

ECE6703J

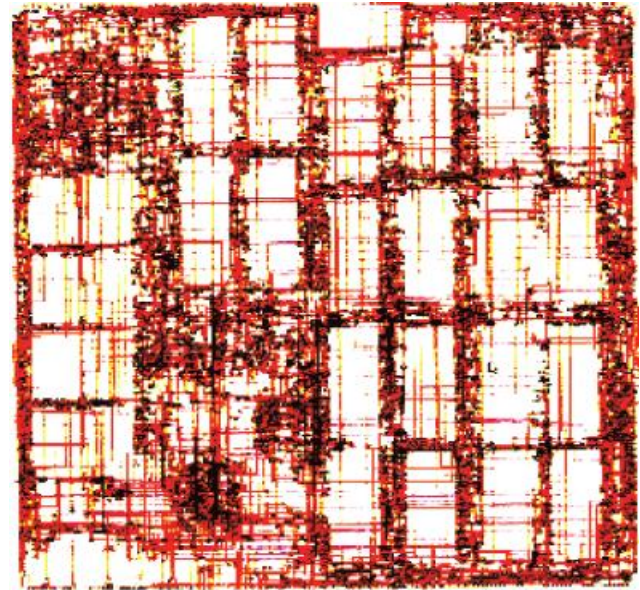
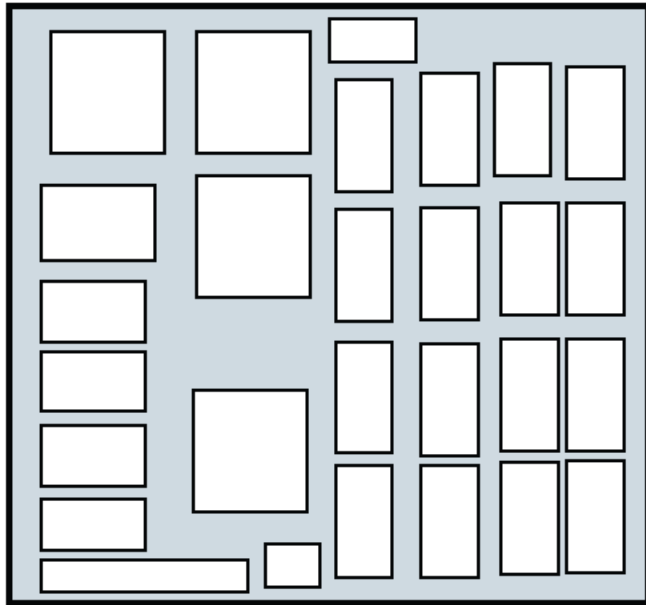
Computer-Aided Design of Integrated Circuits

Routing Basics and Maze Routing

Outline

- Routing Basics
- Maze Routing
 - 2-Point Nets in 1 Layer
 - Multi-Point Nets
 - Multi-Layer Routing
 - Non-Uniform Grid Costs

Routing: The Problem



Thousands of macro blocks

Millions of gates

Millions of wires

Kilometers of wire

Basic Routing Challenges

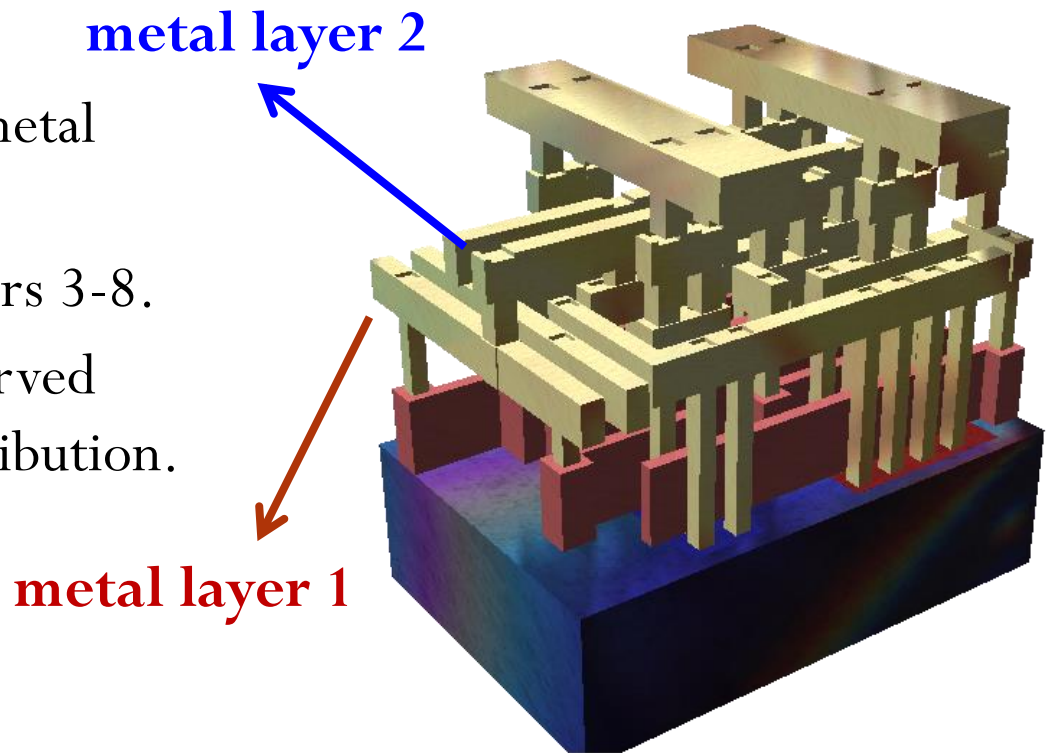
- **Scale**: Big chips have an enormous number (**millions**) of wires.
 - So many. Turns out **NOT** every wire gets to take an “**easy**” path to connect its pins.
 - Must connect them all. However, can’t afford to route many wires manually.
- **Geometric complexity**: At nanoscale, **geometry rules** (e.g., the distance between two adjacent wires) are complex — makes routing hard.

Basic Routing Challenges (cont.)

