

1 An analysis of underlying relationships between factors  
2 related to operating costs and revenue in Australian  
3 vineyards.

4 Author<sup>1,1,1</sup>

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## 5 1. Introduction

6 Historically strong demands for Australian wine have helped to create a  
7 thriving industry. However, recent pressures brought on by a loss of tourism  
8 and labour due to the COVID-19 pandemic, the global freight crisis, war in  
9 Europe, tariffs and rising inflation has negatively affected the industry's out-  
10 look (Wine Australia, 2021; Australia, 2021a). The 2021-2022 financial year  
11 alone saw a decline of 19% in exports solely due to tariffs (Wine Australia,  
12 2022). A greater understanding of the different underlying conditions leading  
13 to improved performance in agricultural productivity and sustainability at  
14 scale are key to making data-informed decisions to aid in increasing a nations  
15 agricultural sustainability (OECD, 2019). Specifically within the Australian  
16 Wine and vine industry there is a need to further understand the driving  
17 relationships between resource use and economic output, where these rela-  
18 tionships can lead to determining better and efficient methods and develop  
19 benchmarks with local growers (Luke Mancini, 2020).

20 An unprecedented amount of data regarding the Australian winegrowing  
21 industry has been collected through Sustainable Winegrowing Australia, of-  
22 fering new insights into the driving economic forces of the Australian wine

industry. This dataset allows insights into the economic outcome of vineyards through the incorporation of operating costs and grape revenue from grape sales within the data. We use this data to study these economic outcomes and their statistical relationships to vineyards’ utilisation of the resources. We further compare the relationships between different resources to address the extensive collinearity found within the data (Chen and Guestrin, 2016). We adopt XGBoosted models for this analysis because they are able to overcome multicollinearity as well as highlight the level of importance that predictor variables have on response variables.

## 2. Methods

### 2.1. Data

Data used in this analysis were obtained from Sustainable Winegrowing Australia. Australia’s national wine industry sustainability program. The program aims to support grape-growers and winemakers in demonstrating and improving their sustainability (SWA, 2022). Data recorded by SWA are entered manually by winegrowers using a web based interface tool. A total of 6049 observations were collected from 2012/2013 to 2021/2022 financial years, with each observation comprising 23 variables reflecting a vineyard’s state for the given year (see Table 2.1).

The data originally contained only two multiclass variables: year and region. Related binary variables, such as the use of river water and the use of dam water, were combined to create a single multiclass variable. This was done by first converting each combination that occurred into a unique category (such as river and dam water used, as opposed to the two separate

Table 1: Summary of variables used in the analysis. The recorded column indicate the number of values that were either greater than zero or that were not missing.

<b>Variable</b>	<b>Units</b>	<b>Recorded</b>	<b>Number of Classes</b>
Water Used	Mega Litres	5846	
Diesel	Litres	5585	
Biodiesel	Litres	25	
LPG	Litres	958	
Herbicide Spray	Times per year	2026	
Year	Class	6049	10
Disease	Class	6049	2
Region	Class	6049	58
Solar	Kilowatt Hours	622	
Irrigation Type	Class	6049	20
Petrol	Litres	4309	
Slashing	Times per year	2290	
Yield	Tonnes	5935	
Irrigation Energy	Class	6049	16
Area Harvested	Hectares	6049	
Electricity	Kilowatt Hours	1014	
Insecticide Spray	Times per year	1092	
Fertiliser	KGs of Nitrogen	795	
Fungicide Spray	Times per year	2260	
Cover Crop	Class	6049	32
Water Type	Class	6049	39
Grape Revenue	AUD	853	
Operating Costs	AUD	853	

categories prior). These variables were then one-hot-encoded, changing each variable class into a binary value, with one indicating the presence of the class and zero indicating its absence. Further details about classes and their frequency is available in the appendices.

The variable region represented one of the 65 Geographical Indicator Regions (GI Region) used to describe different unique localised traits of vineyards across Australia (Halliday, 2009; Oliver et al., 2013; SOAR et al., 2008). Each region is explicitly defined under the Wine Australia Corporation Act of 1980 (Attorney-General’s Department, 2010).

## 2.2. *XGBoosted Trees*

XGBoosted (eXtreme Gradient Boosting) trees, described in more detail below (and further in the appendix), were created using the XGBoost library (Chen and Guestrin, 2016) in the Python Programming language (G. van Rossum, 1995). XGBoosted trees are a boosted tree ensemble method that can be used to classify classes, or predict continuous response variables. They were chosen for this analysis as the data contained a mixture of class and continuous variables. Moreover, XGBoosted trees are unaffected by multicollinearity, and offer high predictive performance for a wide variety of purposes (Chen and Guestrin, 2016).

XGBoosted models were constructed with operational cost and grape revenue as the predicted variables. The analyses were aimed at uncovering what factors influenced these variables and to what extent. As the purpose of the analysis was to identify relationships between variables and to show how they interact, an XGBoosted tree was created for each of the predictor variables as well. Trees for the predictor variables did not include operational cost or

72 grape revenue as predictors. By creating an XGBoosted tree for each variable  
73 it meant that every variable would have a measure of its relative importance  
74 to every other variable (see Section 2.3). Together these models were used to  
75 measure the interrelationships of the ten most important variables in deter-  
76 mining operational cost and grape revenue using variable importance. These  
77 measures of relative importance were used to illustrate the highly interrelated  
78 nature of variables within vineyards. The interaction between variables was  
79 depicted through the use of Sankey and Chord diagrams; with variable im-  
80 portance measures being used to show the strength of connection between  
81 the respective predictor variable and the response (see section 2.3).

82 Due to constraints from the XGBoost library region could only be incor-  
83 porated as a one-hot-encoded variable when used as a predictor. To better  
84 show what variables were related to region overall, another XGBoost tree  
85 was created with Region as the predicted value. The difference for this model  
86 was that relative variable importance would only be measured for each re-  
87 gion specifically, as opposed to a variables overall importance in determining  
88 region. Separately profit (the difference between revenue and operational  
89 costs) and year was looked at in prior analyses (see appendix) but these  
90 results were not included due to low average loss values and model stability.

