

1 Highlights

2 **An analysis of interrelations between economic and environmental**
3 **variables in Australian Winegrowing.**

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An analysis of interrelations between economic and environmental variables in Australian Winegrowing.

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1. Introduction

In the past decade, the Australian winegrowing industry has undergone a variety of pressures, such as changing market demands, disease and drought (Australia, 2021a). Furthermore, natural resources are likely to decrease, as pressures from climate change increase, making it more important than ever to improve the efficiency and sustainability of crops (AGDEE, 2021). It has become crucial for those in the wine industry to address issues relating to environmental sustainability and economic viability, with a growing need for the industry to close the research gaps between sustainable practices and their real and perceived environmental and economic advantages (Montalvo-Falcón et al., 2023; Ouvrard et al., 2020). This paper aims to provide a comprehensive analysis of the intricate relationships between economic and environmental variables within the winegrowing sector. By employing statistical machine learning we show how interconnected vineyard variables are. Utilising a ten year data set that spans Australia we show the predominant elements in classifying region and year, as well as determining a vineyards potential operational costs and profit.

This analysis utilises XGBoosted trees to classify region and year; and to determine operating cost and profit of Australian vineyards. Classification

and regression trees are utilised as surrogate models to shed insight into the key partitions used by the XGBoost ensembles. Variable importance is further used to illustrate the interconnectedness of the different predictor variables, and to show the similarity in variable importance between different response variables (particularly between region and operational cost). This study aims to assist in uncovering the complexity of variables that are affected by a variety of vineyard management decisions to illustrate complex interplay of variables. This study endeavours to gain insight into the similarity in predictor variable importance between year, region, operational costs and profit.

2. Methods

2.1. Data

Data used in this analysis were obtained from Sustainable Winegrowing Australia. Australia’s national wine industry sustainability program, which aims to facilitate grape-growers and winemakers in demonstrating and improving their sustainability (SWA, 2022). Data recorded by the SWA is entered manually by winegrowers using a web based interface tool. A total of 6091 observations were collected from 2012/2013 to 2021/2022 financial years. 23 variables were used for each observation reflecting a vineyards account for the given year (see Table 2.1). The profit variable was additionally transformed and included as another separate variable, profitable; depicting whether a vineyard was profitable or not.

The data originally contained only two multiclass variables: year and region. Variables that measured the same metric from different sources (such

Table 1: Summary of variables used in the analysis. The recorded column indicate values that were either greater than zero or that were not missing.

Variable	Units	Recorded	Number of Classes
Water Used	Mega Litres	5846	
Diesel	Litres	5585	
Biodiesel	Litres	25	
LPG	Litres	958	
Herbicide Spray	Times per year	2026	
Year	Class	6091	10
Disease	Class	6091	2
Region	Class	6091	58
Solar	Kilowatt Hours	622	
Irrigation Type	Class	6091	20
Petrol	Litres	4309	
Slashing	Times per year	2290	
Yield	Tonnes	5935	
Irrigation Energy	Class	6091	16
Area Harvested	Hectares	6091	
Electricity	Kilowatt Hours	1015	
Insecticide Spray	Times per year	1092	
Fertiliser	Kilograms of Nitrogen	795	
Fungicide Spray	Times per year	2260	
Cover Crop	Class	6091	32
Water Type	Class	6091	39
Profit	AUD	³ 853	
Operating Costs	AUD	853	

as water collected from rivers versus water from dams) were converted into multiclass variables representing the source. The total amount used from these variables was retained as a separate variable. Occurrences of multiple sources were defined as separate classes.

The variable region represented one of the 65 Geographical Indicator Regions (GI Region) used to describe different unique localised traits of vineyards across Australia (Halliday, 2009; Oliver et al., 2013; SOAR et al., 2008). Each region is explicitly defined under the Wine Australia Corporation Act of 1980 (Attorney-General’s Department, 2010).

2.2. XGBoosted Trees

XGBoosted (eXtreme Gradient Boosting) trees were created using the XGBoost library (Chen and Guestrin, 2016) in the Python Programming language (G. van Rossum, 1995). They were chosen for this analysis as they provide both a high predictive performance and ability to effectively capture complex relationships. An XGBoosted tree was created for each variable to show how they interacted. Each tree included all but the economic variables (profit and operating cost), which were only included once as response variables.