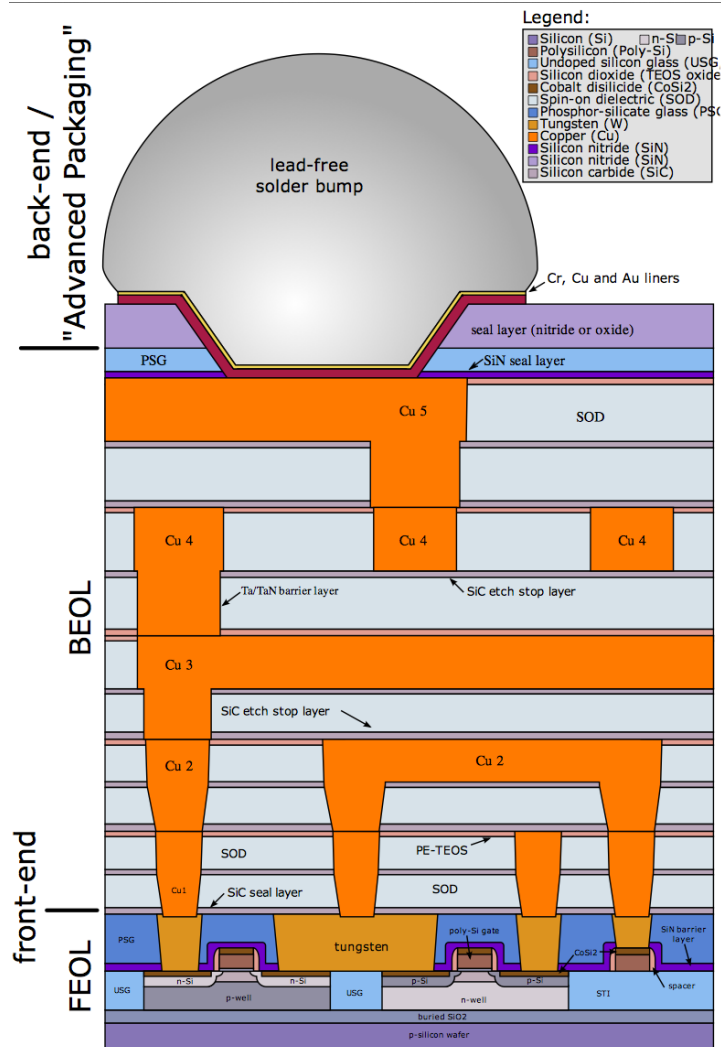
- Electrical complexity
 - It's **not enough** to make sure you connect all the wires.
 - You also must ensure that the **delays** through the wires are not too big.
 - And that wire-to-wire **interactions** (crosstalk) don't mess up behavior.

Physical Assumptions

- **Many layers** of wiring are available for routing.
 - Made of metal (today, copper).
 - Wires in different layers are connected by **vias**.
- A simplified view
 - Standard cells are using metal on layers 1,2.
 - Routing wires are on layers 3-8.
 - Upper layers (9, 10) reserved for power and clock distribution.

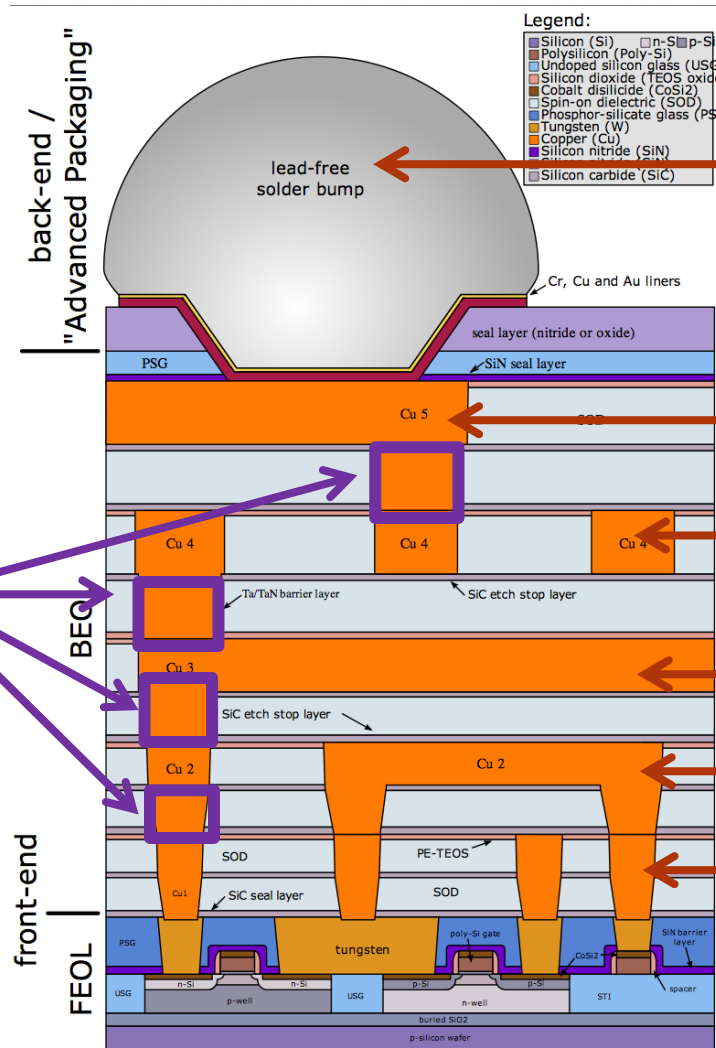


Typical Example (5 Layers)



- Cross sectional view of a chip with 5 layers of wiring, along with packaging connection ("bump").

Typical Example (5 Layers)



Package interconnect, (like a via), but from chip to board

Thicker layer

metal layer 5 (less resistance) for clock, power

metal layer 4 } For connecting gates

metal layer 3

metal layer 2 } Wiring for cells

metal layer 1 } Transistors to make gate-level logic

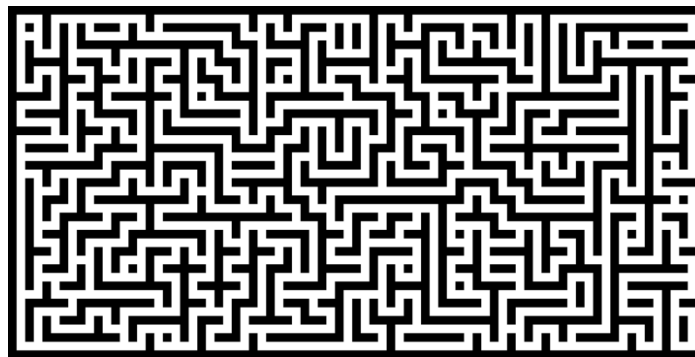
Vias, connect Metal layers k and $k+1$

Algorithm Comparison: Placement vs Routing

- There are lots of different placement algorithms.
 - Iterative methods, such as simulated annealing-based method.
 - Analytical methods based on solving/optimizing large systems of equations.
- There are **not quite so many** routing algorithms.
 - There are several routing data structures – to represent the geometry efficiently.
 - But there is **one very, very big idea** at core of most real routers.

