Visual Question Answering: SAN

Presentation slides for DL4NLP project

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Project Introduction

工作简介

- VQA 以一张图片和一个关于图片内容的自然语言形式的问题作为输入,要求输出正确答案
- Dataset VQAv2
- Summary 属于一种多标签分类的问题,计算损失的时候采用多标签损失

开发环境

- 开发工具: ModelArts Ascend Notebook环境,选用Ascend910芯片作为训练芯片
- 开发包、资源库
 - Mindspore1.3.0
 - numpy
- 系统运行要求: python3.7.5 与可运行 Mindspore1.3.0 的开发环境

Read more about Our Repository

DataLoader 数据集简介

VQAv2数据集的构成如下:

- 1张图片有大概5个问题
- 1个问题有10个答案
- test没有annotation文件

Question

```
question{
"question_id" : int, #问题id
"image_id" : int, #问题对应的图片id
"question" : str #具体的问题
}
```

Annotations

DataLoader

数据预处理

- 问题与答案对齐
- 图片与问题对齐

数据集加载

数据类型与预处理如下:

- 1. img: 图片为三通道RGB模式,加载成三维的Tensor即可
- 2. question: 预处理,进行词形还原,大小写转换等,再通过预训练的Tokenizer进行one-hot编码,扩充成 定长向量输出。
- 3. Answers: 预处理,进行词形还原,大小写转换等,自己构造词汇表进行one-hot编码

```
Generating answers vocab...

Answers vocab is generated
(4, 128)
[[ 0. 10. 0. ... 0. 0. 0. ]
[ 0. 0. 0. ... 0. 0. 0. ]
[ 0. 0. 0. ... 0. 0. 0. ]
[ 0. 0. 0. ... 0. 0. 0. ]
(4, 3, 224, 224)
```

Image Embedding

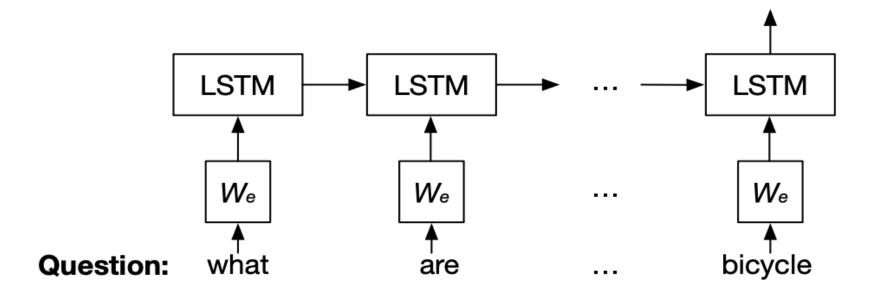
直接输入图片(3x224x224)到搭建的卷积网络,输出特征(196x768),而非直接使用提取好的特征

```
self.simple_cnn = nn.SequentialCell([
            nn.Conv2d(self.in_channels, self.channels, kernel_size=3, stride=2, padding=0, pad_mode='same'),
            nn.BatchNorm2d(
                self.channels, eps=1e-4, momentum=0.9, gamma_init=1, beta_init=0,
                moving_mean_init=0, moving_var_init=1),
            nn.ReLU(),
            nn.MaxPool2d(kernel_size=3, stride=2, pad_mode="same"),
            nn.Conv2d(self.channels, self.channels * 2, kernel_size=3, stride=1, padding=0, pad_mode='same'),
            nn.BatchNorm2d(self.channels*2),
            nn.ReLU(),
            nn.MaxPool2d(kernel_size=2, stride=2),
            nn.Conv2d(self.channels * 2, self.channels*4, kernel_size=3, stride=1, padding=0, pad_mode='same'),
            nn.BatchNorm2d(self.channels * 4),
            nn.ReLU(),
            nn.MaxPool2d(kernel_size=2, stride=2),
            nn.Conv2d(self.channels*4, output_size, kernel_size=3, stride=1, padding=0, pad_mode='same')
        ])
```

