# Design and Analysis of Algorithms Part II: Sorting and Searching

**Lecture 5: Heapsort and Sorting in Linear Time** 



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## **Outline**

- Introduction to Part II
- Heapsort Problem
  - Priority Queues
  - (Binary) Heap
  - Heapsort
- Lower Bound for Sorting
- Sorting in Linear Time
  - Counting Sort
  - Radix Sort

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## Introduction to Part II

- In Part II, we will illustrate sorting and searching problems using several examples:
  - Quicksort (快速排序)
  - Selection Problem (选择问题)
  - Heapsort and Priority Queues (堆排序与优先队列)
  - Lower Bound for Sorting (基于比较排序的下界)
  - Sorting in Linear Time (线性时间排序)

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Sizes: Job A — 100 pages

Job B — 10 pages

Job C − 1 page



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Average finish time with FIFO service:

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Average finish time with FIFO service:

$$(100 + 110 + 111) / 3 = 107 time units$$

Average finish time for shortest-job-first service:

$$(1+11+111)/3 = 41 time units$$

- The elements in the queue are printing jobs, each with the associated number of pages that serves as its priority
- Processing the shortest job first corresponds to extracting the smallest element from the queue
- Insert new printing jobs as they arrive

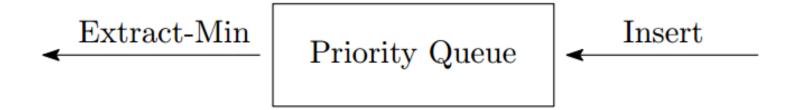
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A queue capable of supporting two operations: Insert and Extract-Min?

## **Priority Queue**

Priority queue is an abstract data structure that supports two operations

- Insert: inserts the new element into the queue
- Extract-Min: removes and returns the smallest element from the queue



- Unsorted list + a pointer to the smallest element
  - Insert in

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  - Insert in O(1) time
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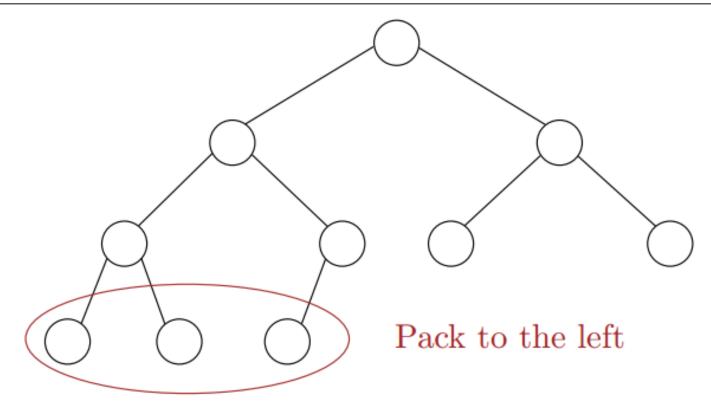
#### Question

Is there any data structure that supports both these priority queue operations in  $O(\log n)$  time?

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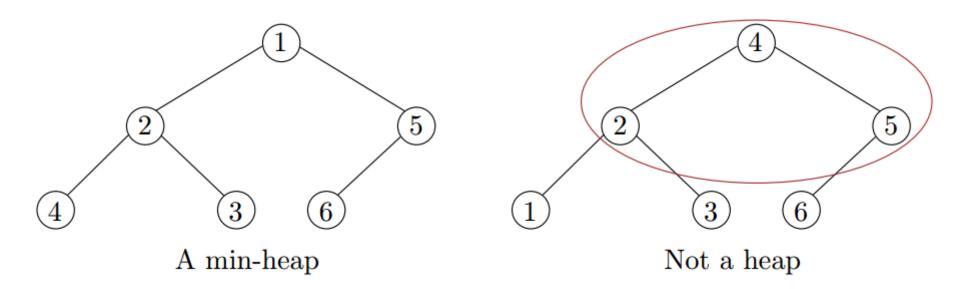
# (Binary) Heap



Heaps are "almost complete binary trees"

- All levels are full except possibly the lowest level.
- If the lowest level is not full, then nodes must be packed to the left.

# Heap-order Property



Heap-order property (Min-heap):

The value of a node is at least the value of its parent.

A[Parent(i)] ≤ A[i]

## **Heap Properties**

- If the heap-order property is maintained, heaps support the following operations efficiently (assume there are n elements in the heap)
  - Insert in O(log n) time
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- Structure properties
  - A heap of height h has between  $2^h$  to  $2^{h+1}-1$  nodes. Thus, an n-element heap has height  $\Theta(\log n)$ .

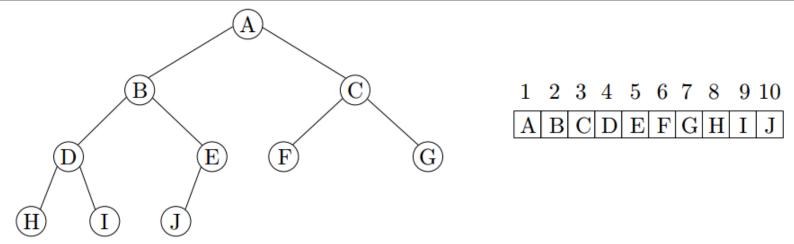
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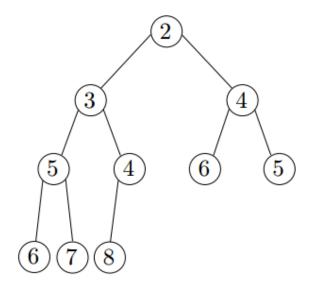
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- The structure is so regular, it can be represented in an array and no links are necessary!

## Array Implementation of Heap

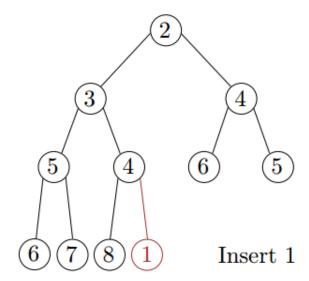


- The root is in array position 1.
- For any element in array position i,
  - The left child is in position 2i.
  - The right child is in position 2i+1.
  - The parent is in position [i/2].
- We will draw the heaps as trees, with the understanding that an actual implementation will use simple arrays.

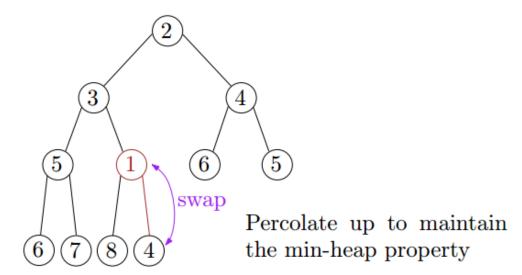
- Add the new element to the next available position at the lowest level
- Restore the min-heap property if violated
  - General strategy is percolate up (or bubble up): if the parent of the element is larger than the element, then interchange the parent with child.



