

Partitioned Local Depth Algorithm (PaLD) is a cluster algorithm discovered by Dr. Kenneth S. Berenhaut at Wake Forest University. The idea of this algorithm is to find the probability that how likely points within a range will support a given point. For example, given point i and j we get their distance as $d(i, j)$, then we create a group of points that are closer to either point i or point j comparing with the distance between point i and point j . We call this group local conflict focus. Each pair of points will have their own local conflict focus and within each local conflict we calculate the probability that how likely a point in the local conflict focus will support that pair of points. The algorithm is shown below

Algorithm 1 Partitioned Local Depth Original Algorithm

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1: Input: distance matrix of the data set  $D$  where  $D_{i,j} = d(i, j)$ , and  $D \in \mathbb{R}^{n \times n}$ 
2: Output: cohesion matrix of the data set  $C$ 
3: procedure ORIGPALD( $D$ )
4:    $C \leftarrow 0$ 
5:   for  $i = 1$  to  $n$  do
6:     for  $j = 1$  to  $n$  satisfying  $j \neq i$  do
7:        $U_{i,j} \leftarrow \{k | d(k, i) \leq d(j, i) \text{ or } d(k, j) \leq d(j, i)\}$ 
8:       for  $l$  in  $U_{i,j}$  do
9:         if  $d(l, i) < d(l, j)$  then
10:            $C_{i,l} \leftarrow C_{i,l} + \frac{1}{\text{size}(U_{i,j})}$ 
11:         if  $d(l, i) > d(l, j)$  then
12:            $C_{j,l} \leftarrow C_{j,l} + \frac{1}{\text{size}(U_{i,j})}$ 
13:         if  $d(l, i) = d(l, j)$  then
14:            $C_{i,l} \leftarrow C_{i,l} + \frac{1}{2 * \text{size}(U_{i,j})}$ 
15:            $C_{j,l} \leftarrow C_{j,l} + \frac{1}{2 * \text{size}(U_{i,j})}$ 
16:    $C \leftarrow \frac{C}{n-1}$ 
17:   return  $C$ 

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There are three nested loops and one more loop in line 7 and each loop has $\mathcal{O}(n)$ except the loop in line 8 which is related to the size of the local conflict focus. Therefore, this algorithm is at least $\mathcal{O}(n^3)$. After a careful discuss we find that the size of a local conflict focus is about linear with n^2 (See $U_{x,y}$ size analysis.), which means the loop in line 8 has $\mathcal{O}(n^2)$ flops. So the overall computational cost of original PaLD algorithm is $\mathcal{O}(n^3)$ and the running time of PaLD algorithm will be large if we use the original algorithm given a large data set.

In order to reduce the running time of PaLD, here we apply a modified optimal blocked matrix multiplication algorithm to PaLD. Before we dive into the modified algorithm, let's see how the optimal blocked matrix multiplication algorithm works.

Algorithm 2 Optimal Blocked Matrix Multiplication Algorithm

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1: Input: A, B are  $n \times n$  matrices,  $b$  divides  $n$ ,  $b \leq \sqrt{M+1} - 1$ , A is partitioned into  $b \times n$  block rows
   so that  $A_{I,:} = A((I-1)b+1 : Ib, 1 : n)$ , B is partitioned into  $n \times b$  block columns so that  $B_{:,J} = B(1 : n, (J-1)b+1 : Jb)$ , C is partitioned into  $b \times b$  blocks so that  $C_{IJ} = C((I-1)b+1 : Ib, (J-1)b+1 : Jb)$ .
2: Ensure:  $C = C + AB$  is  $n \times n$  matrix
3: Output: C, where C is the output of A times B
4: procedure MATMUL-BLOCKED-BETTER(C, A, B, b)
5:    $C \leftarrow 0$ 
6:   for I = 1 to  $n/b$  do
7:     for J = 1 to  $n/b$  do
       Read  $C_{IJ}$  inot fast memory
8:     for k = 1 to n do
       Read  $A_{I,:}(k)$  and  $B_{:,J}(k,:)$  inot fast memory
9:     for i = 1 to b do
10:    for j = 1 to b do
       $C_{IJ}(i,j) + 1 = A_{I,:}(i,k)B_{:,J}(k,j)$ 
      Write  $C_{IJ}$  to slow memory
11:  return C

```

The optimal blocked matrix multiplication algorithm take advantage of the blocks that are stored in the fast memory and reused those blocks as much as possible to save the data movement time between fast memroy and slow memory. We will use the same strategy to reduce the running time of PaLD algorithm. But the challenge in this converting is that PaLD use comparsion instead of multiplication and the comparsion procedure is not exactly the same as matrix multiplication.