Text Embedding: LSTM

According to the paper we refer, the text embdding part is LSTM, which is easy to implemented.

```
from mindspore.nn import LSTM
lstm = LSTM(input_size, hidden_size, num_layers)
```

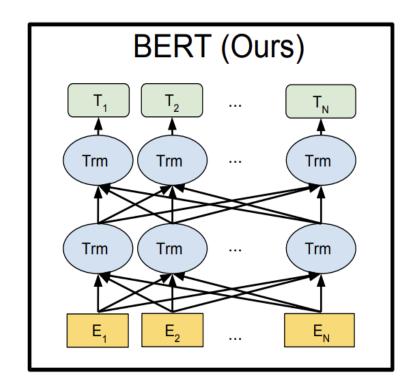


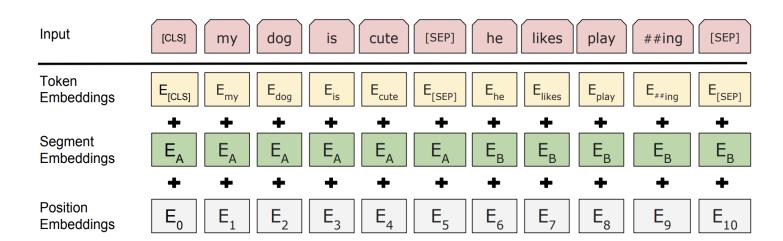
LSTM Shortcome:

- Good RNN variant, but still not good at handling long sequence.
- Only "look forward", not able to "look back"

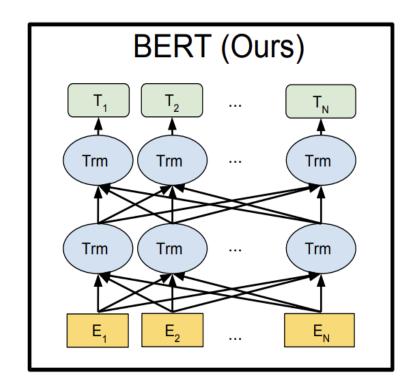
Thus, we consider to use BERT

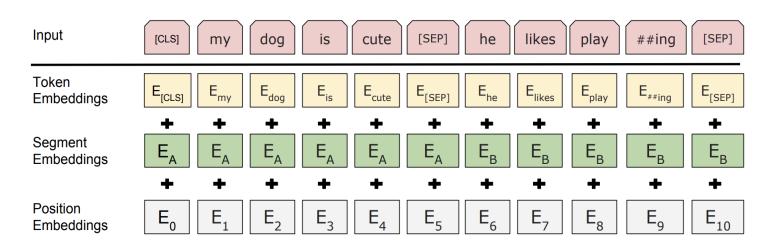
```
class BertModel(BertPretrainCell):
    def construct:
        # Embedding
        token_embedding, segment_embedding, position_embedding = \
            BertEmbeddings(input_ids)
        embedding_output = token_embedding +
            segment_embedding + position_embedding
        # BertEncoder == Transformer
        encoder_outputs = self.encoder(embedding_output,
                                       extended_attention_mask,
                                       head_mask)
        # sequence_output (batch_size, len(sequence), embedding_size)
        # Embedding of every word
        sequence_output = encoder_output[0]
        # pooled_output (batch_size, embedding_size)
        # Embedding of the input sequence
        pooled_output = self.pooler(sequence_output)
        return sequence_output, pooled_output
```



