$\langle A - 1 a_i A\rangle$	<u></u>	$l^i r_0$	$\langle i l^{J_{A-1}} angle r_0$
	√ 0	$l_a^{ij}r_j^a$	$\sum_{(aj)} \delta_{J_{aj}J_A} \delta_{M_{aj}M_A} \langle i l^{A-1} (aj^{-1})\rangle \langle (aj^{-1}) r^A \rangle$
$\langle A - 1 a_a A\rangle$	<u> </u>	$l^i t^a_i r_0$	$\sum_{i} \delta_{jji} \delta_{mm_i} \langle a t^0 i\rangle \langle i l^{J_{A-1}} \rangle r_0$
		$l^i r^a_i$	$\sum_{i} \delta_{J_{A-1}j_i} \delta_{M_{A-1}m_i} \langle a r^{J_A} i\rangle \langle i l^{J_{A-1}} \rangle$
	<u> </u>	$\frac{1}{2}l_b^{ij}t_{ij}^{ab}r_0$	$\frac{1}{2} \sum_{J_{ij}} \sum_{((ij)b)} \delta_{J_{ijb}j} \delta_{M_{ijb}m} \langle a t^0 ((ij)b^{-1}) \rangle \langle ((ij)b^{-1}) l^{J_{A-1}} \rangle r_0$
	€ /2 ()	$l_b^{ij}t_i^ar_j^b$	$ \sum_{(bj)} \delta_{J_A J_{bj}} \delta_{M_A M_{bj}} \sum_{i} \delta_{jj_i} \delta_{mm_i} \langle a t^0 i\rangle \langle i l^{J_{A-1}} (bj^{-1})\rangle \langle (bj^{-1}) r^{J_A} \rangle $
	₹	$rac{1}{2}l_b^{ij}r_{ij}^{ab}$	$\sum_{J_{ij}} \sum_{((ij)b)} \delta_{J_{A-1}J_{ijb}} \delta_{M_{A-1}M_{ijb}} \langle a r^A ((ij)b^{-1}) \rangle \langle ((ij)b^{-1}) l^{A-1} \rangle$
$\langle A a_a^{\dagger} A-1\rangle$	<u> </u>	$l_a^i r_i$	$\sum_{i} \delta_{j_{i}J_{A-1}} \delta_{-m_{i}M_{A-1}} \langle r^{J_{A-1}} i \rangle \langle i l^{J_{A}} a \rangle$
	8	$rac{1}{2}l_{ab}^{ij}r_{ij}^{b}$	$\frac{1}{2} \sum_{J_{ij}} \sum_{((ij)b)} \delta_{J_{ijb}J_{A-1}} \delta_{-M_{ijb}M_{A-1}} \left\langle r^{J_{A-1}} ((ij)b^{-1})\right\rangle \left\langle ((ij)b^{-1}) l^{J_{A}} a\right\rangle$
$\langle A a_i^\dagger A-1\rangle$		l^0r_i	$\delta_{jJ_{A-1}}\delta_{-mM_{A-1}}l^0\left\langle r^{J_{A-1}} i ight angle$
	<u>q</u>	$l_a^j r_{ij}^a$	$\sum_{(aj)} \delta_{J_{aj}J_A} \delta_{-M_{aj}M_A} \langle l^{J_A} (aj^{-1})\rangle \langle (aj^{-1}) r^{J_{A-1}} i\rangle$
	<u> </u>	$-l_a^j t_i^a r_j$	$ -\sum_{j} \delta_{j_{j}J_{A-1}} \delta_{-m_{j}M_{A-1}} \sum_{a} \delta_{jj_{a}} \delta_{mm_{a}} \left\langle r^{J_{A-1}} j\rangle \left\langle j l^{J_{A}} a\rangle \left\langle a t^{0} i\rangle \right\rangle \right. $
	3	$-\frac{1}{2}l_{ab}^{jk}t_i^ar_{jk}^b$	
	<u> </u>	$-\frac{1}{2}l_{ab}^{jk}t_{ik}^{ab}r_j$	

Table 1: Diagram representation of the overlap expressions. In the coupled expressions we have excluded constant angular momentum factors in the interest of brevity.