# Practical Machine Learning - Final Project Coursera

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# **Project Introduction**

# Background

Using devices such as *Jawbone Up*, *Nike FuelBand*, and *Fitbit* it is now possible to collect a large amount of data about personal activity relatively inexpensively. These type of devices are part of the quantified self movement – a group of enthusiasts who take measurements about themselves regularly to improve their health, to find patterns in their behavior, or because they are tech geeks. One thing that people regularly do is quantify how *much* of a particular activity they do, but they rarely quantify *how well they do it*. In this project, your goal will be to use data from accelerometers on the belt, forearm, arm, and dumbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways. More information is available from the website here: http://groupware.les.inf.puc-rio.br/har (http://groupware.les.inf.puc-rio.br/har) (see the section on the Weight Lifting Exercise Dataset).

#### Data

The training data for this project are available here:

https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv (https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv)

The test data are available here:

https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv (https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv)

The data for this project come from this source: http://groupware.les.inf.puc-rio.br/har (http://groupware.les.inf.puc-rio.br/har). If you use the document you create for this class for any purpose please cite them as they have been very generous in allowing their data to be used for this kind of assignment.

# Goal

The goal of your project is to predict the manner in which they did the exercise. This is the *classe* variable in the training set. You may use any of the other variables to predict with. You should create a report describing how you built your model, how you used cross validation, what you think the expected out of sample error is, and why you made the choices you did. You will also use your prediction model to predict 20 different test cases.

# Summary

- · Data Processing
- · Model Building
- Conclusion

# **Data Processing**

# Libraries

library(caret); library(ggplot2); library(randomForest); library(corrplot); library(rattle); library(gbm); library(e1071); library(dplyr)

# **Loading Data**

"stringsAsFactors = TRUE" is used to get a factor type instead of strings. It will be usefull later to get the Confusion Matrices.

train\_test <- read.csv(url("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-trainin
g.csv"), stringsAsFactors = TRUE)
validation <- read.csv(url("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.c
sv"), stringsAsFactors = TRUE)</pre>