Following Chen and Guestrin (Chen and Guestrin, 2016), XGboosted trees predict a value y_i from the input x_i . The method of prediction is achieved through a tree ensemble model, using K additive functions to predict the output.

$$\hat{y}_i = \phi(x_i) = \sum_{k=1}^K f_K(x_i), f_K \in \mathcal{F}, \quad (1)$$

77 where each function f_K is a classification or regression tree, such that all
78 functions are in the set of all decision trees \mathcal{F} , defined by $f(x) = \omega_{q(x)}(q :$
79 $\mathbb{R}^m \rightarrow T, \omega \in \mathbb{R}^T)$. Where, f_K corresponds to an independent tree structure
80 q of ω weights. Each tree has T leaves, which contain a continuous score,
81 represented by ω_i for the i -th leaf. The final prediction is determined by the
82 sum of the score of the corresponding leaves, given by ω . The set of func-
83 tions used by the tree is determined by minimising the regularised objective
84 function, given by:

$$\mathcal{L}(\phi) = \sum_i l(\hat{y}_i, y_i^{t-1} + f_t(x_i)) + \sum_k \Omega(f_K). \quad (2)$$

85 The difference between the prediction and actual variable is a convex loss
86 function l . To optimise l , the difference is calculated for the i -th instance
87 at the t -th iteration. The function f_t is selected according to which value
88 minimises (2). The model complexity is penalised by the function Ω , this
89 acts to smooth weights in an attempt to prevent over fitting.

90 As predictions are made using additive tree functions, XGboosted trees
91 can be used for classification and regression. Due to the mixture of continu-
92 ous, binary and multiclass variables in this analysis, both classification and
93 regression trees were created. The difference between the trees created for
94 this analysis was the objective function used. XGBoosted regression trees
95 were created for continuous variables, using the root-mean-square as the ob-
96 jective function. Binary class variables utilised the logistic loss function as
97 the objective. And, Multiclass variable used the soft max function. All objec-
98 tive functions are defined within the SKlearn library (Buitinck et al., 2013),
99 linked via an API to the XGBoost library (Chen and Guestrin, 2016).

100 Chen and Guestrin (Chen and Guestrin, 2016) further illustrate, using
 101 Taylor expansions, that for a fixed structure $q(x)$ the optimal weight ω_j^* for
 102 a leaf j can be derived. Furthermore, they show the loss reduction after the
 103 split is given by the function:

$$\mathcal{L}_{split} = \frac{1}{2} \left[\frac{(\sum_{i \in I_L} g_i)^2}{\sum_{i \in I_L} h_i + \lambda} + \frac{(\sum_{i \in I_R} g_i)^2}{\sum_{i \in I_R} h_i + \lambda} - \frac{(\sum_{i \in I} g_i)^2}{\sum_{i \in I} h_i + \lambda} \right] - \gamma, \quad (3)$$

104 with the tree structure defined using left I_L and right I_R instance sets of
 105 nodes, with $I = I_L \cup I_R$. Instead of enumerating all possible tree structures,
 106 a greedy algorithm iteratively adds branches to the tree minimising \mathcal{L}_{split}
 107 in (3). The frequency of a variable’s occurrence within a tree is directly
 108 attributed to the minimisation of the objective function (or loss) through
 109 the minimisation of \mathcal{L}_{split} .

110 The frequency of a variable appearing as a node within the ensemble was
 111 used as a measure of importance. This measure was chosen as it connected
 112 a variable to the minimisation of its associated objective function, trans-
 113 lating the value into a simple count metric. Creating XGBoosted trees for
 114 each variable allowed the use of importance to show how strongly variables
 115 were associated with each other. The importance of predictor variables to
 116 economic variables was illustrated through the use of Sankey diagrams con-
 117 structed using the Holoviews python library (Rudiger et al., 2020). Other
 118 variable’s interconnectedness was demonstrated through the use of a chord
 119 diagram also created using Holoviews.

120 Each variable utilised 80% of the data to train the XGBoost ensemble,
 121 with 20% reserved for testing and validation. Testing was done through the
 122 iterative minimisation of the respective objective function for the variables

type. For continuous variables 20% was used as testing data, minimising the root-mean-square function. The final model was validated using repeated k-fold cross validation for 10 folds, repeated 10 times. R^2 scores were used to determine the best regression models during validation. For binary and multiclass variables data was split into 80% training, 10% testing and 10% validation data. Due to class disparity in multiclass variables (most prominently in region) data was stratified into each subset at the same ratio of class occurrence. Validation was summarised through the accuracy, the proportion of true negatives and positives.

