

# Noise, Overfitting, and Bias vs Variance

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*Slides adapted from Iain Styles, School of Computer Science*



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# Intended Learning Outcome

- Understand the effect of noise on machine learning problems
- Understand and explain the concepts of over and underfitting
- Be able to explain these concepts using the idea of bias-variance decomposition



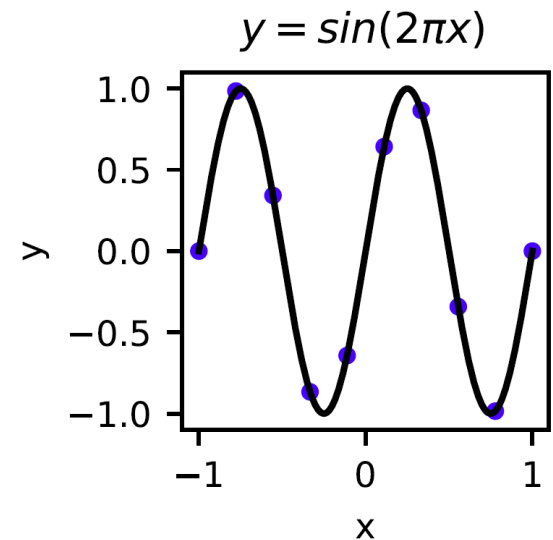
# Model choice

- Remember
  - We want to model the relationship between  $x$  and  $y$  as a mathematical function
    - $f(w, x)$
  - If we know model, we can use that
    - $y(x) = \sin(2\pi x)$ ;
  - But often we do not!
    - We will use a ‘representation’ that describes the data well, which we called a basis



# Visual example

- Keeping to linear models will help us explore the details
- $y(x) = \sin(2\pi x)$ ;
  - So  $f(\mathbf{w}, x) = w_0 \sin(2\pi x)$ ;  
would be a trivial choice
- Assume we have no knowledge about model
  - $f(\mathbf{w}, x) = \sum_{i=0}^{M-1} w_i x_i$



# Visual example

- $y(x) = \sin(2\pi x) = \sum_{i=0}^{M-1} w_i x_i$
- Expand  $y(x)$  using Maclaurin series:

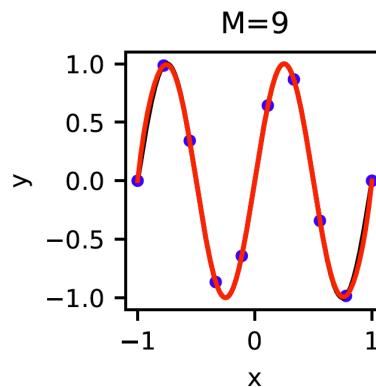
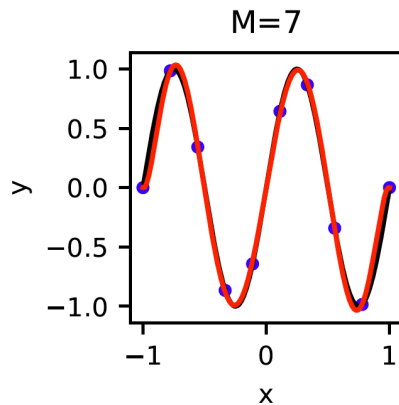
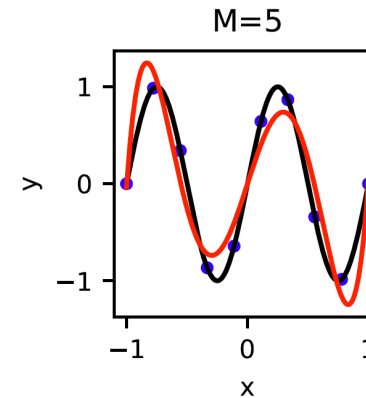
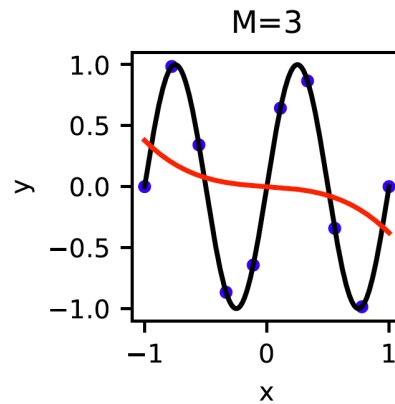
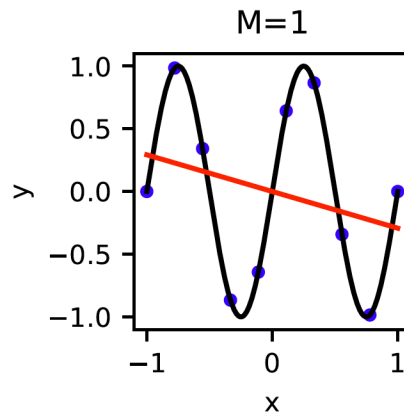
$$\sin(ax) = ax - \frac{a^3 x^3}{3!} + \frac{a^5 x^5}{5!} - \frac{a^7 x^7}{7!} + \dots$$

