Week 3 Spyros Mastorakis

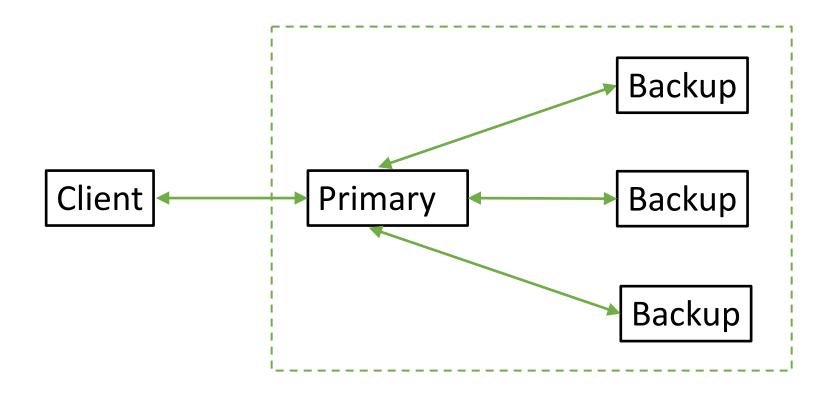
Outline

- Primary backup replication
- Assignment 2

What to do with fail-stop failures?

- Last time: crash failures
 - Replicas can resume execution with saved state
- Today: fail-stop failures
 - All state is lost upon failure
 - Need to replicate state proactively
- Approach: primary backup replication
- Challenges
 - What if primary or backup fails?
 - How can we keep them in sync?

Primary Backup Replication



Key Idea: transparently have two replicas, primary and backup

- Primary interacts with client
- Backup stores copy of primary's state

Handling failures

- How to handle primary failure?
 - Promote one of the backups to be the primary

- How to handle backup failure?
 - Add another machine as a backup

When to sync?

- It is okay for the primary to be out of sync until a change is externally visible
 - External consistency: primary backup in sync to external world
- Implications for when primary should sync with backups?
 - Sync must happen before any state change is externally visible

What to transfer during sync

- Heavyweight: send snapshot of primary's state
 - Slow!
 - When is this necessary?
 - When bootstrapping a new backup

- Lightweight: send every operation
 - Why is this okay?
 - Leverage determinism of state machine
 - Send any state necessary for backup to mimic execution

Transparent Primary Backup

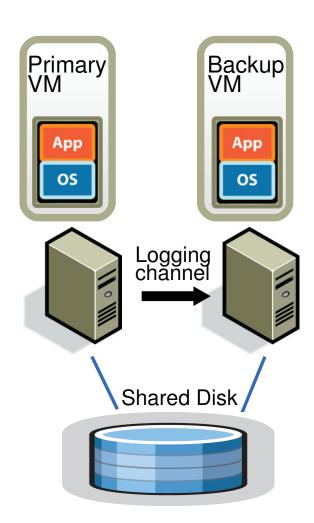
- Application relies on library to keep primary and backups in sync
- Library functions
 - Receive message from client
 - Sync with backups before sending response to client

- Will this solution work?
 - No! Does not capture nondeterminism in execution

VMM—based Primary Backup

- Primary and backup execute on two VMs
 - Primary logs inputs and outputs to log
 - Backup applies inputs from log
 - Primary waits for backup output