The use of the XGBoost library incorporates regularisation techniques built into the software to mitigate over-fitting and enhance model generalisation. The further use of cross validated grid search functions allowed for the selection of better performing hyperparameters when selecting the final model. The performance measure for model selection was root-mean-square error for continuous variables. The receiver operator characteristic's area under the curve was used for category variables (Hanley and McNeil, 1982). Multiclass variables utilised the one verse one approach to minimise sensitivity to class disparity (Ferri et al., 2009; Hand and Till, 2001).

2.3. *Classification and Regression Trees*

Classification and Regression Trees were created for region, year, profit and operating cost. These models describe the partitions that are useful in predicting these variables; giving insight into the trees that make up the ensembles created by XGBoost. These trees were created using the rparts and caret packages (Kuhn, 2008; Terry Therneau and Beth Atkinson, 2022) in the R statistical programming language (R Core Team, 2021).

148 Decision trees were validated using K-fold cross validation. Each model
149 was validated using 10 folds, utilising a random selection of different samples
150 ten separate times to validate each of the decision trees. The same measure
151 of accuracy as the XGBoosted trees was used for comparison.

152 **3. Results**

153 *3.1. Region*

154 Region classification performed at 32.34% (3.67% standard deviation) and
155 56.82% accuracy (50.58% validation accuracy), for the classification tree and
156 XGBoosted ensemble respectively. The most prominent feature used to clas-
157 sify regions with the classification tree was water source (see Figure 1). This
158 differed from the variables that illustrated the greatest importance for the
159 XGBoosted ensemble (see Figure (2), with predictor variables being highly
160 interrelated in importance. Area, water, fuel and yield were more deter-
161 mining factors when predicting region using XGBoost. Although water and
162 diesel were two of the three most frequently occurring variables in predicting
163 region, they were not as connected to the other predictor variables as Yield
164 and area harvested were.

165 It is reasonable that regions, being subjected to different rainfalls and
166 temperatures, would require different amounts of water, and would have
167 access to different water sources. The relation of area harvested and fuel
168 (particularly petrol) is prominent with other predictors. Due to the wide
169 variety of uses of petrol and diesel, it is likely that they are representative of
170 other activities within the vineyard, such as pruning and harvesting. With
171 predictors such as yield and area being highly interconnected as they likely

172 operate as proxy variables to other factors, possibly other present variables.

173 Many of the regions had significantly lower reporting rates, resulting in
174 much poorer classification performance. The regions with the most samples
175 performed the best. Notably bordering regions were routinely grouped to-
176 gether and misclassified as the same region. Two areas that suffered the
177 most from this, specifically with the classification tree were the Limestone
178 Coast (cool coastal areas in South Australia) and the warmer inland regions
179 along the Murray Darling. The classification tree likely had more difficulty
180 discerning vineyards closer to the river using only water sources due to the
181 greater access to river water in these areas.

182 *3.2. Year*

183 The classification tree and XGBoosted ensemble performed similarly for
184 classifying year with 35.20% (6.28% standard deviation) and 51.81% (42.20%
185 validation accuracy) respectively. Electricity and the type of irrigation were
186 highly influential within the classification tree. Similarly, electricity was the
187 most frequently occurring node in the XGBoost ensemble. However, other
188 variables such as slashing passes, and fungicide and herbicide spraying were
189 more prevalent than in the classification tree. Weed and disease outbreaks
190 are likely an influential factor when classifying different years, making the
191 decisions to spray and slash unique factors that differ year to year. Climatic
192 differences between years are likely tied to the influence of yield and water
193 use.