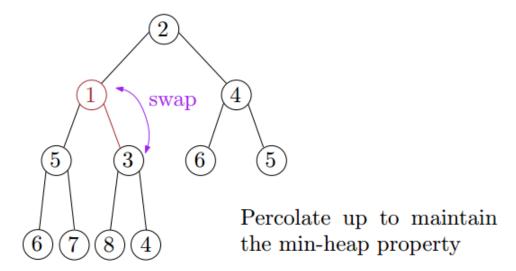
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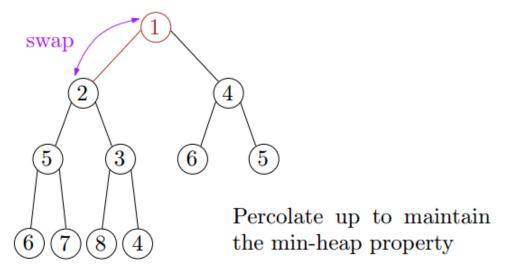
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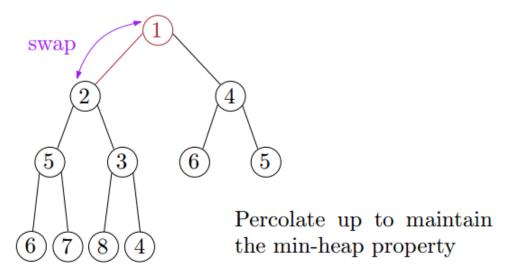


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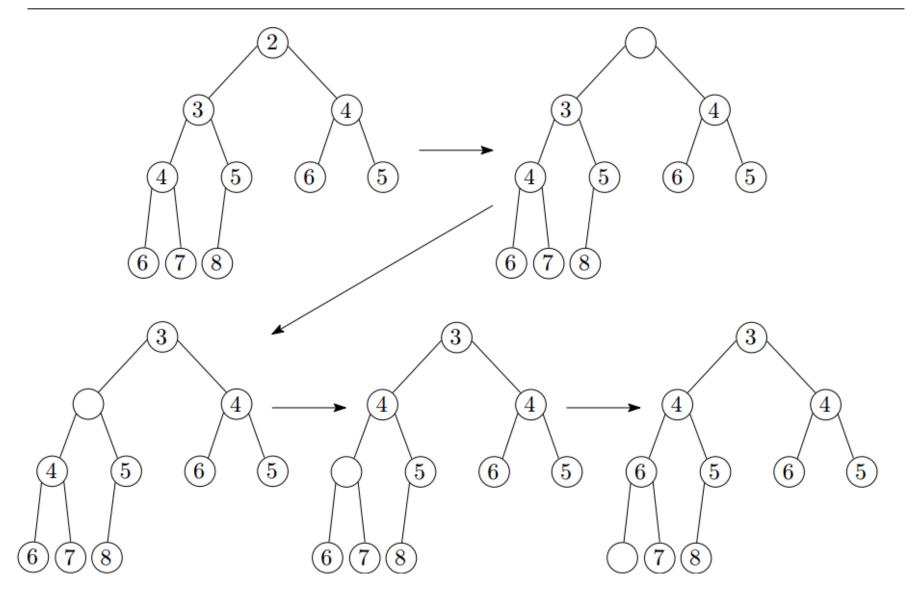
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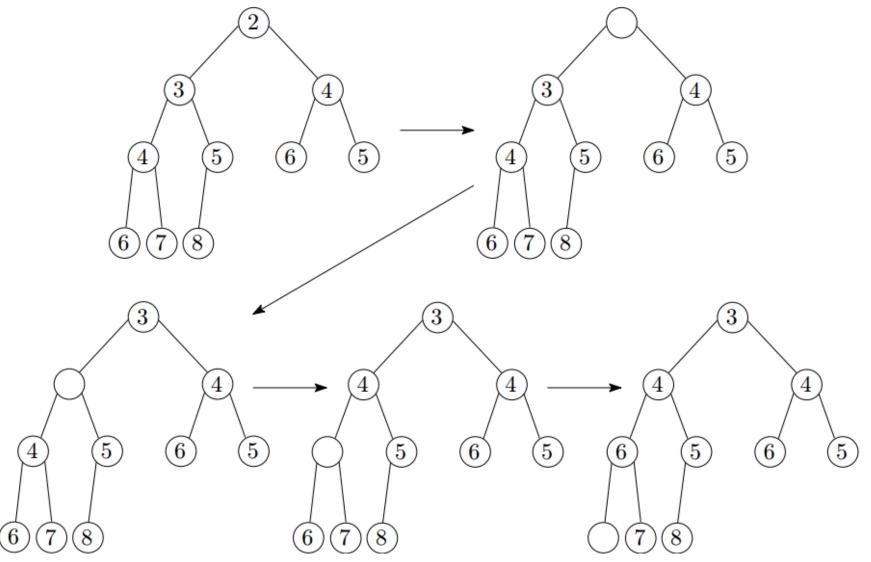


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- Time complexity = O(height) = O(log n)

# Extract-Min: First Attempt



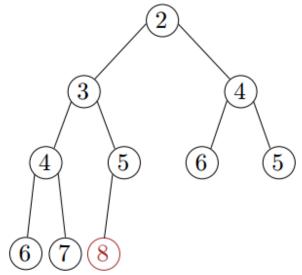
## Extract-Min: First Attempt



Min-heap property preserved, but completeness not preserved!

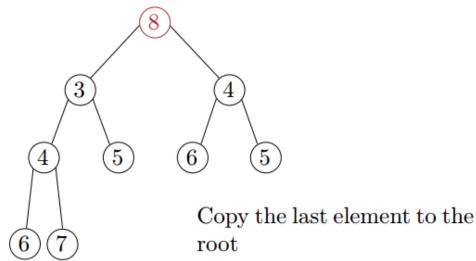
## Extract-Min

- Copy the last element to the root (i.e., overwrite the minimum element stored there)
- Restore the min-heap property by percolate down (or bubble down): if the element is larger than either of its children, then interchange it with the smaller of its children.

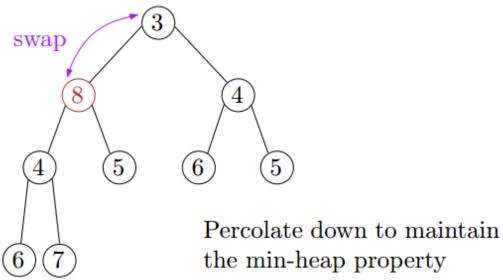


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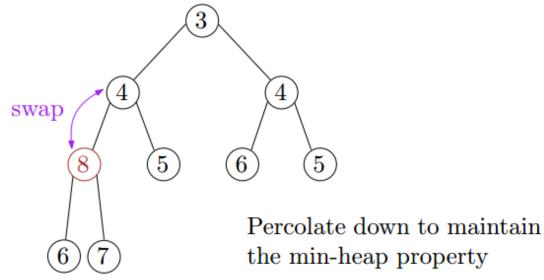
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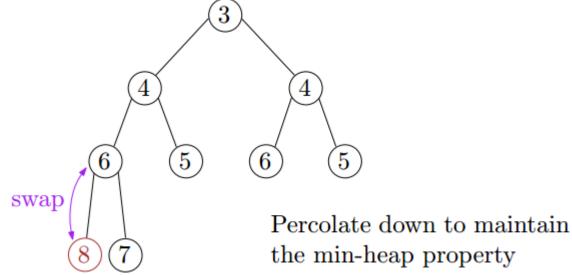
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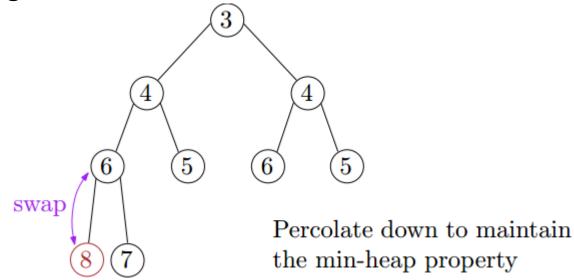


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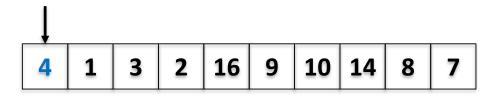
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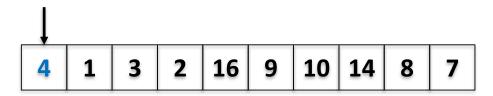
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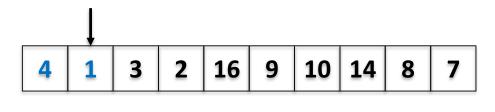
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- Total time complexity: O(n log n)



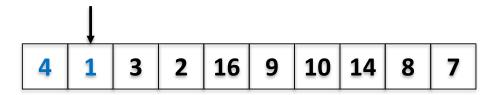


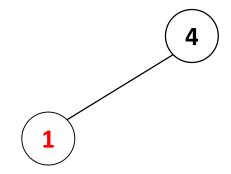


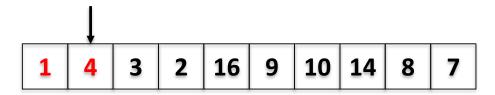
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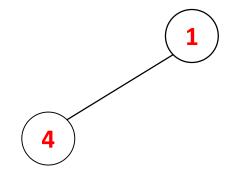