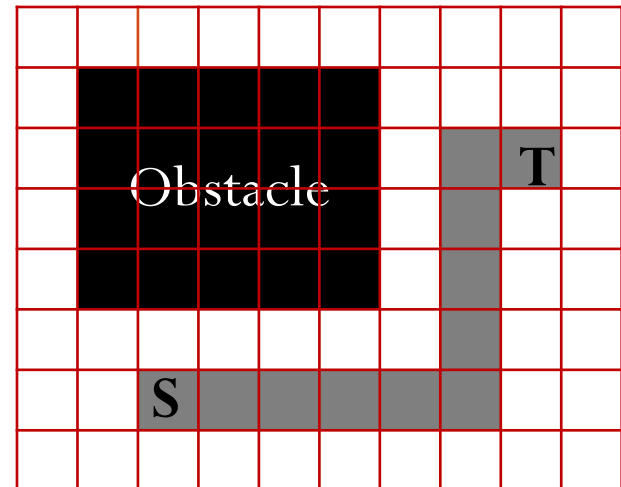
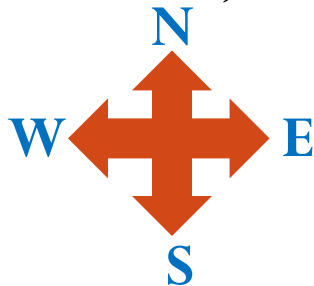
Big Idea Called “Maze Routing”

- Given a maze, find a shortest path from entrance to exit.
- From one famous early paper:
 - E.F. Moore. “The shortest path through a maze”, in Proceedings of the International Symposium on the Theory of Switching, pp 285--292, Cambridge, MA, Apr. 1959.



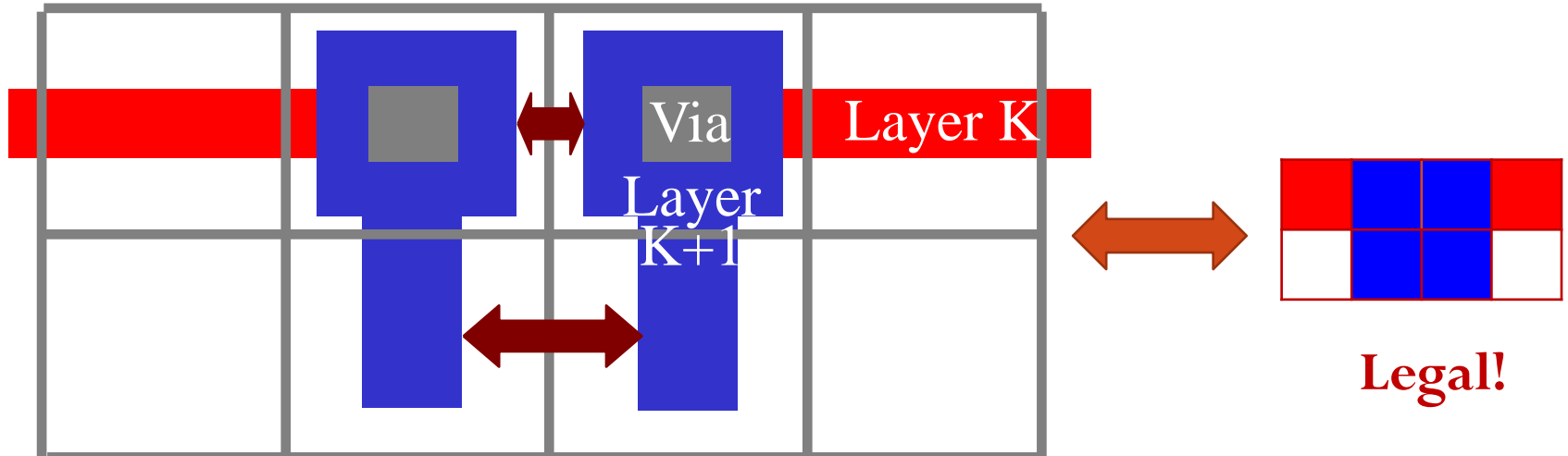
How Do We Get “Mazes” from Routing Problem?

- Make a big geometric assumption: **Gridded routing**.
 - The layout surface is a **grid of regular squares**.
 - We can mark **obstacles** (also called **blockages**) where we are not allowed to route.
 - A legal wire path = **a set of connected grid cells**, through **unblocked** cells in grid.
- Wires are also strictly **horizontal and vertical**.
 - No diagonal (e.g., 45°) angles.
A path goes east/west, or north/south, in this grid.



Grid Assumption

- Wires and their vias fit in the grid cell.
- All pins we want to connect are at the **center** of grid cell.
- Grid assumption is a critical assumption – implies many real geometrical constraints on wires (designers use these constraints!).
 - All wires are roughly the **same** size (width).
 - If we choose the grid size proper, then there are no geometry rule (e.g., spacing) violations.



Maze Routers: Topics

- Router functionality
 - Two-point nets in one layer with unit cost
 - Multi-point nets
 - Multiple layers
 - Non-uniform grid costs
- Implementation mechanics
 - Expansion (a key step in routing)
 - Data structures
 - Depth-first search
- Divide & Conquer: Global routing

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Maze Routing: History

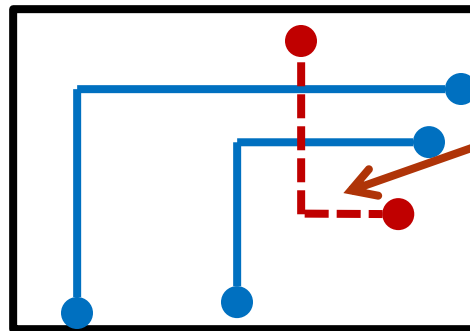
- 1959 – Basic Idea
 - E.F. Moore. “The shortest path through a maze,” In Proceedings of the International Symposium on the Theory of Switching, Apr. 1959, Harvard University Press.
- 1961 – Applied to electronics (board wiring)
 - C.Y. Lee, “An algorithm for path connections and its applications”, IRE Trans. on Electronic Computers, pp. 346-365, Sept. 1961.
 - Lee of Bell Labs invents the algorithm; gets famous for “Lee routers”.

Maze Routing: History

- 1974 – Apply ideas from AI to improve the routing speed
 - F. Rubin, “The Lee path connection algorithm”, IEEE Trans. on Computers, vol. c-23, no. 9, pp. 907-914, Sept. 1974.