91 XGBoosted trees are an ensemble method that combines multiple decision  
92 trees together to create a more accurate predictive model. The gradient  
93 boosting aspect of the ensemble is the use of a loss function used to create  
94 new decision trees that add to the ensemble. Each new tree created is done so  
95 using a loss function that is optimised iteratively to improve upon prior tree's  
96 predictive power. The loss function can be any convex function, allowing

97 gradient descent to traverse the loss space until, no improvements can be  
98 made via traversal. Because the loss function is only required to be convex,  
99 both classifiers and regressors can be used. Regularisation methods can also  
100 be incorporated to help prevent over fitting.

### 101 2.3. Variable Importance

102 Due to XGBoost creating a large amount of decision trees, the inter-  
103 pretability of these models is obfuscated by the intricate relationships within  
104 complicated ensembles. A measure of variable importance was the technique  
105 used to highlight a variables influence within the ensemble. Variable impor-  
106 tance can be measured in multiple ways; we used the frequency of a variable  
107 appearing as a node within the ensemble as a measure of its importance.  
108 This measure was chosen as it connected a variable to the minimisation of  
109 its associated objective function. The measure of a variable’s importance  
110 within this study can then be interpreted as how often a variable was the  
111 optimal choice in reducing the loss function of the ensemble. Importantly,  
112 multiclass variables being one-hot-encoded (see Section 2.1) are given an im-  
113 portance score for each individual class; for example, each specific region will  
114 have its own importance score.

115 The Sankey and Chord diagrams were constructed using the Holoviews  
116 python library (Rudiger et al., 2020). Both Chord and Sankey diagrams  
117 illustrated variable importance through the size of the bands between two  
118 variables. The number at the end of a connection in a Sankey diagram indi-  
119 cates a variable’s importance, or the number of times it appeared within the  
120 ensemble. Sankey and Chord diagrams are presented together; with Sankey  
121 diagrams showing the connection of a variable to its ten most important pre-

dictor variables. Chord diagrams were used alongside a Sankey diagram to show the interconnectedness of the ten most prominent variables within its associated Sankey diagram. Chord diagrams formed circles, with variables being connected through their relative importance. The importance values for the Chord diagrams were taken from the models of those individual variables, with the diagram being simplified to just the ten variables in the associated Sankey diagram, for readability's sake.

#### 2.4. Validation

The predictive accuracy of each tree was assessed through a validation process. For each model the data was split into training data, which constituted 80% of the original data. The remaining 20% was used in testing and validation. Categorical data was stratified to conserve the same proportion of class occurrences between training, testing and validation data. For continuous variables 20% was used as testing data and the models were validated using 10 repetitions of the sampling process (10-fold cross validation).  $R^2$  scores were used to determine the best regression models during validation.  $R^2$  was used instead of RMSE to allow the comparison of models with different units to each other when considering how well each model extrapolated to further data. For binary and multiclass variables, validation was summarised through the accuracy, the proportion of true negatives and positives.

The XGBoost library incorporates regularisation techniques built into the software to mitigate over-fitting and enhance model generalisation. This allowed us to utilise cross validated grid search functions when selecting for better performing hyperparameters. The performance measure for model

147 selection was root-mean-square error for continuous variables. The receiver  
148 operator characteristic’s area under the curve was used for category variables  
149 (Hanley and McNeil, 1982). Multiclass variables utilised the one verse one  
150 approach to minimise sensitivity to class disparity (Ferri et al., 2009; Hand  
151 and Till, 2001).

### 152 **3. Results**

#### 153 *3.1. Revenue*

154 The prediction of revenue performed similarly to operating cost achieving  
155 an  $R^2$  of 0.7716 (with a standard deviation of 0.1525). The value of predic-  
156 tors’ relative importance was then calculated through the number of nodes  
157 used within the XGBoost. Values for relative importance were then used to  
158 construct Sankey and Chord diagrams to compare the contribution of each  
159 variable to predicting revenue.

160 In order of importance, predictors of revenue were fuel use(petrol 307 and  
161 diesel 144), yield (285), size (216) and water use (199). Here, the values in the  
162 brackets indicate the relative importance of each variable (see C.10). Overall  
163 regions contributed to 234 nodes in the ensemble making them collectively the  
164 third most important variable. The chord diagram illustrates that vineyard  
165 area is also of high relative importance to other variables especially slashing.  
166 The overall importance of area to other variables is evident by its larger  
167 circumference within the chord diagram (see B in Figure C.10).

#### 168 *3.2. Operating Costs*

169 Comparatively to revenue, operating cost performed better with the XG-  
170 Boosted regression ensemble achieving an  $R^2$  of 0.8025 (with a standard



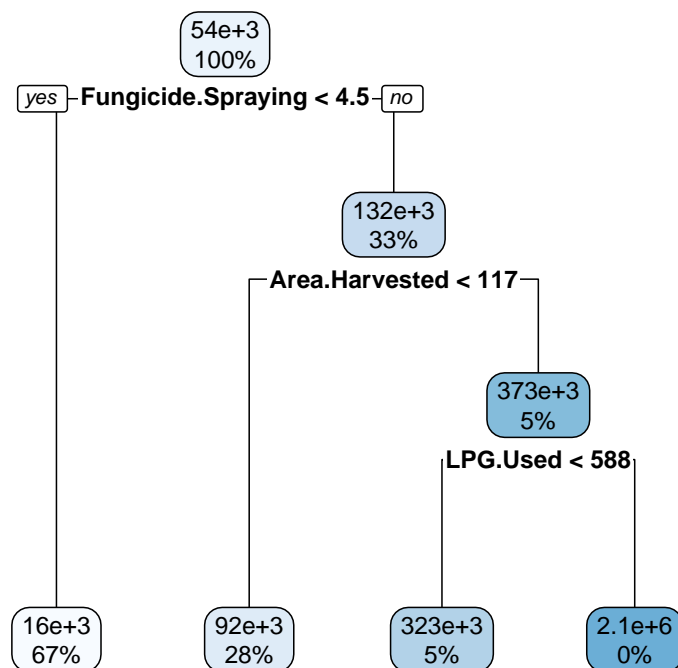


Figure 1: Decision tree predicting revenue. Each node indicates the class predicted, and the proportion of elements agreeing with nodes partitioning, with the left direction indicating a yes to the nodes rule.