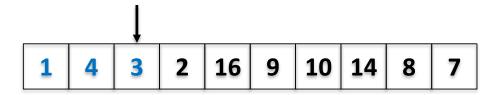
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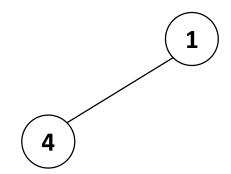


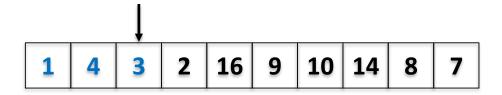


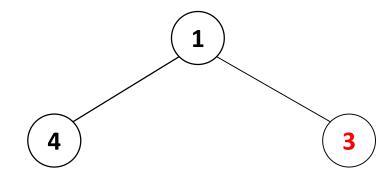


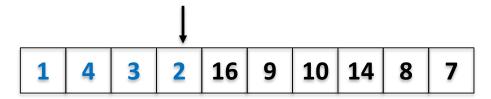


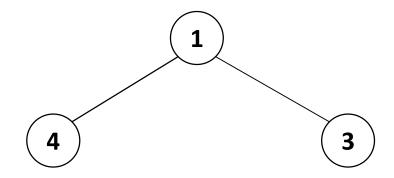


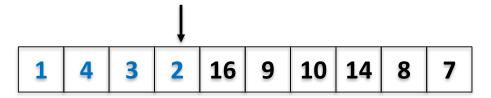


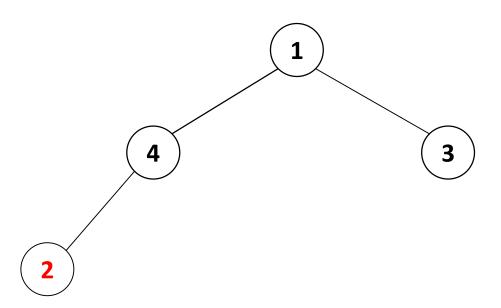


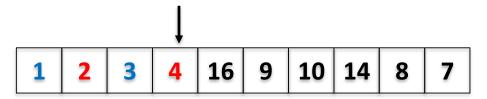


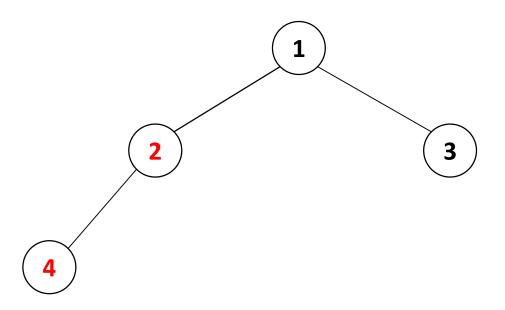


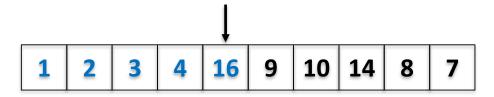


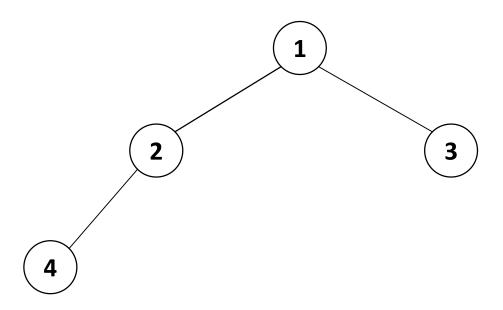


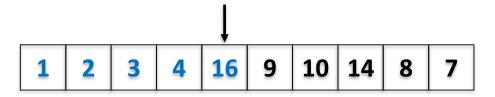


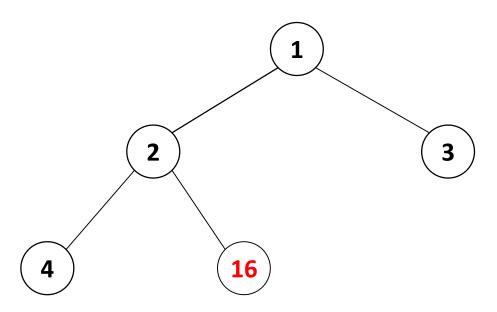


