

proximal Algorithms. Neal Parikh 2013.

Setting: $f: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ closed proper convex. $\Rightarrow \text{epi } f$ nonempty closed convex.

proximal operator

$$\text{prox}_f(v) = \underset{x}{\text{argmin}} (f(x) + \frac{1}{2} \|x-v\|_2^2)$$

$$\text{prox}_{\lambda f}(v) = \underset{x}{\text{argmin}} (f(x) + \frac{\lambda}{2} \|x-v\|_2^2) = \underset{x}{\text{argmin}} (\lambda f(x) + \frac{1}{2} \|x-v\|_2^2)$$

在 v 附近最小化 $f(x)$ 的点

v 的位移: 距离增加和 $f(x)$ 增加的 tradeoff.

Gradient descent perspective

$$\text{prox}_{\lambda f}(v) \approx v - \lambda \nabla f(v)$$

↑
step size

important property: link with fixed point theory: $\text{prox}_f(x^*) = x^*$ iff x^* minimize $f(x)$

properties & definitions of proximal operators:

① f separable $f(x,y) = \varphi(x) + \psi(y) \Rightarrow \text{prox}_f(v,w) = (\text{prox}_{\varphi}(v), \text{prox}_{\psi}(w))$

↓
sum. joint.

② $x \in \mathbb{R}^n, f(x) = \sum_{i=1}^n f_i(x_i) \Rightarrow (\text{prox}_f(v))_i = \text{prox}_{f_i}(x_i)$

③ $f(x) = \alpha \varphi(x) + b, \alpha > 0 \Rightarrow \text{prox}_{\lambda f}(v) = \text{prox}_{\alpha \lambda \varphi}(v)$

$f(x) = \varphi(\alpha x + b), \alpha \neq 0 \Rightarrow \text{prox}_{\lambda f}(v) = \frac{1}{\alpha} (\text{prox}_{\alpha \lambda \varphi}(\alpha v + b) - b)$

④ orthogonal $Q, f(x) = \varphi(Qx) \Rightarrow \text{prox}_{\lambda f}(v) = Q^T \text{prox}_{\lambda \varphi}(Qv)$

⑤ $f(x) = \varphi(x) + a^T x + b, \Rightarrow \text{prox}_{\lambda f}(v) = \text{prox}_{\lambda \varphi}(v - \lambda a)$

⑥ $f(x) = \varphi(x) + \frac{\rho}{2} \|x-a\|_2^2, \Rightarrow \text{prox}_{\lambda f}(v) = \text{prox}_{\lambda \varphi}((\frac{\tilde{\lambda}}{\tilde{\lambda}+1})v + (\frac{1}{\tilde{\lambda}+1})a) \quad \tilde{\lambda} = \frac{\lambda}{1+\lambda\rho}$

Fixed point algorithms:

defs: ① contraction: f Lipschitz continuous with $K < 1, d(fx, fy) \leq K d(x,y), K < 1$

② non-expansive: f Lipschitz continuous with $K=1, d(fx, fy) \leq d(x,y)$

③ firmly non-expansive: f ~~Lipschitz~~ $\|d(fx, fy)\|^2 \leq (x-y)^T (fx-fy)$ [can prove to be Lipschitz-1] [vector space]

④ averaged operator: N is nonexpansive: $T = (1-\alpha)I + \alpha N$

Thms: ① contraction can find fixed point $fx=x^*$ by $x^{(k+1)} = f(x^{(k)})$

② averaged operator can also find fixed point using ①

③ firmly nonexpansive operators are indeed $\frac{1}{2}$ averaged operator. $\forall T \text{ firm} \Rightarrow 2I - T$ nonexp

④ averaged operators are closed under composition, but firmly nonexpansives are not.

⑤ proximal operators are firmly expansive operators



⑥ if N is only nonexpansive, update by $x^{(k+1)} = (1-\alpha)x^{(k)} + \alpha N(x^{(k)})$ [JN average].

def: proximal average of $f_1 \dots f_m$. closed proper convex g s.t. $\frac{1}{m} \sum_{i=1}^m \text{prox}_{f_i} = \text{prox}_g$.

Moreau decomposition: $v = \text{prox}_f(v) + \text{prox}_{f^*}(v)$ f^* : conjugate = $\sup_x (y^T x - f(x))$

e.g. $v = \pi_L(v) + \pi_{L^\perp}(v)$. $f(x) = I_L(x)$, $(I_L(x))^* = I_{L^\perp}(x)$ $\text{prox}_{I_L}(v) = \pi_L(v)$

e.g. $v = \pi_K(v) + \pi_{K^\circ}(v)$ $K^\circ = \{y: y^T x \leq 0, \forall x \in K\}$ polar cone, negative ~~cone~~ of dual cone.

can be used as. $\text{prox}_{f^*}(v) = v - \text{prox}_f(v)$.

"Smooth" approximation perspective of proximal operator.

infimal convolution: $f \square g(v) = \inf_x [f(x) + g(v-x)]$ $v \in \text{dom } f + \text{dom } g$.