$$- w \approx (0, 6.28, -41.34, 0, 81.61, \dots)$$

- So if we start generating data using this approximation by increasing order, and compare to actual model. with no noise!



# Polynomial fit of $y(x) = \sin(2\pi x)$ ;



What do you observe?

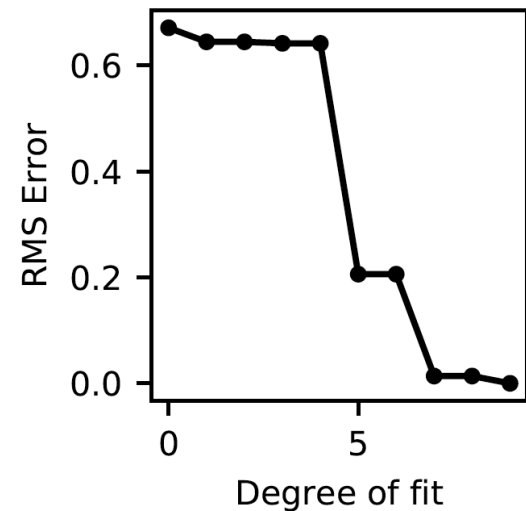


# How good is the fit?

- Root-mean-square (RMS) error

$$R = \sqrt{\frac{1}{N} \sum_i r_i^2}$$

- Modelled (approximated) function converges with little change at M-7



# Coefficients of the fitted polynomial

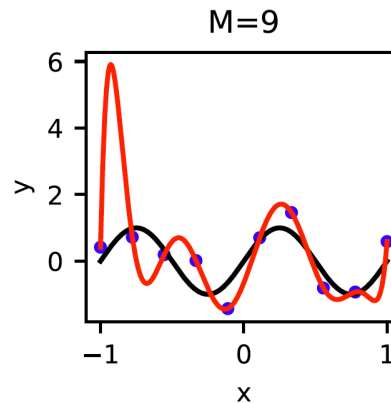
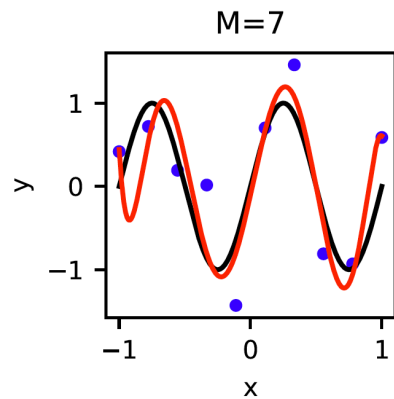
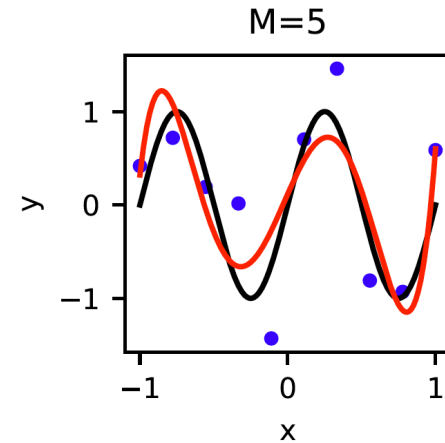
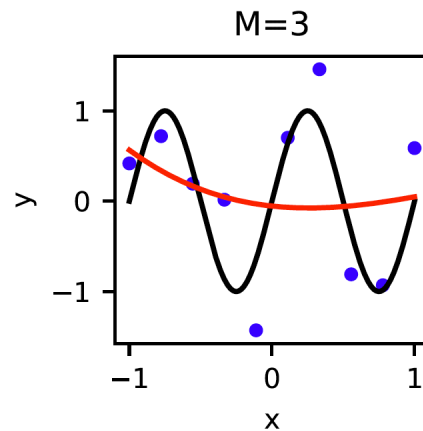
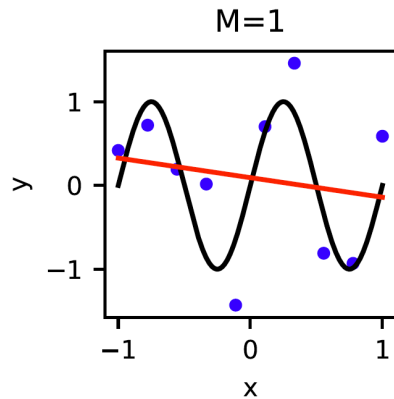
M	$w_0$	$w_1$	$w_2$	$w_3$	$w_4$	$w_5$	$w_6$	$w_7$	$w_8$	$w_9$
0	0.00									
1	0.00	-0.29								
2	0.00	-0.29	-0.00							
3	0.00	-0.07	-0.00	-0.31						
4	0.00	-0.07	0.00	-0.31	-0.00					
5	0.00	3.85	-0.00	-16.51	0.00	12.69				
6	0.00	3.85	-0.00	-16.51	0.00	12.69	-0.00			
7	-0.00	6.00	0.00	-35.84	-0.00	54.04	0.00	-24.20		
8	-0.00	6.00	0.00	-35.84	-0.00	54.04	0.00	-24.20	-0.00	
9	-0.00	6.28	0.00	-41.12	-0.00	78.61	0.00	-63.77	-0.00	20.00
True	0	6.28	0	-41.34	0	81.61	0	-76.7	0	42.1

