Inversion Homework #1

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Appendix A

Exercise 4

Let

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 2 & 1 & 3 \\ 4 & 6 & 7 & 11 \end{bmatrix} \tag{1}$$

Find bases for $\mathcal{N}(\mathbf{A})$, $\mathcal{R}(\mathbf{A})$, $\mathcal{N}(\mathbf{A}^T)$, and $\mathcal{R}(\mathbf{A}^T)$. What are the dimensions of the four subspaces?

Solution:

To find $\mathcal{N}(\mathbf{A})$, we solve the system of equations $\mathbf{A}\mathbf{x} = 0$,

$$\mathbf{A}\mathbf{x} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 2 & 1 & 3 \\ 4 & 6 & 7 & 11 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
 (2)

Put the system of equations into an augmented matrix,

$$\begin{bmatrix}
1 & 2 & 3 & 4 & 0 \\
2 & 2 & 1 & 3 & 0 \\
4 & 6 & 7 & 11 & 0
\end{bmatrix}$$
(3)

and then find the reduced row echelon form (RREF),

$$\begin{bmatrix}
1 & 0 & -2 & -1 & 0 \\
0 & 1 & \frac{5}{2} & \frac{5}{2} & 0 \\
0 & 0 & 0 & 0 & 0
\end{bmatrix}$$
(4)

We can find that

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 2x_3 + x_4 \\ -\frac{5}{2}x_3 - \frac{5}{2}x_4 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 2 \\ -\frac{5}{2} \\ 1 \\ 0 \end{bmatrix} x_3 + \begin{bmatrix} 1 \\ -\frac{5}{2} \\ 0 \\ 1 \end{bmatrix} x_4$$
 (5)

So,

$$\mathcal{N}(\mathbf{A}) = \mathbf{space} \begin{pmatrix} \begin{bmatrix} 2 \\ -\frac{5}{2} \\ 1 \\ 0 \end{bmatrix} \begin{bmatrix} 1 \\ -\frac{5}{2} \\ 0 \\ 1 \end{bmatrix} \end{pmatrix}, \tag{6}$$

and the dimension of $\mathcal{N}(\mathbf{A})$ is 2.

To find $\mathcal{R}(\mathbf{A})$, the equations becomes $\mathbf{A}\mathbf{x} = \mathbf{b}$,

$$\mathbf{A}\mathbf{x} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 2 & 1 & 3 \\ 4 & 6 & 7 & 11 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \mathbf{b}$$
 (7)

Because the \mathbf{RREF} of \mathbf{A} is

$$\begin{bmatrix} 1 & 0 & -2 & -1 \\ 0 & 1 & \frac{5}{2} & \frac{5}{2} \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
 (8)

We can write \mathbf{b} as a linear combination of the first two columns of \mathbf{A} :

$$\mathbf{b} = x_1 \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 2 \\ 6 \end{bmatrix}, \tag{9}$$

i.e.

$$\mathcal{R}(\mathbf{A}) = \mathbf{space} \begin{pmatrix} \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} & \begin{bmatrix} 2 \\ 2 \\ 6 \end{bmatrix} \end{pmatrix}, \tag{10}$$

and the dimension of $\mathcal{R}(\mathbf{A})$ is 2.

To find $\mathcal{N}(\mathbf{A}^T)$ and $\mathcal{R}(\mathbf{A}^T)$, we first calculate the **RREF** of \mathbf{A}^T .

$$\mathbf{A}^T = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 2 & 6 \\ 3 & 1 & 7 \\ 4 & 3 & 11 \end{bmatrix},\tag{11}$$

RREF of A is
$$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$
 (12)

So,

$$\mathbf{x} = \begin{bmatrix} -2 \\ -1 \\ 0 \end{bmatrix} x_3,\tag{13}$$

i.e.

$$\mathcal{N}(\mathbf{A}^T) = \mathbf{space} \begin{pmatrix} \begin{bmatrix} -2\\ -1\\ 0 \end{bmatrix} \end{pmatrix},$$

$$\mathcal{R}(\mathbf{A}^T) = \mathbf{space} \begin{pmatrix} \begin{bmatrix} 1\\ 2\\ 3\\ 4 \end{bmatrix} \begin{bmatrix} 2\\ 2\\ 1\\ 3 \end{bmatrix} \end{pmatrix}.$$
(14)

And the dimension of $\mathcal{N}(\mathbf{A}^T)$ is 1, the dimension of $\mathcal{R}(\mathbf{A}^T)$ is 2.