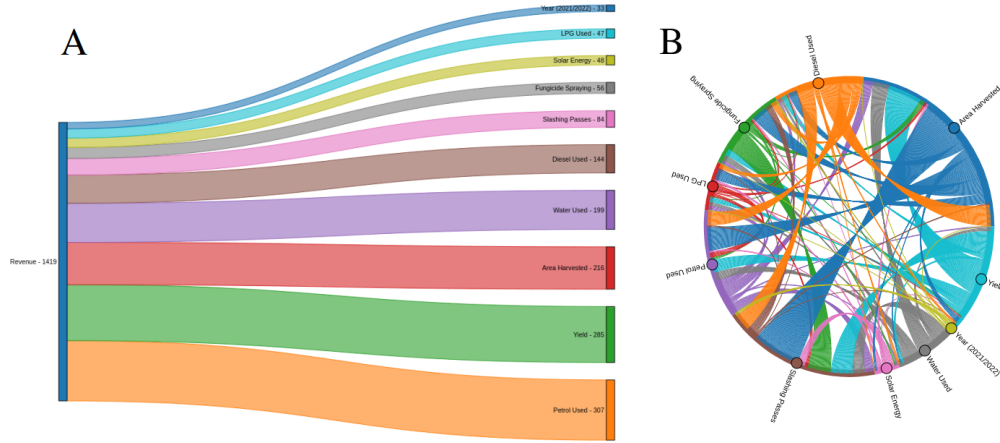


Figure 2: The left-hand side depicts the 10 most important variables in predicting revenue using XGBoosted trees as a measure of node occurrence, using a Sankey diagram. The right-hand side depicts the interrelated importance of the ten predictor variables using a chord diagram.

deviation of 0.1033). The relationships to operating cost through variable importance were found to be similar to that of revenue, with fuel, water, area and yield having the largest number relative importance (see figure 4). A surprising difference is that the most important operational consideration for operating cost is the use of fungicide, compared to revenue where slashing is the most important (comparing Figure 6). The variables that feed into these decisions are also very different with diesel having the highest relative importance to slashing, and area having the greatest relative importance to the need for fungicide.

Again, region played a determining factor overall, contributing to 334 nodes within the ensemble making it the most important variable when considering all regions together. It was surprising that electricity, slashing and

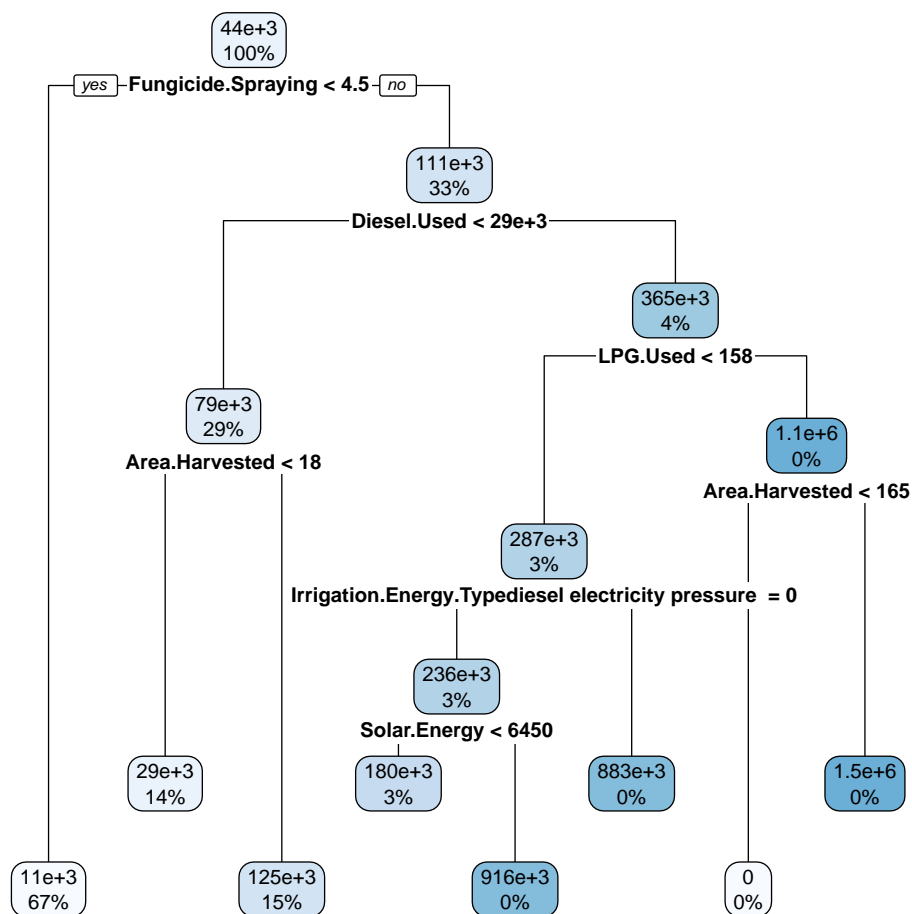


Figure 3: A surrogate model decision tree predicting operating costs. Each node indicates the class predicted, and the proportion of elements agreeing with nodes partitioning, with the left direction indicating a yes to the nodes rule.

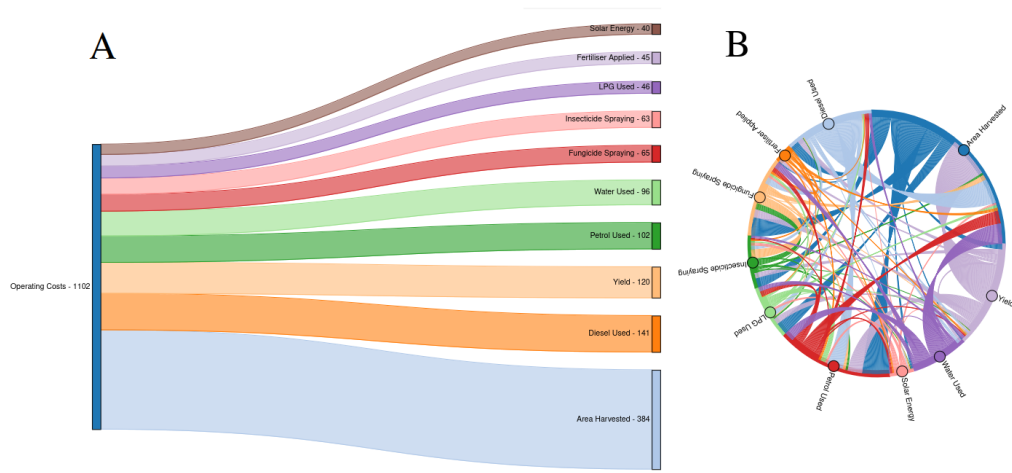


Figure 4: The left-hand side, A, depicts the 10 most important variables in predicting Operating Costs using XGBoosted trees as a measure of node occurrence, using a Sankey diagram. The number at the end of each band in the diagram is that variable's importance. The right-hand side, B, depicts the importance of the 10 variables in Sankey diagram relative to one another.