194 Over half of the interrelated importance of the predictor variables is domi-
195 nated by area harvested, yield and slashing passes. Although all the predictor
196 variables are highly connected, their relative importance is not as prominent

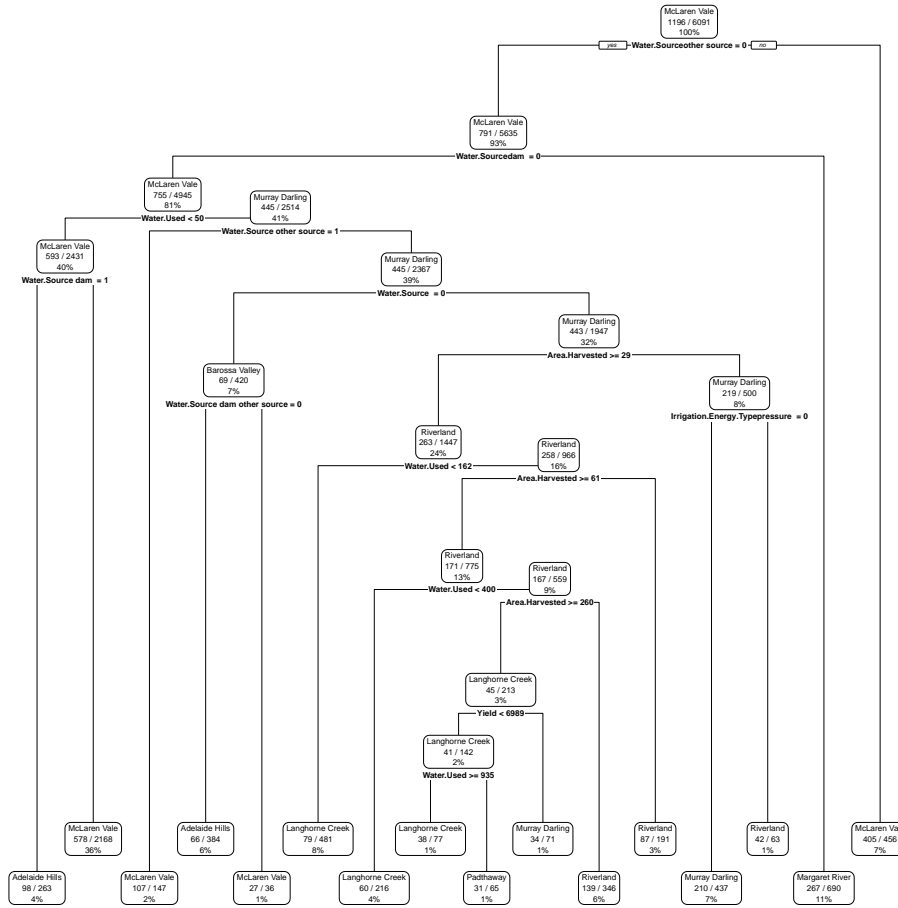


Figure 1: Decision tree predicting Region. Each node indicates the class predicted, and the proportion of elements agreeing with nodes partitioning, with the left direction indicating a yes to the nodes rule.

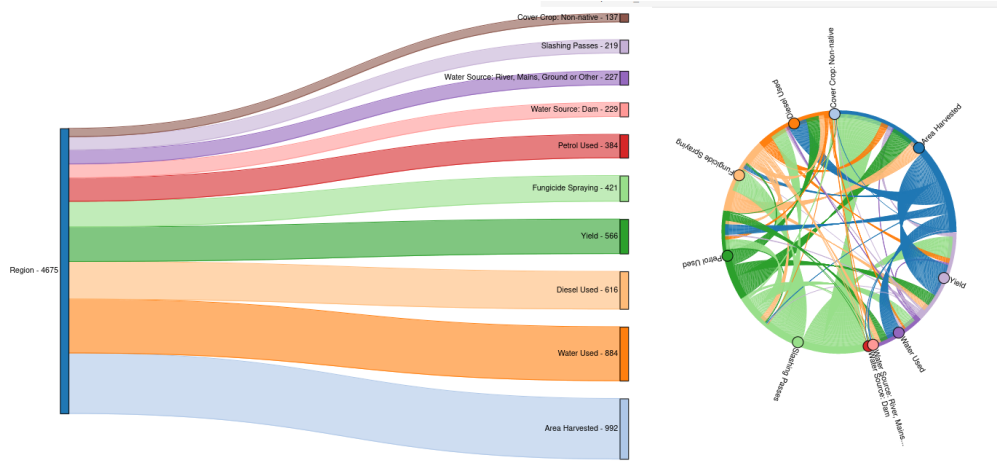


Figure 2: The left-hand side depicts the 10 most important variables in predicting Region using XGBoosted trees as a measure of node occurrence, using a Sankey diagram. The right-hand side depicts the interrelated importance of the ten predictor variables using a chord diagram.

as the three major variables. It is of particular note of the relative importance of slashing to area, fuel and yield; as these are not directly related activities. The connection between slashing and spraying is that those who do a set number of spraying or slashing passes tended to do that many passes for all slashing and spraying activities.

