

New Batch Method

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Abstract to be added.

We begin by defining a Gaussian probability distribution on $SE(3)$ (assuming the norm $\|\Sigma\|$ is small) as

$$\rho(H; M, \Sigma) = \frac{1}{(2\pi)^3 |\Sigma|^{\frac{1}{2}}} e^{-\frac{1}{2} F(M^{-1}H)}$$

where $\|\Sigma\|$ denotes the determinant of Σ and

$$F(H) = [\log^\vee(H)]^T \Sigma^{-1} [\log^\vee(H)].$$

Previously, in order to determine the mean of the convolution of two PDFs, Baker-Campbell-Hausdorff formula is used given the assumption that function f_1 and f_2 are both highly focused. If $X, Y \in se(3)$,

$$\log(e^X e^Y) = X + Y + \frac{1}{2}[X, Y] + \frac{1}{12}([X, [X, Y]] + [Y, [Y, X]]) + \dots \quad (1)$$

If X and Y are further constrained to be small so that $\|X\| \ll 1$ and $\|Y\| \ll 1$, then the first approximation of Eq.(?) can be written as:

$$\log(e^X e^Y) = X + Y \quad (2)$$

As shown in [?], the mean of covariance of the convolution of two highly focused functions are:

$$M_{1*2} = M_1 M_2 \text{ and } \Sigma_{1*2} = Ad(M_2^{-1}) \Sigma_1 Ad^T(M_2^{-1}) + \Sigma_2 \quad (3)$$

where

$$Ad(H) = \begin{pmatrix} R & \mathbb{O} \\ \hat{\mathbf{x}}R & R \end{pmatrix} \quad (4)$$

1 First Order Approximation of M

Though this approximation works well when the distribution of X is treated as a Delta function, it fails to extend to the case where its distribution is a general PDF $f(X)$. In an alternative to the first order approximation using Baker-Campbell-Hausdorff formula, it is possible to only assume $M^{-1}H$ is small so that $\|M^{-1}H - \mathbb{I}\| \ll 1$. Given the Taylor expansion of the matrix logarithm described as:

$$\log(\mathbb{I} + X) = X - \frac{1}{2}X^2 + \frac{1}{3}X^3 - \dots \quad (5)$$

Then it is straight forward to have:

$$\begin{aligned} \log(M^{-1}H) &= \log(\mathbb{I} + (M^{-1}H - \mathbb{I})) \\ &= (M^{-1}H - \mathbb{I}) - (M^{-1}H - \mathbb{I})^2/2 + (M^{-1}H - \mathbb{I})^3/3 - \dots \end{aligned} \quad (6)$$

Given the definition of the mean M of a probability density $f(H)$ as:

$$\int_{SE(3)} \log(M^{-1}H) f(H) dH = \mathbb{O} \quad (7)$$

The first order approximation of Eq.(?) is:

$$\int_{SE(3)} (M^{-1}H - \mathbb{I}) f(H) dH \approx \mathbb{O} \quad (8)$$

$$M^{-1} \int_{SE(3)} H f(H) dH \approx \mathbb{I} \quad (9)$$

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Define the first order approximation of M as \hat{M} :

$$\hat{M} \doteq \int_{SE(3)} H f(H) dH \quad (10)$$

$$f_A(H) = \frac{1}{n} \sum_{i=1}^n \delta(A_i^{-1}H) \text{ and } f_B(H) = \frac{1}{n} \sum_{i=1}^n \delta(B_i^{-1}H).$$

If $f(H)$ is of the form of $f_A(H)$ given above, then

$$\begin{aligned} \sum_{i=1}^n \log(M_A^{-1}A_i) &= \mathbb{O} \text{ and} \\ \Sigma_A &= \frac{1}{n} \sum_{i=1}^n \log^\vee(M_A^{-1}A_i) [\log^\vee(M_A^{-1}A_i)]^T. \end{aligned} \quad (11)$$

Discrete version will be:

$$\hat{M}_A \doteq \sum_{i=1}^n A_i \left(\frac{1}{n} \sum_{j=1}^n \delta(A_j^{-1}A_i) dH \right) = \frac{1}{n} \sum_{i=1}^n A_i \quad (12)$$

Note that \hat{M} is generally not a group element in $SE(3)$, and the corresponding $SE(3)$ version can be obtained by projecting \hat{M} into $SE(3)$ using singular value decomposition (SVD) technique.:

$$R_{\hat{M}} = U \Sigma V^T \quad (13)$$

The rotation part of the projected \hat{M} (named as \hat{M}_{proj}) is:

$$R_{\hat{M}_{proj}} = UV^T \quad (14)$$

More details are needed to actually project \hat{M} into $SE(3)$.

2 Second Order Approximation of M

Take the second order approximation in Eq.(??):

$$\int_{SE(3)} \left((M^{-1}H - \mathbb{I}) - \frac{1}{2} (M^{-1}H - \mathbb{I})^2 \right) f(H) dH \approx \mathbb{O} \quad (15)$$

$$\int_{SE(3)} \left(2M^{-1}H - \frac{1}{2} HM^{-1}H - \frac{3}{2} \mathbb{I} \right) f(H) dH \approx \mathbb{O} \quad (16)$$

Multiply M on both side of Eq.(??):

$$\int_{SE(3)} \left(2H - \frac{1}{2} HM^{-1}H - \frac{3}{2} M \right) f(H) dH \approx \mathbb{O} \quad (17)$$