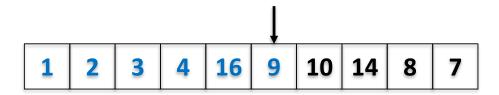


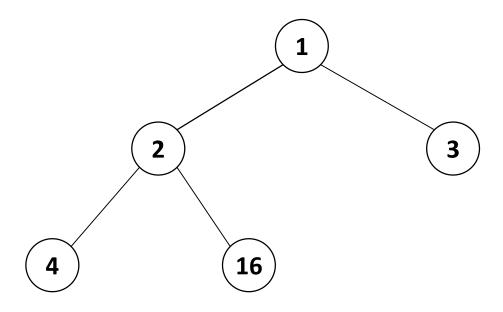


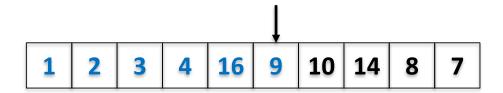


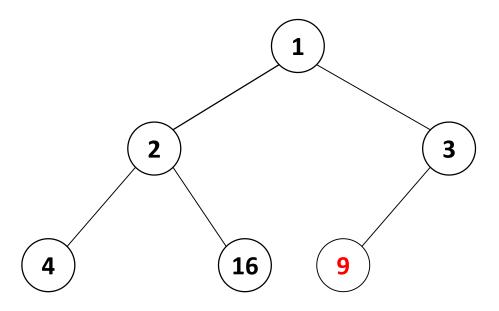




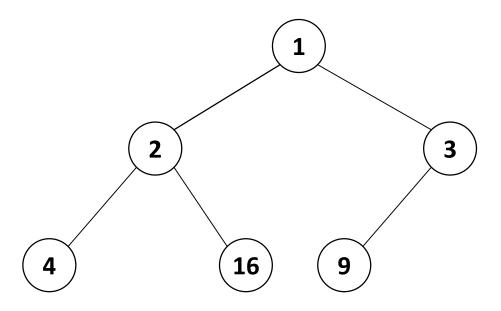




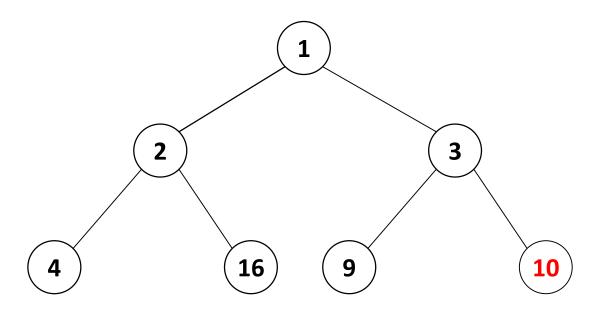


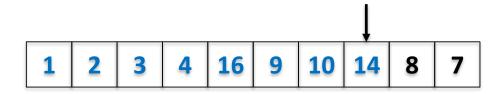


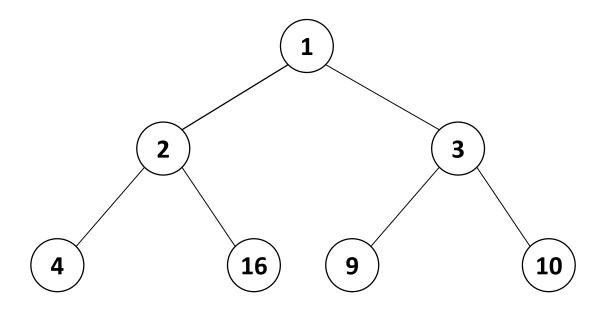


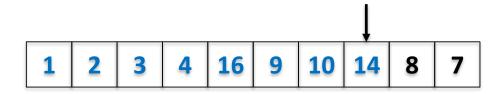


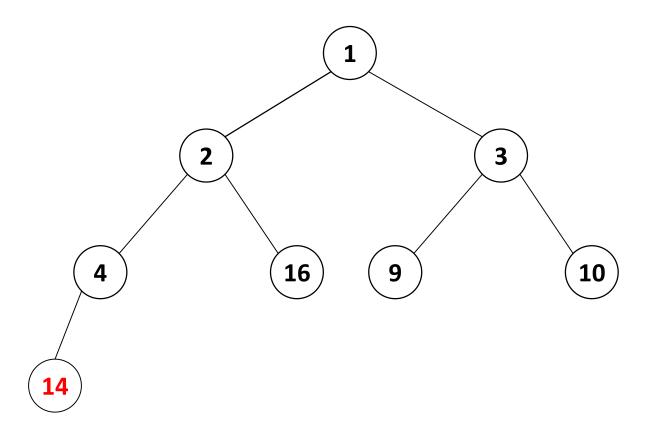




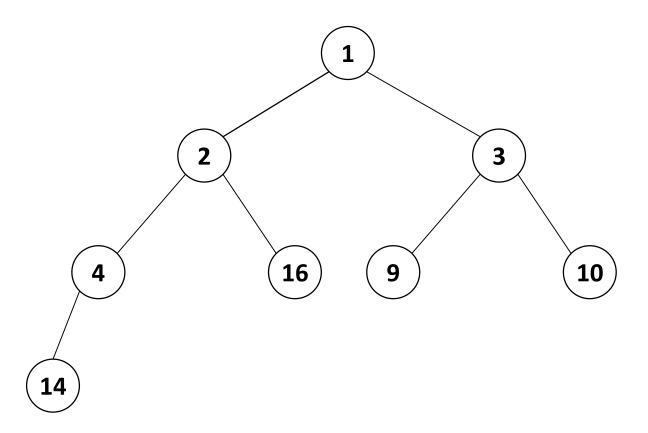


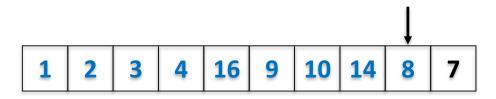


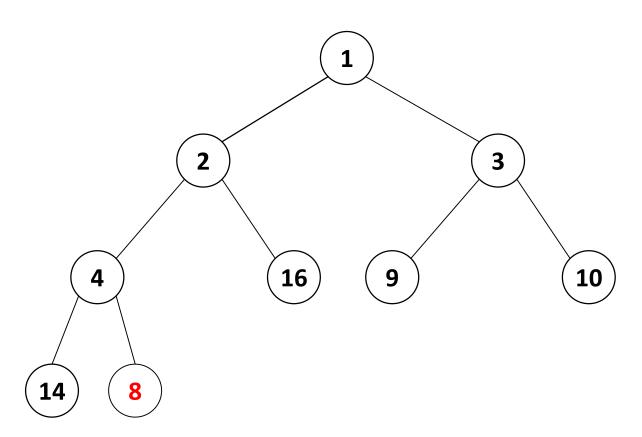


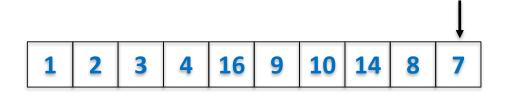


