

The 1% Project: Polka-Resilient-Actuator (Polka-RA)

You have a powerful and unique set of components. We will pivot the "Polka-DePIN-Bot" concept from a mobile robot fleet to a **Decentralized, Resilient, Off-Grid Actuation and Monitoring System**—a project that maximizes the use of your specific hardware and directly addresses the "Resilient Apps" theme in a way no other team is likely to attempt.

This project, **Polka-Resilient-Actuator (Polka-RA)**, focuses on verifiable, off-grid control, which is a critical need in regions with unstable infrastructure.

1. The "Woah" Factor: Off-Grid, Verifiable Actuation

The core innovation is using the **LilyGO TTGO T-Call ESP32 SIM800L** to establish a resilient, off-grid connection to the Polkadot network via GSM/GPRS. This proves that the system is truly **resilient** and not dependent on local Wi-Fi or fiber, which is a major win for the "Resilient Apps" theme.

Project Name: Polka-Resilient-Actuator (Polka-RA)

Hackathon Track: User-centric Apps / Polkadot Tinkerers (Advanced)

Core Function: A decentralized, on-chain system for remotely controlling and verifying the execution of physical tasks (e.g., watering, monitoring) in an off-grid environment.

2. Hardware Mapping and Technical Implementation

We will use your available components to build a sophisticated, multi-functional prototype.

Component	Role in Polka-RA	Your Expertise Used	Polkadot Integration
LilyGO TTGO T-Call ESP32 SIM800L	Resilient Gateway. Uses the SIM800L (GSM/GPRS) to connect to the Polkadot network via a lightweight client.	Embedded Systems, Programming	Submits transactions (Proof of Actuation) and listens for on-chain commands.
ESP-CAM	Verifiable Sensor. Captures images of the physical action (e.g., water flowing) before and after actuation.	AI (Image Processing)	Captures images, hashes them, and sends the hash to the Polkadot chain for immutable verification.
Arduino Mega / Nano RP2040	Actuator Controller. Controls the motors, pump, and relay based on commands received from the ESP32.	Programming, Robotics	Controls the 8 Servos (e.g., for a multi-valve system), Nema 17 (e.g., for linear movement), Pump , and Relay .
Relay, Pump, Servos, Nema 17	Physical Actuators. The devices that perform the "useful" work.	Robotics, Embedded Systems	The physical output that is controlled by the decentralized command.

A. Polkadot Integration: The Resilient Command Pallet

We will use a custom **Substrate Pallet** (or a smart contract on a Polkadot Parachain like Moonbeam) to manage the resilient command flow:

- Command Submission:** A user submits a command (e.g., `ActuatePump(duration)`) via a dApp. This command is stored on-chain.
- Off-Grid Polling:** The **LilyGO TTGO T-Call** periodically wakes up, connects via GPRS, and queries the Polkadot chain for new commands addressed to its unique device ID.
- Verifiable Actuation:**
 - The device captures a "**Pre-Actuation**" image hash via the ESP-CAM and sends it to the chain.
 - It executes the command (e.g., turns on the pump via the Relay).

- It captures a "**Post-Actuation**" image hash and sends it to the chain, along with a **Proof of Actuation** (a signed transaction confirming the action was taken).
4. **Automated Payment/Reward:** The Polkadot chain verifies the Proof of Actuation and automatically releases a small reward to the device's wallet for completing the task.

B. The "Wow" Factor: Demonstrating Resilience

The key to winning is the narrative around the **LilyGO TTGO T-Call**.

- **Scenario:** Demonstrate the system operating in a location with **NO Wi-Fi**. Show the GPRS connection status and the successful submission of a transaction to the Polkadot chain.
- **The Proof:** The dApp will display the two image hashes (**Pre** and **Post** actuation) stored immutably on the Polkadot chain, proving that the physical action was not only commanded but **verifiably executed** in an off-grid, resilient manner.

3. Judging Criteria Optimization

This adapted project is now hyper-optimized for the hackathon's theme and your resources.

Criteria	Polka-RA's Edge
Technological Implementation	Highest Score. Requires complex, low-level programming for the ESP32 SIM800L (GPRS) , integration of multiple microcontrollers (Mega/Nano), and the use of Rust/Substrate for the on-chain logic. This is a highly advanced technical stack.
Resilience	Perfect Alignment. The use of GPRS/GSM for off-grid communication is the ultimate demonstration of a "Resilient App" in a challenging environment like Burundi.
Creativity	High. It moves beyond simple data logging to Decentralized Actuation , using the blockchain not just for data, but for resilient, verifiable command and control of physical hardware.
Potential Impact	High. The model is immediately applicable to off-grid infrastructure, remote monitoring, and automated farming in developing regions, directly addressing the "radically useful" motto.

4. Action Plan for the Hackathon

1. Phase 1: Resilient Communication (LilyGO)

- Get the LilyGO TTGO T-Call to successfully connect to the internet via GPRS.
- Implement a lightweight Polkadot client (e.g., using a library or raw HTTP/WebSocket calls) to submit a simple transaction.

2. Phase 2: Verifiable Actuation (Mega/Nano/ESP-CAM)

- Write the firmware to receive a command from the ESP32 and actuate the **Pump** and **Relay**.
- Integrate the **ESP-CAM** to capture and hash images before and after actuation.

3. Phase 3: Polkadot Pallet & Demo

- Develop the `Command-Pallet` in Substrate to store the command and verify the image hashes.
- Create a compelling video that shows the entire loop: **On-chain Command -> Off-Grid GPRS Transmission -> Physical Actuation -> On-chain Verification (Image Hashes)**.

This project is a guaranteed showstopper and perfectly tailored to your unique strengths and resources.