

ON THE DYNAMICS OF TRANSMISSION CAPACITY AND LOAD LOSS DURING CASCADING FAILURES IN POWER GRIDS

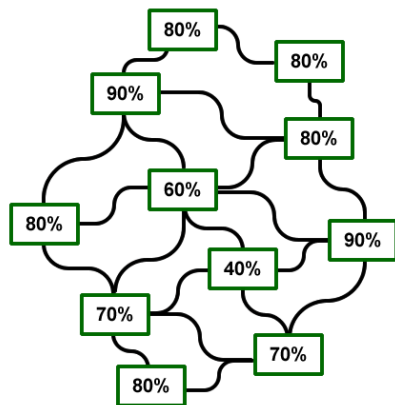
Rezoan A. Shuvro*, Pankaz Das*, Mahshid Rahnamay-Naeini~ , Francesco Sorrentino`, Majeed M. Hayat*

*Department of Electrical and Computer Engineering, Marquette University, Milwaukee, WI, USA

~Electrical Engineering Department, University of South Florida, Tampa, FL, USA

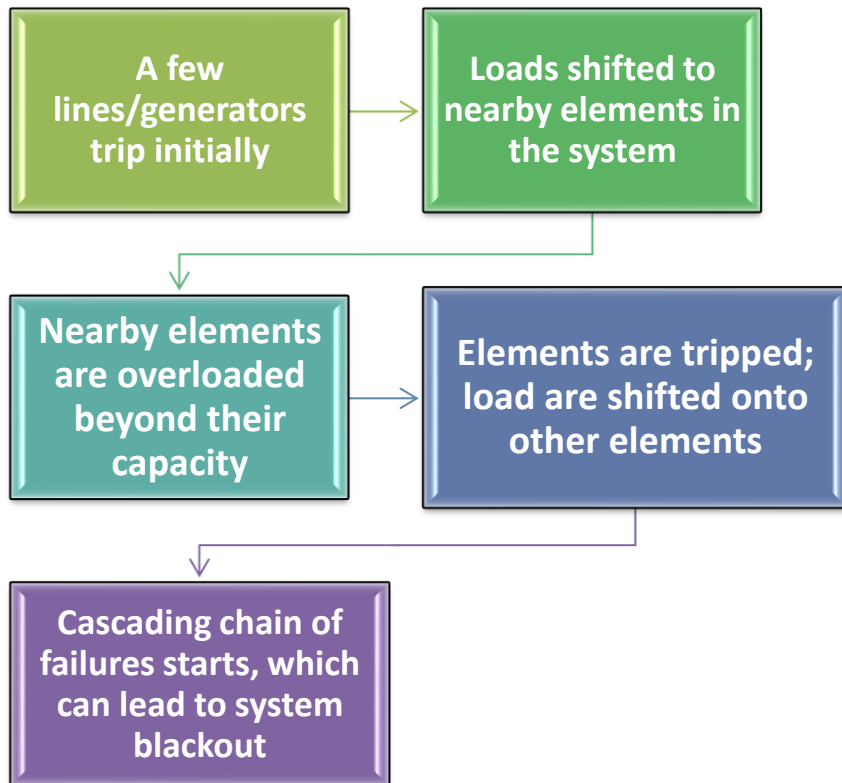
`Department of Mechanical Engineering, University of New Mexico, Albuquerque, NM, USA