# Cleaning the training data

#Describing Data
str(train\_test %>% select(classe, everything()));dim(train\_test)

```
## 'data.frame': 19622 obs. of 160 variables:
## $ classe
                            : Factor w/ 5 levels "A", "B", "C", "D", ...: 1 1 1 1 1 1 1 1 1 1 1
. . .
## $ X
                            : int 1 2 3 4 5 6 7 8 9 10 ...
                           : Factor w/ 6 levels "adelmo", "carlitos",..: 2 2 2 2 2 2 2 2 2
## $ user name
## $ raw_timestamp_part_1 : int 1323084231 1323084231 1323084232 1323084232 1
323084232 1323084232 1323084232 1323084232 ...
## $ raw_timestamp_part_2 : int 788290 808298 820366 120339 196328 304277 368296 440390
484323 484434 ...
## $ cvtd_timestamp
                           : Factor w/ 20 levels "02/12/2011 13:32",..: 9 9 9 9 9 9 9 9 9
9 ...
## $ new_window
                           : Factor w/ 2 levels "no", "yes": 1 1 1 1 1 1 1 1 1 1 ...
## $ num window
                           : int 11 11 11 12 12 12 12 12 12 12 ...
## $ roll belt
                           : num 1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
## $ pitch_belt
                           : num 8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
## $ yaw_belt
                           : num -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -9
4.4 ...
## $ total_accel_belt
                           : int 3 3 3 3 3 3 3 3 3 ...
## $ kurtosis_roll_belt
                           : Factor w/ 397 levels "","-0.016850",..: 1 1 1 1 1 1 1 1 1 1 1
. . .
                           : Factor w/ 317 levels "","-0.021887",..: 1 1 1 1 1 1 1 1 1 1 1
## $ kurtosis_picth_belt
## $ kurtosis_yaw_belt
                           : Factor w/ 2 levels "","#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
                           : Factor w/ 395 levels "","-0.003095",..: 1 1 1 1 1 1 1 1 1 1 1
## $ skewness_roll_belt
. . .
                           : Factor w/ 338 levels "","-0.005928",..: 1 1 1 1 1 1 1 1 1 1 1
## $ skewness_roll_belt.1
## $ skewness yaw belt
                           : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
                           : num NA NA NA NA NA NA NA NA NA ...
## $ max roll belt
## $ max picth belt
                           : int NA NA NA NA NA NA NA NA NA ...
                           : Factor w/ 68 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1
## $ max_yaw_belt
. . .
## $ min roll belt
                           : num NA NA NA NA NA NA NA NA NA ...
                           : int NA ...
## $ min pitch belt
                           : Factor w/ 68 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 1
## $ min yaw belt
. . .
## $ amplitude_roll_belt
                           : num NA NA NA NA NA NA NA NA NA ...
## $ amplitude pitch belt
                           : int NA NA NA NA NA NA NA NA NA ...
## $ amplitude_yaw_belt
                           : Factor w/ 4 levels "","#DIV/0!","0.00",..: 1 1 1 1 1 1 1 1 1
1 ...
## $ var total accel belt
                           : num NA NA NA NA NA NA NA NA NA ...
                                  NA NA NA NA NA NA NA NA NA ...
## $ avg roll belt
                            : num
                           : num NA NA NA NA NA NA NA NA NA ...
## $ stddev roll belt
## $ var_roll_belt
                                  NA NA NA NA NA NA NA NA NA ...
                           : num
## $ avg pitch belt
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
                                  NA NA NA NA NA NA NA NA NA ...
## $ stddev pitch belt
                           : num
## $ var pitch belt
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_belt
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
## $ stddev yaw belt
                                  NA NA NA NA NA NA NA NA NA ...
                           : num
## $ var yaw belt
                           : num
                                  NA NA NA NA NA NA NA NA NA ...
## $ gyros belt x
                           : num
                                  ## $ gyros belt y
                           : num
                                  0 0 0 0 0.02 0 0 0 0 0 ...
                           : num -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 0
## $ gyros_belt_z
## $ accel belt x
                           : int -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
## $ accel_belt_y
                           : int 4453243424...
```

```
: int 22 22 23 21 24 21 21 21 24 22 ...
##
   $ accel belt z
   $ magnet_belt_x
                            : int
                                  -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
##
                                  599 608 600 604 600 603 599 603 602 609 ...
##
   $ magnet belt y
                            : int
                                  -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
  $ magnet belt z
                            : int
   $ roll arm
                                  ##
                            : num
##
  $ pitch_arm
                                  22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
                                  $ yaw arm
##
                            : num
                                  34 34 34 34 34 34 34 34 34 ...
                            : int
##
  $ total_accel_arm
## $ var_accel_arm
                                  NA NA NA NA NA NA NA NA NA ...
                            : num
##
  $ avg_roll_arm
                            : num
                                  NA NA NA NA NA NA NA NA NA ...
