

**Undergraduate Research Assistant** Sichuan University  
*Image Processing and Image Assessment* Dec. 2022 – Mar. 2024

- Proposed a self-collaboration strategy for **unsupervised image restoration** based on **GANs**, boosting performance by **> 1.5 dB** without added inference complexity
- Developed a degradation-aware **no-reference image quality assessment** through **contrastive learning** by both degradation and quality representations, implemented on both **CNN** and **Transformer** frameworks

## PROJECTS

**Auto-Patrolling Robot** | *Python, Face Recognition, Depth Estimation, LLM, Linux* May 2023 – Aug. 2023

- Developed a cyber-police robot capable of navigating complex indoor environments with scenes integrated with **Llama**, such as intersection, corner, and unknown obstacles, based on **Linux** and **C**
- Innovated a **real-time intersection detection** algorithm based on **depth estimation** with **Swin-Transformer** architecture, achieving a **12%** improvement in accuracy and **3%** reduction in processing latency
- Implemented a **security personnel authentication system** using **facial recognition** deep learning model
- Built a hardware system based on **Raspberry Pi**, integrating dual ultrasonic sensors and infrared sensors for precise long- range and short-range **obstacle avoidance**, achieving a **5%** reduction in latency

**Multi-function Image Restoration App** | *Java, INT8 Quantization, Android, Object Detection* Mar. 2024 – Jun. 2024

- Applied **model compression** techniques such as pruning and **INT8 quantization** with **Java**, reducing model parameters by **8% – 10%**, for denoising, crack repair, super- resolution, and old photo restoration respectively
- Developed an **Android App** integrating various image restoration functions powered by deep learning models, while also porting the **YOLOv5** model to enable real-time detection

## SKILLS

**Programming Languages:** Python, C/C++, JavaScript, Java, HTML/CSS, MATLAB

**Tools and Frameworks:** Git, Docker, VS Code, Visual Studio, PyCharm, Linux, Android, AWS, CoLab

**Machine Learning:** PyTorch, TensorFlow, OpenCV, Pandas, Numpy, MMCV, Matplotlib

## PUBLICATIONS

*Jingtong Yue\*, Zhiwei Lin\*, et al.* RobuRCDet: Enhancing Robustness of Radar-Camera Fusion in Bird's Eye View for 3D Object Detection. ICLR 2025 [Paper] [Code]

*Jingtong Yue, Xin Lin, Zijiu Yang, Chao Ren.* Dual-Representation Interaction Driven Image Quality Assessment with Restoration Assistance. WACV 2025 [Paper]

Additional published papers in [TPAMI Paper], [TCSVT Paper]