- Coefficients are not quite correct
  - Effect of limited sample domain (Maclaurin series is over  $[-\infty \infty]$ )
- Low order terms match well
- $M = 9$  has zero error
  - Exactly fits all data point
- A strong hint as to what can go wrong





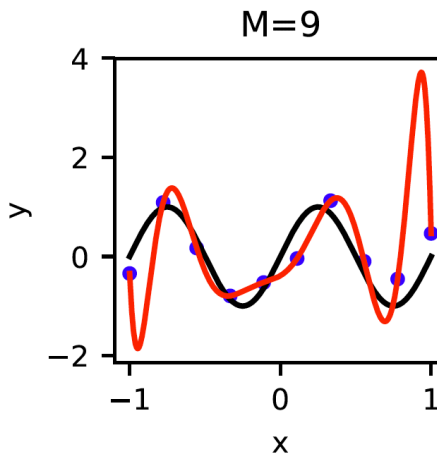
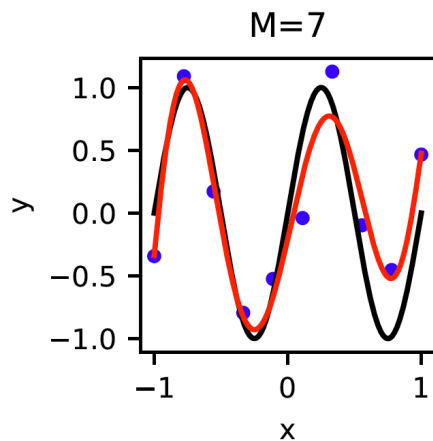
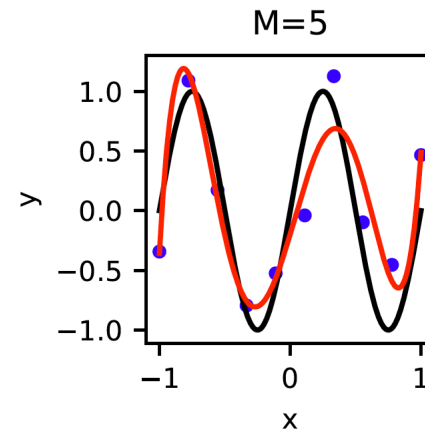
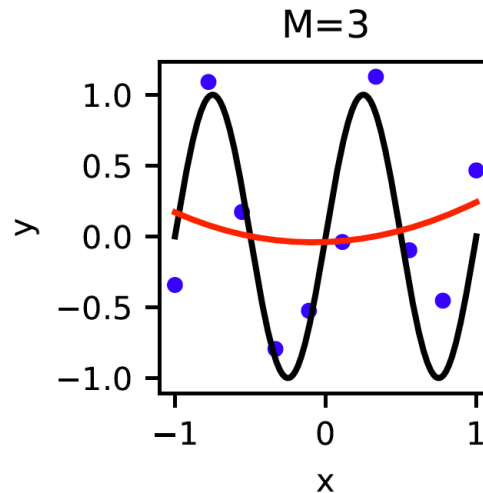
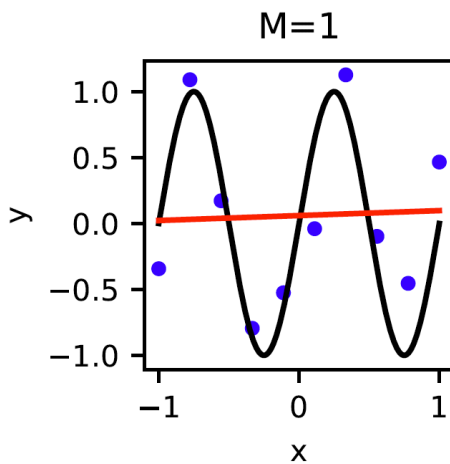
# Polynomial fit of $y(x) = \sin(2\pi x) + \varepsilon$