Moreau envelope: $M_{\lambda f}(x) = \inf_x [f(x) + \frac{\lambda}{2} \|v-x\|_2^2]$

if define $h(x, v) = f(x) + \frac{1}{2\lambda} \|v-x\|_2^2$

$M_{\lambda f}(v) = h(\text{prox}_{\lambda f}(v), v)$

(Moreau-Tosida regularization)

$M_{\lambda f}(v)$ & $f(x)$ have the same minimizers.

Always continuously differentiable

Always have domain \mathbb{R}^n

Establish a approximation relationship between $M_{\lambda f}(x)$ and $f(x)$:

M_f is a smoothed version of f .

property $(f \square g)^* = f^* \square g^* \Rightarrow M_f^* = f^* + (\frac{1}{2\lambda} \|\cdot\|_2^2)^* \Rightarrow M_f^* = f^* + \frac{1}{2\lambda} \|\cdot\|_2^2$

$M_f^* = M_f$

$\Rightarrow M_f = (f^* + \frac{1}{2\lambda} \|\cdot\|_2^2)^*$ dual \rightarrow regularize \rightarrow dual. (it's smooth)
(get strong convex)

$M_{\lambda f}$ differentiable, so we can take derivative.

~~$M_{\lambda f}(\text{prox}_{\lambda f}(x))$~~ ~~$M_{\lambda f}(x) = h(\text{prox}_{\lambda f}(x), x)$~~ =

~~$M_{\lambda f}(v) = h(\text{prox}_{\lambda f}(v), v) = f(\text{prox}_{\lambda f}(v)) + \frac{1}{2\lambda} \|v - \text{prox}_{\lambda f}(v)\|_2^2$~~

$\Rightarrow \text{prox}_{\lambda f}(x) = x - \lambda \nabla M_{\lambda f}(x)$ \rightarrow approximate $\nabla f(x)$. [so it's a gradient descent step].

$\text{prox}_f(x) = \nabla M_f(x)$.

proximal operator is the resolvent of subdifferential operator.

$\text{prox}_{\lambda f} = (I + \lambda \partial f)^{-1}$ what's nontrivial here: $(I + \lambda \partial f)^{-1}$ becomes single-valued mapping
 \uparrow subgradient of f

More perspective from gradient descent:

① $\text{prox}_{\lambda f}(x) = x - \lambda \nabla M_{\lambda f}(x)$.

② if $\nabla f(x)$ exists, first-order approximation $\hat{f}_v^{(1)}(x) = f(v) + \nabla f(v)^T (x-v)$.

then $\text{prox}_{\hat{f}_v^{(1)}}(v) = v - \lambda \nabla f(v)$. explain: minimize first-order approximation of $f(x)$ at point v (near v)
result is a gradient descent step from v .

③ if $\nabla^2 f(x)$ exists, second-order approximation $\hat{f}_v^{(2)}(x) = f(v) + \nabla f(v)^T (x-v) + \frac{1}{2} (x-v)^T \nabla^2 f(v) (x-v)$

then $\text{prox}_{\hat{f}_v^{(2)}}(v) = v - (\nabla^2 f(v) + \frac{1}{\lambda} I)^{-1} \nabla f(v)$ explain: similar, but 2-order, result in a Levenberg-Marquardt step.

Trust Region problem perspective.

trust region problem:

$$\min f(x) \\ \text{s.t. } \|x - v\|_2 \leq \rho.$$

proximal problem:

$$\min f(x) + \frac{1}{2\lambda} \|x - v\|_2^2$$

relationship: solution for some ρ $\xleftarrow{\text{is a}}$ solution

solution $\xrightarrow{\quad}$ unconstrained minimizer of f / solution for some λ

Above is the interpretation of proximal operator.

Algorithms.

[1] Direct proximal minimization

$$x^{k+1} = \text{prox}_{\lambda f}(x^k). \quad \text{guarantee convergence with } \lambda_k > 0, \sum_{k=1}^{\infty} \lambda_k = \infty.$$

application: ill-conditioned f [we add a quadratic term to be strong convex]

perspective: $x^{k+1} = \arg\min_x f(x) + \frac{1}{2\lambda_k} \|x - x^k\|_2^2$ regularization gets smaller as $x \rightarrow x^*$.
e.g. of application: iterative refinement. $f(x) = \frac{1}{2} x^T A x - b^T x$. ill-conditioned A .
the impact of the term disappears with iterations.

$$\begin{aligned} \text{prox}_{\lambda f}(x^k) &= (A + \frac{1}{\lambda} I)^{-1} (b + \frac{1}{\lambda} x^k) \\ &= x^k + (A + \frac{1}{\lambda} I)^{-1} (b - A x^k) \\ &\quad \downarrow \\ &\quad \hat{A}. \quad \text{iteratively compensating for } \hat{A} - A \text{ difference.} \end{aligned}$$

[2] Proximal gradient Method.