183 spraying passes were not more prominent in operating costs due to the in-  
184 trinsic nature as an agricultural expense.

### 185 *3.3. Region*

186 When considered overall, Region was a highly informative variable based  
187 on measures of importance for both operating cost and revenue. As noted  
188 above, Region was the third most important variable for determining rev-  
189 enue. The Barossa Valley region and Tasmania were the two most important  
190 regions in relation to revenue; these two regions are considered to be some of  
191 the highest revenue per hectare regions in Australia (Wine Australia, 2022).  
192 These two regions are also relative opposites in winegrowing climates with  
193 the Barossa having a warm and dry climate focussing on Shiraz grapes and  
194 Tasmania having a cool wet climate that favours Pinot.

195 As also noted above Region was also a key determinant of operating costs.  
196 Again Tasmania was the most important, followed by the Adelaide Hills. In  
197 contrast to revenue, both climates are considered cool and wet, and warmer  
198 drier regions such as the Barossa and Hunter Valley only contributed roughly  
199 half the same number of nodes to the ensemble. Based on further analysis  
200 of Regions (Figure 6) the inclusion of slashing and fungicide spraying is the  
201 likely reason with fungal and weed pressure being greater in cooler wetter  
202 regions.

203 The XGBoost ensemble, did not perform well when predicting operating  
204 costs or revenue with 56.82% accuracy (50.58% validation accuracy). The  
205 difference in accuracy is in part due to the large number of classes (58 re-  
206 gions). The ensemble had a great emphasis on area, water, fuel and yield as  
207 determining factors (see Figure (6)).

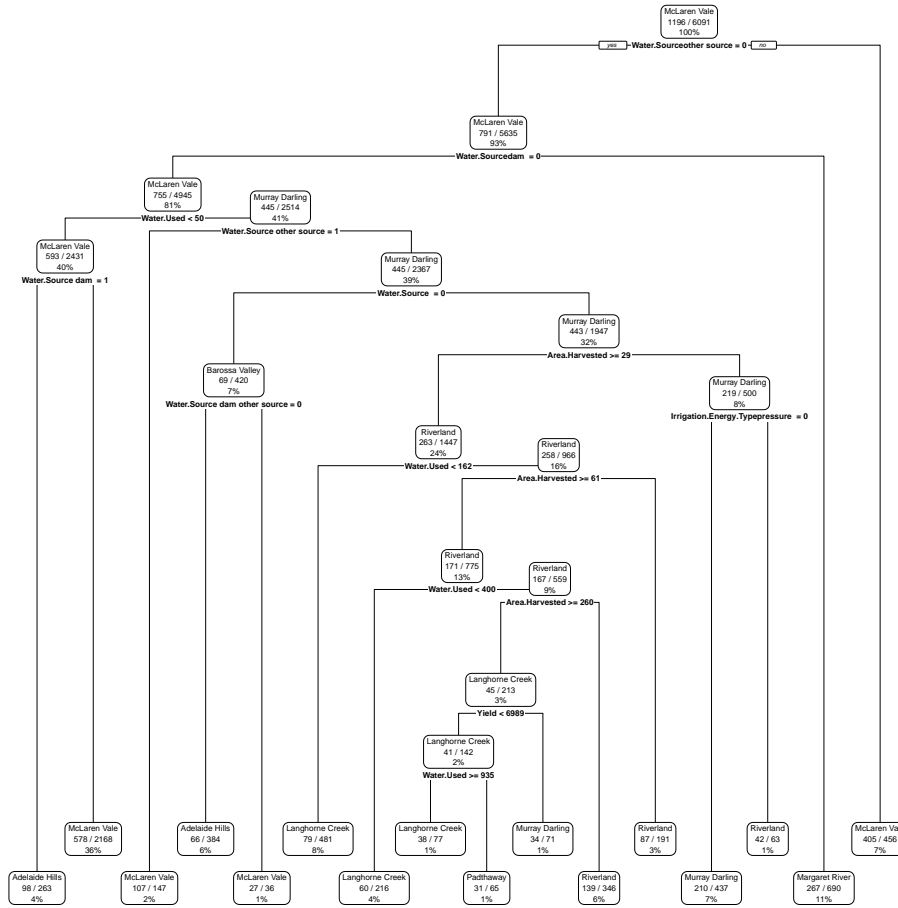


Figure 5: Decision tree predicting Region. Each node indicates the class predicted, and the proportion of elements agreeing with nodes partitioning, with the left direction indicating a yes to the nodes rule.

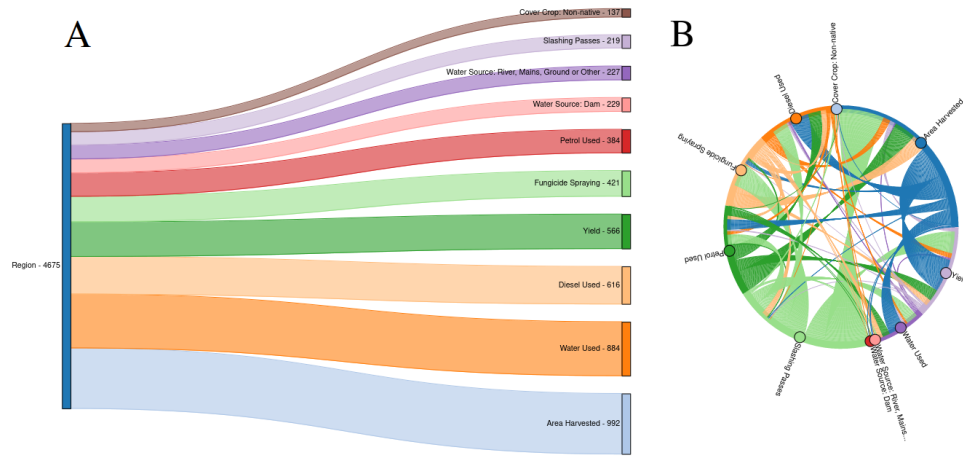


Figure 6: The left-hand side, A, depicts the 10 most important variables in predicting Region using XGBoosted trees as a measure of node occurrence, using a Sankey diagram. The number at the end of each band in the diagram is that variable's importance. The right-hand side, B, depicts the importance of the 10 variables in Sankey diagram relative to one another.

