## Homework 3

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1. (Bellman convergence) prove that the value iteration algorithm in a discrete MDP converges to a unique optimal value function. Does the policy converge uniquely? What would a counterexample be?

**Convergence** Using Bellman equation, the value function at state  $S \in \mathcal{S}$  for policy  $\pi$  is defined as

$$V^{\pi}(s) := R(s) + \gamma \sum_{S' \in \mathcal{S}} \Pr[S' \mid s, \pi(s)] V^{\pi}(s')$$

Using value iteration, we update the value function for each state at each iteration by

$$\hat{V}(s) \leftarrow R(s) + \gamma \max_{a} \sum_{s' \in S} \Pr[S' \mid s, a] \hat{V}(s')$$

Let B be the Bellman backup operator:  $\mathbb{R} \to \mathbb{R}$ , which takes any arbitrary value function at some state  $\hat{V}(S)$  and returns the its new value as updated by the value iteration

$$B\hat{V}(s) := R(s) + \gamma \max_{a} \sum_{s' \in S} \Pr[s' \mid s, a] \hat{V}(s')$$

We would like to first prove that the Bellman backup operator B is a contraction; in other words, for all  $V_1(s)$  and  $V_2(s)$ 

$$\max_{s \in \mathcal{S}} |BV_1(s) - BV_2(s)| \le \gamma \max_{s \in \mathcal{S}} |V_1(s) - V_2(s)|$$

The proof is as follows

$$|BV_{1}(s) - BV_{2}(s)|$$

$$= \gamma \left| \max_{a} \sum_{s' \in S} \Pr[s' \mid s, a] V_{1}(s') - \max_{a} \sum_{s' \in S} \Pr[s' \mid s, a] V_{2}(s') \right|$$

$$\leq \gamma \max_{a} \left| \sum_{s' \in S} \Pr[s' \mid s, a] V_{1}(s') - \sum_{s' \in S} \Pr[s' \mid s, a] V_{2}(s') \right|$$

$$= \gamma \max_{a} \left| \sum_{s' \in S} \Pr[s' \mid s, a] \left( V_{1}(s') - V_{2}(s') \right) \right|$$

$$= \gamma \max_{a} \sum_{s' \in S} \Pr[s' \mid s, a] \left| \left( V_{1}(s') - V_{2}(s') \right) \right|$$

$$= \gamma \max_{a} \mathbb{E}_{s' \mid s, a} \left[ \left| \left( V_{1}(s') - V_{2}(s') \right) \right| \right]$$

$$\leq \gamma \max_{s' \in S} \left| \left( V_{1}(s') - V_{2}(s') \right) \right|$$

$$= \gamma \max_{s' \in S} \left| \left( V_{1}(s) - V_{2}(s) \right) \right|$$

For the optimal value function  $V^*$ , we have  $BV^* = V^*$ , therefore

$$\max_{s \in \mathcal{S}} |B\hat{V}(s) - V^{\star}(s)| \leq \gamma \max_{s \in \mathcal{S}} |\hat{V}(s) - V^{\star}(s)|$$

This means the updated values for the states are getting closer to the optimal values after each iteration. Thus,  $\hat{V}(s)$  converges to  $V^*$  by value iteration algorithm.

2. Prove that if we look ahead k steps at the Q function, the value function converges to the same value function as the typical case when we look ahead 1 step at the Q function.

Denote  $B_k$  to be the Bellman backup operator for looking k-step ahead for any value function V. Then

$$B_k V(s_1) := R(s_1) + \gamma \max_{a_1} \sum_{s_2 \in \mathcal{S}} \Pr[s_2 \mid s_1, a_1] \bigg( R(s_2) \\ + \gamma \max_{a_2} \sum_{s_3 \in \mathcal{S}} \Pr[s_3 \mid s_2, a_2] \bigg( \cdots \bigg( R(s_k) + \max_{a_k} \sum_{s_{k+1} \in \mathcal{S}} \Pr[s_{k+1} \mid s_k, a_k] V(s_{k+1}) \bigg) \bigg) \bigg)$$

It is easy to show that for any two value functions  $V_1$  and  $V_2$ 

$$\begin{split} |B_{k}V_{1}(s_{1}) - B_{k}V_{2}(s_{1})| \\ &= \gamma^{k} \bigg| \max_{a_{1}} \max_{a_{2}} \cdots \max_{a_{k}} \sum_{s_{2} \in \mathcal{S}} \Pr[s_{2} \mid s_{1}, a_{1}] \sum_{s_{3} \in \mathcal{S}} \Pr[s_{3} \mid s_{2}, a_{2}] \cdots \sum_{s_{k+1} \in \mathcal{S}} \Pr[s_{k+1} \mid s_{k}, a_{k}] V_{1}(s_{k+1}) \\ &- \max_{a_{1}} \max_{a_{2}} \cdots \max_{a_{k}} \sum_{s_{2} \in \mathcal{S}} \Pr[s_{2} \mid s_{1}, a_{1}] \sum_{s_{3} \in \mathcal{S}} \Pr[s_{3} \mid s_{2}, a_{2}] \cdots \sum_{s_{k+1} \in \mathcal{S}} \Pr[s_{k+1} \mid s_{k}, a_{k}] V_{2}(s_{k+1}) \bigg| \\ &= \gamma^{k} \max_{a_{1}} \max_{a_{2}} \cdots \max_{a_{k}} \sum_{s_{2} \in \mathcal{S}} \Pr[s_{2} \mid s_{1}, a_{1}] \sum_{s_{3} \in \mathcal{S}} \Pr[s_{3} \mid s_{2}, a_{2}] \cdots \sum_{s_{k+1} \in \mathcal{S}} \Pr[s_{k+1} \mid s_{k}, a_{k}] \\ & \bigg| V_{1}(s_{k+1}) - V_{2}(s_{k+1}) \bigg| \\ &\leq \gamma^{k} \max_{s_{k+1} \in \mathcal{S}} \bigg| V_{1}(s_{k+1}) - V_{2}(s_{k+1}) \bigg| \\ &= \gamma^{k} \max_{s \in \mathcal{S}} \bigg| V_{1}(s) - V_{2}(s) \bigg| \end{split}$$

Thus the operator for looking k-step ahead is also a contraction. Similarly, this algorithm will also converge and converge to the same value as looking one step ahead.