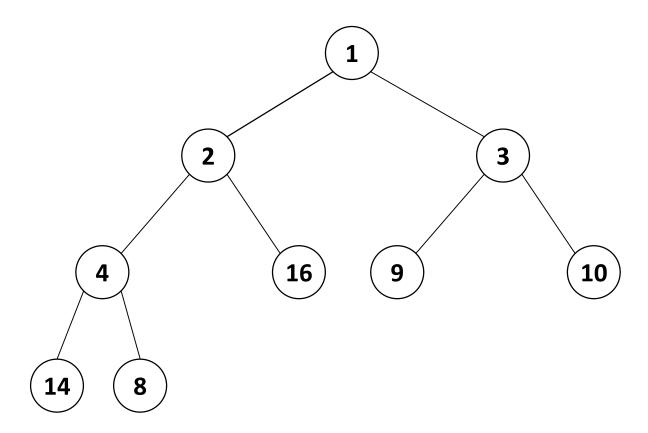


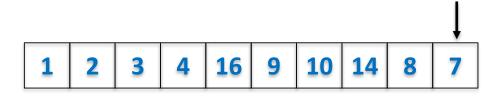


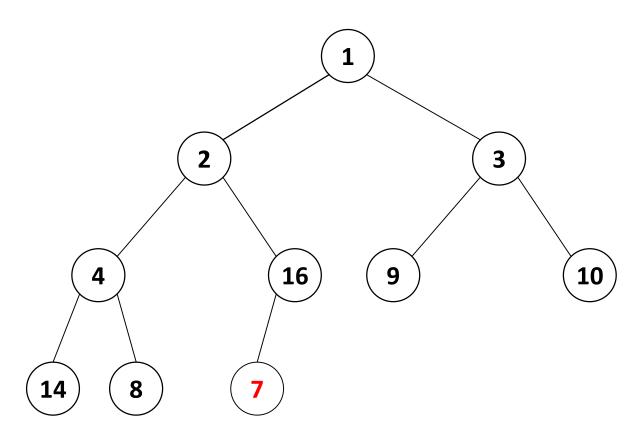


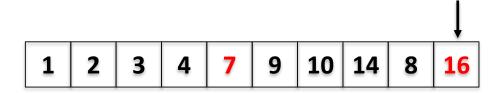


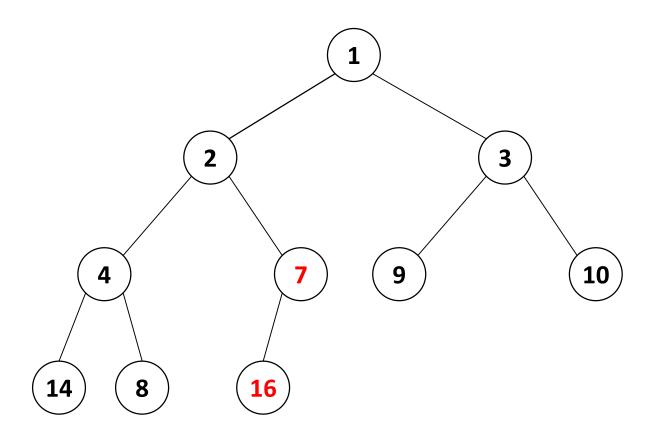




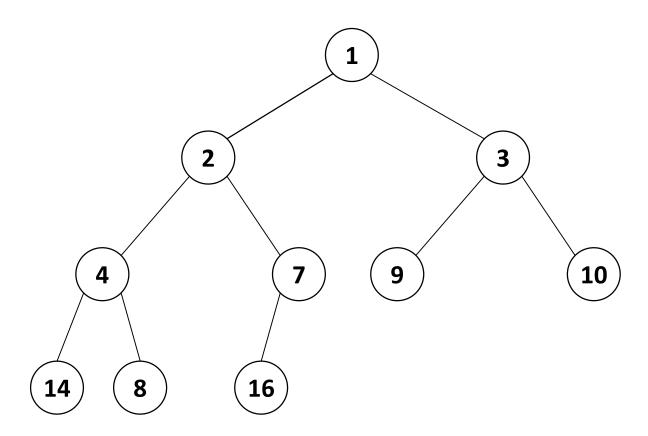




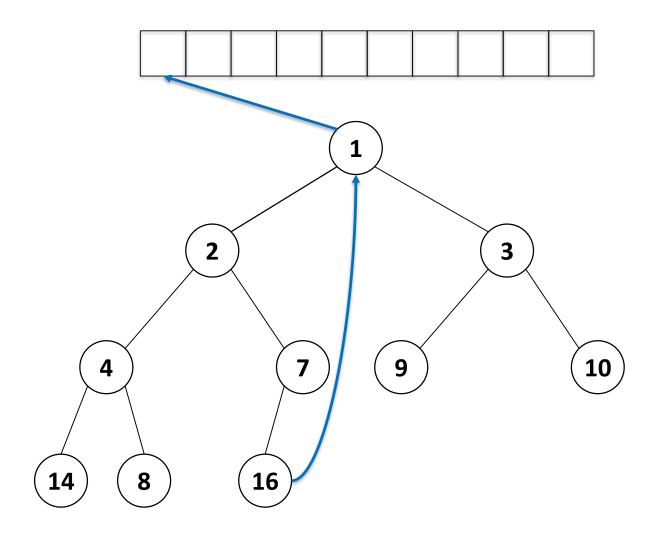




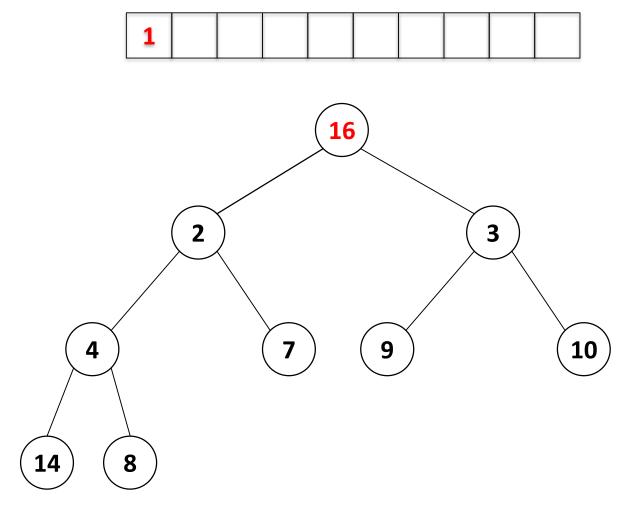


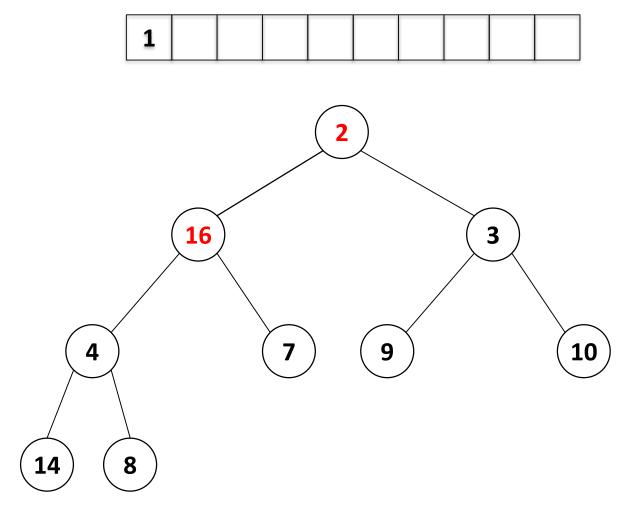


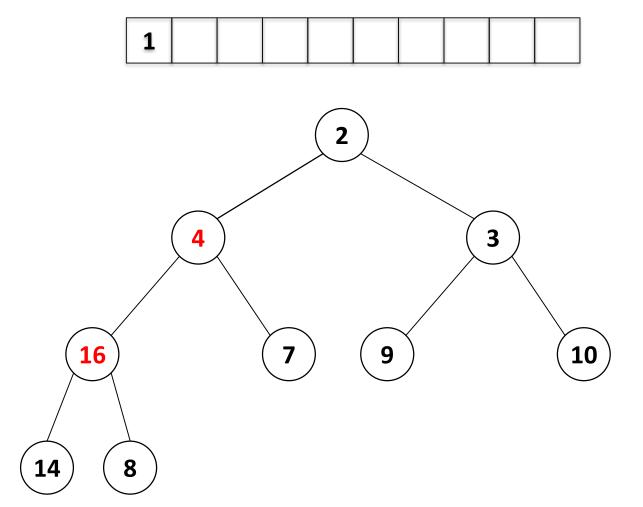
Perform n Extract-Min operations

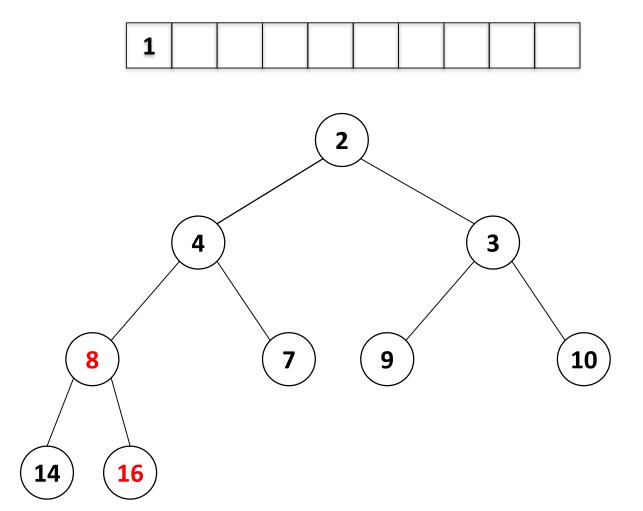


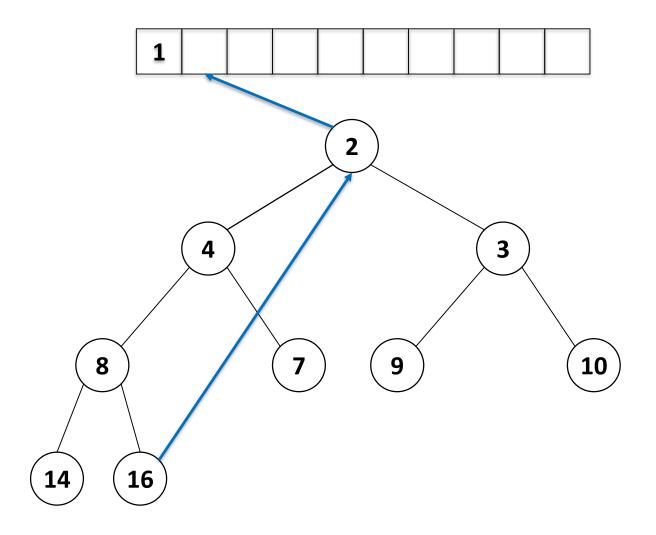
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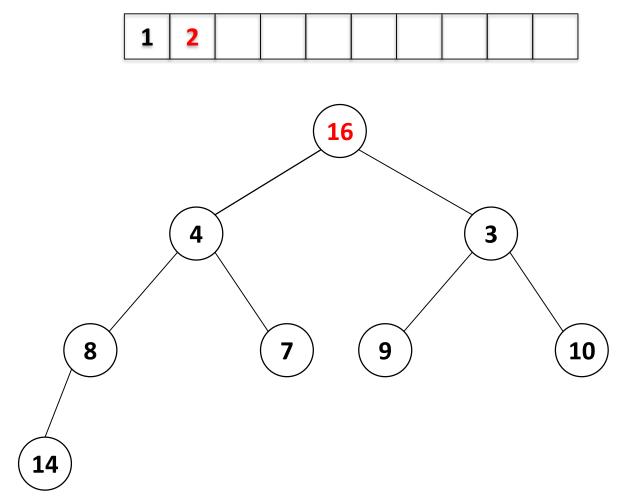