208 Many of the regions had significantly lower reporting rates, resulting in  
209 much poorer classification performance. The regions with the most samples  
210 performed the best. Bordering regions were routinely grouped together and  
211 misclassified as the same region. Two areas that suffered the most from this  
212 were the Limestone Coast (cool coastal areas in South Australia) and the  
213 warmer inland regions along the Murray Darling.

#### 214 **4. Discussion**

215 This study has explored the relationships between vineyard resource use,  
216 operations and geographical properties to revenue and operating costs  
217 geographical regions with respect to a vineyards revenue and operating  
218 costs. The analysis was based on a large national study of XXX

219 Three main findings were identified. First, the most important predicted  
220 of revenue were XXX

221 With YYY showing the relationships among the corresponding set of  
222 predictor variables

223 Second XXX for operating cost

224 Third for regions...

225 highlight how decisive regional influences can be determining a vineyard's  
226 economic outcomes.

227 Several physical parameters such as climate, geography and soil are pre-  
228 determined by a vineyard's location; making it a widely considered key de-  
229 terminant of grape yield and quality (Abbal et al., 2016; Agosta et al., 2012;  
230 Fraga et al., 2017). The association between yield and region is demonstrated  
231 by its rank of fourth-highest variable importance when determining region



232 (see Figure 6).

233 Warmer regions are known to be beneficial in hastening the ripening pro-  
234 cess of winegrapes (Webb et al., 2011). Warmer regions are also associated  
235 with lower quality grapes, caused largely due to this hastened ripening (Bot-  
236 ting et al., 1996). In general warmer regions are not associated with higher  
237 yields, but if a vineyard in a warmer region is sufficiently irrigated much  
238 higher yields can be achieved than in cooler regions (Camps and Ramos,  
239 2012). It is likely that the combination of larger vineyards with higher water  
240 use is a determining factor in classifying regions which favour larger produc-  
241 tion of grapes; reflected through region using water use so prominently in the  
242 XGBoost ensemble. The link to water resources in defining regions is also  
243 an important consideration, as vineyards can leverage higher irrigation rates  
244 given more accessible water resources. A further consideration in the link  
245 between revenue and region is that grape prices are set at a regional level by  
246 buyers (Wine Australia, 2022). It is also important to consider that some  
247 regions carry particular fame regarding the quality of their produce such as  
248 Tasmania, the Hunter Valley and Barossa Valley (Halliday, 2009). This clas-  
249 sification can be contrasted with other warmer regions of higher rainfall that  
250 use the warmer climate to concentrate their grapes, increasing the flavour  
251 profile (and thus quality) (Goodwin I, Jerie P, 1992; MG McCarthy et al.,  
252 1986).

253 In part some winegrowing strategies are restricted simply through access  
254 to water resources, being reflected through the region classification tree (see  
255 Figure 5). Regions are likely to have varying access to different water sources,  
256 such as those along the River Murray being able to utilise river water for

257 crops, unlike most coastal regions which may be drawing from surface or  
258 underground water sources. Similarly, the connection between region and  
259 fuel use is likely an indicator of the level of infrastructure within the region  
260 because vineyards in regions without pressurised water will need to use more  
261 fuel to pressurise their irrigation systems.

262 Operational costs showed similar importance across fuel, water and trac-  
263 tor use. The dominating factor of area likely played a large part in deter-  
264 mining how costly a tractor pass would be, or in defining the ratio of water  
265 applied to the amount of vines. The node frequency was high for area but  
266 much lower in general across the other variables, which could indicate the  
267 need to be specific when attempting to determine the cause of a operational  
268 cost. Although it was attempted to capture the complexity between how  
269 variables interacted when determining operational costs (see Figure 4), it  
270 is likely yet more complicated. An example of how interrelated operational  
271 costs can be, is the optimisation of tractor passes to achieve multiple goals  
272 in a pass, being shown to reduce energy use in vineyards, decreasing running  
273 costs, as well as reducing soil compaction (Capello et al., 2019).

274 When determining revenue, similar variables were used to operational  
275 cost; with region also being of high variable importance relative to other  
276 variables (when considering all regions together in importance). It is difficult  
277 to extrapolate the specific influence of location on a vineyard’s outcomes due  
278 to the broad and varying definition of a region. Utilising the Geographical  
279 Indicator regions defined by Wine Australia (Australia, 2021b) is a limitation  
280 in one way, as it is too broad to fully capture a vineyards location and how  
281 that influences variables at a more granular level. However, as buyers set

282 prices at regional levels, it is still important to consider this factor.

283       Decisions made on the ground have far-reaching effects and are difficult  
284 to completely capture. A larger number of tractor passes used as a preven-  
285 tative measure for occurrences such as disease may incur higher operational  
286 costs but could be critical in preventing long term losses. Although the  
287 models demonstrated a good predictive fit (via large  $R^2$  values), the ability  
288 to predict operational costs is limited by the variables incorporated in the  
289 analysis. Other factors such as erosion and soil health are also influenced by  
290 tractor use and would contribute to these operational costs but are difficult  
291 to measure and were not available as part of the data (Capello et al., 2019,  
292 2020). Reductions in fuel, water and tractor use are obvious methods to  
293 reduce operational costs but not necessarily achievable decisions. Without  
294 fully capturing more granular activities for example the specific reasons for  
295 fuel use, it is difficult to determine what decisions specifically influence the  
296 operational costs.

297       The reasoning for any particular decision can be widely varying. More  
298 sophisticated models, specifically those that utilise expert opinion, may also  
299 help to capture and address the decision-making process. An example is the  
300 optimisation of fungicide sprays using Bayesian models that forecast disease  
301 risk (Lu et al., 2020).

302       Separately revenue and operating cost did have a greater predictabil-  
303 ity than their counterpart profit. The disparity in accuracy between profit  
304 and other economic outcomes is reflective of the complexity in trying to  
305 address challenges such as climate change, disease and changing market de-  
306 mands (Wine Australia, 2020, 2021, 2022). The difference between turning a

profit or loss is dependent on predictable factors unforecasted factors, farming practice and farmers' decisions. The difference between vineyards that make profit and those that do not could be a multitude of factors including differences in farming practices not captured within this study. Some decisions leading to latent effects such as large scale soil deposition in extreme rain events can be caused by soil compaction due to overworking a vineyard (Capello et al., 2020).

