

# [6G] Stochastic Analysis of Twice differentiable

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Stochastic Analysis

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## Stochastic Analysis

Stochastic Analysis는 앞서와 마찬가지로의 증명 과정을 따른다. 그런데, Stochastic의 경우 는 보다 고차원의 미분 값에 대한 생각을 하지 않을 수가 없다.

The stochastic analysis for an optimization algorithm follows the same procedure of a conventional proof . However, in the stochastic analysis, we should consider the high dimensional differential of an objective function, due to the properties of a random process.

## Definition of Stochastic Model

일단 다음과 같이 생각한다.

Consider the following stochastic model

### Model

Consider the random process  $X_t \in \mathbf{R}^n$  with a Wiener process  $W_t \in \mathbf{R}^n$  with a constant variance  $\Sigma \in \mathbf{R}^{n \times n}$  which is symmetric matrix, such that

$$X_t = x_t^Q + \Sigma W_t \quad (1)$$

where  $x_t^Q \in \mathbf{R}^n$  is a deterministic value.

Let the other random process  $Y_t \in \mathbf{R}^n$  such that

$$Y_t = X_{t+1} = x_{t+1}^Q - (\lambda_t h_t)^Q + \Sigma W_{t+1} \quad (2)$$

Let a random process  $Z_t(s) \in \mathbf{R}^n$  for  $s \in \mathbf{R}[0, 1]$  such that

$$\begin{aligned} Z_t(s) &= X_t + s(Y_t - X_t) \\ &= x_t^Q + \Sigma W_t + s(-\lambda_t h_t) + s\Sigma(W_{t+1} - W_t) \end{aligned}$$

Let  $\Delta W_t = W_{t+1} - W_t$ , then

$$Z_t(s) = x_t^Q - s(\lambda_t h_t) + \Sigma(W_t + s\Delta W_t) \quad (3)$$

Considering the differentiate of  $Z_t(s)$  to  $s$ , we obtain

$$\frac{dZ_t(s)}{ds} = -\lambda_t h_t + \Sigma \Delta W_t$$

By the definition of the stochastic differential, we define the differential of  $Z_t(s)$  such that

$$dZ_t(s) = -\lambda_t h_t ds + \Sigma \Delta W_t ds \quad (4)$$

Consider the final term, i.e.  $\Delta W_t ds$ . The integration of  $dZ_t(s)$  to  $s$  is as follows:

$$\int_0^s dZ_t(s) = Z_t(s) - Z_t(0) = -s\lambda_s h_t \int_0^s ds + \Sigma \int_0^s \Delta W_t ds. \quad (5)$$

Since the integration of  $dZ_t(s)$  should be equal to (3), the integration of final term to  $\Delta W_t$  is evaluated as follows.

$$\int_0^s \Delta W_t ds = s(W_{t+1} - W_t) = \int_t^{t+1} s dW_\tau \quad (6)$$

Thereby, when  $s = 0$ ,  $\tau = t$ , and  $s = 1$ ,  $\tau = t + 1$ , we obtain the following differential equation in the sense of (3)

$$\Delta W_t ds = s dW_\tau$$

In consequence, the stochastic differential equation of  $Z_t(s)$  is same to the following:

$$dZ_t(s) = -\lambda_t h_t ds + s \cdot \Sigma dW_\tau \in \mathbf{R}^n \quad (7)$$

In (7), by the product rule of the stochastic differential, the dot product of the vector differential  $dZ_t(s)$  is evaluated as

$$dZ_t(s)^2 = dZ_t(s)^T dZ_t(s) = s^2 dW_\tau \Sigma^T \Sigma dW_\tau = s^2 \text{Tr}(\Sigma \Sigma^T) d\tau \in \mathbf{R} \quad (8)$$

In (8), while  $d\tau$  and  $ds$  contain the same domain, the scale of both are different. Since when  $s$  is increased from 0 to  $s$ , the  $\tau$  is increased from 0 to 1. If let  $\bar{s} = \max s$ ,  $\forall s \in \mathbf{R}[0, 1]$  in the analysis, then

$$\tau = t + \frac{s}{\bar{s}}, \quad \text{for } \tau = \begin{cases} t+1 & s = \bar{s} \\ t & s = 0 \end{cases}$$

Considering the scale of both parameters we can obtain the following relation.