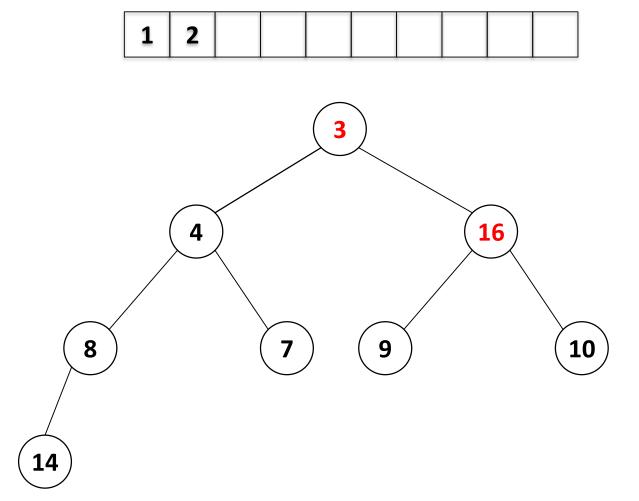


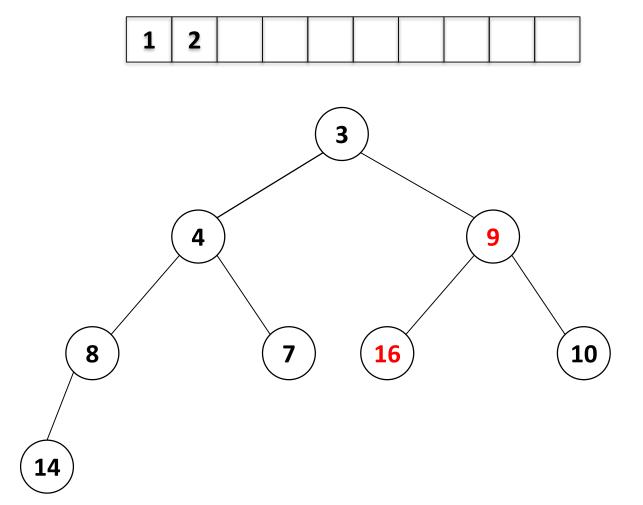


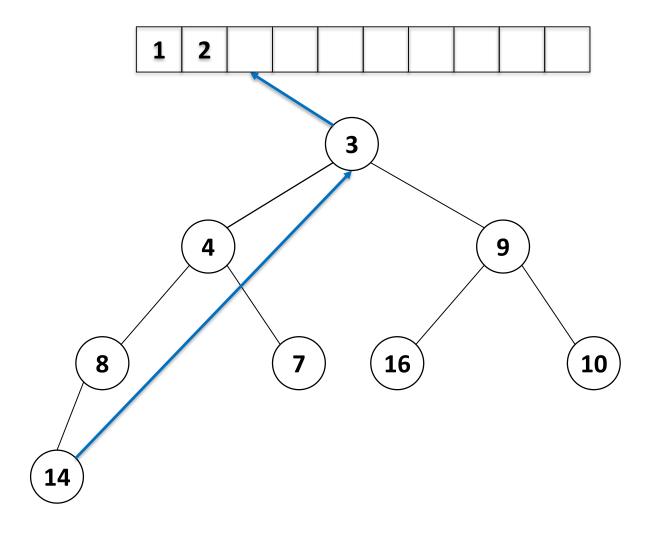


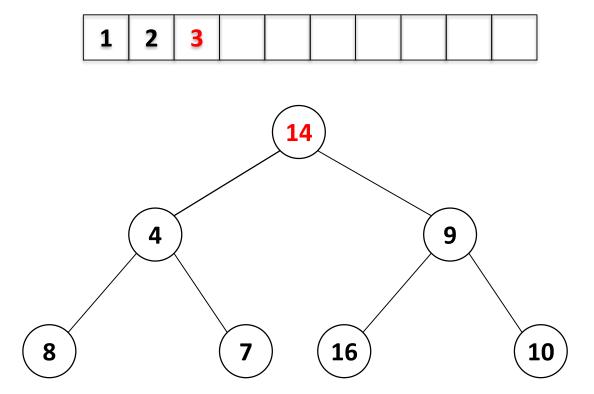


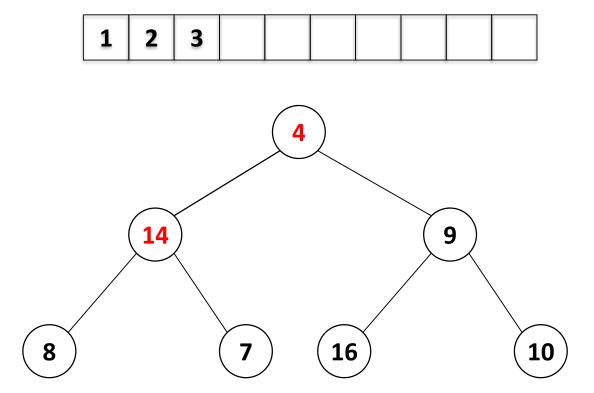




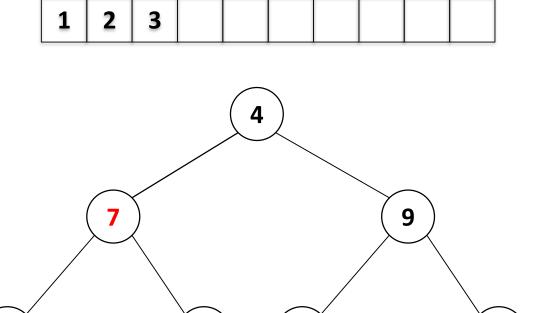






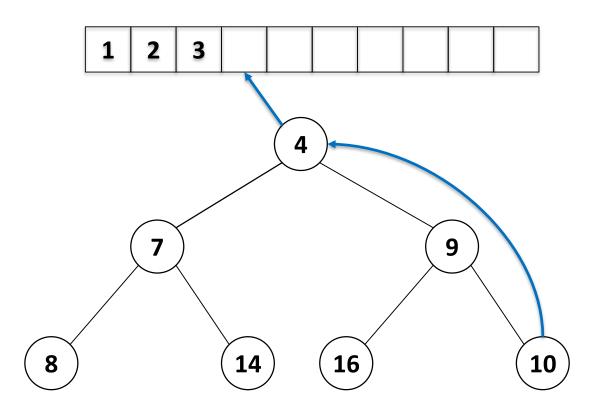


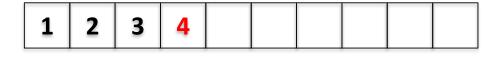
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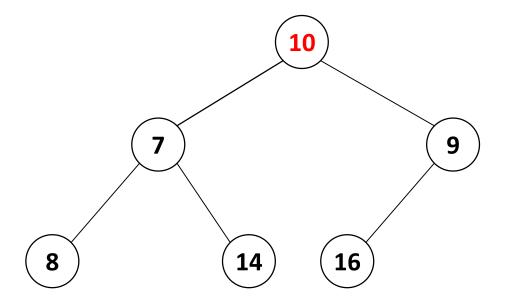


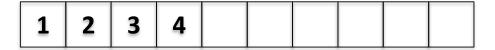
16

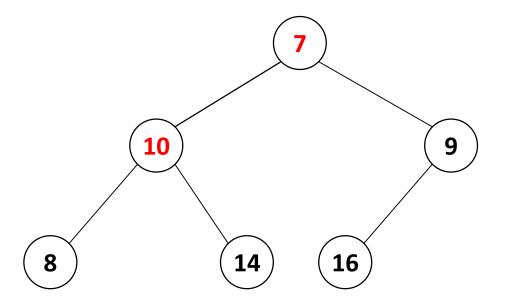
10



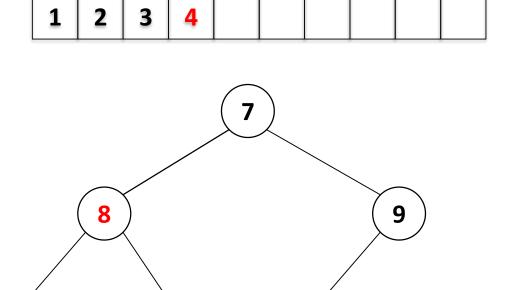






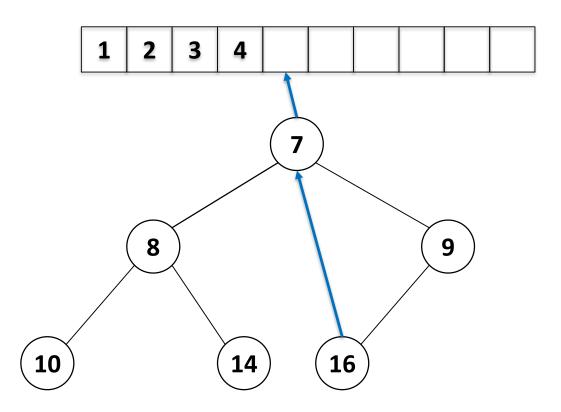


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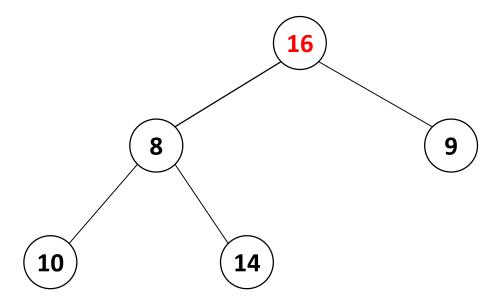