Cascading Failures in Power Grid : Overview

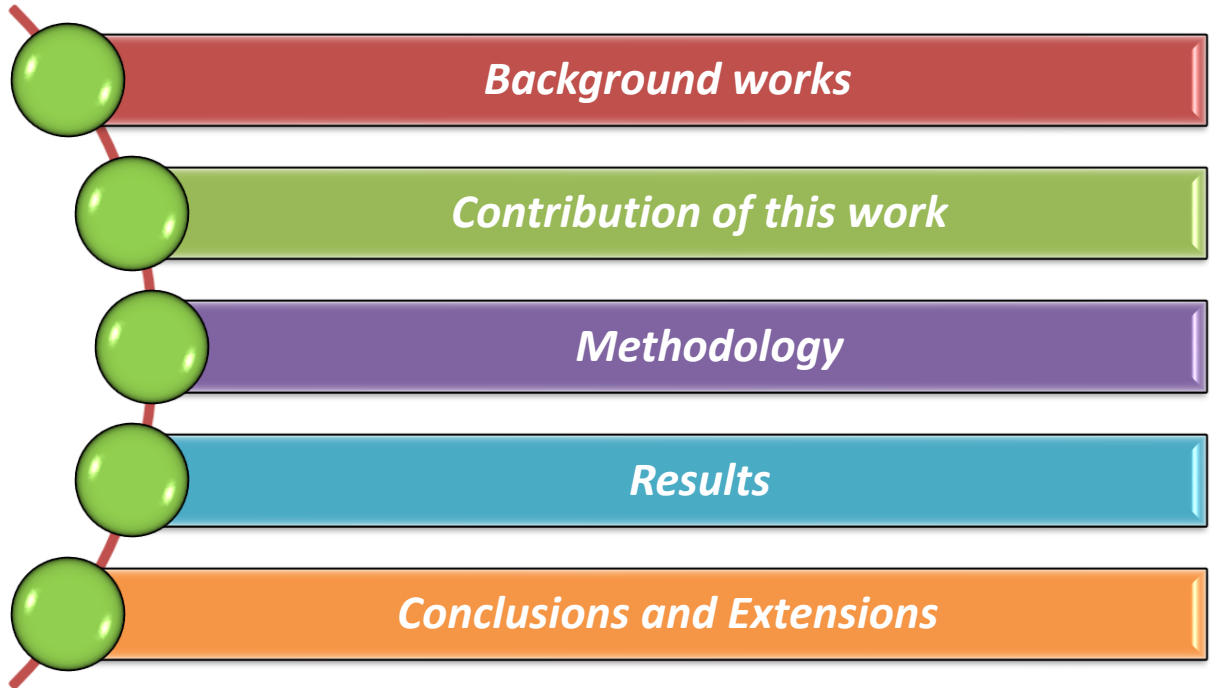


Network running normally

Source: Wikipedia



Outline of the Presentation



Background: Model for cascading failures: Markov chain based on a reduced state space of the power-grid variables

Main ideas of the *stochastic abstract-state evolution (SASE)* approach (1):

- Simplify the state space of the complex power system (**equivalence classes**)

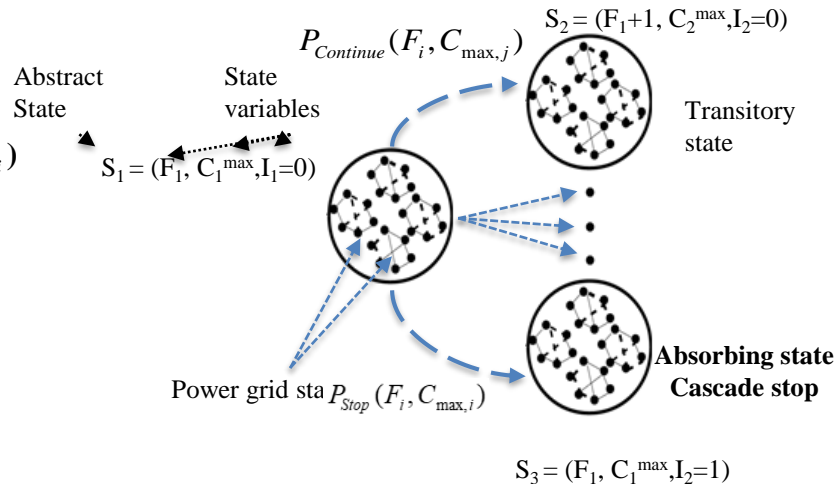
Aggregate state variables: $S_i = (F_i, C_i^{\max}, I_i)$

F : number of failed lines

C_{\max} : maximum capacity of failed lines

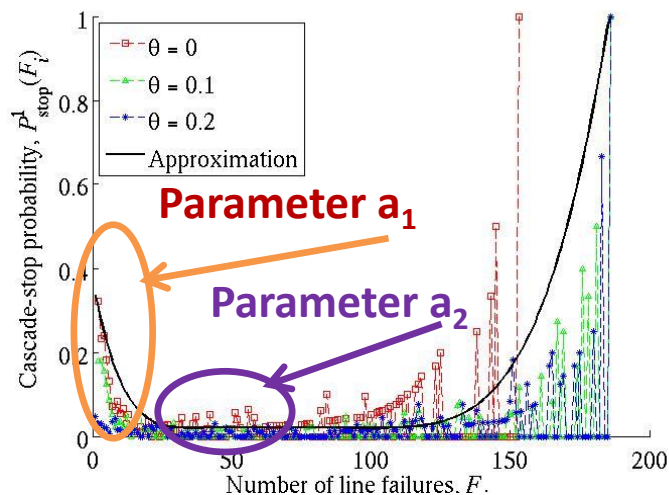
I : Cascade-stability of power grid

- Capturing the effects of the omitted variables through the transition probabilities and their parametric dependence on physical attributes and **operating characteristics** of the system.