## $ stddev roll arm
                                  NA NA NA NA NA NA NA NA NA ...
                            : num
  $ var roll arm
                                  NA NA NA NA NA NA NA NA NA ...
##
                            : num
## $ avg_pitch_arm
                                  NA NA NA NA NA NA NA NA NA ...
                            : num
## $ stddev_pitch_arm
                            : num
                                  NA NA NA NA NA NA NA NA NA ...
##
  $ var_pitch_arm
                            : num
                                  NA NA NA NA NA NA NA NA NA ...
  $ avg yaw arm
                                  NA NA NA NA NA NA NA NA NA ...
                            : num
                                  NA NA NA NA NA NA NA NA NA ...
##
   $ stddev_yaw_arm
                            : num
## $ var_yaw_arm
                                  NA NA NA NA NA NA NA NA NA ...
                            : num
                                  ## $ gyros_arm_x
                            : num
## $ gyros_arm_y
                            : num
                                  0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03
. . .
                                  -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
## $ gyros_arm_z
                            : num
                                  -288 -290 -289 -289 -289 -289 -289 -288 -288 ...
## $ accel_arm_x
                            : int
## $ accel_arm_y
                            : int 109 110 110 111 111 111 111 111 109 110 ...
## $ accel arm z
                            : int
                                  -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
                                  -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
## $ magnet arm x
                            : int
   $ magnet_arm_y
                            : int
                                  337 337 344 344 337 342 336 338 341 334 ...
## $ magnet arm z
                            : int 516 513 513 512 506 513 509 510 518 516 ...
## $ kurtosis_roll_arm
                            : Factor w/ 330 levels "","-0.02438",..: 1 1 1 1 1 1 1 1 1 1 1
                            : Factor w/ 328 levels "","-0.00484",..: 1 1 1 1 1 1 1 1 1 1 1
##
   $ kurtosis_picth_arm
. . .
                            : Factor w/ 395 levels "","-0.01548",..: 1 1 1 1 1 1 1 1 1 1
## $ kurtosis_yaw_arm
                            : Factor w/ 331 levels "","-0.00051",..: 1 1 1 1 1 1 1 1 1 1 1
## $ skewness_roll_arm
. . .
                            : Factor w/ 328 levels "","-0.00184",..: 1 1 1 1 1 1 1 1 1 1 1
## $ skewness pitch arm
                            : Factor w/ 395 levels "","-0.00311",..: 1 1 1 1 1 1 1 1 1 1 1
## $ skewness_yaw_arm
##
   $ max roll arm
                                  NA NA NA NA NA NA NA NA NA ...
                            : num
                                  NA NA NA NA NA NA NA NA NA ...
##
   $ max picth arm
                            : num
  $ max yaw arm
                            : int
                                  NA NA NA NA NA NA NA NA NA ...
##
  $ min roll arm
                            : num
                                  NA NA NA NA NA NA NA NA NA ...
##
  $ min pitch arm
                                  NA NA NA NA NA NA NA NA NA ...
                            : num
##
   $ min yaw arm
                            : int
                                  NA NA NA NA NA NA NA NA NA ...
##
   $ amplitude roll arm
                            : num
                                  NA NA NA NA NA NA NA NA NA ...
  $ amplitude pitch arm
                            : num
                                  NA NA NA NA NA NA NA NA NA ...
##
  $ amplitude yaw arm
                            : int
                                  NA NA NA NA NA NA NA NA NA ...
##
  $ roll dumbbell
                                  13.1 13.1 12.9 13.4 13.4 ...
                            : num
##
  $ pitch_dumbbell
                            : num
                                  -70.5 -70.6 -70.3 -70.4 -70.4 ...
                            : num
##
   $ yaw dumbbell
                                  -84.9 -84.7 -85.1 -84.9 -84.9 ...
## $ kurtosis_roll_dumbbell : Factor w/ 398 levels "","-0.0035","-0.0073",..: 1 1 1 1 1 1 1
1 1 1 ...
## $ kurtosis_picth_dumbbell : Factor w/ 401 levels "","-0.0163","-0.0233",..: 1 1 1 1 1 1 1
111...
   $ kurtosis_yaw_dumbbell
                            : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
   $ skewness roll dumbbell : Factor w/ 401 levels "","-0.0082","-0.0096",..: 1 1 1 1 1 1
```

```
1 1 1 ...
## $ skewness_pitch_dumbbell : Factor w/ 402 levels "","-0.0053","-0.0084",..: 1 1 1 1 1 1 1
1 1 1 ...
## $ skewness_yaw_dumbbell : Factor w/ 2 levels "","#DIV/0!": 1 1 1 1 1 1 1 1 1 1 1 ...
## $ max_roll_dumbbell
                             : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_dumbbell
                            : num NA NA NA NA NA NA NA NA NA ...
                             : Factor w/ 73 levels "","-0.1","-0.2",...: 1 1 1 1 1 1 1 1 1 1 1
## $ max_yaw_dumbbell
## $ min_roll_dumbbell
                             : num NA NA NA NA NA NA NA NA NA ...
## $ min_rorr_dumbbell

## dumbbell
                             : num NA NA NA NA NA NA NA NA NA ...
                             : Factor w/ 73 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1
. . .
##
   [list output truncated]
```

```
## [1] 19622 160
```