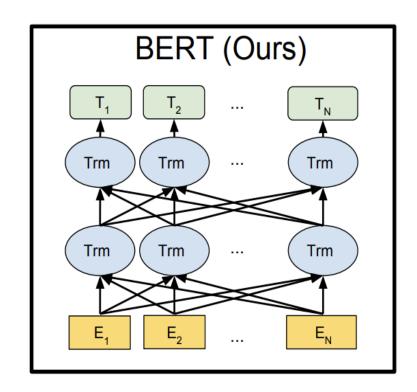


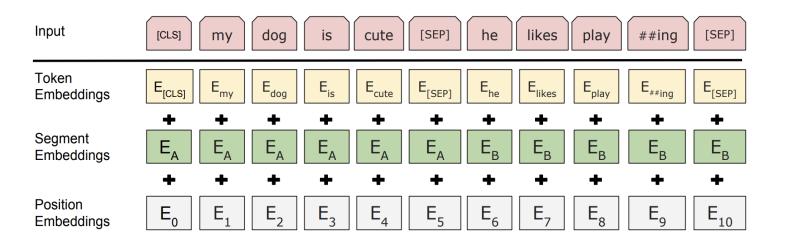
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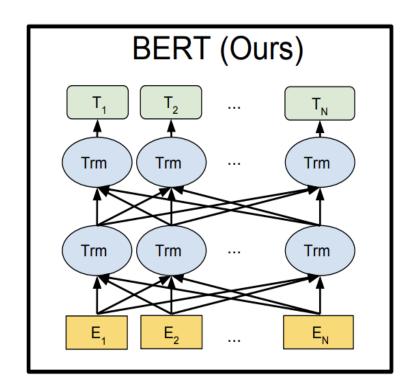


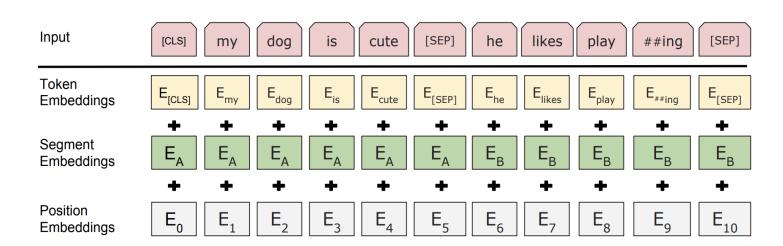
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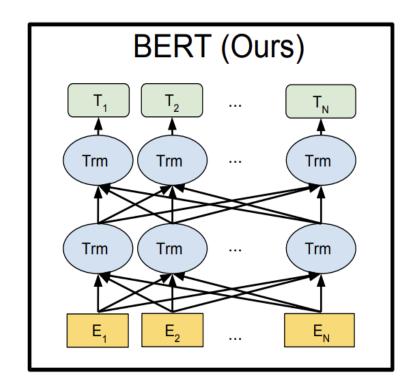


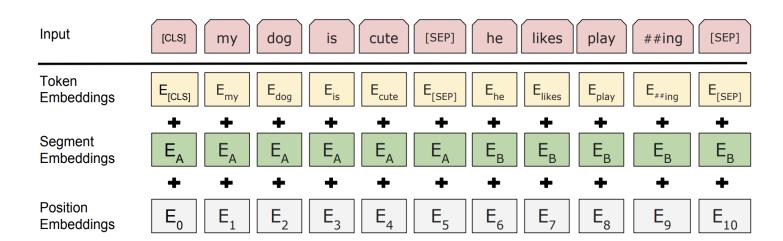
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Stacked Attention Network

模型功能

- 使用多层 Attention 识别图像中不同区域与句子向量的相关程度。
- 筛选与句子向量有关的区域,与答案建立联系。
- 输入问题: What are sitting in the basket on a bicycle?
- 输入图片:

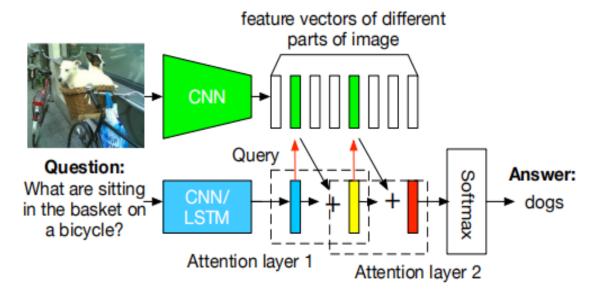


■ 经过两层 Attention:



■ 输出答案: Dogs.