$$d\tau = \frac{1}{\bar{s}} ds \quad (9)$$

Therefore, from (8), we obtain the dot product of the vector differential  $dZ_t(s)$  is using (9) when  $s = \bar{s}$ ,

$$dZ_t(s)^2 = \frac{s^2}{\bar{s}} \text{Tr}(\Sigma \Sigma^T) ds = s \cdot \text{Tr}(\Sigma \Sigma^T) ds \quad (10)$$

## Deduction of an exact form of the Taylor expansion with the twice differentiable form

The deterministic version of the exact Taylor expansion with the twice differentiable form for a objective function  $f(x) : \mathbf{R}^n \rightarrow \mathbf{R}$  is

$$f(y) - f(x) = \langle \nabla f(x), y - x \rangle + \int_0^1 (1-s) \langle y - x, H(x + s(y-x))(y-x) \rangle ds$$

where  $H(x) \in \mathbf{R}^{n \times n}$  is a Hessian of  $f(x)$ .

For evaluation of the stochastic version, we let a function  $g(s) = f(Z_t(s))$ . The first order differentiation to  $s$  is

$$\begin{aligned} \frac{dg(s)}{ds} &= \frac{1}{ds}(dg(s)) \\ &= \frac{1}{ds} \left( \frac{\partial f(Z_t(s))}{\partial Z_t(s)} dZ_t(s) + \frac{1}{2} \frac{\partial^2 f(Z_t(s))}{\partial Z_t^2(s)} dZ_t(s)^2 \right) \\ &= \left( \frac{\partial f(Z_t(s))}{\partial Z_t(s)} \frac{dZ_t(s)}{ds} + \frac{1}{2} \frac{1}{ds} \frac{\partial^2 f(Z_t(s))}{\partial Z_t^2(s)} dZ_t(s)^2 \right) \end{aligned} \quad (11)$$

Substituting (???) and (10) to the (11), we can obtain

$$\begin{aligned} \frac{dg(s)}{ds} &= \nabla f(X_t)^T \frac{dZ_t(s)}{ds} + \frac{1}{2} \frac{1}{ds} s \cdot \text{Tr} \left( \Sigma \frac{\partial^2 f(Z_t(s))}{\partial Z_t^2(s)} \Sigma^T \right) ds \\ &= \langle \nabla f(X_t), -(\lambda_t h_t)^Q + \Sigma \Delta W_t \rangle + \frac{1}{2} s \cdot \text{Tr} \left( \Sigma \frac{\partial^2 f(Z_t(s))}{\partial Z_t^2(s)} \Sigma^T \right). \end{aligned} \quad (12)$$

For the second order differentiation of  $g(s)$ , let  $y(Z_t(s)) = \frac{dg(s)}{ds}$ . Then

$$\frac{d^2 g(s)}{ds^2} = \frac{dy}{ds} = \left( \frac{\partial y(Z_t(s))}{\partial Z_t(s)} \cdot \frac{dZ_t(s)}{ds} + \frac{1}{2} s \cdot \text{Tr} \left( \Sigma \frac{\partial^2 y(Z_t(s))}{\partial Z_t(s)^2} \Sigma^T \right) \right) \quad (13)$$

For the first term of (13), we span it to the diffierial of  $f(X)$  such that

$$\begin{aligned} \frac{\partial y(Z_t(s))}{\partial Z_t(s)} \cdot \frac{dZ_t(s)}{ds} &= \frac{\partial}{\partial Z_t(s)} \left( \frac{\partial f(Z_t(s))}{\partial Z_t(s)} \cdot \frac{dZ_t(s)}{ds} \right) \cdot \frac{dZ_t(s)}{ds} \\ &= \frac{\partial^2 f(Z_t(s))}{\partial Z_t(s)^2} \cdot \left( \frac{dZ_t(s)}{ds} \right)^2 + \frac{\partial f(Z_t(s))}{\partial Z_t(s)} \cdot \frac{\partial^2 f(Z_t(s))}{\partial Z_t(s) \partial s} \cdot \frac{\partial Z_t(s)}{\partial s} \end{aligned} \quad (14)$$

Subsequently, by the definition of vedtor valued differetiation, the first term of (14) is

$$\frac{\partial^2 f(Z_t(s))}{\partial Z_t(s)^2} \cdot \left( \frac{dZ_t(s)}{ds} \right)^2 = \left\langle \frac{dZ_t(s)}{ds}, \frac{\partial^2 f(Z_t(s))}{\partial Z_t(s)^2} \frac{dZ_t(s)}{ds} \right\rangle.$$

In addition, for the analysis of the second term, we evaluate the following differentiation as follows.

