

### PRATICAL NO :- 3

```
#include <Servo.h>
Servo myservo;
int pos = 0;

void setup()
{
  myservo.attach(4);
}
void loop()
{
  for(pos = 0; pos <= 180; pos += 1)
  {
    myservo.write(pos);
    delay(15);
  }
  for(pos = 180; pos >= 0; pos -= 1)
  {
    myservo.write(pos);
    delay(15);
  }
}
```

#### PRATICAL NO :-4

```
#include <Servo.h>
Servo sm1, sm2, sm3;
int pos = 0;
void setup()
{
  sm1.attach(10);
  sm2.attach(11);
  sm3.attach(12);
}
void loop()
{
  for (pos = 0; pos <= 180; pos += 1)
  {
    sm1.write(pos);
    sm2.write(pos);
    sm3.write(pos);
    delay(15);
  }
  for (pos = 180; pos >= 0; pos -= 1)
  {
    sm1.write(pos);
    sm2.write(pos);
    sm3.write(pos);
    delay(15);
  }
}
```

## **PRATICAL NO :-5**

```
void setup()
{
  pinMode(0,OUTPUT);
  pinMode(1,OUTPUT);
  pinMode(2,OUTPUT);
  pinMode(3,OUTPUT);
  pinMode(4,OUTPUT);
  pinMode(5,OUTPUT);
  pinMode(6,OUTPUT);
}

void loop()
{
  digitalWrite(0,LOW);
  digitalWrite(1,HIGH);
  digitalWrite(2,HIGH);
  digitalWrite(3,LOW);
  digitalWrite(4,LOW);
  digitalWrite(5,LOW);
  digitalWrite(6,LOW);
  delay(500);

  //2

  digitalWrite(0,HIGH);
  digitalWrite(1,HIGH);
  digitalWrite(2,HIGH);
  digitalWrite(3,LOW);
  digitalWrite(4,HIGH);
  digitalWrite(5,LOW);
  digitalWrite(6,HIGH);
  delay(500);
  //3
  digitalWrite(0,HIGH);
  digitalWrite(1,HIGH);
  digitalWrite(2,HIGH);
  digitalWrite(3,HIGH);
  digitalWrite(4,LOW);
  digitalWrite(5,LOW);
  digitalWrite(6,HIGH);
  delay(500);
}
```

## **PRATICAL NO :- 6**

```

#include <LiquidCrystal.h>
int THERMISTORPIN = 0, BCOEFFICIENT = 3380 ;
float THERMISTORNOMINAL = 10000 , TEMPERATURENOMINAL = 25 , SERIESRESISTOR =
10000 ;
LiquidCrystal lcd(12, 11, 5, 4, 3, 2);
int sample[5];

void setup()
{
  Serial.begin(9600);
  lcd.begin(16, 2);
}

void loop()
{
  int i;
  float average;
  for(i=0;i<5;i++)
  {
    sample[i] = analogRead(THERMISTORPIN);
    delay(10);
  }
  average =0;
  for(i=0;i<5;i++)
  {
    average += sample[i];
  }
  average /= 5;
  average = 1023 / average - 1;
  average = SERIESRESISTOR / average;

  float steinhart;
  steinhart = average / THERMISTORNOMINAL;
  steinhart = log(steinhart);
  steinhart /= BCOEFFICIENT;
  steinhart += 1.0 / (TEMPERATURENOMINAL + 273.15);
  steinhart = 1.0 / steinhart;
  steinhart -= 273.15;

  lcd.print("Temp = ");
  lcd.print((int)steinhart);
  lcd.print(" C");
  delay(500);
  lcd.clear();
}

```

```

void setup()
{
  Serial.begin(9600);
  pinMode(7, OUTPUT);
  pinMode(6, INPUT);
}
void loop()
{
  digitalWrite(7, LOW);
  delayMicroseconds(2);

  digitalWrite(7, HIGH);
  delayMicroseconds(10);
  digitalWrite(7, LOW);

  long Duration = pulseIn(6, HIGH);
  int Distance = Duration * 0.034 / 2;
  Serial.print("Distance: ");
  Serial.print(Distance);
  Serial.println(" cm");
}

```

After paste the hex file of Arduino . go to ultrasonic sensor and also open the hex file and click ok.

**Note :-** IN ultrasonic practical (practical 8) and infrared practical (practical 7) add the hex file to both Arduino and (ultrasonic sensor) (infrared sensor )