## 5. Conclusion

This study has provided valuable insights into the multifaceted dynamics governing operational costs and revenue. The impact of different regions highlighted the complex interrelatedness of variables within a vineyard. We relate how factors such as water and fuel intersect to impact operational costs and how different seasonal events affect these operations; as well as the significance of context-specific decision-making. While this investigation utilised a broad regional classification, the potential benefits of adopting a more nuanced approach and incorporating expert knowledge have been highlighted. Further work could pursue causal models and the creation of decision support systems. It is difficult to untangle the predictive and correlative nature of a variable compared to the causal reasons. By delving deeper into the complex interplay of variables, further advancements can be made in optimising vineyard management strategies for lowering operational costs, increasing revenue and enhancing sustainability.

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## 413 **Appendix A. Continuous variables**

414 The Table below shows the ranges of each of the continuous variables:



	count	mean	std	min	0.25	0.5	0.75
Vineyard Solar	622	22916.89	104808	1	1170.75	5500	14860
Biodiesel	25	6635.932	11768.832104	1	200	500	10000
Fungicide Spray	2260	7.724801	3.279794	1	6	7	9
LPG	958	327.831399	861.538804	1	40	95.835	240
Petrol	4309	825.276809	1556.621119	1	135	306.66	903
Insecticide Spray	1092	1.707189	1.316042	0	1	1	2
Water Used	5846	7301838	558206600	0.0007	13.2655	43	146.8
Fertiliser	795	91149.89	483913.4	1	560	4759.5	45148
Diesel	5585	11677.070183	24380.588742	0.1267	1240	3850	12500
Yield	5935	772.902449	2175.113895	0.03	68	192.3	601.8
Herbicide Spray	2026	2.646199	2.598899	0	2	2	3
Slashing	2290	3.311485	1.826788	1	2	3	4
Electricity	1014	58223.07	177626.3	0.019	2160	9637	36498
Area Harvested	6049	66.52604	133.4525	2.220446E-16	10.13	24.5	66.8
Grape Revenue	875	377972	606286.8	1	76000	172964	38674
Operating Costs	853	314187.1	511522.6	1	57315	140000	32740

## 415 **Appendix B. Categorical variables**

416     ?? The tables below describe each possible class a multiclass variable  
417 could have taken and the frequency that it occurred.

418 *Appendix B.1. water types*

419 *Appendix B.2. cover crop types*

420 *Appendix B.3. irrigation type*

421 *Appendix B.4. irrigation energy type*

422 *Appendix B.5. year*

423 *Appendix B.6. giregion*

## 424 **Appendix C. XGBoost**

425     Following Chen and Guestrin (Chen and Guestrin, 2016), XGboosted  
426 trees predict a value  $y_i$  from the input  $x_i$ . The method of prediction is  
427 achieved through a tree ensemble model, using  $K$  additive functions to pre-  
428 dict the output. Each of  $f_k$  functions is a classification or regression tree, such  
429 that all functions are in the set of all decision trees, given by  $\mathcal{F}$ , is defined  
430 by  $f(x) = \omega_{q(x)}(q : \mathbb{R}^m \rightarrow T, \omega \in \mathbb{R}^T)$ . Where each function corresponds to  
431 an independent tree structure  $q$  of  $\omega$  weights. Each tree has  $T$  leaves, which  
432 contain a continuous score, represented by  $\omega_i$  for the  $i$ -th leaf. The final  
433 prediction is determined by the sum of the score of the corresponding leaves,  
434 given by:

$$\hat{y}_i = \phi(x_i) = \sum_{k=1}^K f_k(x_i), f_k \in \mathcal{F}, \quad (\text{C.1})$$

435     The set of functions,  $\mathcal{F}$ , used by the tree is determined by minimising a  
436 regularised objective function,  $\mathcal{L}$  given by:

---

water types

---

river water

groundwater

surface water dam

recycled water from other source

groundwater and surface water dam

not listed

mains water

river water and groundwater

groundwater and recycled water from other source

other water

river water and surface water dam

groundwater and water applied for frost control

groundwater and mains water

river water and groundwater and surface water dam

recycled water from other source and mains water

groundwater and recycled water from other source and mains water

river water and mains water

surface water dam and mains water

groundwater and other water

river water and groundwater and mains water

groundwater and surface water dam and recycled water from other source

river water and water applied for frost control

groundwater and surface water dam and mains water

surface water dam and recycled water from other source

river water and recycled water from other source

river water and other water

river water and surface water dam and mains water

river water and groundwater and surface water dam and mains water

mains water and other water

---

## Cover crop types

---

permanent cover crop volunteer sward

permanent cover crop non native

permanent cover crop native

annual cover crop

groundwater and surface water dam

annual cover crop and permanent cover crop volunteer sward

bare soil

permanent cover crop non native and permanent cover crop volunteer sward

annual cover crop and permanent cover crop non native

bare soil and permanent cover crop volunteer sward

bare soil and permanent cover crop non native

annual cover crop and permanent cover crop non native and permanent cover crop volunteer sward

bare soil and annual cover crop

permanent cover crop native and permanent cover crop volunteer sward

bare soil and permanent cover crop native

annual cover crop and permanent cover crop native

permanent cover crop native and permanent cover crop non native

permanent cover crop native and permanent cover crop non native and permanent cover crop volunteer sward

annual cover crop and permanent cover crop native and permanent cover crop non native and permanent cover crop volunteer sward

bare soil and annual cover crop and permanent cover crop volunteer sward

bare soil and permanent cover crop non native and permanent cover crop volunteer sward

annual cover crop and permanent cover crop native and permanent cover crop volunteer sward

bare soil and annual cover crop and permanent cover crop native

annual cover crop and permanent cover crop native and permanent cover crop non native

bare soil and annual cover crop and permanent cover crop non native

bare soil and annual cover crop and permanent cover crop native and permanent cover crop non native

bare soil and annual cover crop and permanent cover crop non native and permanent cover crop volunteer sward

bare soil and annual cover crop and permanent cover crop native and permanent cover crop non native

bare soil and permanent cover crop native and permanent cover crop non native

Irrigation type	frequency
dripper	4800
dripper and non irrigated	342
Not listed	319
dripper and overhead sprinkler	201
dripper and undervine sprinkler	91
non irrigated	65
undervine sprinkler	53
dripper and flood	53
overhead sprinkler	46
dripper and overhead sprinkler and undervine sprinkler	28
overhead sprinkler and undervine sprinkler	12
dripper and non irrigated and overhead sprinkler	11
flood and undervine sprinkler	10
dripper and flood and undervine sprinkler	7
dripper and flood and non irrigated and overhead sprinkler and undervine sprinkler	3
dripper and flood and overhead sprinkler	3
non irrigated and undervine sprinkler	2
dripper and flood and non irrigated	1
dripper and non irrigated and overhead sprinkler and undervine sprinkler	1
flood and	1

