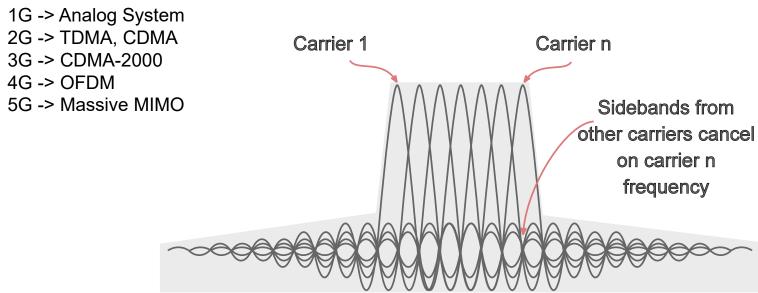


# Recovering Clipped OFDM Symbols with Bayesian Inference

Jinkun Zhang

### **OFDM System**

- Orthogonal Frequency-Division Multiplexing (OFDM) is a method of encoding digital data on multiple orthogonal carrier frequencies.
- OFDM was first introduced in 1966 (Bell Lab)
- OFDM is one of the basic idea of 4G LTE.





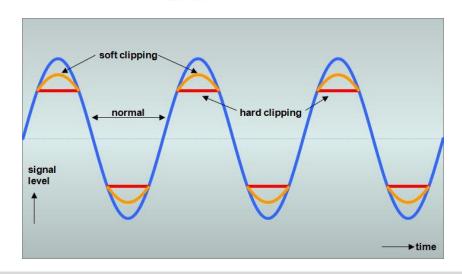
## **Clipping Distortion**

Frequency domain signal is drawn from a finite set (Constellation)

$$X_l \in \mathcal{S}, \quad |\mathcal{S}| = Q$$

Time domain signal may have high peak power

$$x_n = \frac{1}{\sqrt{N}} \sum_{l=1}^N X_l e^{2\pi j \frac{ln}{N}} \qquad \qquad \tilde{x}_n = \begin{cases} x_n & \text{, if } |x_n| \le A \\ A e^{j \operatorname{Arg}(x_n)} & \text{, if } |x_n| > A \end{cases}$$



#### Input-BackOff:

$$(IBO)_{dB} = 10\log_{10}\left(\frac{A^2}{\mathbf{E}\left[x_n^2\right]}\right)$$



#### Channel

We assume time invariant frequency selective channel

$$y_n = \sum_{m=0}^{M-1} h_m \tilde{x}_{n-m} + w_n$$

Also assume perfect sync. and equalization

$$\bar{Y}_l = \frac{Y_l}{H_l} = \tilde{X}_l + \frac{W_l}{H_l}$$

$$\bar{y}_n = \tilde{x}_n + \epsilon_n \quad , \sigma_{\epsilon}^2 = \frac{\sigma_w^2}{N} \sum_{l=1}^N \frac{1}{|H_l|^2}$$

### MAP Approach

Set hyperparameter z<sub>n</sub>

$$\bar{y}_n = \tilde{x}_n + \epsilon_n = x_n(1 - z_n) + Ae^{j\text{Arg}(x_n)}z_n + \epsilon_n, \quad z_n \in \{0, 1\}$$

Prior

$$\Pr(z_n) = \begin{cases} 1/2 & \text{, } z_n = 0 \\ 1/2 & \text{, } z_n = 1 \end{cases}$$

$$\Pr(X_l = S_u) = \frac{1}{Q}$$

$$\Pr(\sigma_{\epsilon}^2) = \mathcal{IG}(a_0, b_0)$$



### MAP Approach

Likelihood

$$\Pr(\bar{\mathbf{y}}|\mathbf{x}, \mathbf{z}, \sigma_{\epsilon}^{2}) = \prod_{n=1}^{N} \Pr(\bar{y}_{n}|x_{n}, z_{n}, \sigma_{\epsilon}^{2})$$

$$= \prod_{n:z_{n}=0} \mathcal{N}(\bar{y}_{n}|x_{n}, \sigma_{\epsilon}^{2}) \times \prod_{n:z_{n}=1} \mathcal{N}(\bar{y}_{n}|Ae^{j\phi_{x_{n}}}, \sigma_{\epsilon}^{2})$$

 Directly maximizing the full posterior w.r.t all variables would be hard to implement because the parameter space is too large