Background: Transition probabilities of MC are parameterized by grid's physical operating characteristics

$P_{Stop}^1(F_i, C_{\max,i})$ is Data-driven and determined parametrically with the aid of Monte-Carlo power-flow-optimization



$$P_{Stop}^1(F_i) = \begin{cases} a_1 \left(\frac{a_2 L - F_i}{a_2 L} \right)^4 + \varepsilon & 1 \leq F_i \leq a_2 L \\ \varepsilon & a_2 L \leq F_i \leq 0.6L \\ \min \left\{ \left(\frac{F_i - 0.6L}{L - 0.6L} \right)^4 + \varepsilon, 1 \right\} & 0.6L \leq F_i \leq L \end{cases}$$

The parameters are mapped to physical operating characteristics:

Transmission capacity estimation error

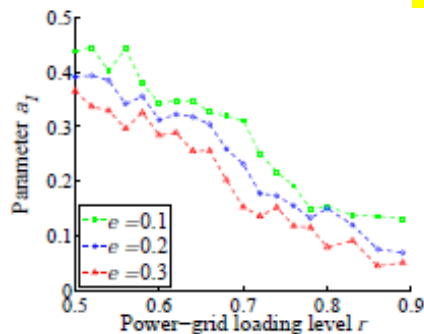
$$e \in [0,1]$$

Load shedding implementation constraints

$$\theta \in [0,1]$$

Power-grid loading level

$$r \in [0,1]$$



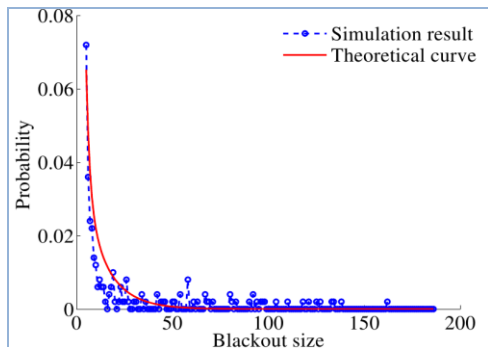
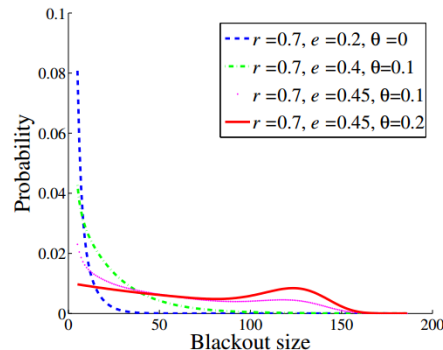
$$P_{Stop}^1(F_i, C_{\max,i})$$

Parametrized by the three physical operating characteristics

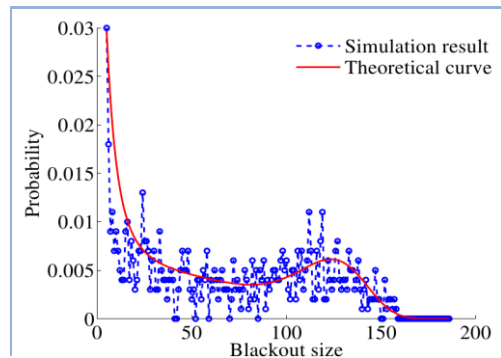


Background: Model can provide blackout-size distribution analytically for any initial condition

- Conditional probability that a power grid eventually reaches a state with n failures.
- Communication reliability limitations (e and q) and large loading levels (r) increase the probability of large blackouts.
- Model was validated using power system simulations



Normal operation of the power grid (**good** operating characteristics settings) Example of good scenario: $r=0.7, e=0.1, \theta=0$



Operation of the power grid under stress (**bad** operating characteristics settings) Example of bad scenario: $r=0.7, e=0.45, \theta=0.2$



Motivations for this work

In a recent study by cascading failure working group [1], following critical metrics for cascading failures were identified:

- **Size and distribution of the blackout size**
- **Amount of Load shedding** and Load shed distribution
- Critical transmission lines

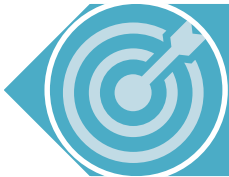
Contribution of this work



Steady state distribution of the transmission line failures are calculated analytically.



Average transmission capacity loss during cascading failures are calculated analytically. .



Amount of Load shed was calculated using the linear correlation between load shedding and capacity of the failed lines.