- Primary-backup monitor each other
 - If primary fails, backup takes over

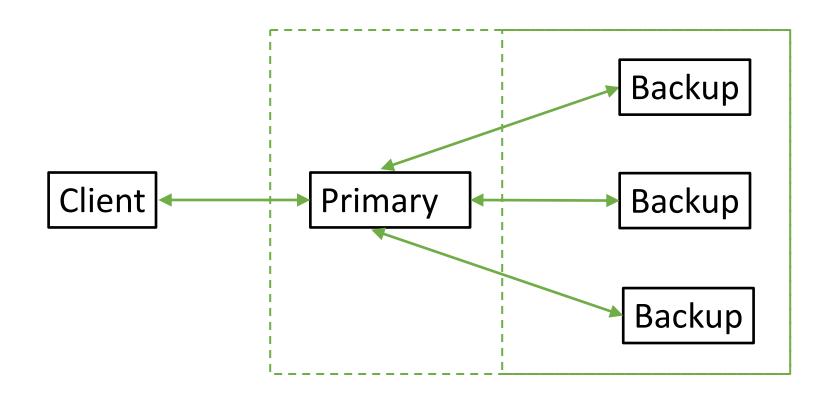


Log-based VM replication

 Primary VMM sends log entries to backup VMM over the logging channel

- Backup VMM (hypervisor) replays log entries
 - Stops backup VM at next input event or nondeterministic instruction
 - Delivers same input event as primary used
 - Delivers same nondeterministic value as primary
- Ensures backup and primary state never diverge

Primary Backup Replication



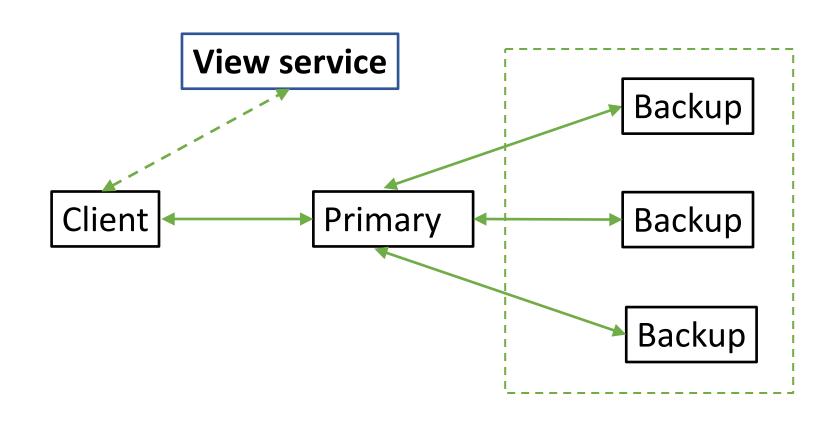
Client perspective

- What does a worker need to know in order to register itself with the replicated master?
 - Needs to know which machine is primary

- Can the primary be hardcoded into client app code?
 - No! Primary will get replaced when it fails

- How does the client discover the current primary?
 - Needs reliable service to do primary lookups

Primary Backup Replication



View Service

- Maintains current membership of primary-backup service (i.e., view)
 - Each view → (view number, primary, backup)
- When does a view service change the view?
 - When primary or any backup fails
 - Periodically exchange heartbeat messages to detect failures
- What if view service is down or not reachable?

Transitioning between views

View service broadcasts view change to all replicas

Primary must ACK new view once backup is up to date

- Two implications
 - Liveness detection timeout > state transfer time
 - Cannot change view if primary fails during sync

View Service

- Summary: view change has three steps
 - View service announces new view to all replicas
 - Primary syncs with new backup if there is one
 - Primary acknowledges new view

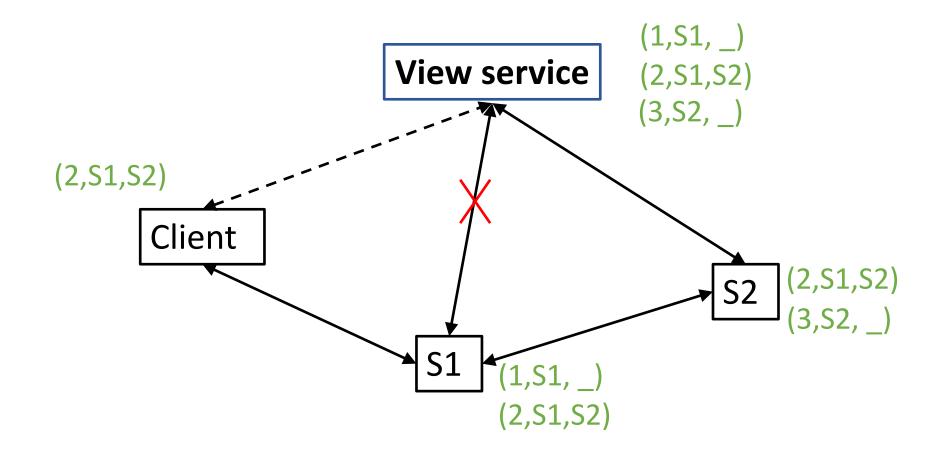
Stuck if primary fails in the midst of this process

