```
1.
```

```
//互斥信号量,保护缓冲区
   semaphore mutex = 1;
                             //共享缓冲区奇数
   semaphore odd = 0;
   semaphore even = 0;
                             //共享缓冲区偶数
   semaphore empty = N;
                             //共享缓冲区空位
   void P1() {
   while(true) {
      int x = produce();
      P(empty);
      P(mutex);
      put(x);
      V(mutex);
      if (x % 2 == 0)
          V(even);
      else
          V(odd);
   }
   }
   void P2() {
   while(true) {
       P(odd);
      P(mutex);
      getodd();
      V(mutex);
      V(empty);
      countodd();
   }
   }
   void P3() {
   while(true) {
       P(even);
       P(mutex);
      geteven();
      V(mutex);
      V(empty);
      counteven();
   }
}
```

```
semaphore empty = M; // empty=0 表示空锅
                     // full=M 表示满锅
semaphore full = 0;
semaphore mutex = 1; // 保护对 S 的访问
int S = 0;
                      // 锅中肉的份数
void savagery() {
   while (true) {
      P(full);
      P(mutex);
      S = S - 1;
      V(mutex);
      V(empty);
      getServingFromPot();
      eat();
   }
}
void chef(){
   int i;
   while(true) {
      for (int i = 0; i < M; i++)
         P(empty);
      P(mutex);
      S = S + M;
      V(mutex);
      for(int i =0;i < M;i++)
         V(full);
      putServingsInPot(M);
   }
```

```
3.
```

```
semaphore empty = 1000; // empty = 0 缓冲区空
                               // full = 1000 缓冲区满
   semaphore full = 0;
   semaphore only = 1;
                               //保护只有一个消费者线程在取产品
   semaphore mutex = 1;
                               //保护对 num 的访问
   int num = 0;
                                // 缓冲区产品数
   void producer() {
   while(true) {
      product = produce();
      P(empty);
      P(mutex);
      num++;
      V(mutex);
      V(full);
      insert_product(product);
   }
   }
   void customer() {
   int i;
   while(true) {
      P(only);
      for (i = 0; i < 10; i++) {
          P(full);
         P(mutex);
         num--;
         V(mutex);
         V(empty);
         custome_product();
      V(only);
   }
}
```