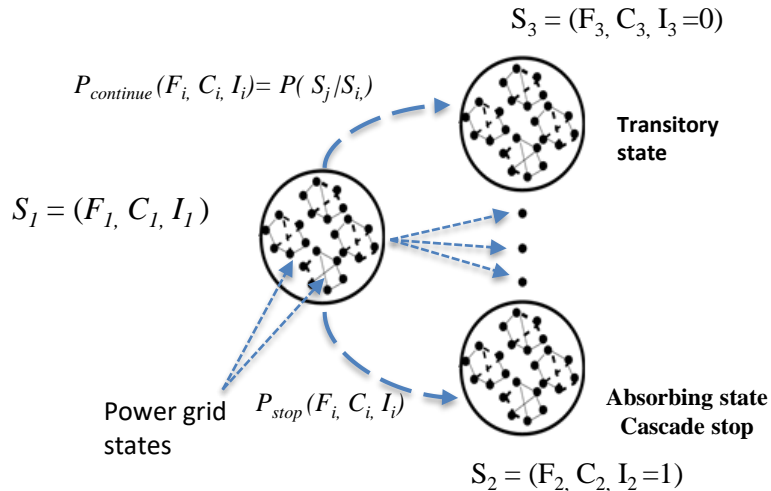
Dynamics of transmission capacity and load loss

- Aggregate state variables: $S_i = (F_i, C_i, I_i)$

- F_i : number of failed lines
- C_i : capacity of last failed lines
- I_i : Cascade-stability of power grid

- State transition probabilities of the Markov chain:

$$f(S_j|S_i) = \begin{cases} 1 & \text{if } F_j = F_i, C_j = C_i, I_j = I_i = 1, \\ P_{stop}(S_i) & \text{if } F_j = F_i, C_j = C_i, I_j = 1, \\ P(S_j|S_i) & \text{if } F_j = F_i + 1, C_j \in \mathcal{C}, I_j = 0, \\ 0 & \text{otherwise.} \end{cases}$$



Formulation allows to track the average transmission capacity loss

- $P(S_j|S_i)$ was formulated using $P_{stop}(S_i)$ as

$$P(S_j|S_i) = \left(\alpha(C_j)^\beta (1 + \gamma C_i(C_j - C_{th})) \right) (1 - P_{stop}(S_i))$$

- The parameters α, β, γ and C_{th} are calculated as described in [2].
- Here, C_{th} is a threshold in capacity values, where transmission lines with capacity lower than C_{th} are more vulnerable to failure in the next step.

Average transmission line failures and capacity loss in the steady state

- From the Markov chain, we calculate the distribution of the failed transmission lines of the power grid at the steady state

$$p(F_i|S_0) = \sum_{l=1}^{|C|} \pi_{2(F_i-1)|C|+2(l-1)+1}$$

- We calculate the expected number of transmission-line failures and the expected total capacity loss, given the initial condition, S_0 using the distribution of the failed transmission lines,

$$E[F_i|S_0] = \sum_{F_i=1}^M F_i p(F_i|S_0).$$

$$E[ATC_{F_i}|S_0] = \sum_{F_i=1}^M ATC_{F_i} p(F_i|S_0).$$

ATC_{F_i} is the average total capacity (ATC) loss with a total of F_i failures



Calculating average transmission capacity loss in the steady state

- we introduce the following recursion to calculate the average total capacity (ATC) loss during cascading failures

$$ATC_{F_j} = ATC_{F_i} + ACL_{F_j}$$

Here, ACL_{F_j} is the *average capacity loss* in the current state with F_j failures, ATC_{F_i} is the average total capacity (ATC) loss with a total of F_i failures

- To calculate ACL_{F_j} , we need the marginal probabilities of initial line-failures with capacity C_i at the current state. After the occurrence of an initial event, we calculate the marginal probability at successive steps as follows,

$$P_{F_j}^{C_j} = \sum_{C_i \in \mathcal{C}} P(C_j | C_i) P(C_i)$$

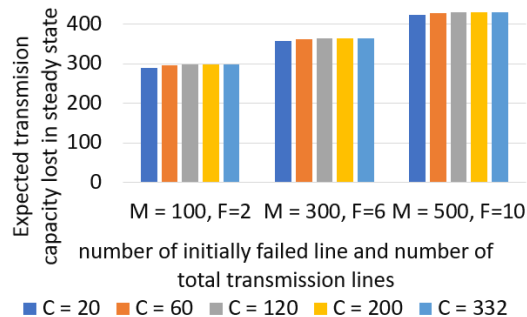
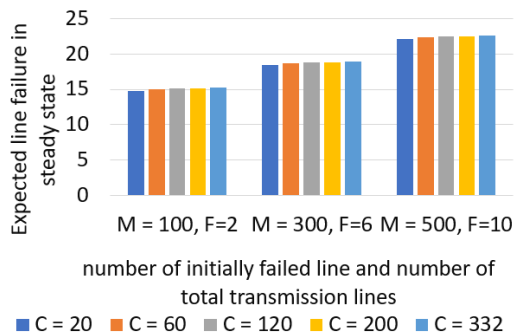
- $P(C_j | C_i) = P(S_j | S_i)$ is obtained using the equation shown in previous slide
- $P(C_j | C_i)$ equals $P(S_j | S_i)$ because of our definition of the transition matrix

