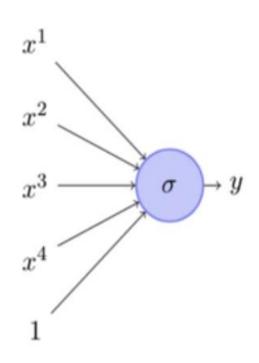




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Why do we need a different learning rate for every feature?



$$y = f(x) = \frac{1}{1 + e^{-(\mathbf{w} \cdot \mathbf{x} + b)}}$$

 $\mathbf{x} = \{x^1, x^2, x^3, x^4\}$

$$\mathbf{w} = \{w^1, w^2, w^3, w^4\}$$

$$\nabla w_{\mathbf{x}}^{1} = (f(\mathbf{x}) - y) * f(\mathbf{x}) * (1 - f(\mathbf{x})) * x^{1}$$
$$\nabla w^{2} = (f(\mathbf{x}) - y) * f(\mathbf{x}) * (1 - f(\mathbf{x})) * x^{2}$$

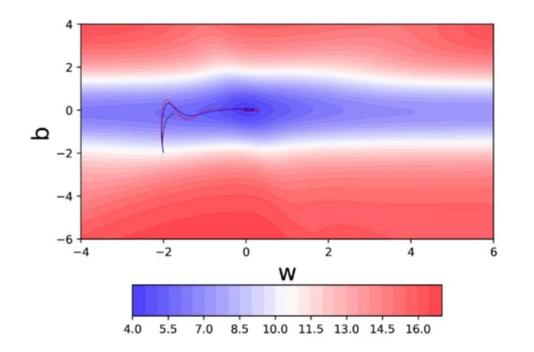
Can we have a different learning rate for each parameter which takes care of the frequency of features?

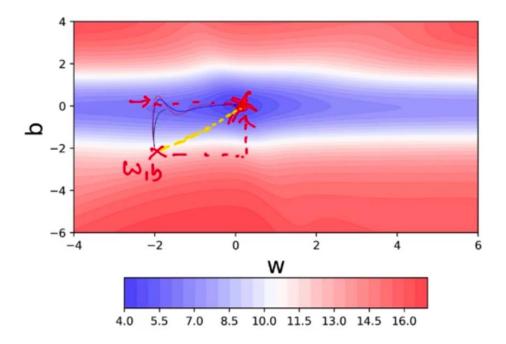
Adaptive Learning Rate

Intuition: Decay the learning rate for parameters in proportion to their update history (fewer updates, lesser decay)

Adagrad

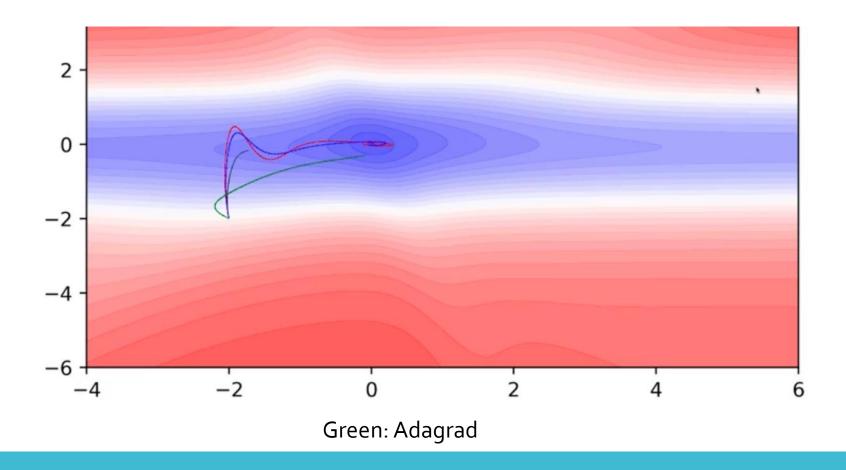
$$egin{aligned} v_t &= v_{t-1} + (
abla w_t)^2 \ w_{t+1} &= w_t - rac{\eta}{\sqrt{(v_t)} + \epsilon}
abla w_t \end{aligned}$$





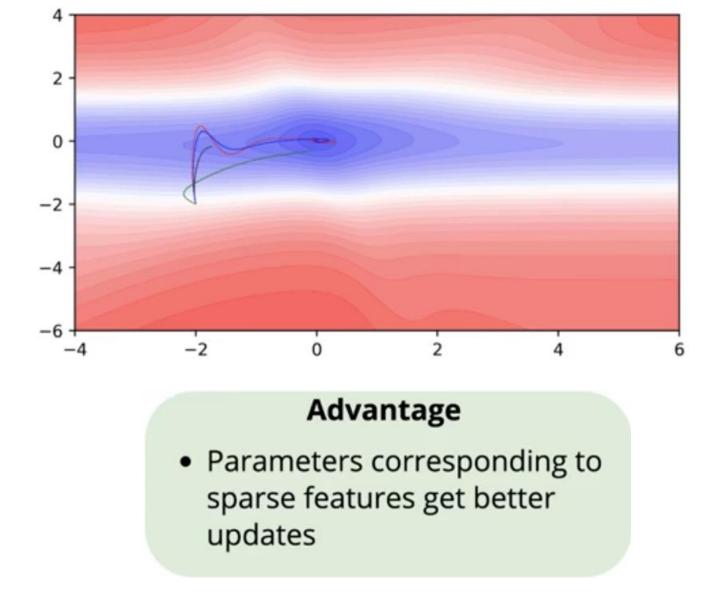
Black: GD, Red: MGD, Blue: NAGD

Vanilla Vs MGD Vs NAGD (while dealing with sparse features)



Adagrad (20 epochs result)

Adagrad -Advantage & Disadvantage



Disadvantage: The learning rate decays very aggressively as the denominator grows (not good for parameters corresponding to dense features).

