1

Memory Allocation

MEMORY ALLOCATION — DYNAMIC

- = allocate + free memory chunks of arbitrary size at arbitrary points in time
- almost every program uses it (heap)
- don't have to statically specify complex data structures
- $-\ \mbox{can}$ have data grow as function of input size
- $-\ \mbox{kernel}$ itself uses dynamic memory allocation for its data structures

implementation: has huge impact on performance, both in user and kernel space

fact: it is impossible to construct memory allocator that always performs well

ightarrow need to understand trade-offs to pick good allocation strategy

DYNAMIC MEMORY ALLOCATION — PRINCIPLE

initial: pool of free memory

tasks

- satisfy arbitrary allocate + free requests from pool
- track which parts are in use/are free

restrictions

- cannot control order/number of requests
- cannot move allocated regions \rightarrow fragmentation = core problem!

DYNAMIC MEMORY ALLOCATION — BITMAP

idea:

- divide memory in allocation units of fixed size
- use bitmap to keep track if allocated (1) or free (0) $\,$

problem: needs additional data structure to store allocation length (otherwise cannot infer whether two adjacent allocations belong together or not from bitmap)

Dynamic Memory Allocation - List

method 1: use one list-node for each allocated data

- extra space needed for list
- allocation lengths already stored

 $\textbf{method 2} : use \ one \ list-node \ for \ each \ unallocated \ data$

- $-\ \mathsf{can}\ \mathsf{keep}\ \mathsf{list}\ \mathsf{in}\ \mathsf{unallocated}\ \mathsf{area}\ \mathsf{(store}\ \mathsf{size}\ \mathsf{of}\ \mathsf{free}\ \mathsf{area}\ \mathsf{+}\ \mathsf{pointer}\ \mathsf{to}\ \mathsf{next}\ \mathsf{free}\ \mathsf{area}\ \mathsf{in}\ \mathsf{free}\ \mathsf{area})$
- $-\ additional\ data\ structure\ needed\ to\ store\ allocation\ lengths$
- can search for free space with low overhead

method 3: both

DYNAMIC MEMORY ALLOCATION — PROBLEMS

fragmentation is hard to handle

factors needed for fragmentation to occur:

- different lifetimes
- $\ \textit{different sizes}$
- inability to relocate previous allocations

all fragmentation factors present in dynamic memory allocators!

${\bf ALLOCATION-BEST\ FIT\ VS.\ WORST\ FIT}$

 $\textbf{idea}: keep\ large\ free\ memory\ chunks\ together\ for\ larger\ allocation\ requests\ that\ may\ arrive\ later$

best-fit: allocate smallest free block large enough to store allocation request

- must search entire list
- -problem: sawdust remainder so small that over time left with unusable sawdust everywhere the sawdust of the sawdust everywhere the sawdust of the sawdust everywhere everywhere the sawdust everywhere the sawdust everywhere the sawdust everywhere the sawdust everywhere everywhere
- idea: minimize sawdust by turning strategy around

worst-fit: allocate largest free block

- must search entire list
- reality: worse fragmentation than best-fit

ALLOCATION — FIRST FIT

idea: if fragmentation occurs with best and worst fit, optimize for allocation speed

principle: allocate first hole big enough

- fastest allocation policy
- produced leftover holes of variable size
- reality: almost as good as best-fit

FIRST FIT - VARIANTS

first-fit sorted by address order

LIFO first-fit

next fit

ALLOCATION — BUDDY ALLOCATOR

idea: allocate memory in powers of 2

- all chunks have fixed 2^n -size \rightarrow allocation request rounded up to next-higher power of 2
- all chunks naturally aligned

no sufficiently small block available:

- select larger available chunk, split into two same-sized buddies
- continue until appropriately sized chunk is available

two buddies both free (2^n) : merge to 2^{n+1} -chunk