### Iterative MAP Approach

- We introduce iterative/stochastic algorithm, update each variable separately.
- This approach can be interpreted as an extension of EM strategy.

```
Algorithm 1: Iterative/Stochastic MAP Estimation
```

```
Result: transmitted signal \hat{\mathbf{x}}, hyperparameter \hat{\mathbf{z}}, receiver noise power \hat{\sigma}^2_{\epsilon}

1 Compute \bar{\mathbf{y}} at the receiver;

2 Start point \mathbf{x}^{(0)}, \mathbf{z}^{(0)}, \sigma^{(0)}_{\epsilon} drawn from the given prior;

3 k \leftarrow 1;

4 do

5 Drawn \mathbf{z}^{(k)} \sim \Pr(\mathbf{z} | \mathbf{x}^{(k-1)}, \sigma^{(k-1)}_{\epsilon}, \bar{\mathbf{y}});

6 Update: \mathbf{x}^{(k)} = \arg\max_{\mathbf{x}} \Pr(\mathbf{x} | \mathbf{z}^{(k)}, \sigma^{(k-1)}_{\epsilon}, \bar{\mathbf{y}});

7 Drawn (\sigma^2_{\epsilon})^{(k)} \sim \Pr(\sigma^2_{\epsilon} | \mathbf{z}^{(k)}, \mathbf{x}^{(k)}, \bar{\mathbf{y}});

8 k \leftarrow k + 1;

9 while k \leq K_{max};

10 return (\hat{\mathbf{x}}, \hat{\mathbf{z}}, \hat{\sigma}^2_{\epsilon}) \leftarrow (\mathbf{x}^{(k)}, \mathbf{z}^{(k)}, (\sigma^2_{\epsilon})^{(k)})
```



# Iterative MAP Approach (Algorithm)

Detail conditional posterior

$$\begin{aligned} \mathbf{Pr} & \mathbf{Z_{n}} \\ & p = \frac{\Pr(z_{n} = 1 | \bar{y}_{n}, x_{n}, \sigma_{\epsilon}^{2})}{\Pr(z_{n} = 0 | \bar{y}_{n}, x_{n}, \sigma_{\epsilon}^{2}) + \Pr(z_{n} = 1 | \bar{y}_{n}, x_{n}, \sigma_{\epsilon}^{2})} \\ & = \mathrm{Sigmoid}(\frac{1}{\sigma_{\epsilon}^{2}} \left[ \left| \bar{y}_{n} - Ae^{j\phi_{x_{n}}} \right|^{2} - \left| \bar{y}_{n} - x_{n} \right|^{2} \right]) \end{aligned}$$

• 
$$\mathbf{X}_{l}$$

$$\hat{X}_{l} = \arg \max_{S_{u}} \Pr(X_{l} = S_{u} | \mathbf{X}_{-l}, \bar{\mathbf{y}}, \mathbf{z}, \sigma_{\epsilon}^{2})$$

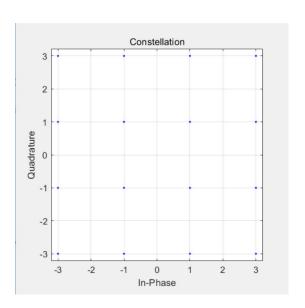
$$= \arg \max_{S_{u}} \sum_{n:z_{n}=0} |\bar{y}_{n} - x_{n,X_{l}=S_{u}}|^{2} + \sum_{n:z_{n}=1} |\bar{y}_{n} - Ae^{j\phi_{x_{n},X_{l}=S_{u}}}|^{2}$$

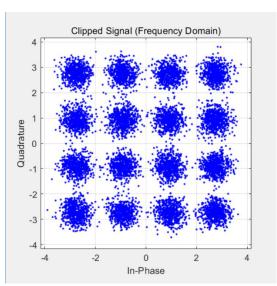
• 
$$\sigma_{\epsilon}$$
  $\Pr(\sigma_{\epsilon}^{2}|\bar{\mathbf{y}},\mathbf{x},\mathbf{z}) \propto \Pr(\bar{\mathbf{y}}|\mathbf{x},\mathbf{z},\sigma_{\epsilon}^{2})\Pr(\sigma_{\epsilon}^{2})$   $\propto \mathcal{IG}(a_{N},b_{N})$   $a_{N}=a_{0}+\frac{N}{2}$   $b_{N}=b_{0}+\frac{1}{2}\sum_{k=1}^{N}\left(\bar{y}_{n}-x_{n}(1-z_{n})-Ae^{j\phi_{x_{n}}}z_{n}\right)^{2}$ 

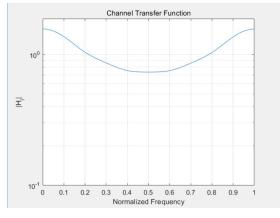
# **Implementation**

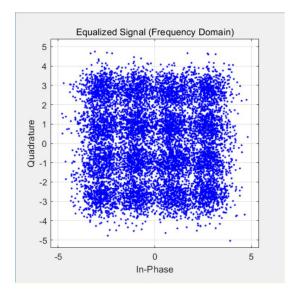
Simple convolution channel

16QAM Constellation











# **Implementation**

- N = 100000, IBO = 2.93dB,  $K_{Max} = 10$
- 20 trails
- Time Complexity: O(KQN²)