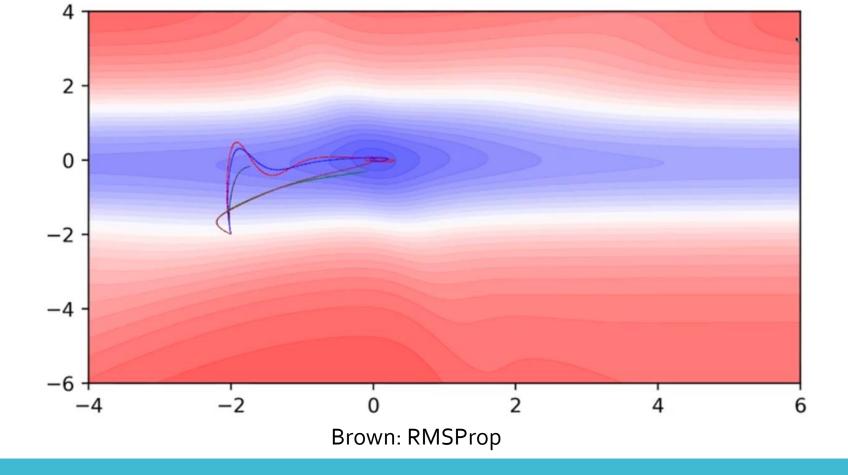
Intuition: Why not decay the denominator and prevent its rapid growth?

Adagrad

$$egin{aligned} v_t &= v_{t-1} + (
abla w_t)^2 \ w_{t+1} &= w_t - rac{\eta}{\sqrt{(v_t)} + \epsilon}
abla w_t \end{aligned}$$

RMSProp

$$v_t = eta * v_{t-1} + (1-eta)(
abla w_t)^2 \ w_{t+1} = w_t - rac{\eta}{\sqrt{(v_t)} + \epsilon}
abla w_t$$



RMSProp (converged in 25 epochs – Dense Features)

Observations

- Adagrad got stuck when it was close to convergence (it was no longer able to move in vertical (b) direction because of the decayed learning rate).
- RMSProp overcomes this problem by being less aggressive on the decay.

Momentum based Gradient Descent Update Rule

$$egin{aligned} v_t &= \gamma * v_{t-1} + \eta
abla w_t \ w_{t+1} &= w_t - v_t \end{aligned}$$

Adam

RMSProp

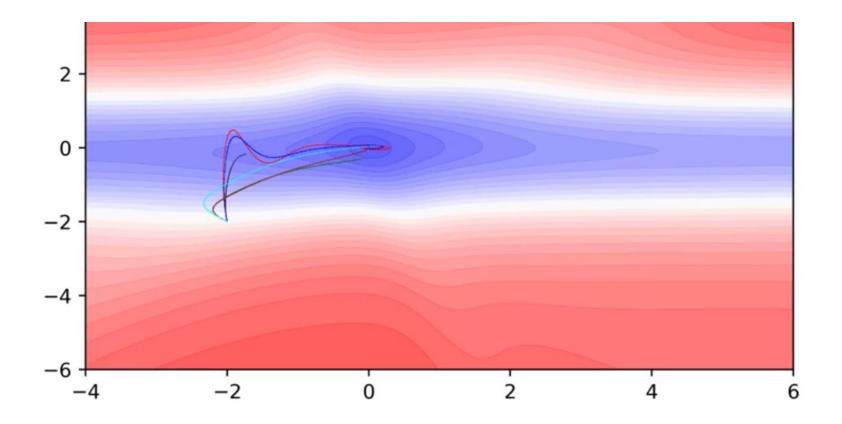
$$egin{aligned} v_t &= eta * v_{t-1} + (1-eta)(
abla w_t)^2 \ w_{t+1} &= w_t - rac{\eta}{\sqrt{(v_t)} + \epsilon}
abla w_t \end{aligned}$$

Adam

$$egin{aligned} m_t &= eta_1 * v_{t-1} + (1-eta_1)(
abla w_t) \ v_t &= eta_2 * v_{t-1} + (1-eta_2)(
abla w_t)^2 \ w_{t+1} &= w_t - rac{\eta}{\sqrt{(v_t)} + \epsilon} m_t \end{aligned}$$

$$m_t = rac{m_t}{1-eta_1^t} \ v_t = rac{v_t}{1-eta_2^t}$$

Cyan: Adam



Summary

Initialise w, b

Iterate over data:

compute ŷ

 $compute \mathcal{L}(w,b)$

$$w_{111} = w_{111} - \eta \Delta w_{111}$$

$$w_{112} = w_{112} - \eta \Delta w_{112}$$

....

$$w_{313} = w_{313} - \eta \Delta w_{313}$$

till satisfied

Algorithms

- GD
- Momentum based GD
- Nesterov Accelerated GD
- AdaGrad
- RMSProp
- Adam

Strategies

- Batch
- Mini-Batch (32, 64, 128)
- Stochastic