

## Derivatives with respect to vectors

Let  $x \in R^n$  (a column vector) and let  $f : R^n \rightarrow R$ . The derivative of  $f$  with respect to  $x$  is the row vector:

$$\frac{\partial f}{\partial x} = \left( \frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right)$$

$\frac{\partial f}{\partial x}$  is called the gradient of  $f$ .

The Hessian matrix is the square matrix of second partial derivatives of a scalar valued function  $f$ :

$$H(f) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & & \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix} \quad (1)$$

The mixed derivatives of  $f$  are the entries off the main diagonal in the Hessian. Assuming that they are continuous, the order of differentiation does not matter.

If the gradient of  $f$  is zero at some point  $x$ , then  $f$  has a critical point at  $x$ . The determinant of the Hessian at  $x$  is then called the discriminant. If this determinant is zero then  $x$  is called a degenerate critical point of  $f$ . Otherwise it is non-degenerate.

For a non-degenerate critical point  $x$ , if the Hessian is positive definite at  $x$ , then  $f$  attains a local minimum at  $x$ . If the Hessian is negative definite at  $x$ , then  $f$  attains a local maximum at  $x$ . If the Hessian has both positive and negative eigenvalues then  $x$  is a saddle point for  $f$  (this is true even if  $x$  is degenerate). Otherwise the test is inconclusive.

Let  $x \in R^n$  (a column vector) and let  $f : R^n \rightarrow R^m$ . The derivative of  $f$  with respect to  $x$  is the  $m \times n$  matrix:

$$\frac{\partial f}{\partial x} = \begin{bmatrix} \frac{\partial f(x)_1}{\partial x_1} & \cdots & \frac{\partial f(x)_1}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial f(x)_m}{\partial x_1} & \cdots & \frac{\partial f(x)_m}{\partial x_n} \end{bmatrix} \quad (2)$$

$\frac{\partial f}{\partial x}$  is called the Jacobian matrix of  $f$ .

Examples:

Let  $u, x \in R^n$  (column vectors).

1. The derivative of  $u^T x = \sum_{i=1}^n u_i x_i$  with respect to  $x$ :

$$\frac{\partial \sum_{i=1}^n u_i x_i}{\partial x_i} = u_i \Rightarrow \frac{\partial u^T x}{\partial x} = (u_1, \dots, u_n) = u^T \quad (3)$$

2. The derivative of  $x^T x = \sum_{i=1}^n x_i^2$  with respect to  $x$ :

$$\frac{\partial \sum_{i=1}^n x_i^2}{\partial x_i} = 2x_i \Rightarrow \frac{\partial x^T x}{\partial x} = (2x_1, \dots, 2x_n) = 2x^T \quad (4)$$

We will compute this derivative once again using the product rule: first holding  $x$  constant and then holding  $x^T$  constant.

$$\frac{\partial (f(x)^T g(x))}{\partial x} = \frac{\partial (f(x)^T g(\bar{x}))}{\partial x} + \frac{\partial (f(\bar{x})^T g(x))}{\partial x} \quad (5)$$

Placing a bar over a vector to indicate that it is being treated as constant, we have:

$$\frac{\partial x^T x}{\partial x} = \frac{\partial x^T \bar{x}}{\partial x} + \frac{\partial \bar{x}^T x}{\partial x} = x^T + x^T = 2x^T \quad (6)$$

3. Let  $A \in R^{m \times n}$  and  $x \in R^n$ . Let  $a_1^T, \dots, a_m^T$  be the rows of  $A$ .

$$Ax = \begin{bmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_m^T \end{bmatrix} x = \begin{bmatrix} a_1^T x \\ a_2^T x \\ \vdots \\ a_m^T x \end{bmatrix} \quad (7)$$

$$\frac{\partial Ax}{\partial x} = \begin{bmatrix} \frac{\partial a_1^T x}{\partial x} \\ \frac{\partial a_2^T x}{\partial x} \\ \vdots \\ \frac{\partial a_m^T x}{\partial x} \end{bmatrix} = \begin{bmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_m^T \end{bmatrix} \quad (8)$$

$$\Rightarrow \frac{\partial Ax}{\partial x} = A \quad (9)$$

4. Example: Let  $A \in R^{m \times n}$  and  $x \in R^n$ .

$$\frac{\partial x^T Ax}{\partial x} = \frac{\partial x^T A \bar{x}}{\partial x} + \frac{\partial \bar{x}^T Ax}{\partial x} \quad (10)$$

To compute these derivatives we will use  $\frac{\partial x^T u}{\partial x} = \frac{\partial u^T x}{\partial x} = u^T$  by substituting  $u_1 = A\bar{x}$  and  $u_2^T = \bar{x}^T A$ .

$$\begin{aligned} \frac{\partial x^T Ax}{\partial x} &= \frac{\partial x^T A \bar{x}}{\partial x} + \frac{\partial \bar{x}^T Ax}{\partial x} = \\ \frac{\partial x^T u_1}{\partial x} + \frac{\partial u_2^T x}{\partial x} &= u_1^T + u_2^T = x^T A^T + x^T A = x^T (A + A^T) \end{aligned} \quad (11)$$

If  $A$  is symmetric then  $A = A^T$  and  $\frac{\partial x^T Ax}{\partial x} = 2x^T A$ . Taking the second derivative, we have:

$$\frac{\partial^2 x^T Ax}{\partial x^2} = A + A^T \quad (12)$$

The chain rule: Let  $U \subseteq R^n, V \subseteq R^p$  be open sets. Let  $f : U \rightarrow V$  be differentiable in  $a \in U$  and let  $g : V \rightarrow R^p$  be differentiable in  $b = f(a)$  then  $g(f(x)) : U \rightarrow R^p$  is differentiable in  $a$  and  $\frac{\partial g(f(a))}{\partial a} = \frac{\partial g(b)}{\partial b} \frac{\partial f(a)}{\partial a}$ .

Example: We will compute again example 4, this time we will define  $u = \bar{x}$  and use the chain rule:

$$\begin{aligned} \frac{\partial x^T Ax}{\partial x} &= \frac{\partial x^T A \bar{x}}{\partial x} + \frac{\partial \bar{x}^T Ax}{\partial x} = \\ &= \frac{\partial (x^T A) u}{\partial x} + \frac{\partial u^T (Ax)}{\partial x} \end{aligned} \quad (13)$$

Now define  $b_1 = A^T x$  and  $b_2 = Ax$ ,

$$\frac{\partial(x^T A)u}{\partial x} + \frac{\partial u^T(Ax)}{\partial x} = \frac{\partial b_1^T u}{\partial b} \frac{\partial b_1}{\partial x} + \frac{\partial u^T b_2}{\partial b_2} \frac{\partial b_2}{\partial x} = \quad (14)$$

$$u^T A^T + u^T A = x^T (A + A^T)$$