Exercise 10

Show that if $\mathbf{x} \perp \mathbf{y}$, then

$$\|\mathbf{x} + \mathbf{y}\|_{2}^{2} = \|\mathbf{x}\|_{2}^{2} + \|\mathbf{y}\|_{2}^{2}.$$
 (15)

Solution:

$$\|\mathbf{x} + \mathbf{y}\|_{2}^{2} = \|\mathbf{x}\|_{2}^{2} + \|\mathbf{y}\|_{2}^{2} + 2\|\mathbf{x}\|_{2}\|\mathbf{y}\|_{2}\cos\theta$$
(16)

Because $\mathbf{x} \perp \mathbf{y}$, so $\cos \theta = 0$, i.e.

$$\|\mathbf{x} + \mathbf{y}\|_{2}^{2} = \|\mathbf{x}\|_{2}^{2} + \|\mathbf{y}\|_{2}^{2} \tag{17}$$

We can consider another solution,

$$\|\mathbf{x} + \mathbf{y}\|_{2}^{2} = \sum_{i=1}^{n} (x_{i} + y_{i})^{2} = \sum_{i=1}^{n} x_{i}^{2} + \sum_{i=1}^{n} y_{i}^{2} + 2\sum_{i=1}^{n} x_{i}^{2} y_{i}^{2} = \|\mathbf{x}\|_{2}^{2} + \|\mathbf{y}\|_{2}^{2}$$
(18)

because $\mathbf{x}^T \mathbf{y} = \sum_{i=1}^n x_i^2 y_i^2 = 0$ when $\mathbf{x} \perp \mathbf{y}$.

Exercise 11

In this exercise, we will derive the formula (A.88) for the 1-norm of a matrix. Begin with the optimization problem

$$\|\mathbf{A}\|_{1} = \max_{\|\mathbf{x}\|_{1}=1} \|\mathbf{A}\mathbf{x}\|_{1}. \tag{19}$$

(a) Show that if $\|\mathbf{x}\|_1 = 1$, then

$$\|\mathbf{A}\mathbf{x}\|_{1} \le \max_{j} \sum_{i=1}^{m} |A_{i,j}|.$$
 (20)

Solution:

We define that **A** is a $m \times n$ matrix and **x** is a $m \times 1$ vector. Then we can write that:

$$\|\mathbf{A}\mathbf{x}\|_{1} = \sum_{i=1}^{m} |\mathbf{A}\mathbf{x}|_{i} = \sum_{i=1}^{m} \left| \sum_{j=1}^{n} A_{i,j} x_{j} \right|$$

$$\leq \sum_{i=1}^{m} \sum_{j=1}^{n} |A_{i,j}| |x_{j}| = \sum_{j=1}^{n} \left(\sum_{i=1}^{m} |A_{i,j}| \right) |x_{j}|$$

$$\leq \left(\max_{j} \sum_{i=1}^{m} |A_{i,j}| \right) \sum_{j=1}^{n} |x_{j}| = \max_{j} \sum_{i=1}^{m} |A_{i,j}|,$$
(21)

i.e.

$$\|\mathbf{A}\mathbf{x}\|_{1} \le \max_{j} \sum_{i=1}^{m} |A_{i,j}|.$$
 (22)

Note that $\|\mathbf{x}\|_1 = \sum_{j=1}^n |x_j| = 1$.

(b) Find a vector \mathbf{x} such that $\|\mathbf{x}\|_1 = 1$, and

$$\|\mathbf{A}\mathbf{x}\|_1 = \max_{j} \sum_{i=1}^{m} |A_{i,j}|.$$
 (23)

Solution:

To find such \mathbf{x} , we assume that the maximum is arrived in the k^{th} column, i.e.

$$\max_{j} \sum_{i=1}^{m} |A_{i,j}| = \sum_{i=1}^{m} |A_{i,k}|.$$
(24)

So, we can write that:

$$\|\mathbf{A}\mathbf{x}\|_{1} = \sum_{i=1}^{m} \left| \sum_{j=1}^{n} A_{i,j} x_{j} \right| = \sum_{i=1}^{m} |A_{i,k}|,$$

$$\implies \left| \sum_{j=1}^{n} A_{i,j} x_{j} \right| = |A_{i,k}|,$$

$$\implies x_{j} = \begin{cases} 0 & j \neq k \\ 1 & j = k \end{cases}.$$

$$(25)$$

Thus, the vector $\mathbf{x} = (0, 0, ..., 1, 0, ..., 0)^T$, i.e. the k^{th} component of the vector is $\mathbf{1}$, otherwise is $\mathbf{0}$.

