

OS LAB 2

AIM: Write a C program to simulate the following CPU scheduling algorithm to find turnaround time and waiting time.

1. Priority (pre-emptive & Non-pre-emptive)
2. Round Robin (Experiment with different quantum sizes for RR algorithm)

SOURCE CODE

```
#include<stdio.h>

void findWaitingTime(int processes[], int n, int burstTime[], int priority[], int waitingTime[])
{
    int remainingTime[n];
    for (int i = 0; i < n; i++)
        remainingTime[i] = burstTime[i];

    int completed = 0;
    int currentTime = 0;

    while (completed != n)
    {
        int highestPriorityIndex = -1;
        int highestPriority = -1;

        for (int i = 0; i < n; i++)
        {
            if (remainingTime[i] > 0 && priority[i] > highestPriority)
            {
                highestPriority = priority[i];
                highestPriorityIndex = i;
            }
        }
    }
}
```

```
    if (highestPriorityIndex == -1)
    {
        currentTime++;
        continue;
    }

    remainingTime[highestPriorityIndex]--;

    if (remainingTime[highestPriorityIndex] == 0)
    {
        completed++;

        waitingTime[highestPriorityIndex] = currentTime + 1 - burstTime[highestPriorityIndex];

        if (waitingTime[highestPriorityIndex] < 0)
            waitingTime[highestPriorityIndex] = 0;
    }

    currentTime++;
}

void findTurnaroundTime(int processes[], int n, int burstTime[], int waitingTime[], int
turnaroundTime[])
{
    for (int i = 0; i < n; i++)
        turnaroundTime[i] = burstTime[i] + waitingTime[i];
}

void findAverageTime(int processes[], int n, int burstTime[], int priority[])
{

```

```
int waitingTime[n], turnaroundTime[n], totalWaitingTime = 0, totalTurnaroundTime = 0;

findWaitingTime(processes, n, burstTime, priority, waitingTime);

findTurnaroundTime(processes, n, burstTime, waitingTime, turnaroundTime);

printf("\nProcess\tBurst Time\tPriority\tWaiting Time\tTurnaround Time\n");

for (int i = 0; i < n; i++)
{
    totalWaitingTime += waitingTime[i];
    totalTurnaroundTime += turnaroundTime[i];
    printf("%d\t%d\t%d\t%d\t%d\n", processes[i], burstTime[i], priority[i], waitingTime[i],
turnaroundTime[i]);
}

printf("\nAverage Waiting Time: %.2f", (float)totalWaitingTime / n);
printf("\nAverage Turnaround Time: %.2f", (float)totalTurnaroundTime / n);
}

void priorityNonPreemptiveScheduling(int processes[], int n, int burstTime[], int priority[])
{
    for (int i = 0; i < n - 1; i++)
    {
        for (int j = 0; j < n - i - 1; j++)
        {
            if (priority[j] > priority[j + 1])
            {
                int temp = priority[j];
                priority[j] = priority[j + 1];
                priority[j + 1] = temp;
            }
        }
    }
}
```

```
        temp = burstTime[j];
        burstTime[j] = burstTime[j + 1];
        burstTime[j + 1] = temp;

        temp = processes[j];
        processes[j] = processes[j + 1];
        processes[j + 1] = temp;
    }
}

printf("\nPriority Non-Preemptive Scheduling:\n");
findAverageTime(processes, n, burstTime, priority);
}

void priorityPreemptiveScheduling(int processes[], int n, int burstTime[], int priority[])
{
    int remainingTime[n];
    for (int i = 0; i < n; i++)
        remainingTime[i] = burstTime[i];

    int completed = 0;
    int currentTime = 0;

    while (completed != n)
    {
        int highestPriorityIndex = -1;
        int highestPriority = -1;

        for (int i = 0; i < n; i++)
```

```
{  
    if (remainingTime[i] > 0 && priority[i] > highestPriority)  
    {  
        highestPriority = priority[i];  
        highestPriorityIndex = i;  
    }  
}  
  
if (highestPriorityIndex == -1)  
{  
    currentTime++;  
    continue;  
}  
  
remainingTime[highestPriorityIndex]--;  
  
if (remainingTime[highestPriorityIndex] == 0)  
{  
    completed++;  
  
    int finishTime = currentTime + 1;  
  
    int waitingTime = finishTime - burstTime[highestPriorityIndex];  
  
    if (waitingTime < 0)  
        waitingTime = 0;  
  
    printf("Process %d:\n", processes[highestPriorityIndex]);  
    printf("Waiting Time: %d\n", waitingTime);  
    printf("Turnaround Time: %d\n", finishTime);  
}
```

```
        currentTime++;
    }
}

void roundRobinScheduling(int processes[], int n, int burstTime[], int quantum)
{
    int remainingTime[n];
    for (int i = 0; i < n; i++)
        remainingTime[i] = burstTime[i];

    int completed = 0;
    int currentTime = 0;

    while (completed != n)
    {
        for (int i = 0; i < n; i++)
        {
            if (remainingTime[i] > 0)
            {
                if (remainingTime[i] <= quantum)
                {
                    currentTime += remainingTime[i];
                    remainingTime[i] = 0;
                    completed++;

                    printf("Process %d:\n", processes[i]);
                    printf("Waiting Time: %d\n", currentTime - burstTime[i]);
                    printf("Turnaround Time: %d\n", currentTime);
                }
                else
            }
        }
    }
}
```

```
        {
            currentTime += quantum;
            remainingTime[i] -= quantum;
        }
    }
}
}
```

```
int main()
{
    int n, choice;

    printf("Enter the number of processes: ");
    scanf("%d", &n);

    int processes[n], burstTime[n], priority[n];

    printf("Choose the scheduling algorithm:\n");
    printf("1. Priority Non-Preemptive\n");
    printf("2. Priority Preemptive\n");
    printf("3. Round Robin\n");
    printf("Enter your choice: ");
    scanf("%d", &choice);

    switch (choice)
    {
        case 1:
            for (int i = 0; i < n; i++)
            {
                printf("Enter burst time for process %d: ", i + 1);
                scanf("%d", &burstTime[i]);
            }
        }
    }
```

```
    printf("Enter priority for process %d: ", i + 1);
    scanf("%d", &priority[i]);
    processes[i] = i + 1;
}
priorityNonPreemptiveScheduling(processes, n, burstTime, priority);
break;
```