Maze Routing: Strategy

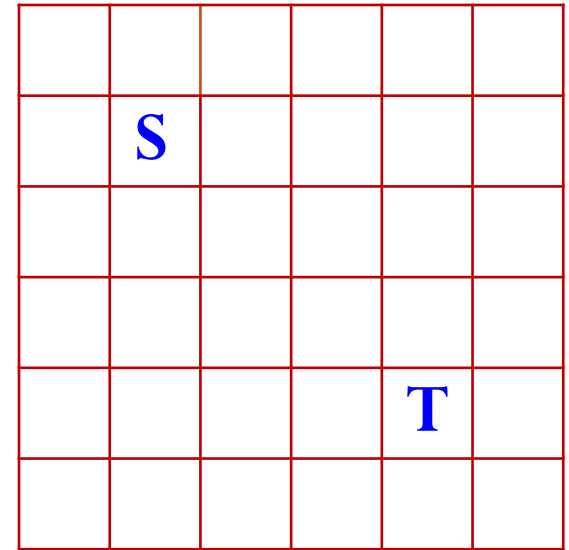
- Strategy
 - **One net at a time**: completely wire **one net**, then move onto next net.
 - **Optimize net path**: find the **best** wiring path.
- Problems
 - Early nets wired may **block** path of later nets.
 - We are just going to ignore this one for the moment...



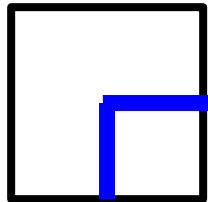
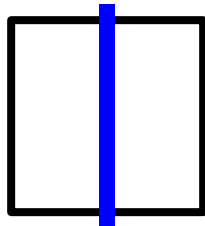
Blocked!
Impossible to route

Maze Router: Basic Idea for 2-Pin Nets

- Given:
 - Grid** - each square cell represents where **one** wire can cross.
 - A **source** (S) and a **target** (T)
- Problem:
 - Find shortest path connecting **source** cell (S) and **target** cell (T).
 - When using cells, a wire can



cross or **bend**



Maze Routing Key Step: Expansion

S

Start at the **source**

	1	
1	S	1
	1	

Find all new cells that are reachable at **pathlength 1**, i.e., 1 unit from S in total path length.

		2		
	2	1	2	
2	1	S	1	2
	2	1	2	
		2		

Using the **pathlength 1** cells, find all new cells which are reachable at **pathlength 2**.

Repeat until the target is reached ...

Maze Router Step 1: Expand

- Strategy
 - Expand **one cell at a time** until a shortest path from S to T are found.
 - Expansion creates a **wavefront** of paths that search broadly out from source cell until target is reached.
 - “Reached” means specifically we **label** it with a pathlength number.

2	1	2	3	4	5
1	S	1	2	3	4
2	1	2	3	4	5
3	2	3	4	T 5	
4	3	4			
	4				

How to Implement Expand?

- A **queue** of reachable squares from the source is used.
- The cell of the source is set with a distance value of 0.
- It is enqueued into an initial empty queue.
- **While** the queue is not empty.
 - A cell is **dequeued** from the queue and made the **examine cell**.
 - **For each** **unreached unblocked** square adjacent to the **examine cell**
 - Mark its distance as “1 + the distance value of the **examine cell**”
 - Is this cell the target? If yes, path found and return.
 - Otherwise, **enqueued** the cell into the queue.
- When queue becomes empty but has not reached target yet, means no path found.

Breadth-first search!

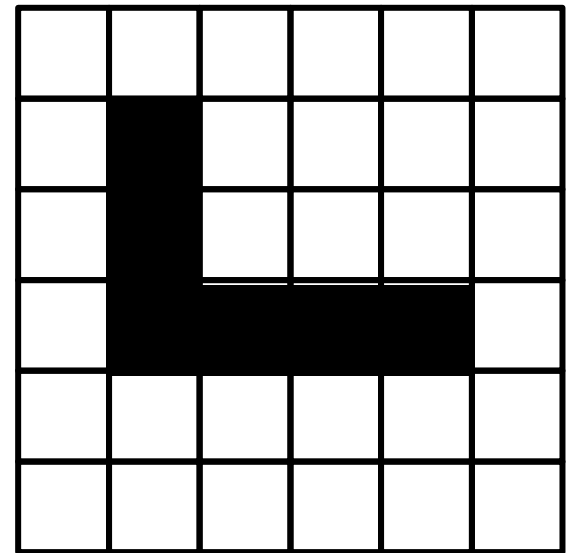
Maze Router Step 2: Backtrace

- Now what? **Backtrace**
 - Select a shortest path (**any** shortest path) from target back to source.
 - Here, just follow the pathlengths in the cells in **descending order**.
 - Mark these cells as **obstacles**, so they cannot be used again for later wires we want to route.

2	1	2	3	4	5
1	S	1	2	3	4
2	1	2	3	4	5
3	2	3	4	T	5
4	3	4			
	4				

Maze Router Step 3: Clean-Up

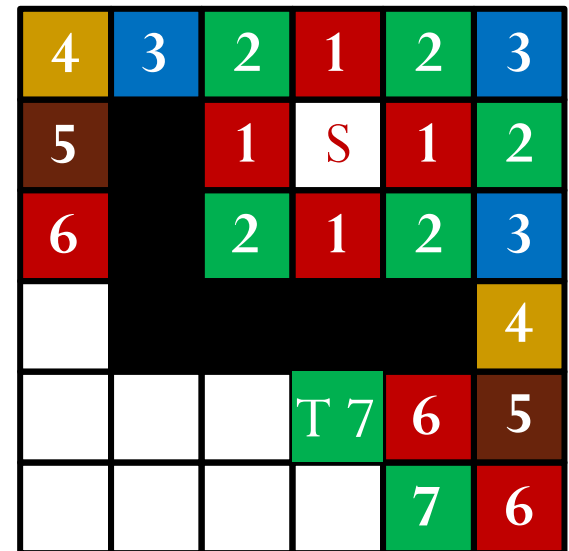
- Now what? **Clean-up**
 - Clean up the grid for the next net, i.e., removing path lengths, etc.
 - Leave the new S to T path as an **obstacle**.
 - Now, ready to route the **next** net!



Maze Router with Obstacles

- Any cell you cannot use for a wire is an **obstacle** or a **blockage**.
- There may be parts of the routing surface you just cannot use.
- But most importantly, you label each newly routed net as a blockage.
- Thus, all future nets must **route around** this blockage.