(c) Conclude that

$$\|\mathbf{A}\|_{1} = \max_{\|\mathbf{x}\|_{1}=1} \|\mathbf{A}\mathbf{x}\|_{1} = \max_{j} \sum_{i=1}^{m} |A_{i,j}|.$$
 (26)

Solution:

$$\|\mathbf{A}\|_{1} = \|\mathbf{A}\|_{1} \|\mathbf{x}\|_{1} \ge \|\mathbf{A}\mathbf{x}\|_{1},$$

$$\Longrightarrow \|\mathbf{A}\|_{1} = \max_{\|\mathbf{x}\|_{1}=1} \|\mathbf{A}\mathbf{x}\|_{1} = \max_{j} \sum_{i=1}^{m} |A_{i,j}|.$$
(27)

Appendix B

Exercise 6

Suppose that $\mathbf{x} = (X_1, X_2)^T$ is a vector composed of two random variables with a multivariate normal distribution with expected value μ and covariance matrix \mathbf{C} , and that \mathbf{A} is a 2 by 2 matrix. Use properties of expected value and covariance to show that $\mathbf{y} = \mathbf{A}\mathbf{x}$ has expected value $\mathbf{A}\mu$ and covariance \mathbf{ACA}^T

Solution:

According to the question, we know that the JDF of this multivariate normal distribution (the dimension is 2) is:

$$f(\mathbf{x}) = |2\pi \mathbf{C}|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}(\mathbf{x} - \mu)^T \mathbf{C}^{-1}(\mathbf{x} - \mu)\right), \tag{28}$$

and we can simply define $D = |2\pi \mathbf{C}|^{-\frac{1}{2}}$ as D is a constant. Thus,

$$f(\mathbf{x}) = D \exp\left(-\frac{1}{2}(\mathbf{x} - \mu)^T \mathbf{C}^{-1}(\mathbf{x} - \mu)\right).$$
(29)

So,

$$E[\mathbf{y}] = E[\mathbf{A}\mathbf{x}] = \int_{-\infty}^{\infty} \mathbf{A}\mathbf{x} f(\mathbf{x}) \, d\mathbf{x} = \mathbf{A} \int_{-\infty}^{\infty} \mathbf{x} f(\mathbf{x}) \, d\mathbf{x} = \mathbf{A} E[\mathbf{x}] = \mathbf{A} \mu. \tag{30}$$

To covariance matrix of y, we consider that:

$$\mathbf{y} = \mathbf{A}\mathbf{x}, \Longrightarrow \mathbf{x} = \mathbf{A}^{-1}\mathbf{y},\tag{31}$$

and then, we replace \mathbf{x} with $\mathbf{A}^{-1}\mathbf{y}$ in $f(\mathbf{x})$:

$$f = D \exp\left(-\frac{1}{2}(\mathbf{x} - \mu)^T \mathbf{C}^{-1}(\mathbf{x} - \mu)\right)$$

$$= D \exp\left(-\frac{1}{2}(\mathbf{A}^{-1}\mathbf{y} - \mu)^T \mathbf{C}^{-1}(\mathbf{A}^{-1}\mathbf{y} - \mu)\right)$$

$$= D \exp\left(-\frac{1}{2}(\mathbf{A}^{-1}\mathbf{y} - \mathbf{A}^{-1}\mathbf{A}\mu)^T \mathbf{C}^{-1}(\mathbf{A}^{-1}\mathbf{y} - \mathbf{A}^{-1}\mathbf{A}\mu)\right).$$

$$= D \exp\left(-\frac{1}{2}(\mathbf{y} - \mathbf{A}\mu)^T (\mathbf{A}^T)^{-1} \mathbf{C}^{-1}\mathbf{A}^{-1}(\mathbf{y} - \mathbf{A}\mu)\right)$$

$$= D \exp\left(-\frac{1}{2}(\mathbf{y} - \mathbf{A}\mu)^T (\mathbf{A}\mathbf{C}\mathbf{A}^T)^{-1}(\mathbf{y} - \mathbf{A}\mu)\right)$$
(32)

It's obvious that the covariance matrix of \mathbf{y} is \mathbf{ACA}^T

Exercise 9

Using MATLAB, repeat the following experiment 1000 times. Generate five exponentially distributed random numbers from the exponential probability density function (B.10) with means $\mu = 1/\lambda = 10$. You may find the library function **exprnd** to be useful here. Use (B.74) to calculate a 95% confidence interval for the 1000 mean determinations. How many times out of the 1000 experiments did the 95% confidence interval cover the expected value of 10? What happens if you instead generate 50 exponentially distributed random numbers at time? Discuss your results.