3.3. Operating Costs

There was a pronounced difference in accuracy between the regression tree and the XGBoost model when predicting Operating costs. With the regression tree achieving an R^2 of 0.0931 (with a standard deviation of 0.0197) in its cross validation. The XGBoosted regression ensemble achieved an R^2 of 0.8025 (with a standard deviation of 0.1033).

Within the XGBoost ensemble's nodes for operating costs (see figure 5)

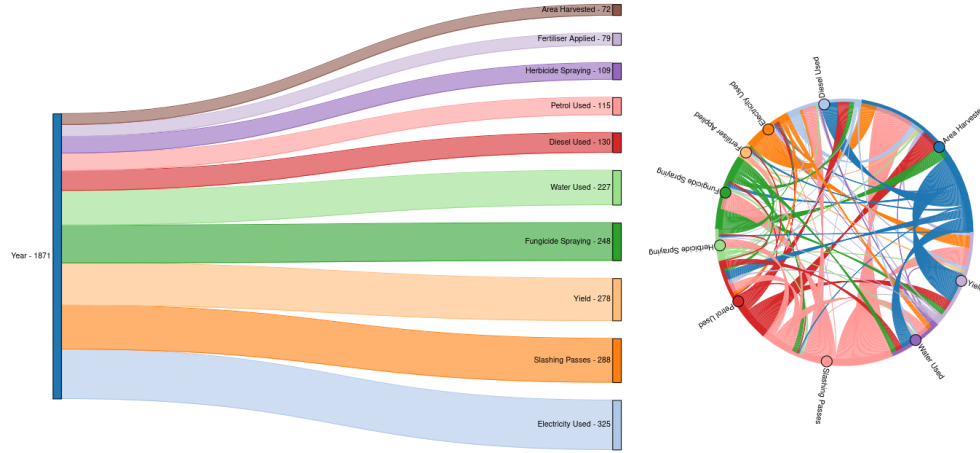


Figure 4: The left-hand side depicts the 10 most important variables in predicting Year using XGBoosted trees as a measure of node occurrence, using a Sankey diagram. The right-hand side depicts the interrelated importance of the ten predictor variables using a chord diagram.

209 fuel, water, area and yield occurred the most, similarly to region. Both
 210 diesel and petrol were of more relative importance (being ranked higher)
 211 in operating costs than water was compared with region. It is surprising
 212 that electricity, slashing and spraying was not more prominent in operating
 213 costs. However, Figure 4 shows that electricity, slashing and spraying are
 214 important variables in determining area and yield. Electricity in particular
 215 is used predominantly for irrigation and so is related largely to the size of a
 216 vineyard. However, slashing and spraying are measured in discrete tractor
 217 passes and show a surprising connection to the overall size of a vineyard,
 218 despite not being scaled to any measure of size. This would mean that,
 219 although measured as the same increment, a slashing or spraying pass in
 220 a larger vineyard would consume more fuel and wages than in a smaller

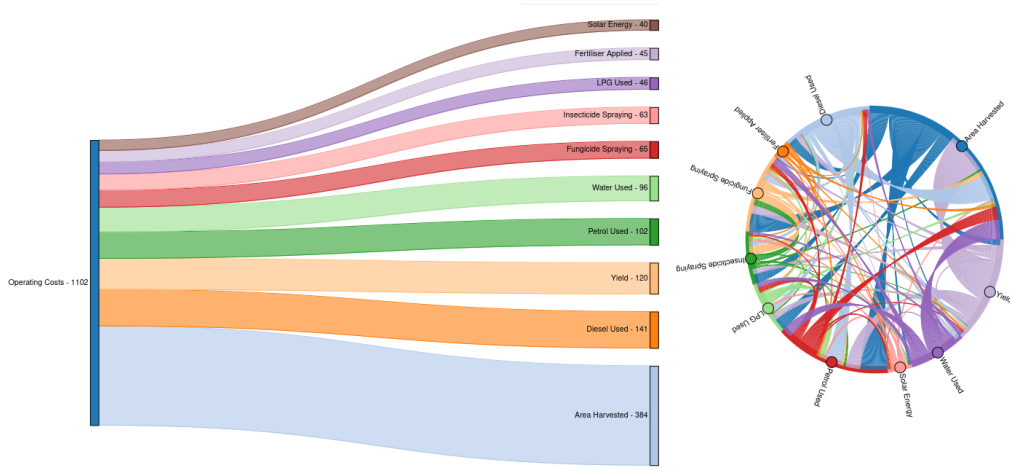


Figure 5: The left-hand side depicts the 10 most important variables in predicting Operating Costs using XGBoosted trees as a measure of node occurrence, using a Sankey diagram. The right-hand side depicts the interrelated importance of the ten predictor variables using a chord diagram.

vineyard.