Scalability of View Service

- Does every client need to contact view service before any operation?
 - No--clients can cache view across operations

- When to invalidate cached view?
 - Client invalidates cache when no response or negative response from replica it thinks is primary

Split Brain scenario



Avoiding Split Brain

- Primary must forward all operations to backups
 - Goal: get ACKs from backups that they too recognize primary

- Why can't backups be mistaken about who is primary?
 - Only a backup can be promoted as a primary

View Service Sequence Examples

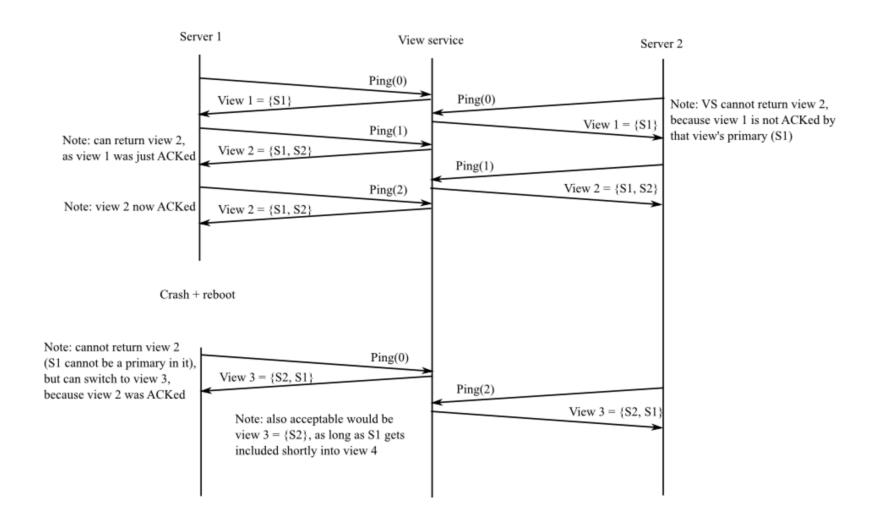
- Valid sequence of views
 - $(1, S1, _) \rightarrow (2, S1, S2) \rightarrow (3, S1, S3) \rightarrow (4, S3, S4) \rightarrow (5, S4, _)$

- Examples of invalid transitions between views:
 - $(1, S1, S2) \rightarrow (2, S3, S4)$
 - $(1, S1, S2) \rightarrow (2, _, S2)$
 - $(1, S1,) \rightarrow (2, S2, S1)$
 - $(2, S1, _) \rightarrow (1, S1, S2)$

Assignment 2

- Primary backup replication for a key/value service
- Coordination on who is the primary and who is a backup server through viewservice
- Viewservice monitors whether each server is alive or dead

Assignment 2 (cont'd)



Part A: Implementing the viewservice

- Based on previous figure, add field(s) to ViewServer in server.go in order to keep track of the most recent time at which the viewservice has heard a Ping from each server
- Viewservice keeps track of whether the primary for the current view has acknowledged it
- Viewservice needs to make periodic decisions, for example to promote the backup if the viewservice has missed DeadPings pings from the primary
- Study the test cases before you start programming
 - If you fail a test, you may have to look at the test code in test_test.go to figure out the failure scenario is

Part B: Primary backup key/value service

- Assumption: the viewservice never halts or crashes
- Implement the client and server parts
- Clients use the service by creating a Clerk object (see client.go) and calling its methods, which send RPCs to the service:
 - If the current primary does not respond, or doesn't think it's the primary, have the client consult the viewservice
- Server side:
 - Pings viewservice to find the current view
 - Primary forwards updates to backup
 - When a server becomes the backup in a new view, the primary should send it the primary's complete key/value database