Expand



Maze Router with Obstacles

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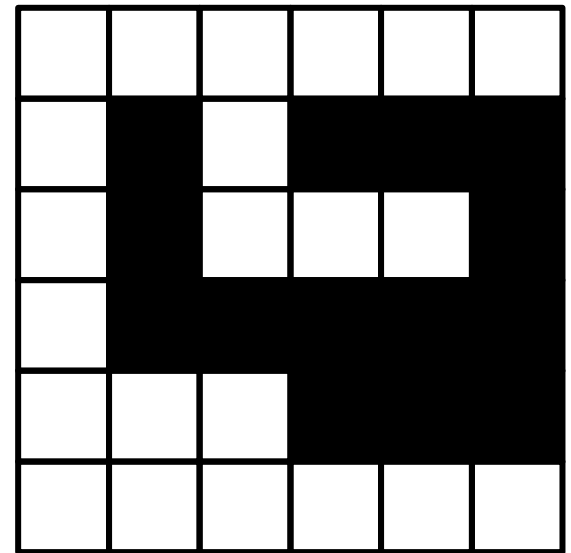
Backtrace

4	3	2	1	2	3
5		1	S	1	2
		2	1	2	3
					4
			T 7	6	5
				7	6

Maze Router with Obstacles

- Any cell you cannot use for a wire is an **obstacle** or a **blockage**.
- There may be parts of the routing surface you just cannot use.
- But most importantly, you label each newly routed net as a blockage.
- Thus, all future nets must **route around** this blockage.

Clean-up



Classical Maze Router: Summary

- Expand
 - **Breadth-first-search** to find a path from source to target.
- Backtrace
 - Walk shortest path back to the source and mark the path.
- Clean-Up
 - Erase all distance marks from other grid cells before next net is routed. The cells on the new path are set as used (obstacles).

Outline

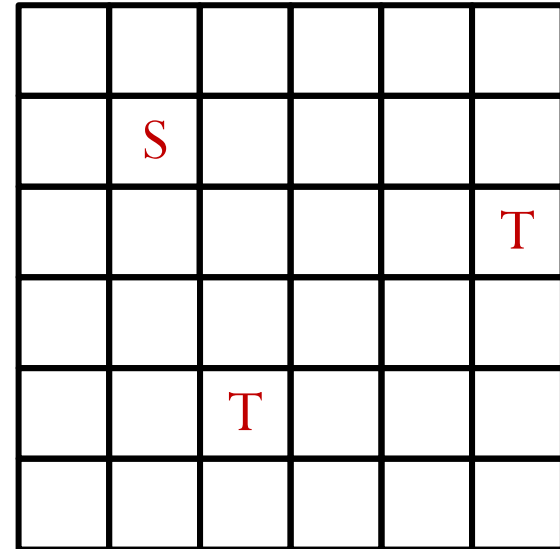
- Routing Basics
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 - 2-Point Nets in 1 Layer
 - Multi-Point Nets
 - Multi-Layer Routing
 - Non-Uniform Grid Costs

Applications: Multi-point Nets

- Multi-point Nets
 - **One** source → **Many** targets
 - You get this with any net that has >1 **fanout** (i.e., almost all real nets).
- Simple strategy
 - Start: Pick **one** point as source, label **all the others** as targets.
 - First: Use maze route algorithm to find path from source to **nearest** target.
 - **Note**: You don't know which target is “nearest” yet, routing will find it.
 - Next: Re-label **all** cells on found path as **sources**, then rerun maze router using all sources simultaneously.
 - Repeat: For each remaining unconnected target point.

Multi-point Nets

- Given:
 - A source and **many targets**.
- Problem:
 - Find a **short** path connecting the source and all targets.



Multi-point Nets

- First segment of path...
 - Run maze route to find the closest target.
 - Start at source, go until we find **any target**.

2	1	2	3	4	
1	S	1	2	3	4
2	1	2	3	4	T
3	2	3	4		
	3	T	4		

Multi-point Nets

- Next ...
 - Backtrace and re-label the **whole** route as **sources** for the next pass.
- Note — this is different
 - We don't relabel the path as **blockage**, as we did before.
 - We label it as **source**, so we can find paths from any point on this segment, to the rest of the targets.

2	1	2	3	4	
1	S	1	2	3	4
2	1	2	3	4	T
3	2	3	4		
	3	T 4			

Multi-point Nets

- Next...
 - We will **expand this entire set** of source cells to find next segment of the net.
 - Idea is we will look for paths of length 1 away from this whole set of sources, then length 2, 3, etc,
...
 - ... until we reach another target.

2	1	2	3	4	
1	S	1	2	3	4
1	S	1	2	3	T 4
1	S	1	2	3	
1	S	S	1	2	3
2	1	1	2	3	

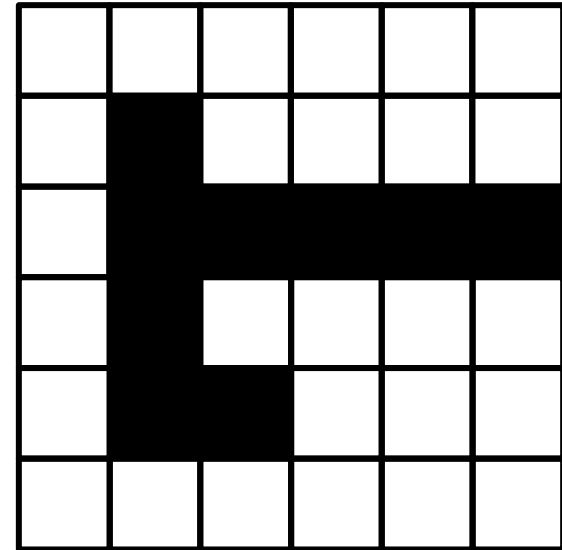
Multi-point Nets

- Next: **Backtrace** as before.
 - Follow pathlengths in decreasing order from target, to some source cell.

2	1	2	3	4	
1	S	1	2	3	4
1	S	1	2	3	T 4
1	S	1	2	3	
1	S	S	1	2	3
2	1	1	2	3	

Multi-point Nets

- Finally...
 - Do usual cleanup.
 - Mark all of the segment cells as used and clean-up the grid.
 - Now, have embedded a **multi-point net**, and rendered it as an **obstacle** for future nets.



Aside: Is This Strategy “Optimal”?