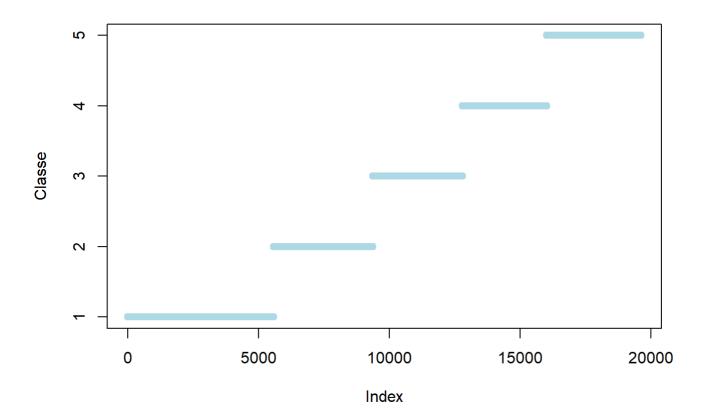
```
class(train_test$classe);summary(train_test %>% select(classe))
```

```
## [1] "factor"
```

```
## classe
## A:5580
## B:3797
## C:3422
## D:3216
## E:3607
```

We are going to predict the variable *classe* that is composed of 5 possible outputs A, B, C, D and E as *factor* type.

```
par(mfrow=c(1,1))
plot(train_test$X,train_test$classe,xlab = "Index",ylab = "Classe",col="light blue")
```



By looking at the data, it can be noticed that the first seven columns are not related to the *classe* variable that is to be predicted, and there are columns containing NAs. More specifically, with the example of the index, the *classe* variable is ordered according to the index. By adding the index to our models, it can bias them as *X* should not have links with *classe* except by the way the data are ordered.

Let's remove these first seven columns and all the column containing NAs.

```
train_test <- train_test[,-c(1:7)]
train_test <- train_test[ , colSums(is.na(train_test)) == 0]</pre>
```

Then we remove the near zero variance variables to clean even more the data.

```
nzcv <- nearZeroVar(train_test)
train_test <- train_test[,-nzcv]</pre>
```

# **Data Partitioning**

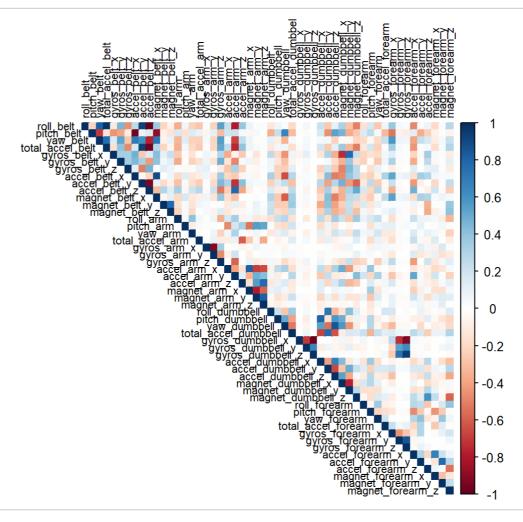
We decide to split it to sub-training and sub-testing set, with 85% going to the first one as the initial training set is very large.

```
set.seed(33244)
inTrain <- createDataPartition(y=train_test$classe, p=0.85, list = FALSE)
training <- train_test[inTrain,]
testing <- train_test[-inTrain,]
dim(training)</pre>
```

```
## [1] 16680 53
```