Solution:

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- (1) About 847 times.
- (2) 959 times out of the 1000 experiments did the 95% confidence interval cover the expected value of 10 when I instead generate 50 exponentially distributed random numbers at time.
- (3) The random numbers under 50 samplings is closer to the exponential distribution than that under 5 samplings. Long live understanding!

Appendix C

Exercise 1

Let

$$f(\mathbf{x}) = x_1^2 x_2^2 - 2x_1 x_2^2 + x_2^2 - 3x_1^2 x_2 + 12x_1 x_2 - 12x_2 + 6.$$
(33)

Find the gradient, $\nabla f(\mathbf{x})$, and Hessian, $\mathbf{H}(f(\mathbf{x}))$. What are the critical points of f? Which of these are minima and maxima of f?

Solution:

$$\nabla f(\mathbf{x}) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix}$$

$$= \begin{bmatrix} 2x_1 x_2^2 - 2x_2^2 - 6x_1 x_2 + 12x_2 \\ 2x_1^2 x_2 - 4x_1 x_2 + 2x_2 - 3x_1^2 + 12x_1 - 12 \end{bmatrix}.$$
(34)

And

$$\mathbf{H}(f(\mathbf{x})) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} \end{bmatrix}
= \begin{bmatrix} 2x_2^2 - 6x_2 & 4x_1x_2 - 4x_2 - 6x_1 + 12 \\ 4x_1x_2 - 4x_2 - 6x_1 + 12 & 2x_1^2 - 4x_1 + 2 \end{bmatrix}.$$
(35)

A point \mathbf{x}^* is a critical point when $\nabla f(\mathbf{x}^*) = \mathbf{0}$,

$$\nabla f(\mathbf{x}) = \begin{bmatrix} 2x_1x_2^2 - 2x_2^2 - 6x_1x_2 + 12x_2 \\ 2x_1^2x_2 - 4x_1x_2 + 2x_2 - 3x_1^2 + 12x_1 - 12 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$
 (36)

Solving the function, we can get 2 critical points:

$$\mathbf{x}^* = (x_1, x_2) : (0, 6), (2, 0). \tag{37}$$

As the bottom figure shown (fig ??), (0,6) is minima of f, f(0,6) = -30, and f doesn't exist maxima or its maxima is a infinite value.

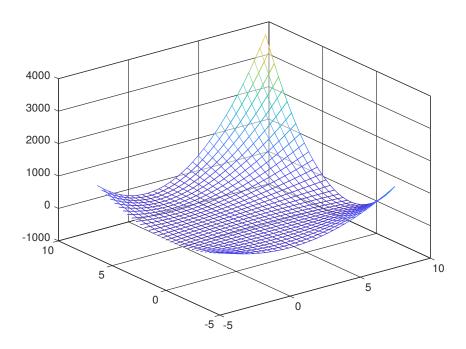


Figure 1: a function f graph of Appendix C exercise 1

Exercise 2

Find a Taylor's series approximation for $f(\mathbf{x} + \Delta \mathbf{x})$, where

$$f(\mathbf{x}) = e^{-(x_1 + x_2)^2} \tag{38}$$

is near the point

$$\mathbf{x} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}. \tag{39}$$

Solution:

$$\nabla f(\mathbf{x}) = \begin{bmatrix} -2(x_1 + x_2)e^{-(x_1 + x_2)^2} \\ -2(x_1 + x_2)e^{-(x_1 + x_2)^2} \end{bmatrix},$$

$$\mathbf{H}(f(\mathbf{x})) = \begin{bmatrix} -2(1 - 2(x_1 + x_2)^2)e^{-(x_1 + x_2)^2} & -2(1 - 2(x_1 + x_2)^2)e^{-(x_1 + x_2)^2} \\ -2(1 - 2(x_1 + x_2)^2)e^{-(x_1 + x_2)^2} & -2(1 - 2(x_1 + x_2)^2)e^{-(x_1 + x_2)^2} \end{bmatrix},$$

$$f(\mathbf{x} + \Delta \mathbf{x}) = f(\mathbf{x}) + \nabla f(\mathbf{x})^T \Delta \mathbf{x} + \frac{1}{2} \Delta \mathbf{x}^T \mathbf{H}(f(\mathbf{x})) \Delta \mathbf{x} + o^n.$$
(40)

Because
$$\mathbf{x} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$
, so:

$$f(\mathbf{x} + \Delta \mathbf{x}) = e^{-25} + \left[-10e^{-25}, -10e^{-25} \right] \Delta \mathbf{x} + \frac{1}{2} \Delta \mathbf{x}^T \begin{bmatrix} 98e^{-25} & 98e^{-25} \\ 98e^{-25} & 98e^{-25} \end{bmatrix} \Delta \mathbf{x} + o^n$$
(41)