Then we calculate ACL_{F_j} using

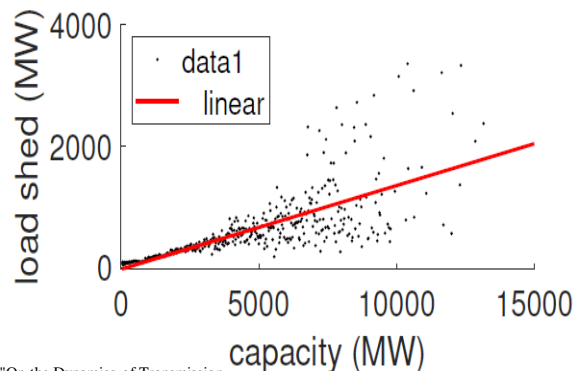
$$ACL_{F_j} = \sum_{C_j \in \mathcal{C}} C_j P_{F_j}^{C_j}$$

Prediction of expected loss in transmission capacity or loss in load delivery after initial trigger

- Expected number of line failure and expected transmission capacity loss for different total number of transmission lines, M and initially failed transmission lines, F

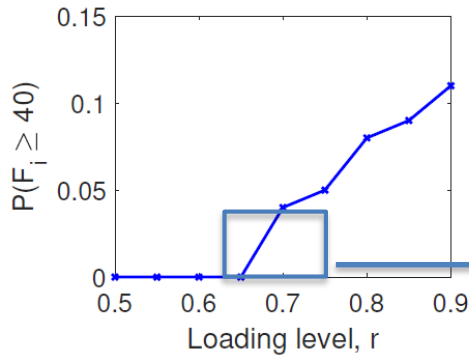


- Parametric prediction of load loss from average transmission capacity loss using linear regression using cascading failure data generated from simulation

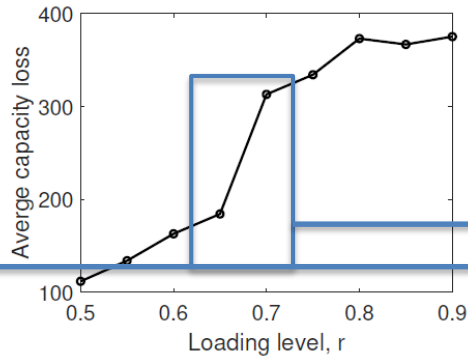


Model predicts critical initial triggers of cascading failures for a given set of grid operating settings

- $P(F_i \geq 40)$ and ATCL for various r , $e = 0.45$, $\theta = 0.2$.
- For $r \geq 0.65$, the probability of a cascade increases with the grid loading level r



(a) $P(F_i \geq 40)$



(b) ATCL

Critical loading level above which a sharp transition in transmission line failure and average transmission capacity loss was observed

Critical initial conditions for various grid sizes

- Table below shows the severity of cascading failure for different values of M (total number of lines) and F (number of failed lines) (e.g., the red-colored zones indicate a cascade).
- We use a threshold of 300MW for ATCL (which corresponds to a small amount of load loss), above which we consider a cascading failure event. Note that the ATCL value was chosen arbitrarily for the purpose of classifying cascade events
- Expected transmission capacity loss during cascading failures for different total number of transmission lines, M and initially failed transmission lines, F (red indicates $\geq 300\text{MW}$).

	M =100	M =200	M =300	M =400	M =500
F=2	290	262	236	214	196
F=3	315	296	270	247	228
F=4	336	324	301	279	259
F=5	355	349	330	309	289
F=6	375	371	357	337	318

Conclusions and Extensions

- This work allows to calculate the following analytically.
 - ✓ **The blackout size distribution**
 - ✓ **Average transmission capacity loss**
 - ✓ **Amount of load shed**
- Role of cyber threat on the resilience of the grid was captured in a subsequent paper.
 - **‘Balancing Smart Grid’s Performance Enhancement and Resilience to Cyber Threat’ (to be presented at the resilience week 2019).**
- Currently we are working on devising optimal policies to mitigate cascading failures optimally.



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