case 2:

```
for (int i = 0; i < n; i++)
{
    printf("Enter burst time for process %d: ", i + 1);
    scanf("%d", &burstTime[i]);
    printf("Enter priority for process %d: ", i + 1);
    scanf("%d", &priority[i]);
    processes[i] = i + 1;
}
priorityPreemptiveScheduling(processes, n, burstTime, priority);
break;
```

case 3:

```
{
    int quantum;
    printf("Enter the time quantum for Round Robin: ");
    scanf("%d", &quantum);
    for (int i = 0; i < n; i++)
    {
        printf("Enter burst time for process %d: ", i + 1);
        scanf("%d", &burstTime[i]);
        processes[i] = i + 1;
    }
    roundRobinScheduling(processes, n, burstTime, quantum);
}
```



```
    }  
    break;  
  
    default:  
        printf("Invalid choice. Exiting...\n");  
        return 0;  
    }  
  
    return 0;  
}
```

OUTPUT SCREENSHOTS

```

C:\Users\adity\Desktop\4th: x + v
Enter the number of processes: 5
Choose the scheduling algorithm:
1. Priority Non-Preemptive
2. Priority Preemptive
3. Round Robin
Enter your choice: 1
Enter burst time for process 1: 1
Enter priority for process 1: 2
Enter burst time for process 2: 3
Enter priority for process 2: 1
Enter burst time for process 3: 2
Enter priority for process 3: 14
Enter burst time for process 4: 2
Enter priority for process 4: 4
Enter burst time for process 5: 1
Enter priority for process 5: 3

Priority Non-Preemptive Scheduling:

Process Burst Time Priority Waiting Time Turnaround Time
2 3 1 6 9
1 1 2 5 6
5 1 3 4 5
4 2 4 2 4
3 2 14 0 2

Average Waiting Time: 3.40
Average Turnaround Time: 5.20
Process returned 0 (0x0) execution time : 19.607 s
Press any key to continue.

```

```

C:\Users\adity\Desktop\4th: x + v
Enter the number of processes: 3
Choose the scheduling algorithm:
1. Priority Non-Preemptive
2. Priority Preemptive
3. Round Robin
Enter your choice: 3
Enter the time quantum for Round Robin: 2
Enter burst time for process 1: 4
Enter burst time for process 2: 3
Enter burst time for process 3: 5
Process 1:
Waiting Time: 4
Turnaround Time: 8
Process 2:
Waiting Time: 6
Turnaround Time: 9
Process 3:
Waiting Time: 7
Turnaround Time: 12

Process returned 0 (0x0) execution time : 23.237 s
Press any key to continue.

```