- Does this method give us guaranteed **shortest** multi-point net?
 - No!
 - This method is just a **good heuristic**.
 - The **optimal** path has a name: called a **Steiner Tree**.

Aside: About Steiner Tree Constructions



- How hard is to get the optimal Steiner Tree?
 - NP-hard!
- Why this is hard, in general?
 - You don't know at start where the right "**Steiner points**" are, to make shortest wire.
 - There are simple heuristics work well – but no guarantee to get the **best** Steiner tree.

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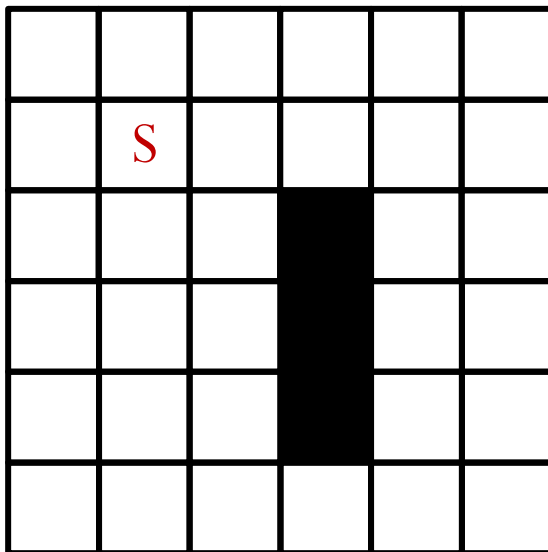
Application: Multi-Layer Routing

- All chips (and all boards) have many **parallel** wiring layers.
 - Chips: 10+ layers of metal in modern technologies.
 - Boards: 20+ layers in the most advanced boards.
- How – mechanically – do we handle multiple wiring layers?
 - Idea: **Parallel grids, vertically stacked, one for each layer.**
 - Use **vias** to access other layers.
- New expansion process
 - On each individual layer: to north/south/east/west neighbors.
 - To **adjacent** layers: **up/down** (between layers) using a via.

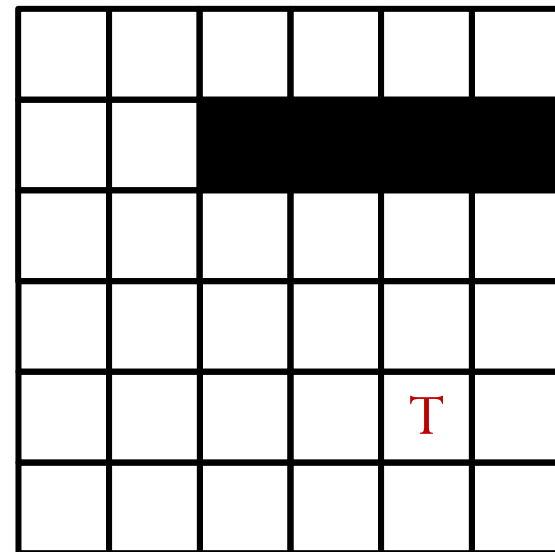
2-Layer Example: Parallel Grids, Vertically Stacked

- Expansion can now go **UP** (Layer 1 \rightarrow 2) and **DOWN** (Layer 2 \rightarrow 1).

Layer 1



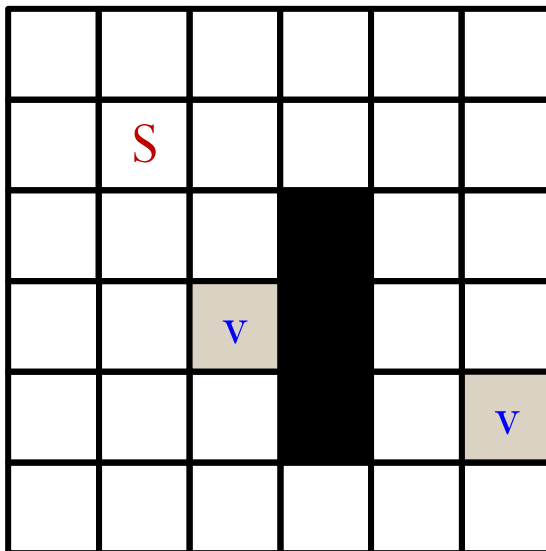
Layer 2



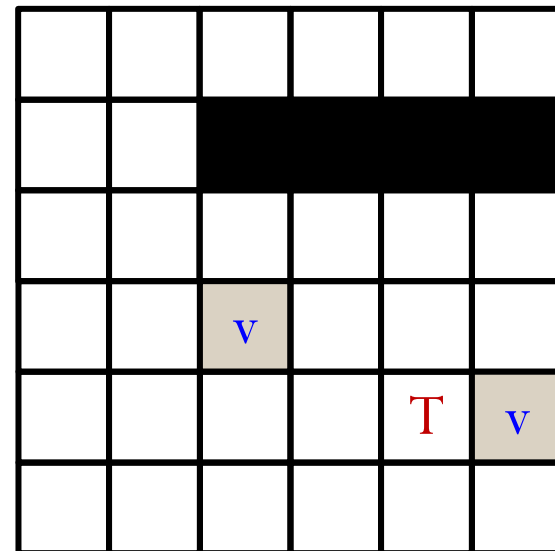
Vias

- **Constraint**: vias **cannot** be put everywhere – they are **only** allowed where “v” in grid.

Layer 1



Layer 2



2-Layer Example: Expand Step

Layer 1

2	1	2	3		
1	S	1	2	3	
2	1	2			
3	2	v 3			
	3				v

Layer 2

		v4			
				T	v

- New: What happens when we reach a place we can put a via?
 - Answer: we can expand on **the other** layer, keep adding unit cell costs (For now, assume that the cost of going through a via is just 1)...

2-Layer Example: Expand Step

- Now, expanding on both layers

Layer 1

2	1	2	3	4	5
1	S	1	2	3	4
2	1	2		4	5
3	2	v 3		5	6
4	3	4		6	v
5	4	5	6		

Layer 2

	6	5	6	7	
6	5	v 4	5	6	7
	6	5	6	T 7	v
		6			

2-Layer Example: Backtrace Step

- Backtrace: go through cells and also through vias.