**16** 

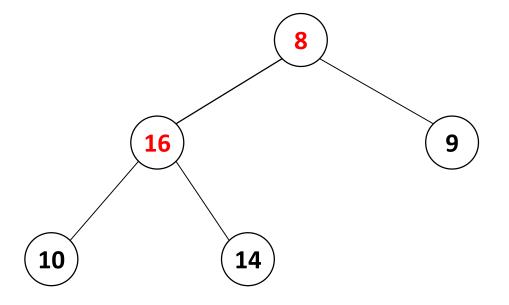
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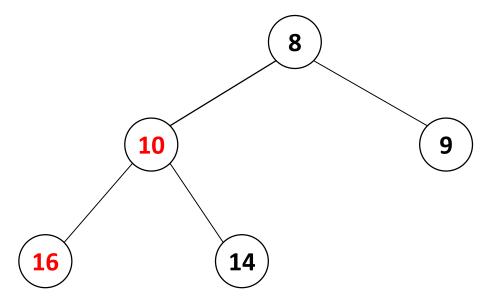


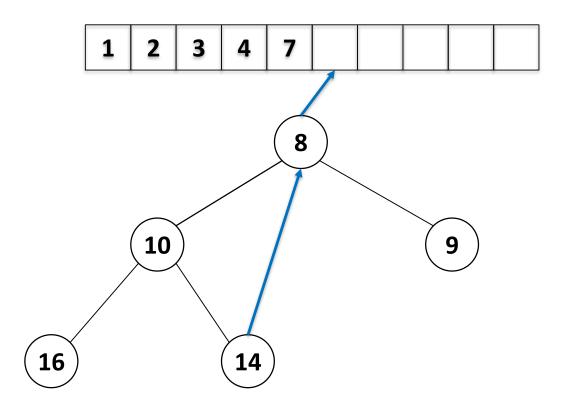




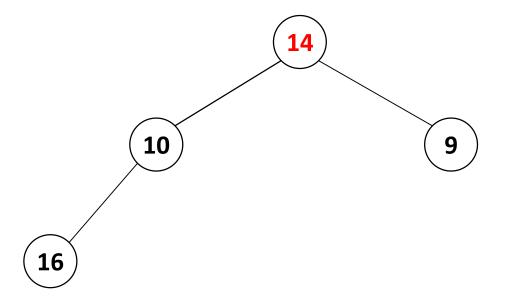




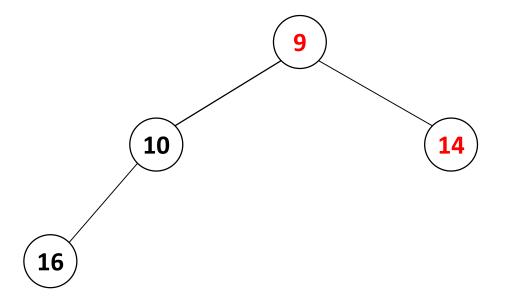


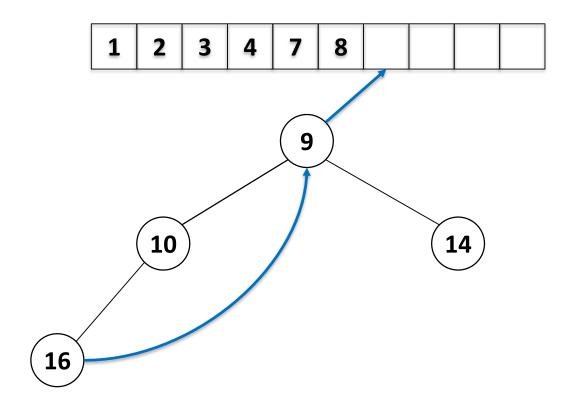




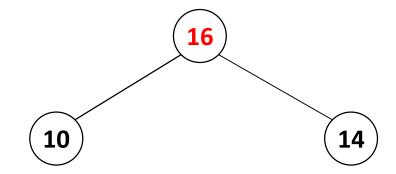




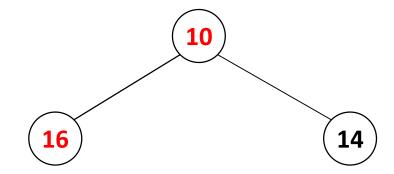


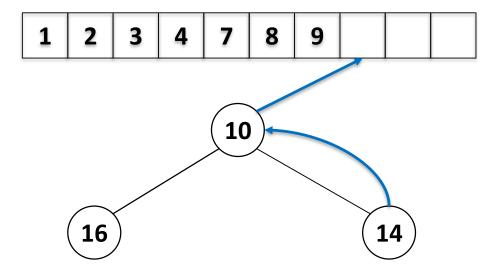




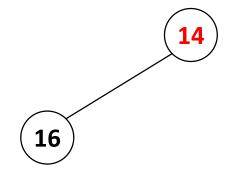


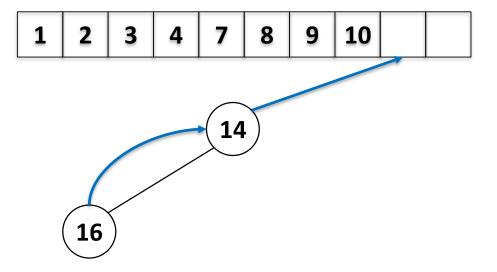








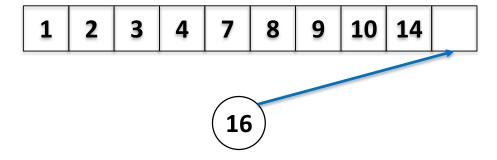




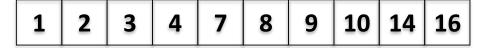
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#### Summary

• Priority queue is an abstract data structure that supports two operations: Insert and Extract-Min.

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 If priority queues are implemented using heaps, then these two operations are supported in O(log n) time.

 Heapsort takes O(n log n) time, which is as efficient as merge sort and quicksort.

#### **Outline**

- Introduction to Part II
- Heapsort Problem
  - Priority Queues
  - (Binary) Heap
  - Heapsort
- Lower Bound for Sorting
- Sorting in Linear Time
  - Counting Sort
  - Radix Sort

# Review of Classical Sorting Algorithms



John von Neumann Merge Sort Algorithm was invented in 1945



Quicksort Algorithm was invented in 1959



J. W. J. Williams
Heapsort Algorithm
was invented in 1964

Which algorithm is the best in practice?

- All sorting algorithms seen so far are based on comparing elements
  - E.g., insertion sort, merge sort, and heapsort

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#### Question

Can we do better?