■ 整体模型结构:



Attention Distribution

- 在SAN中,最核心的问题为 Attention
 Distribution: 图片中的每个区域与问题的关联程度
 (Attention) 为多少?
- 为此,我们先利用CNN和Bert对图像和问题进行编码:

$$v_I \in R^{d imes m} \ v_Q \in R^d$$

其中, v_I 为编码后的图像矩阵, v_Q 为编码后的问题句向量,d为表示维度,m是图像中区域的个数(利用CNN)。

■ Attention 通过如下计算得到:

$$egin{aligned} h_A &= anh(W_I v_I \oplus W_Q v_Q) \ p_I &= ext{softmax}(W_p h_A) \end{aligned}$$

我们首先让 v_I v_Q 分别通过全连接层,使得它们的维度变为 $R^{k\times m}$ 和 R^k . 这里, \oplus 操作代表把向量加到矩阵的每一列上。图像矩阵的每一列代表每个兴趣区域,因此这里的操作实际上就是把句子向量与每个兴趣区域做融合。由此再将 h_A 通过全连接层和 Softmax,就得到了图像中每个区域在特定句子中能成为兴趣区域的可能性,也就是我们的 Attention Distribution.

ullet 有了 Attention Distribution 后,我们利用它计算 每个区域的权重和 $\hat{v_I} \in R^d$:

$$\hat{v_I} = \sum_i p_i v_i$$

接着,把这个向量与句向量相加,得到整合后的查询向量 $u \in \mathbb{R}^d$ 。

$$u=\hat{v_I}+v_Q$$

■ 以上就是单层Attention的思路。

Attention Distribution

■ 单层 Attention 的表示性并不强,所以我们可以使用多层 Attention,即将查询向量作为新的问题向量,不断输入Attention层进行迭代:

$$egin{aligned} h_A^k &= anh(W_I^k v_I \oplus W_Q^k u^{k-1}) \ p_I &= ext{softmax}(W_p^k h_A^k) \ \hat{v_I}^k &= \sum_i p_i^k v_i \ u^k &= \hat{v_I}^k + u^{k-1} \end{aligned}$$

经过K次Attention迭代后, 我们使用全连接层和Softmax推理答案:

$$p_{
m ans} = \operatorname{softmax}(W_u u^K)$$

Attention方法相较传统方法的优势

- 传统方法仅仅是将整体图片向量与问题向量合并,对区域信息不敏感。
- 相较于传统方法,Attention方法得到的查询向量 u 更具有信息表示性,因为与问题更相关的区域得到了更高的权重。

模型训练及验证

1. 为了支持多个输入(`question`和`img`), 自定义

`WithLossCell`

```
class WithLossCell(nn.Cell):
    def __init__(self, model):
        super(WithLossCell, self).__init__(
            auto_prefix=False)
        self.loss = nn.SoftmaxCrossEntropyWithLogits()
        self.net = model

def construct(self, q, a, img):
    out = self.net(q, img)
    loss = self.loss(out, a)
    return loss
```

2. 定义训练网络

```
#定义网络
model = san.SANModel()
#定义优化器
opt = nn.Adam(params=model.trainable_params())
#定义带Loss的网络
net_with_loss = WithLossCell(model)
#包装训练网络
train_net = TrainOneStepCell(net_with_loss, opt)
#设置训练模式
train_net.set_train(True)
```

模型训练及验证

3.定义验证网络,模型输出只要属于对应问题的十个答案之一即认为正确

4.每个batch计算准确率,最后求平均得到某个epoch的验证准确率

```
class WithAccuracy(nn.Cell):
    def __init__(self, model):
        super(WithAccuracy, self).__init__(
            auto_prefix=False)
        self.net = model

def construct(self, q, a, img):
        out = self.net(q, img)
        out = ops.Argmax(output_type=mindspore.int32)(out)
        return out, a

#model即为训练网络中同一个model
eval_net = WithAccuracy(model)
#设置验证模式
eval_net.set_train(False)
```

```
out, a = eval_net(q, a, img)
predicted = out.asnumpy()
ans = a.asnumpy()
batch_size = ans.shape[0]
acc = 0
for i in range(batch_size):
    if ans[i,predicted[i]]!=0:
        acc += 1
accuracy = acc / batch_size
```

Thanks