3.4. Profit

Predictions of profit performed poorly compared to operating costs with the regression tree having an R^2 of 0.1873 (with a standard deviation of 0.0522) and the XGBoosted ensemble achieving an R^2 of 0.2535 (with a standard deviation of 0.3126). The high standard deviation in the XGBoosted tree was a bias in more accurately predicting vineyards that made profit compared to those that lost money. With much higher R^2 values being achieved in k-folds containing only those that made profits (recording a maximum of 0.7634).

There was a disparity of 66.63% of vineyards recording a profit than those that did not. When predicting if a vineyard would be profitable or not the

classification tree and XGBoosted ensemble did not perform considerably differently from this proportion. With the regression tree achieving an accuracy of 68.66% (and a standard deviation of 0.01%) and the XGBoost ensemble achieving 71.97% accuracy (with a validation accuracy of 70.59%).

It was surprising that operating costs performed substantially better in R^2 compared to profit. Interestingly the important variables when attempting to determine profit were similar to those used to classify region (see Figure 7), with the exception of water used. Both the regression tree and the XGBoosted ensemble used region, specifically the Hunter Valley. The regression tree also used Tasmania when determining profit. Both the Hunter valley and Tasmania are known for the production of high quality grapes used in export wines (Wine Australia, 2022). A major difference between region and profit was the importance given to water use, with water use being a more important variable in predicting region than profit.

4. Discussion

Several physical parameters such as climate, geology and soil are predetermined by a vineyard's location; making it a widely considered key determinant of grape yield and quality (Abbal et al., 2016; Agosta et al., 2012; Fraga et al., 2017). The association between yield and region is demonstrated by its position as fourth most occurring variable within the nodes of the XGBoosted ensemble which determined region (see Figure 2). The association with area and region is likely a connection to the change in land costs, with inland Australian areas (particularly of lower rainfall) being substantially cheaper to buy than coastal regions, allowing larger areas to be purchased

