A standard basis  $\{\vec{e}_i, \vec{e}_1, \dots, \vec{e}_n\}$ , the elements of  $\vec{e}_i$  are all zero except for ith element, which is one.

$$\vec{m} = \begin{bmatrix} d_1 \\ \vdots \\ d_n \end{bmatrix} = d_1 \vec{e}_1 + d_2 \vec{e}_1 + \cdots + d_n \vec{e}_n$$

$$= \sum_{i \neq 1} d_i \vec{e}_i$$

$$G(\vec{m}) = G(\Xi_i \vee i \vec{e}_i)$$

$$= \Xi_i \vee i \vec{e}_i$$

$$G(\vec{m}) = G(\Xi_i \vee i \vec{e}_i) = \Xi_i \vee G(\vec{e}_i)$$

$$G(\vec{m}) = \underbrace{\Xi_{d_i}\vec{e_i}}_{E_i}$$

$$G(\vec{m}) = G(\underbrace{\Xi_{i}}_{E_i}\vec{\Delta_i}\vec{e_i}) = \underbrace{\Xi_{d_i}}_{E_i}G(\underbrace{\vec{e_i}}_{i})$$

$$= [G(\vec{e_i}) - G(\vec{e_n})][\underbrace{\Delta_i}_{\Delta_n}]$$

$$= \vec{p} \vec{m}$$

$$= [G(\vec{e}_i) \cdots G(\vec{e}_n)],$$
and its size is mxn

= [G(e,) ... G(en)] m