After cleaning, we are down to 53 variables. Let's have a look on their correlation

```
par(mfrow=c(1,1))
correl_plot <- corrplot(cor(training[,-53]),method="color",type="upper",tl.col="black",tl.cex
=0.7)</pre>
```



```
M <- abs(cor(training[,-53]))
diag(M) <- 0
# Highly correlated variables
which(M>0.9, arr.ind=T)
```

```
##
                  row col
## total_accel_belt
                  4
                       1
## accel_belt_y
                       1
## accel belt z
                   10
## accel belt x
                       2
## roll_belt
                    1
                       4
## accel_belt_y
                   9
                       4
## accel_belt_z
                   10
                       4
                  2
## pitch belt
## roll belt
## total_accel_belt 4 9
                 10 9
## accel belt z
## roll_belt
                  1 10
## total_accel_belt 4 10
## accel_belt_y
                  9 10
                   19 18
## gyros_arm_y
## gyros_arm_x
                  18 19
## gyros_dumbbell_z 33 31
## gyros_forearm_z 46 31
## gyros_dumbbell_x 31 33
## gyros_forearm_z 46 33
## gyros_dumbbell_x 31 46
## gyros_dumbbell_z 33 46
```

# **Model Building**

For this project, by looking at the structure of the data and the result that we are looking for, we will at first use models based on trees, and then we will try model based predictions.

Five models will be used:

- 1. Decision Tree
- 2. Random Forest
- 3. Gradient Boosting with trees
- 4. Linear Discriminant Analysis
- 5. Naive Bayes

Furthermore, for each model, we will use the raw data and the principal components data to see if the Principal Component Analysis generates a good prediction.

The algorithms will be only explained for the tree model as for the other models, it is the same principle by using the same **caret** functions.

# Preprocessing with PCA

As we have lots of variables, we try to use PCA to reduce dimensionality and by the same time the complexity.

```
preProc <- preProcess(training[,-53],method = "pca",pcaComp=20)
trainPC <- predict(preProc,training[,-53])
testPC <- predict(preProc,testing[,-53])
sum(var(trainPC))/52</pre>
```

```
## [1] 0.9201397
```

## [1] "We choose 20 Principal components as they explain 92.014 % of the variance"

# Training Control Parameters - Cross validations

We only use the 5-folds CV to reduce the overfitting in the different model while not adding too much complexity in our models (especially for the random forest).

```
fitControl <- trainControl(method="cv", number=5)</pre>
```

#### 1. Decision Tree

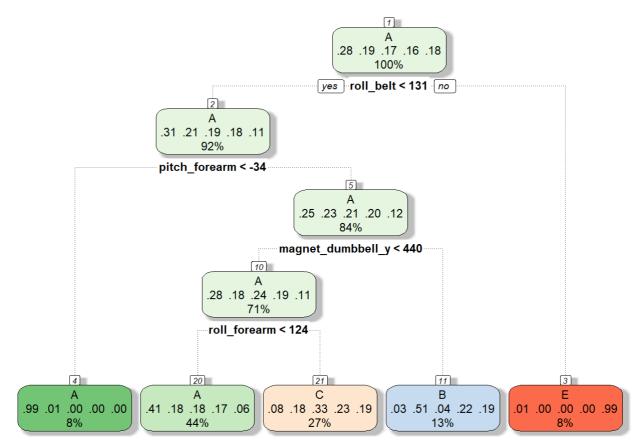
The Decision Tree model iteratively splits variables into groups and evaluates homogeneity within each group

```
#Model Building - Predicting with trees

#Set seed to have the same result each time as it is pseudo-random
set.seed(33244)

#Fit predictive model over different tuning parameters, here in the training data, we fit the
'classe' variable on the 'rpart' method with the 'fitControl' as the train control for the cr
oss validation
fit_tree <- train(classe~., method='rpart',data=training, trControl=fitControl)
#Use the model to predict on the testing set
pred_tree <- predict(fit_tree,newdata=testing)
#Create the confusion matrix to analyze the result on the testing set
cm_tree <- confusionMatrix(pred_tree,testing$classe)

#Plot the tree
par(mfrow=c(1,1))
library(rattle)
fancyRpartPlot(fit_tree$finalModel)</pre>
```



Rattle 2020-May-29 05:50:47 Jim

```
#With PCA
fit_tree_pc <- train(x=trainPC,y=training$classe, method='rpart',trControl=fitControl)
cm_tree_pc <- confusionMatrix(testing$classe,predict(fit_tree_pc,testPC))</pre>
```