What do you observe?



# Polynomial fit of $y(x) = \sin(2\pi x) + \varepsilon_1$ ;



What do you observe?



# Noise corrupts

- Low-order fits similar in most cases
- High-order fits very differently
- Noise in the data leads to noise in the estimated model
  - Robust models cannot model the data very well
- How can we understand this?



# Bias-Variance Decomposition

- ▶ Underlying data generating function  $h(x)$
- ▶ Data  $y = h(x) + \epsilon$
- ▶ Estimated model  $f(x)$

What is the expected value of the least-squares loss?

$$\mathbb{E}[\mathcal{L}] = \mathbb{E}[(y - f)^2] \tag{1}$$



# Bias-Variance Decomposition

We first expand the square

$$\mathbb{E}[\mathcal{L}] = \mathbb{E}[(y - f)^2] \quad (2)$$

$$= \mathbb{E}[y^2] + \mathbb{E}[f^2] - 2\mathbb{E}[yf] \quad (3)$$

The variance of a random variable is:

$$\text{var}[X] = \mathbb{E}[X^2] - (\mathbb{E}[X])^2, \quad (4)$$

and for independent variables  $X$  and  $Y$

$$\mathbb{E}[XY] = \mathbb{E}[X]\mathbb{E}[Y] \quad (5)$$

This allows us to rewrite the loss as

$$\mathbb{E}[\mathcal{L}] = \text{var}[y] + (\mathbb{E}[y])^2 + \text{var}[f] + (\mathbb{E}[f])^2 - 2\mathbb{E}[y]\mathbb{E}[f] \quad (6)$$



# Bias-Variance Decomposition

- ▶ Recall  $y = h(x) + \epsilon$
- ▶ Noise distribution:  $\mathbb{E}[\epsilon] = 0$  and  $\text{var}[\epsilon] = \sigma^2$
- ▶ So  $\mathbb{E}[y] = h$  and  $\text{var}[y] = \sigma^2$ .

The expected loss becomes

$$\mathbb{E}[\mathcal{L}] = \sigma^2 + h^2 + \text{var}[f] + (\mathbb{E}[f])^2 - 2h\mathbb{E}[f] \quad (7)$$

$$= \sigma^2 + \text{var}[f] + h^2 + (\mathbb{E}[f])^2 - 2h\mathbb{E}[f] \quad (8)$$

$$= \sigma^2 + \underbrace{\text{var}[f]}_{\text{variance}} + \underbrace{(h - \mathbb{E}[f])^2}_{\text{bias}} \quad (9)$$



# What does it all mean?

- ▶ How can we interpret this result?
- ▶ Only contribution from data  $y$  is its variance  $\sigma^2$ .
- ▶ All dependency on the *specific sample*,  $y$ , of the data has been absorbed into the other terms.
- ▶ The variance of  $f$  is a consequence of the variance in the data
  - ▶ No noise  $\rightarrow$  always learn the same model
  - ▶ Noisy samples  $\rightarrow$  different models.
  - ▶  $\text{var } f$  is sensitivity of learned model to the choice of data.



# What does it all mean?

- ▶  $h(x) - \mathbb{E}[f(x)]$  is the ability of the estimated model to accurately represent the true model
- ▶ It is the *bias* of the estimate.
- ▶ Fitting  $f(x) = mx * c$  to  $h(x) = \sin(2\pi x)$  has a high bias: cannot represent the data
- ▶ But it has a low variance: insensitive to particular data choice
- ▶ Loss minimisation requires simultaneous minimisation of both bias and variance
  - ▶ Models that both fit *and* generalise well
  - ▶ Nearly always in conflict
- ▶ A fundamental limitation of machine learning.

