# Discussion 02

Spring 2019 – CS 188
Section 2B

#### Logical clocks

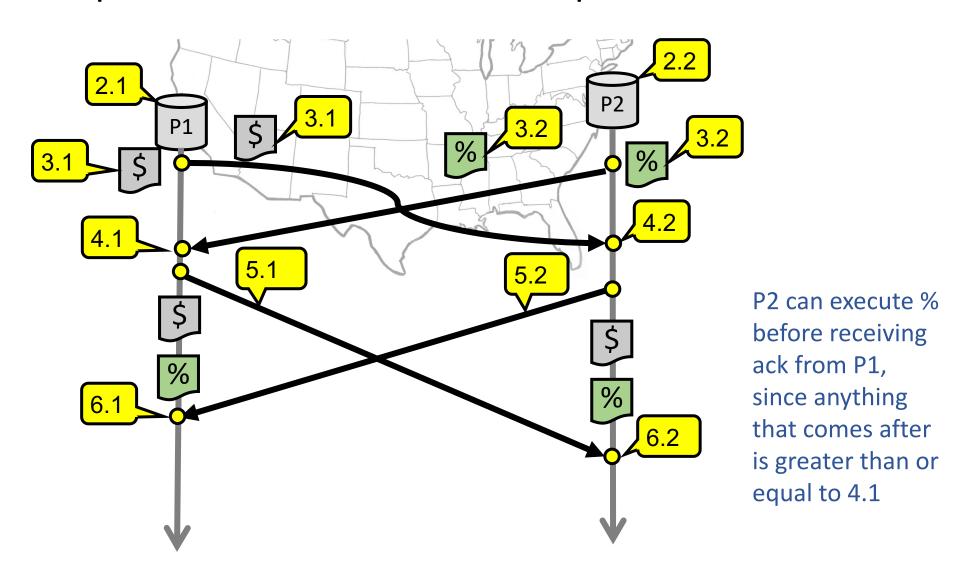
- Lamport clock
  - If a  $\rightarrow$  b, then C(a) < C(b)
  - If a causally leads to b, then C(a) < C(b)
- Vector clock
  - C(a) < C(b) if and only if  $a \rightarrow b$

#### The Lamport Clock Rules

- 1. Each process P<sub>i</sub> has their own local clock C<sub>i</sub>
- 2. Before executing an event,  $C_i \leftarrow C_i + 1$
- 3. Send the local clock value in the message m
- 4. On process P<sub>i</sub> receiving message m:

set C<sub>i</sub> and time of receive event to 1 + max{C<sub>i</sub>, C(m)}

#### Example 1: RSM with Lamport Clocks



#### The Vector Clock Rules

• Initially, all vectors start at [0, 0,..., 0]

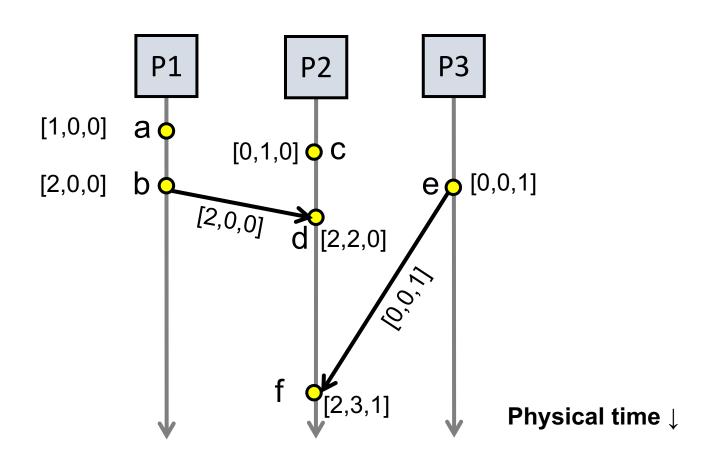
- Two rules for updating a vector
  - 1. For each local event on process i, increment local entry c<sub>i</sub> in vector by 1
  - 2. If process j receives message with vector  $[d_1, d_2, ..., d_n]$ :
    - Set each local entry c<sub>k</sub> = max{c<sub>k</sub>, d<sub>k</sub>}
    - Increment local entry c<sub>i</sub> in vector by 1

#### Example 2: Vector Clocks

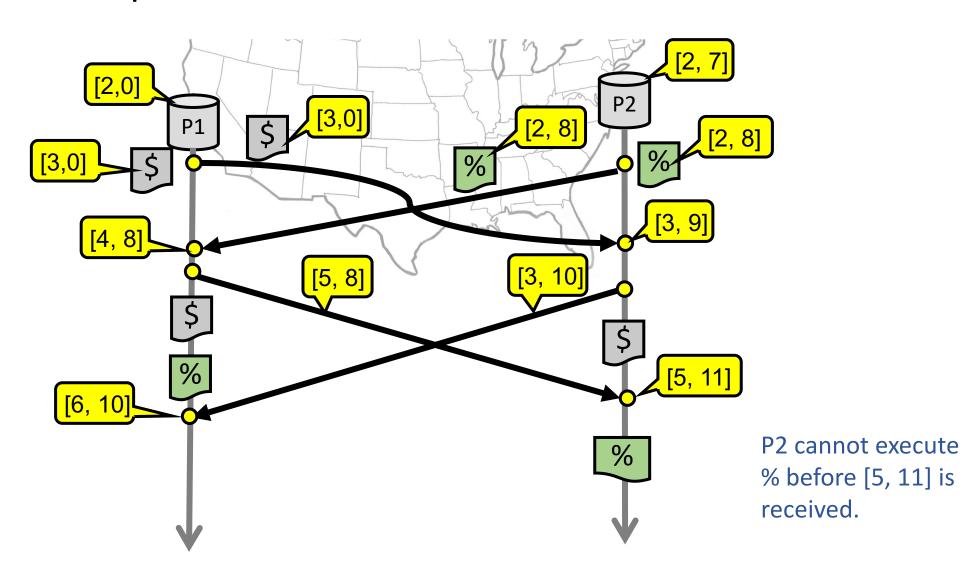
• All vectors start at [0, 0, 0]

Applying local update rule

Applying message rule



### Example 3: RSM with Vector Clocks



#### Recovering from crash failures

- Solution?
  - Checkpointing
    - Problem? Domino effect
    - Solution? Coordinated Checkpointing
      - Chandy-Lamport Snapshot

#### Chandy-Lamport Snapshot Rules

- If it is the first marker message received by P<sub>i</sub>:
  - Record all local state (take checkpoint)
  - Record state of channel from P<sub>i</sub> to P<sub>i</sub> as empty
  - Send marker messages on all outgoing channels
- If duplicate marker message received by P<sub>i</sub>:
  - Stop recording channel from P<sub>i</sub> to P<sub>i</sub>
  - Record state of channel as all messages received since marker
- Snapshot complete when every process has received marker on every incoming channel

## Example 4: Chandy-Lamport example