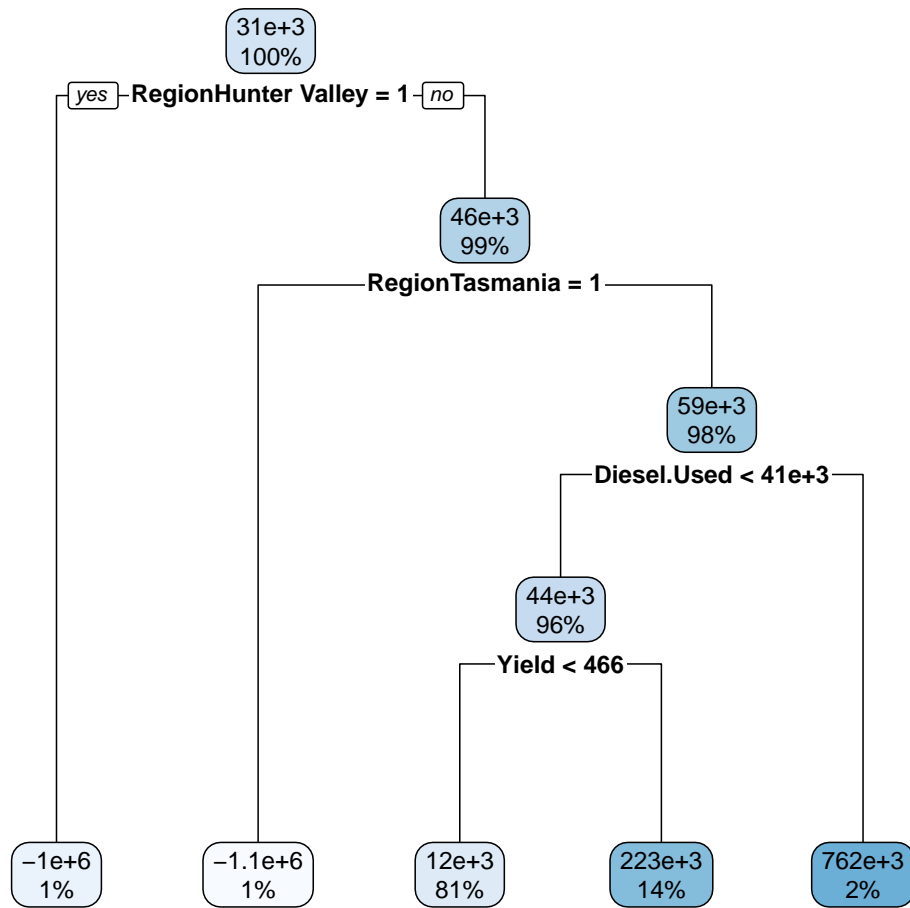


Figure 6: Decision tree predicting Profit. Each node indicates the class predicted, and the proportion of elements agreeing with nodes partitioning, with the left direction indicating a yes to the nodes rule.

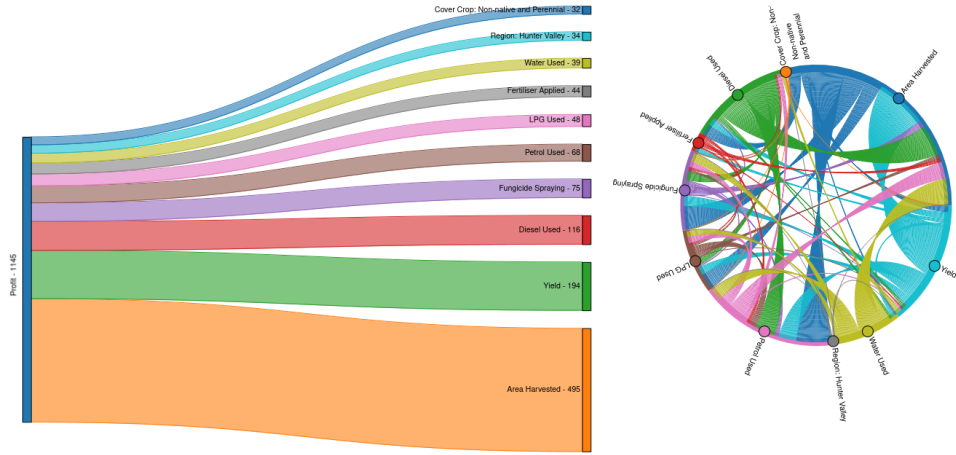


Figure 7: The left-hand side depicts the 10 most important variables in predicting Profit using XGBoosted trees as a measure of node occurrence, using a Sankey diagram. The right-hand side depicts the interrelated importance of the ten predictor variables using a chord diagram.

(Will Chancellor et al., 2019).

Regions with lower land costs are also warmer (Will Chancellor et al., 2019), which is known to be beneficial in hastening the ripening process of winegrapes (WEBB et al., 2011). Warmer regions are also associated with lower quality grapes, caused largely due to this hastened ripening (Botting et al., 1996). In general warmer regions have been associated with lower yields due to their generally lower rainfall, which can be mitigated through applying excess water (Camps and Ramos, 2012). It is likely that the combination of larger vineyards with higher water use is a determining factor in classifying regions which favour larger production of lower quality grapes; reflected through the variables' importance of water use in the XGBoost ensemble. The practice of utilising larger quantities of water for inland Australian wine

269 crops is partly reflected in the prior use of flood style irrigation to saturate
270 soil (BG Coombe and P Iland, 2004). This classification can be contrasted
271 with other warmer regions of higher rainfall that use the warmer climate
272 to concentrate their grapes, increasing the flavour profile (and thus quality)
273 (Goodwin I, Jerie P, 1992; MG McCarthy et al., 1986). This is possibly the
274 connection between the presence of the Hunter Valley within the XGBoost
275 ensemble that determined profit (see Figure 7). With this connection reflect-
276 ing the restriction of possible strategies employable by winegrowers between
277 different regions.

278 In part some winegrowing strategies are restricted simply through access
279 to water resources, being reflected through the region classification tree (see
280 Figure 1). Regions are likely to have varying access to different water sources,
281 such as those along the River Murray being able to utilise river water for
282 crops unlike most coastal regions. Similarly, the connection between region
283 and fuel use is likely an indicator of the level of infrastructure within the
284 region. Where, the need to pressurise irrigation systems from river water or
285 to generate power would require larger amounts of diesel and petrol.