### 2. Random Forest

The Random Forest is more complex than the Decision Tree but based on this one. It bootstraps samples, at each split bootstraps variables, grows multiples trees then votes for the best.

```
#Model Building - Predicting with Random Forest
set.seed(1234)
fit_rf <- train(classe~., method="rf", data=training,trControl= fitControl)
pred_rf <- predict(fit_rf,newdata=testing)
cm_rf <- confusionMatrix(pred_rf,testing$classe)

#With PCA
fit_rf_pc <- train(x=trainPC, y=training$classe, method="rf",trControl=fitControl)
cm_rf_pc <- confusionMatrix(testing$classe, predict(fit_rf_pc,testPC))</pre>
```

# 3. Gradient Boosting with trees

The GBM method takes lots of trees, weights them and creates a classifier that combines them.

```
#Model Building - Gradient Boosting with trees
set.seed(33244)
fit_gbm <- train(classe~., method="gbm", data=training, trControl=fitControl, verbose=FALSE)
pred_gbm <- predict(fit_gbm,newdata=testing)
cm_gbm <- confusionMatrix(pred_gbm,testing$classe)

#With PCA
fit_gbm_pc <- train(x=trainPC, y=training$classe, method="gbm", trControl=fitControl, verbose
=FALSE)
cm_gbm_pc <- confusionMatrix(testing$classe, predict(fit_gbm_pc, testPC))</pre>
```

# 4. Linear Discriminant Analysis

```
#Model building - Linear Discriminant Analysis
set.seed(33244)
fit_lda <- train(classe~., method="lda", data=training, trControl=fitControl)
pred_lda <- predict(fit_lda,newdata=testing)
cm_lda <- confusionMatrix(pred_lda,testing$classe)

#With PCA
fit_lda_pc <- train(x=trainPC, y=training$classe, method="lda",trControl=fitControl)
cm_lda_pc <- confusionMatrix(testing$classe, predict(fit_lda_pc,testPC))</pre>
```

# 5. Naive Bayes

```
set.seed(33244)
fit_nb <- train(classe~., method="nb", data=training, trControl=fitControl)
pred_nb <- predict(fit_nb,newdata=testing)
cm_nb <- confusionMatrix(pred_nb,testing$classe)
fit_nb_pc <- train(x=trainPC, y=training$classe, method="nb",trControl=fitControl)
cm_nb_pc <- confusionMatrix(testing$classe, predict(fit_nb_pc,testPC))</pre>
```

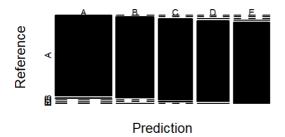
# Overall Comparison between the models

The comparison between the models is made in the testing sample to get the out of sample error.