Substituting Eq.(??) into Eq.(??), we have:

$$2\hat{M} - \frac{1}{2} \int_{SE(3)} HM^{-1}H f(H) dH - \frac{3}{2} M \approx \mathbb{O} \quad (18)$$

The 2nd order approximation of M is denoted by \bar{M} defined as:

$$2\hat{M} - \frac{1}{2} \int_{SE(3)} H\bar{M}^{-1}H f(H) dH - \frac{3}{2} \bar{M} = \mathbb{O} \quad (19)$$

$$2\hat{M} - \bar{M} \frac{1}{2} \int_{SE(3)} \bar{M}^{-1}H\bar{M}^{-1}H f(H) dH - \frac{3}{2} \bar{M} = \mathbb{O} \quad (20)$$

$$2\hat{M} - \frac{1}{2n} \sum_{i=1}^n A_i \bar{M}^{-1} A_i - \frac{3}{2} \bar{M} = \mathbb{O} \quad (21)$$

The second term of Eq.(??) is very similar to the definition of the covariance of $f(H)$, and maybe \bar{M} can be updated using the information of the covariance. Also, take a look at the cubness of variance in the first volume. The same technique as in Eq.(??) can be employed to project \hat{M} into $SE(3)$.

3 First Order Approximation of Σ

Given the definition of the covariance Σ of a PDF $f(H)$ as:

$$\Sigma = \int_{SE(3)} \log^\vee(M^{-1}H) [\log^\vee(M^{-1}H)]^T f(H) dH \quad (22)$$

Its first order approximation $\hat{\Sigma}$ can be written as:

$$\hat{\Sigma} \doteq \int_{SE(3)} (M^{-1}H - \mathbb{I})^\vee [(M^{-1}H - \mathbb{I})^\vee]^T f(H) dH \quad (23)$$

The discrete version for Σ_A will be:

$$\Sigma_A = \frac{1}{n} \sum_{i=1}^n (M_A^{-1}A_i - \mathbb{I})^\vee [(M_A^{-1}A_i - \mathbb{I})^\vee]^T. \quad (24)$$

By defining $Q = M^{-1}H$, Eq.(??) can be written as:

$$\hat{\Sigma} \doteq \int_{SE(3)} (Q - \mathbb{I})^\vee [(Q - \mathbb{I})^\vee]^T f(Q) dQ \quad (25)$$

If $\|G - \mathbb{I}\| \ll 1$, then $\Sigma = \hat{\Sigma}$

$$(Q - \mathbb{I})^\vee = \begin{pmatrix} \frac{1}{2}(R - R^T) \\ \mathbf{t} \end{pmatrix} \quad (26)$$

4 Second Order Approximation of Σ

5 First Order Approximation of M_{1*2}

Given two functions, $f_1, f_2 \in (L^1 \cap L^2)(SE(3))$, the convolution is defined as:

$$(f_1 * f_2)(H) \doteq \int_{SE(3)} f_1(K) f_2(K^{-1}H) dK. \quad (27)$$

The corresponding mean M_{1*2} will be given as:

$$\int_{SE(3)} \log(M_{1*2}^{-1}H) (f_1 * f_2)(H) dH = \mathbb{O} \quad (28)$$

If both Σ_1 and Σ_2 are very small, then $M_{1*2} \approx M_1 M_2$. Without using this approximation, take the assumption that $M^{-1}H$ is small and we will have:

$$\int_{SE(3)} \int_{SE(3)} (M_{1*2}^{-1}H - \mathbb{I}) f_1(K) f_2(K^{-1}H) dK dH \approx \mathbb{O} \quad (29)$$

Define $L = K^{-1}H$,

$$\int_{SE(3)} \int_{SE(3)} (M_{1*2}^{-1}KL - \mathbb{I}) f_1(K) f_2(L) dK dL \approx \mathbb{O} \quad (30)$$

By using Eq.(??) twice,

$$M_{1*2}^{-1} \widehat{M}_1 \widehat{M}_2 \approx \mathbb{I} \quad (31)$$

Define \widehat{M}_{1*2} as:

$$\widehat{M}_{1*2} = \widehat{M}_1 \widehat{M}_2 \quad (32)$$

There are two ways to solve for M_{1*2}^{proj} .

$$M_{1*2}^{proj} = \begin{cases} \left(\widehat{M}_1 \widehat{M}_2 \right)_{proj} \\ \widehat{M}_{1proj} \widehat{M}_{2proj} \end{cases} \quad (33)$$

6 Second Order Approximation of M_{1*2}

For simplicity, we drop the domain of integral $SE(3)$,

$$\int \int \left(2M_{1*2}^{-1}H - \frac{1}{2}M_{1*2}^{-1}HM_{1*2}^{-1}H - \frac{3}{2}\mathbb{I} \right) f_1(K) f_2(K^{-1}H) dK dH \approx \mathbb{O} \quad (34)$$

Substitute $L = K^{-1}H$,

$$\int \int \left(2M_{1*2}^{-1}KL - \frac{1}{2}M_{1*2}^{-1}KLM_{1*2}^{-1}KL - \frac{3}{2}\mathbb{I} \right) f_1(K) f_2(L) dK dL \approx \mathbb{O} \quad (35)$$

Employing the definition of \widehat{M} ,

$$M_{1*2}^{-1} \widehat{M}_1 \widehat{M}_2 \approx \frac{1}{4} \int \int \left(\frac{1}{2}M_{1*2}^{-1}KLM_{1*2}^{-1}KL \right) f_1(K) f_2(L) dK dL + \frac{3}{4}\mathbb{I} \quad (36)$$