Irrigation energy type	frequency
electricity	2162
not listed	2053
pressure	586
electricity and pressure	396
diesel	254
diesel and electricity	227
electricity and solar	96
diesel and electricity and pressure	90
diesel and pressure	74
solar	50
electricity and pressure and solar	23
diesel and electricity and solar	14
diesel and electricity and pressure and solar	10
pressure and solar	9
diesel and solar	4
diesel and pressure and solar and	1

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data year id	frequency
2021/2022	954
2020/2021	860
2019/2020	599
2012/2013	590
2013/2014	549
2015/2016	548
2014/2015	505
2017/2018	493
2016/2017	485
2018/2019	466

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$$\mathcal{L}(\phi) = \sum_i l(\hat{y}_i, y_i^{t-1} + f_t(x_i)) + \sum_k \Omega(f_K). \quad (\text{C.2})$$

437 , where

$$\Omega(f) = \gamma T + \frac{1}{2} \lambda ||\omega||^2 \quad (\text{C.3})$$

438 As predictions are made using additive tree functions, XGboosted trees  
439 can be used for classification or regression. The difference between a predic-  
440 tion,  $\phi(x_i)$ , and actual variable,  $f_k(x_i)$ , is a differentiable convex loss function  
441  $l$ . These properties of  $l$  allow the function to be versatile in which objective  
442 we choose to optimise for, which is also important in being able to process  
443 both continuous and categorical variables. To optimise  $l$ , the difference is  
444 calculated for the i-th instance at the t-th iteration.

giregion	frequency	
McLaren Vale	1195	
Barossa Valley	584	
Murray Darling	521	
Riverland	472	
Adelaide Hills	454	
Langhorne Creek	347	
Margaret River	344	
Coonawarra	284	
Padthaway	202	
Wrattonbully	195	
Clare Valley	149	
Yarra Valley	122	
Eden Valley	92	
Tasmania	89	
Swan Hill	83	
Grampians	73	
Orange	72	
Hunter Valley	70	
Bendigo	53	
Great Southern	51	
Rutherglen	41	
Robe	36	
Tumbarumba	35	
Mornington Peninsula	32	
King Valley	32	32
Southern Fleurieu	30	
Heathcote	29	
Adelaide Plains	25	
Currency Creek	24	



## 445 *Appendix C.1. Loss functions*

446 The functions included as parameters in equation C.2 mean that tradi-  
 447 tional optimisation methods for Euclidean space cannot be used. Chen and  
 448 Guestrin (Chen and Guestrin, 2016) illustrate, using Taylor expansions, that  
 449 for a fixed structure  $q(x)$  the optimal weight  $\omega_j^*$  for a leaf  $j$  can be derived.  
 450 Importantly a loss function can be used to fit a model iteratively to data.  
 451 For this analysis several loss functions were used, as variables took the form  
 452 of continuous, binary and multi-class data. The loss function for making a  
 453 split within the tree structure is given by:

$$\mathcal{L}_{split} = \frac{1}{2} \left[ \frac{(\sum_{i \in I_L} g_i)^2}{\sum_{i \in I_L} h_i + \lambda} + \frac{(\sum_{i \in I_R} g_i)^2}{\sum_{i \in I_R} h_i + \lambda} - \frac{(\sum_{i \in I} g_i)^2}{\sum_{i \in I} h_i + \lambda} \right] - \gamma. \quad (\text{C.4})$$

454 The tree structure being defined using left  $I_L$  and right  $I_R$  instance sets of  
 455 nodes, with  $I = I_L \cup I_R$ . Instead of enumerating all possible tree structures,  
 456 a greedy algorithm iteratively adds branches to the tree minimising  $\mathcal{L}_{split}$   
 457 in (C.4). The frequency of a variable's occurrence within a tree is directly  
 458 attributed to the minimisation of the loss function through the minimisation  
 459 of  $\mathcal{L}_{split}$ .

460 The loss functions used for this analysis were the root-mean-square func-  
 461 tion for continuous variables, the logistic loss function for binary class vari-  
 462 ables, and the soft max function for Multiclass variables. All objective func-  
 463 tions are defined within the SKlearn library (Buitinck et al., 2013), which  
 464 was utilised via an API to the XGBoost library (Chen and Guestrin, 2016).

## 465 *Appendix C.2. Year*

466 The classification tree and XGBoosted ensemble performed similarly for  
467 classifying year with 35.20% (6.28% standard deviation) and 51.81% (42.20%  
468 validation accuracy) respectively. Electricity and the type of irrigation were  
469 highly influential within the classification tree. Similarly, electricity was the  
470 most frequently occurring node in the XGBoost ensemble. Other variables  
471 such as slashing passes, and fungicide and herbicide spraying were more  
472 prevalent than in the classification tree. Weed and disease outbreaks are  
473 likely an influential factor when classifying different years, making the de-  
474 cisions to spray and slash unique factors that differ year to year. Climatic  
475 differences between years are likely tied to the influence of yield and water  
476 use.

477 Over half of the interrelated importance of the predictor variables is domi-  
478 nated by area harvested, yield and slashing passes. Although all the predictor  
479 variables are highly connected, their relative importance is not as prominent  
480 as the three major variables. It is of particular note of the relative importance  
481 of slashing passes to area, fuel and yield; as these are not directly related ac-  
482 tivities. The connection between the number of slashing and spraying passes  
483 is that those who do a set number of spraying or slashing passes tended to  
484 do that many passes for all slashing and spraying activities.

## 485 *Appendix C.3. Profit*

486 Predictions of profit performed poorly compared to operating cost and  
487 revenue with an average  $R^2$  of 0.2535 and standard deviation of 0.3126. With  
488 the large standard deviation being indicative of how unstable the models  
489 created were.