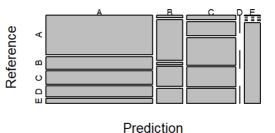
```
##
             Accuracy
                           Kappa AccuracyLower AccuracyUpper AccuracyNull
                                     0.4749805
            0.4932019 0.3356676
                                                    0.5114368
                                                                 0.2845003
## Tree
## Tree PCA 0.3810333 0.1673938
                                     0.3634404
                                                    0.3988632
                                                                 0.7535690
            0.9962610 0.9952699
                                     0.9933199
                                                    0.9981321
                                                                 0.2845003
## RF
## RF PCA
            0.9830048 0.9784964
                                     0.9776547
                                                    0.9873602
                                                                 0.2868797
## GBM
            0.9643100 0.9548426
                                     0.9569584
                                                    0.9707182
                                                                 0.2845003
            0.8130523 0.7632046
## GBM PCA
                                     0.7984857
                                                    0.8269935
                                                                 0.2987763
## LDA
            0.6957852 0.6149481
                                     0.6788017
                                                    0.7123784
                                                                 0.2845003
## LDA PCA
            0.4921822 0.3533047
                                     0.4739624
                                                    0.5104176
                                                                 0.3422842
            0.7433719 0.6713072
                                     0.7271820
                                                    0.7590762
                                                                 0.2845003
## NB
## NB PCA
            0.6094494 0.5050603
                                     0.5915484
                                                    0.6271324
                                                                 0.3052345
            AccuracyPValue McnemarPValue
##
## Tree
             1.009679e-125
                                      NaN
## Tree PCA
              1.000000e+00
                                      NaN
              0.000000e+00
                                      NaN
## RF
## RF PCA
              0.000000e+00
                                      NaN
## GBM
              0.000000e+00 5.930514e-04
## GBM PCA
              0.000000e+00 6.250094e-20
## LDA
              0.000000e+00
                            4.259102e-31
              8.246001e-63 2.673594e-39
## LDA PCA
## NB
              0.000000e+00
                            1.641261e-60
## NB PCA
             2.048762e-253 1.283481e-17
```

```
par(mfrow=c(2,2))
plot(cm_rf$table,cm_rf$byClass,main="Random Forest Confusion Matrix",col="black")
plot(cm_tree$table,cm_tree$byClass,main="Tree Prediction Confusion Matrix")
plot(cm_nb$table,cm_nb$byClass,main="Naive Bayes Confusion Matrix")
plot(cm_gbm$table, cm_gbm$byClass,main="GBM Confusion Matrix", col="black")
```

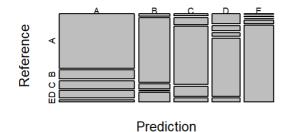
#### **Random Forest Confusion Matrix**



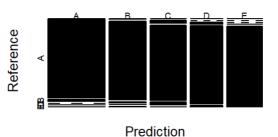
#### **Tree Prediction Confusion Matrix**



#### **Naive Bayes Confusion Matrix**



#### **GBM Confusion Matrix**



We can see that the PCA lower the accuracy in each case. It is hard to interpret why PCA reduces the accuracy, though it can be explained by the fact that PCA is linear while it's possible that we have non-linear dependencies.

According to the different charts above, the ranking by Accuracy and Kappa of the different method without PCA is

Random Forest > Boosting with trees > Naive Bayes > LDA > Decision Tree

The poor accuracy of the tree decision can be understood through its tree chart, it has only taken into account very few variables.

# Conclusion

# Chosen model - Random Forest without PCA

With the overall table, the accuracy of the Random Forest model is the highest, so its out of sample error is the lowest. Even if this model is very long to compute, we choose that one to predict the *classe* of the validation set.

Random Forest Out of sample error:

```
## [1] "Out Sample error is 0.3739 %"
```

Variables by Importance in the Random Forest model:

```
varImp(fit_rf)
```

```
## rf variable importance
##
     only 20 most important variables shown (out of 52)
##
##
##
                        Overall
## roll_belt
                        100.000
## pitch_forearm
                         58.616
## yaw belt
                         53,219
## magnet_dumbbell_y
                         44.011
## pitch belt
                         43.715
## magnet dumbbell z
                         43.468
## roll forearm
                         43.453
## accel_dumbbell_y
                         21.503
## accel_forearm_x
                         17.396
## magnet_dumbbell_x
                         16.193
## roll dumbbell
                         14.884
## magnet_belt_z
                         14.749
## magnet_forearm_z
                         14.730
## accel_belt_z
                         13.753
## total accel dumbbell
                         13.341
## accel dumbbell z
                         12.930
## magnet_belt_y
                         12.694
## yaw_arm
                         11.237
## gyros belt z
                         10.339
## magnet belt x
                          9.715
```

## Validation Prediction

Now, as the model is selected, we apply it to the validation test to predict to which *classe* the 20 test cases belong to.

```
pred_validation <- predict(fit_rf,validation)
pred_validation</pre>
```

```
## [1] B A B A A E D B A A B C B A E E A B B B
## Levels: A B C D E
```

```
paste("The expected Accuracy is ", round((cm_rf$overall[1])*100,digits = 4),"%")
```

## [1] "The expected Accuracy is 99.6261 %"