$\min f(x) + g(x)$. $f(x)$ differentiable. both closed proper convex, $g(x)$ can be non-smooth.

$$x^{k+1} = \text{prox}_{\lambda g}(x^k - \lambda^k \nabla f(x^k)) \Leftrightarrow x^k - \lambda^k \nabla f(x^k) = x^k \oslash M_{\lambda g}(x^k) \approx x^k - \lambda^k \nabla (f + g)(x^k).$$

Convergence: ∇f Lipschitz $= L \Rightarrow \lambda^k = \lambda \in (0, \frac{1}{L}]$, converge with $O(\frac{1}{k})$.

L not known: back-tracking "line" search.
Beck & Teboulle.

$$\begin{aligned} \text{parameter } \beta \in (0, 1), \lambda = \lambda^{k-1} \\ \Rightarrow z = \text{prox}_{\lambda g}(x^k - \lambda \nabla f(x^k)) \\ \text{if } f(z) > \hat{f}_\lambda(z, x^k), \lambda = \beta \lambda \\ \hat{f}_\lambda(x, y) = \frac{1}{2\lambda} \|x - y\|_2^2 + f(y) + \nabla f(y)^T (x - y) \end{aligned}$$

perspective ① Majorization - minimization. (like EM algorithm).

consider minimizing $\varphi(x)$.

step 1: majorization: find convex upper bound $\hat{\varphi}$ of φ (surrogate) tight at x^k : $\begin{cases} \hat{\varphi}(x, x^k) \geq \varphi(x) \\ \hat{\varphi}(x, x) = \varphi(x) \end{cases}$

step 2: minimization: $x^{k+1} = \arg\min_x \hat{\varphi}(x, x^k)$.

For $f(x) + g(x)$, a surrogate is $\hat{f}_\lambda(x, y)$. EM alg will give precisely gradient descent.
For $f(x) + g(x)$. $q_\lambda(x, y) = \hat{f}_\lambda(x, y) + g(y) \Leftrightarrow$ proximal gradient.

perspective @ solution is a fixed point for $\text{prox}_{\lambda g}((I - \lambda \nabla f)(x)) = (I + \lambda \nabla g)^{-1}(I - \lambda \nabla f)(x)$.

[3] Accelerated proximal gradient.

$$y^{k+1} = x^k + \omega^k (x^k - x^{k-1})$$

$$x^{k+1} = \text{prox}_{\lambda g}(y^{k+1} - \lambda^k \nabla f(y^{k+1}))$$

recommend. $\omega^k = \frac{k}{k+3}$

convergence: $\lambda^k = \lambda = O(0, \frac{1}{L})$, rate $O(\frac{1}{k^2})$.

If L not known, again Beck & Teboulle search but use ~~y^k~~ y^k .

[4] ADMM version of proximal gradient.

$$\min f(x) + g(z) \Leftrightarrow \min f(x) + g(z) \text{ s.t. } x = z$$

both f, g can be non-smooth.

recall ADMM (scaled).

$$x^{k+1} = \arg\min_x f(x) + \frac{\rho}{2} \|x - z^k + u^k\|_2^2$$

$$z^{k+1} = \arg\min_z g(z) + \frac{\rho}{2} \|x^{k+1} - z + u^k\|_2^2$$

$$u^{k+1} = u^k + x^{k+1} - z^{k+1}$$

$$\Leftrightarrow x^{k+1} = \text{prox}_{\lambda f}(z^k - u^k)$$

$$z^{k+1} = \text{prox}_{\lambda g}(x^{k+1} + u^k)$$

$$u^{k+1} = u^k + x^{k+1} - z^{k+1}$$

$$\lambda = \frac{1}{\rho}$$

an interesting insight: prove the convergence of ADMM \Leftrightarrow fixedpoint algorithm of a firmly nonexpansive operator.

[5]. Linearized ADMM.

$$\min f(x) + g(Ax) \Leftrightarrow \min f(x) + g(z) \text{ s.t. } Ax - z = 0$$

Original ADMM.

$$x^{k+1} = \arg\min_x f(x) + \frac{\rho}{2} \|Ax - z^k + u^k\|_2^2$$

$$z^{k+1} = \arg\min_z g(z) + \rho u^{kT} (Ax^{k+1} - z) + \frac{\rho}{2} \|Ax^{k+1} - z\|_2^2$$

$$u^{k+1} = u^k + Ax^{k+1} - z^{k+1}$$

only modify x step:

replace $\frac{\rho}{2} \|Ax - z^k + u^k\|_2^2$ with $\frac{\rho}{2} (A^T A x - A^T z^k)^T x$ with.

$$\rho (A^T A x - A^T z^k)^T x + \frac{\mu}{2} \|x - x^k\|_2^2 \quad 0 < \mu \leq \frac{\lambda}{\|A\|_2^2}$$

then new algorithm:

$$x^{k+1} = \arg\min_x f(x) + \frac{\mu}{\lambda} A^T (A x^k - z^k + u^k)$$

$$z^{k+1} = \arg\min_z g(z) + \rho u^{kT} (A x^{k+1} - z) + \frac{\rho}{2} \|A x^{k+1} - z\|_2^2$$

$$u^{k+1} = u^k + A x^{k+1} - z^{k+1}$$