Layer 1

2	1	2	3	4	5
1	S	1	2	3	4
2	1	2		4	5
3	2	v 3		5	6
4	3	4		6	v
5	4	5	6		

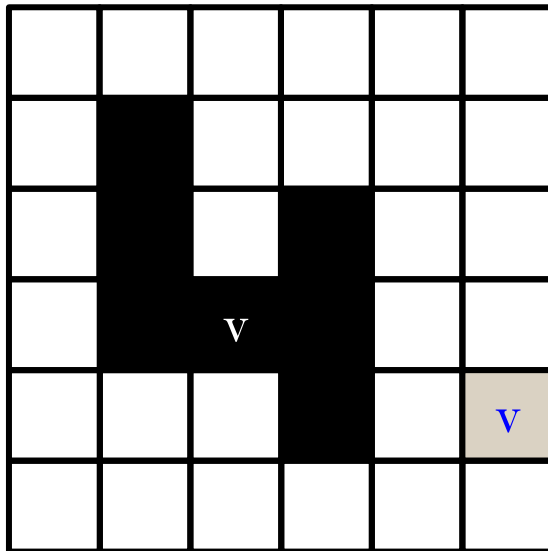
Layer 2

	6	5	6	7	
6	5	v 4	5	6	7
	6	5	6	T 7	v
		6			

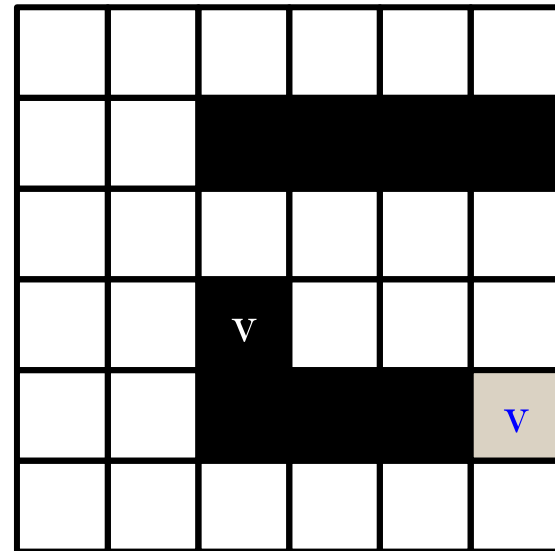
2-Layer Example: Clean-up Step

- Cleanup as usual. Now, new obstacles on **both** layers.

Layer 1



Layer 2



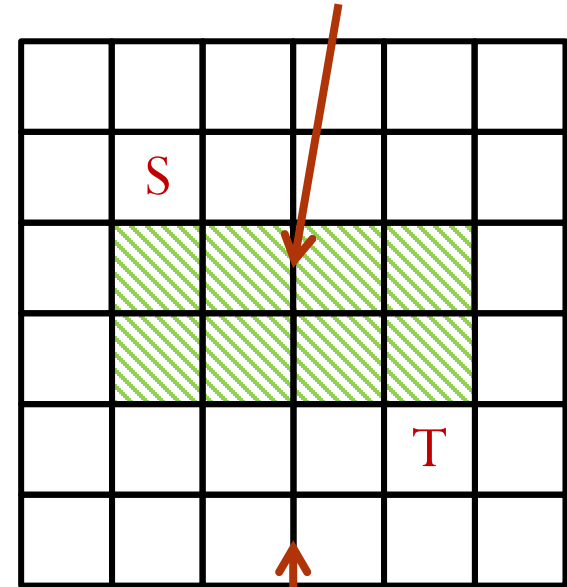
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New Feature: Non-Uniform Grid Costs

- Old problem
 - Each cell in grid costs the **same** to cross it with a wire.
 - Cost=1 over all the cells.
 - Is this necessary? **No!**
- Now
 - Given grid, source and target, we have **different** costs for each cell.
- The objective:
 - Find **minimum cost** path connecting source and target.

Shaded cells cost 3

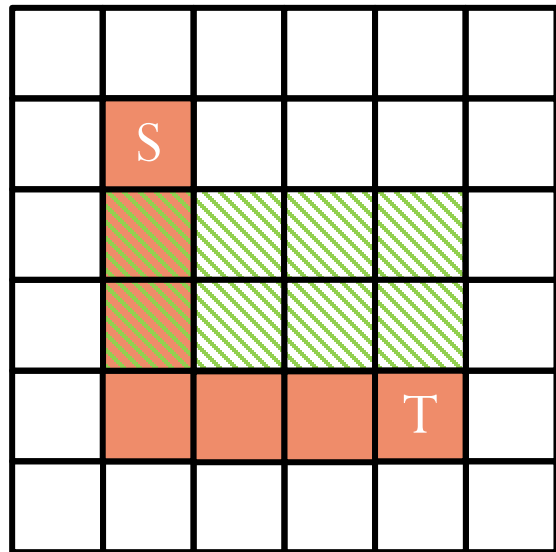


Unshaded cells still cost 1

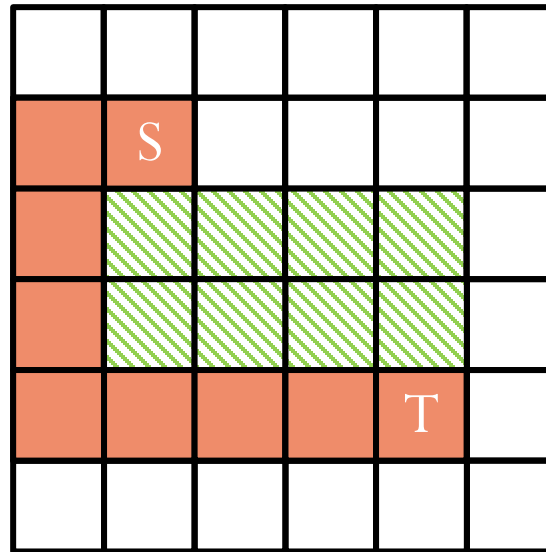


Path Cost

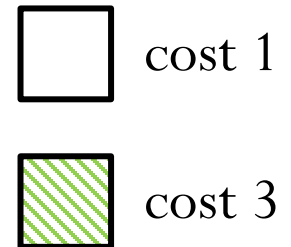
- Define path cost = $\sum_{\text{path}} (\text{cell costs})$



Path Cost = 10



Path Cost = 8



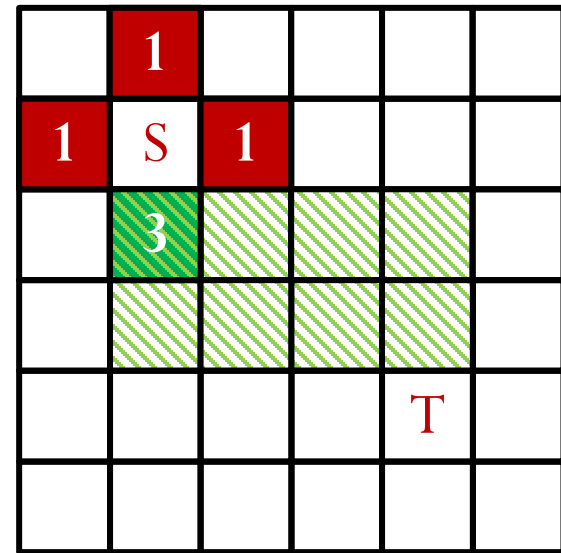
Our convention: when we count the cost, we ignore the first cell, because cost is measured from the center of a grid to the center of another grid.