286 Operational costs showed similar importance across fuel, water and trac-
287 tor use. The dominating factor of area likely played a large part in deter-
288 mining how costly a tractor pass would be, or in defining the ratio of water
289 applied to the amount of vines. The node frequency was high for area but
290 much lower in general across the other variables, which could indicate the
291 need to be more circumstantial in determining operational costs. Although
292 it was attempted to capture the complexity between how variables interacted
293 when determining operational costs (see Figure 5), it is likely yet more com-

294 plicated still. An example of how interrelated operational costs can be, is the
295 optimisation of tractor passes being shown to reduce energy use in vineyards,
296 decreasing running costs, as well as reducing soil compaction (Capello et al.,
297 2019).

298 Decisions made on the ground have far-reaching effects and are difficult
299 to completely capture. Greater tractor use as a preventative measure for
300 occurrences such as disease, may incur higher operational costs but could be
301 critical in preventing long term losses. With factors such as erosion and soil
302 health being difficult to capture but also influenced by tractor use (Capello
303 et al., 2019, 2020). Although, performing well in R^2 , the ability to predict
304 operational costs is limited by the variables incorporated. Reductions in fuel,
305 water and tractor use are obvious methods to reduce operational costs but
306 not necessarily achievable decisions. Without fully capturing more granular
307 activities such as the specifics of what fuel was used for, it is hard to determine
308 what decisions specifically influence the operational costs.

309 Although less important in the XGBoost ensembles for profit, the vari-
310 ables: cover crops, fungicide spraying and slashing are likely linked to broad
311 environmental properties of regions (see Figure 2 and 7). Rainfall being re-
312 lated to fungal growth and disease, as well as weeds. With cover crops being
313 an effective and sustainable method to alleviate these issues (Delpuech and
314 Metay, 2018). It is difficult to extrapolate findings to these methods and the
315 reason for their use due to the broad and varying definition of the regions.
316 Utilising the Geographical Indicator regions defined by Wine Australia (Aus-
317 tralia, 2021b) is a limitation, as it is too broad to fully capture a vineyards
318 location and its influence on more granular variables. The reasoning for us-

319 ing approaches such as cover crops can be widely varying. Where, a cover
320 crop may be employed to help increase soil water retention, reduce erosion,
321 increase biodiversity and reduce weeds (Capello et al., 2019, 2020; Delpuech
322 and Metay, 2018). However, cover crops can introduce competition with
323 grapevines and may reduce yield depending upon the plants used and the
324 density of the cover crop (Gosling and Shepherd, 2005; Monteiro and Lopes,
325 2007). A more granular definition of region may help to better discern the
326 differences in practices, and the reason for employing them. More sophisti-
327 cated models, specifically those that utilise expert opinion, may also help to
328 capture and address the decision making process. An example is the opti-
329 misation of fungicide sprays using Bayesian models that forecast disease risk
330 (Lu et al., 2020).

331 The disparity in accuracy between profit and operational costs is reflective
332 of the complexity in trying to address challenges such as climate change,
333 disease and changing market demands (Wine Australia, 2020, 2021, 2022).
334 The difference between turning a profit or loss is dependent on decisions
335 made and chance. The difference between vineyards that make profit and
336 those that do not could be a multitude of factors including differences in
337 farming practices not captured within this study. Some decisions leading to
338 latent effects such as large scale soil deposition in extreme rain events can
339 be caused by soil compaction due to overworking a vineyard (Capello et al.,
340 2020).

341 5. Conclusion

342 This study has provided valuable insights into the multifaceted dynam-
343 ics governing operational costs, different yearly effects and vineyard regions.
344 Highlighting the complex interrelatedness of variables within a vineyard. The
345 paper underscores how factors such as water and fuel use intersect to impact
346 operational costs. How different yearly events affect these operations and
347 the significance of context-specific decision-making. While this investigation
348 utilised a broad regional classification, the potential benefits of adopting a
349 more nuanced approach and incorporating expert knowledge have been high-
350 lighted. By delving deeper into the complex interplay of variables, further
351 advancements can be made in optimising vineyard management strategies
352 for lowering operational costs and enhancing sustainability.

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