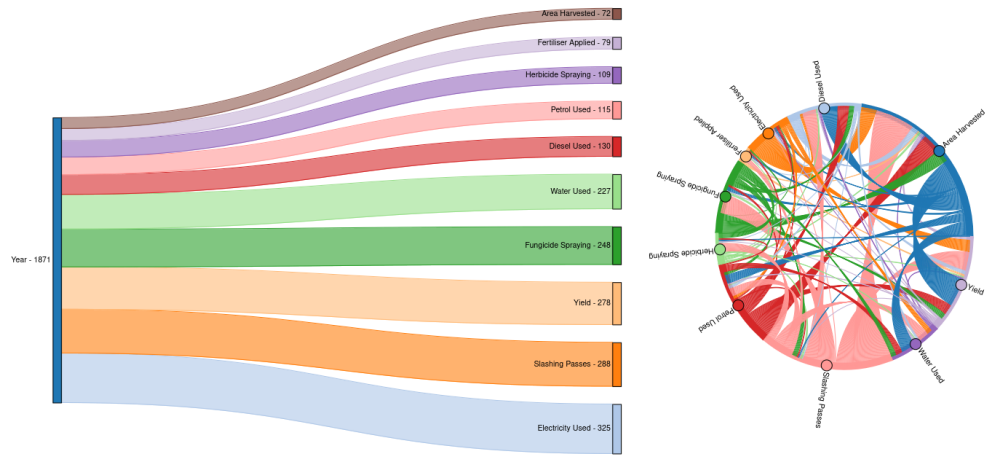


Figure C.8: The left-hand side depicts the 10 most important variables in predicting Year using XGBoosted trees as a measure of node occurrence, using a Sankey diagram. The right-hand side depicts the interrelated importance of the ten predictor variables using a chord diagram.

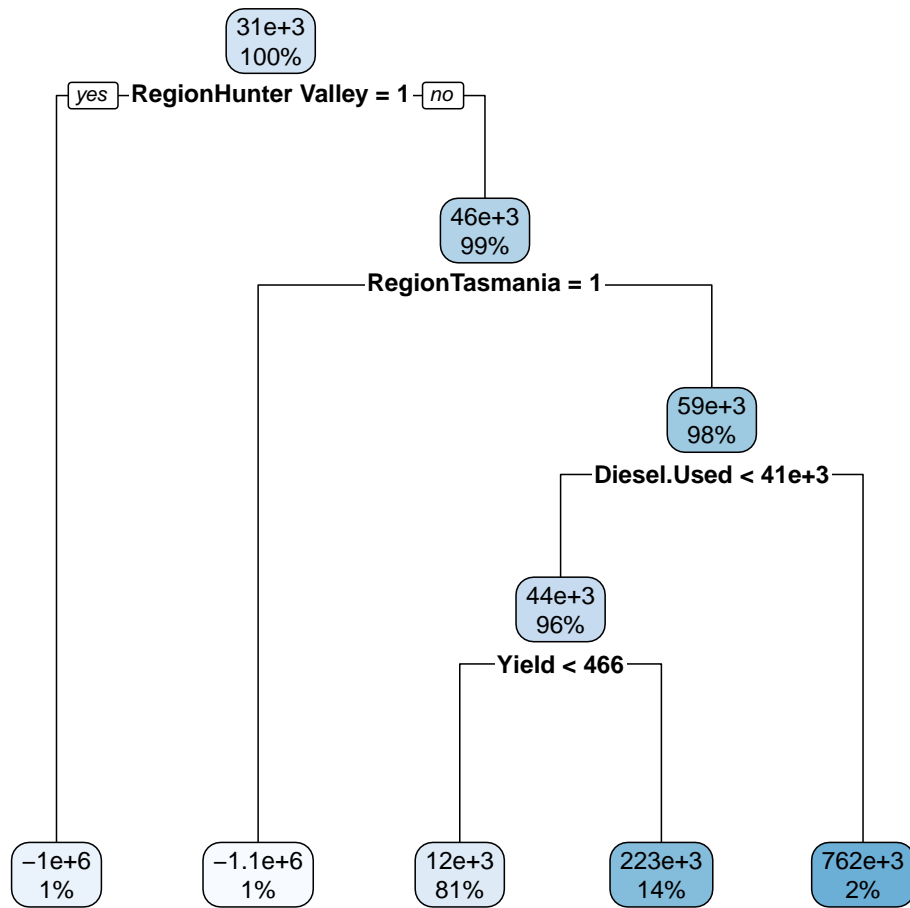


Figure C.9: Decision tree predicting revenue. Each node indicates the class predicted, and the proportion of elements agreeing with nodes partitioning, with the left direction indicating a yes to the nodes rule.

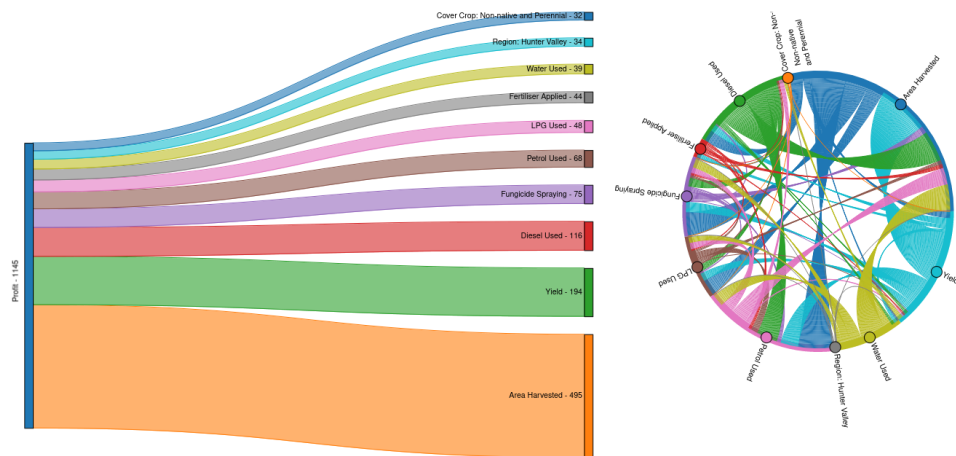


Figure C.10: The left-hand side depicts the 10 most important variables in predicting revenue using XGBoosted trees as a measure of node occurrence, using a Sankey diagram. The right-hand side depicts the interrelated importance of the ten predictor variables using a chord diagram.