Feature: Non-Uniform Grid Costs

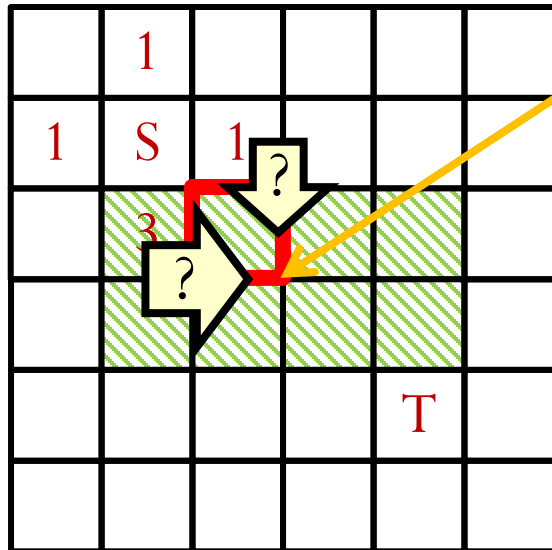
- Vital feature of **all** real routers
 - Use costs to **encourage** wires to take shapes and paths we prefer.
 - Can make the router **avoid congested areas** (too many wires want to be here).
 - Can make **different layers** have different expense to use.
 - Can make **different vias** have different expense to use.
 - Can make **different directions of expansion** have different expense.
 - Example: you want metal 2 mostly vertical, so left-right expansions cost more...
- Expansion process **uses costs**.

Subtle Search Issues with Non-Unit Costs

- Search all cells that are **adjacent** to source S.
 - When we reach a new cell, we label it with a **pathcost**.
 - **pathcost** = **pathcost of neighbor** plus cell's own cost.
- So far, so good...



Subtle Search Issues with Non-Unit Costs

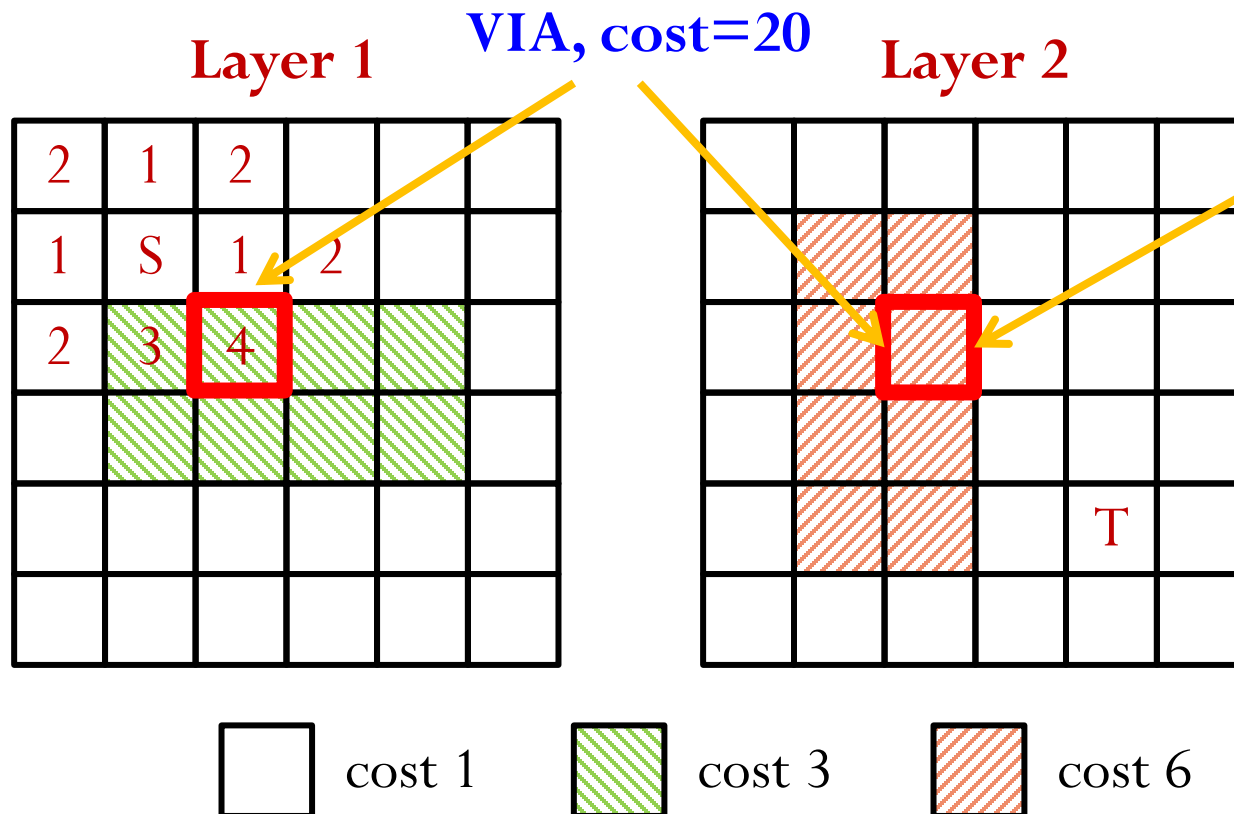


- **What is this cell's pathcost?**

- Is it $1 + 3 = 4$, reached "from" cell with cost 1 that is to the North?
- Is it $3 + 3 = 6$, reached "from" cell with cost 3 that is to the West?
- Answer: 4
 - Always want to label cells with the **minimum pathcost** to reach that cell.
- From this example: the order of expansion is important.

Subtle Issues: Via Costs

- Suppose we want to “expand” from “4” on Layer 1, through a via, to Layer 2.



Cost to reach
this cell is
 $4 + 20 + 6 = 30$:

- 4: **pathcost** to cell on Layer 1
- 20: **via cost**
- 6: this Layer 2 **cell cost**