$$\frac{\partial^2 f(Z_t(s))}{\partial Z_t(s) \partial s} = \frac{\partial}{\partial Z_t(s)} \left( \frac{\partial f(Z_t(s))}{\partial s} \right) = \frac{\partial}{\partial Z_t(s)} (-(\lambda_t h_t)^Q + \Sigma \Delta W_t) = 0$$

For the verification, of the above equation, changing the order of differentiation, we obtain

$$\frac{\partial}{\partial s} \frac{\partial Z_t(s)}{\partial Z_t(s)} = 0.$$

Therefore, the first term of (14) is

$$\frac{\partial y(Z_t(s))}{\partial Z_t(s)} \cdot \frac{dZ_t(s)}{ds} = \left\langle \frac{dZ_t(s)}{ds}, \frac{\partial^2 f(Z_t(s))}{\partial Z_t(s)^2} \frac{dZ_t(s)}{ds} \right\rangle. \quad (15)$$

For the second term of (13), we differentiate twice  $y(Z_t(s))$  with respect to  $Z_t(s)$  as follows.

$$\begin{aligned}
\frac{\partial^2 y(Z_t(s))}{\partial Z_t^2(s)} &= \frac{\partial^2}{\partial Z_t^2(s)} \left( \frac{dg(s)}{ds} \right) \\
&= \frac{\partial^2}{\partial Z_t^2(s)} \left( \frac{\partial f(Z_t(s))}{\partial Z_t(s)} \frac{dZ_t(s)}{ds} + \frac{1}{2} \text{Tr} \left( \Sigma \frac{\partial^2 f(Z_t(s))}{\partial Z_t^2(s)} \Sigma^T \right) \right)
\end{aligned} \tag{16}$$

In (16), the first term of is evaluated as

$$\begin{aligned}
&\frac{\partial^2}{\partial Z_t^2(s)} \left( \frac{\partial f(Z_t(s))}{\partial Z_t(s)} \frac{dZ_t(s)}{ds} \right) \\
&= \frac{\partial}{\partial Z_t(s)} \left( \frac{\partial^2 f(Z_t(s))}{\partial Z_t^2(s)} \frac{dZ_t(s)}{ds} + \frac{\partial f(Z_t(s))}{\partial Z_t(s)} \frac{\partial^2 Z_t(s)}{\partial Z_t(s) \partial s} \right) \\
&= \frac{\partial^3 f(Z_t(s))}{\partial Z_t^3(s)} \frac{dZ_t(s)}{ds} \in \mathbf{R}^{n \times n}, \quad \because \frac{\partial^2 Z_t(s)}{\partial Z_t(s) \partial s} = 0
\end{aligned} \tag{17}$$

Additionally, the second term is

$$\frac{\partial^2}{\partial Z_t^2(s)} H(Z_t(s)) = \frac{\partial^4}{\partial Z_t^4(s)} f(Z_t(s)) \tag{18}$$

where  $\frac{\partial^4}{\partial Z_t^4(s)} f(Z_t(s))$  is a rank-4 tensor such that

$$\Sigma \frac{\partial^4}{\partial Z_t^4(s)} f(Z_t(s)) \Sigma^T \in \mathbf{R}^{n \times n}$$

Finally, since the exact expansion of the twice differential form is evaluated such that

$$f(Y_t) - f(X_t) = g(1) - g(0) = \frac{dg}{ds}(0) + \int_0^1 (1-s) \frac{d^2 g}{ds^2}(s) ds, \tag{19}$$

from (11) to (18), we obtain the following exact expansion of the twice differentiable form.

$$\begin{aligned}
f(Y_t) - f(X_t) &= \left\langle \nabla f(Z_t(s)), \frac{dZ_t(s)}{ds} \right\rangle \Big|_{s=0} + \frac{1}{2} s \cdot \text{Tr} \left( \Sigma H(Z_t(s)) \Sigma^T \right) \Big|_{s=0} \\
&+ \int_0^1 (1-s) \left( \left\langle \frac{dZ_t(s)}{ds}, H(Z_t(s)) \frac{dZ_t(s)}{ds} \right\rangle \right. \\
&\left. + \frac{1}{2} \text{Tr} \left( \Sigma, \left( \frac{\partial^3 f(Z_t(s))}{\partial Z_t^3(s)} \frac{dZ_t(s)}{ds} + \frac{1}{2} \Sigma \frac{\partial^4 f(Z_t(s))}{\partial Z_t^4(s)} \Sigma \right) \Sigma^T \right) \right) ds
\end{aligned} \tag{20}$$