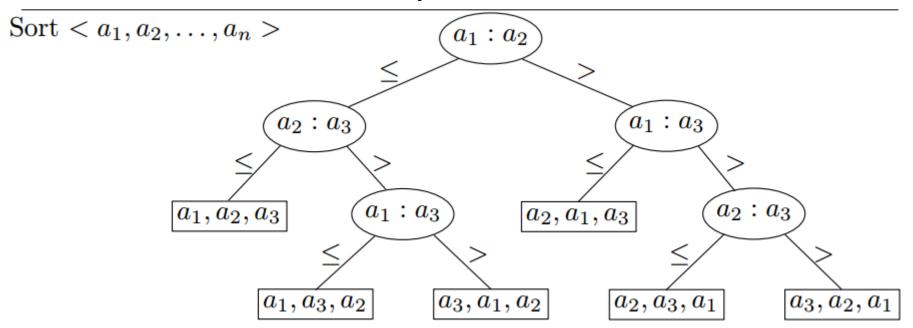
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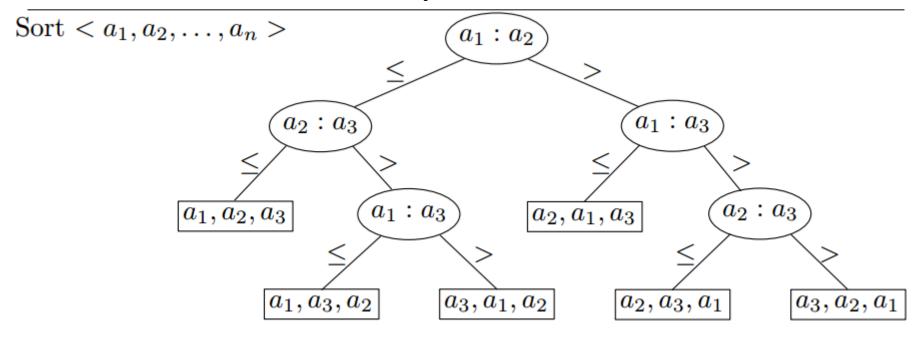
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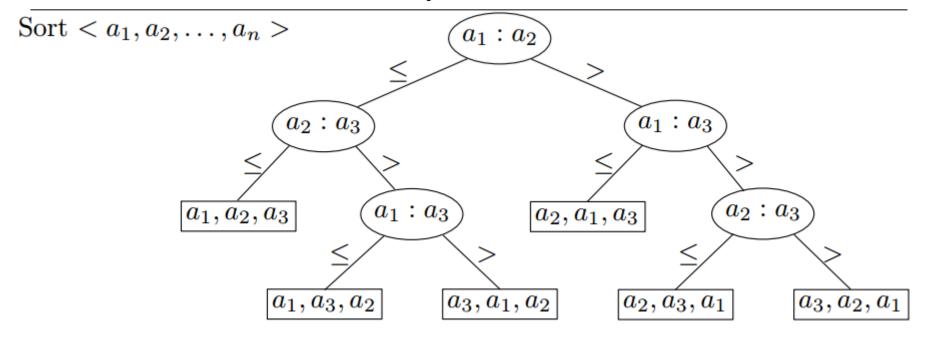
#### Goal

We will prove that any comparison-based sorting algorithm has a worst-case running time  $\Omega(n \log n)$ .

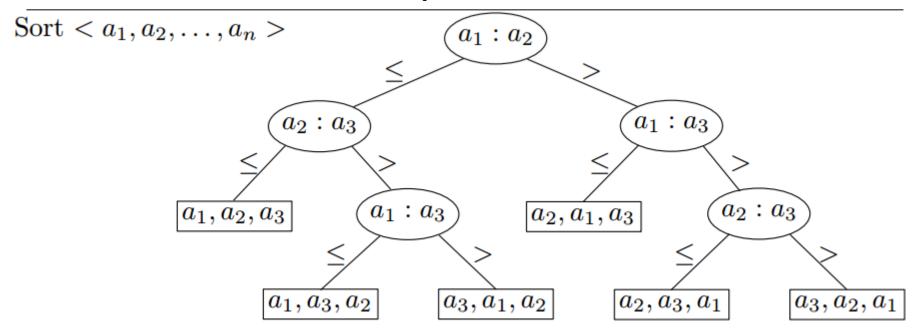




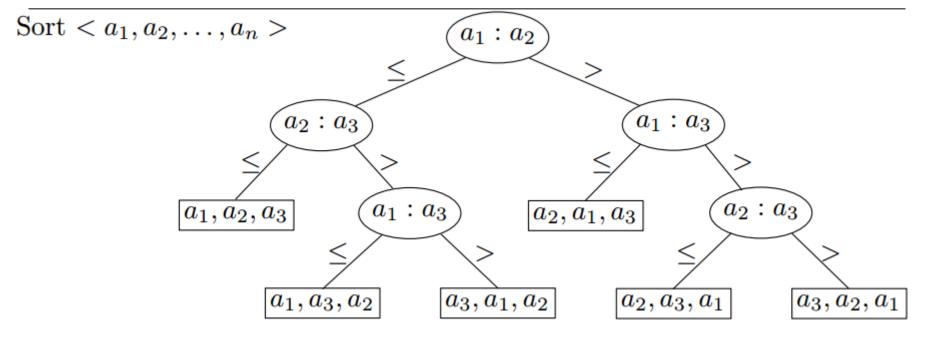
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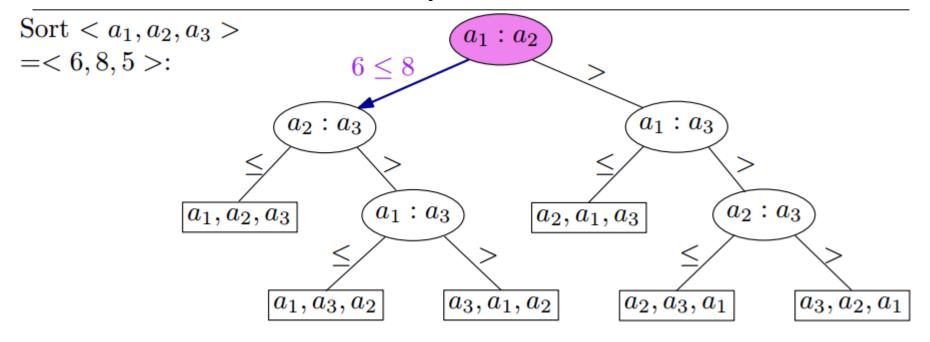
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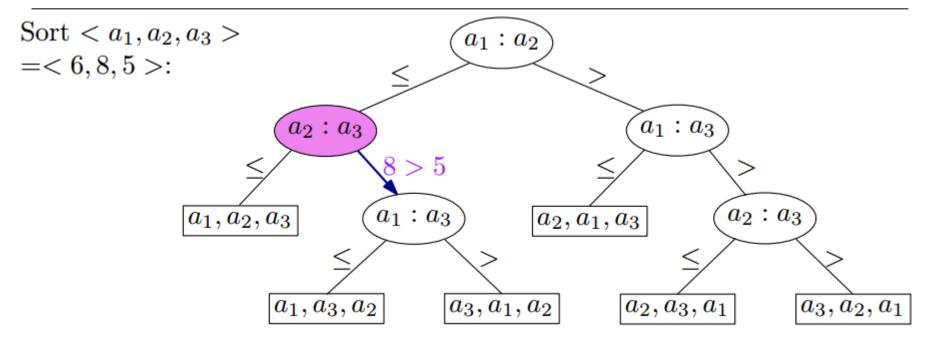
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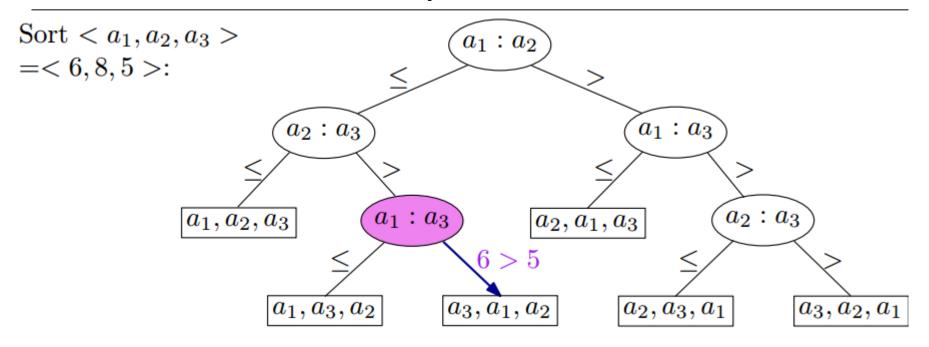
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- Each leaf corresponds to an input ordering



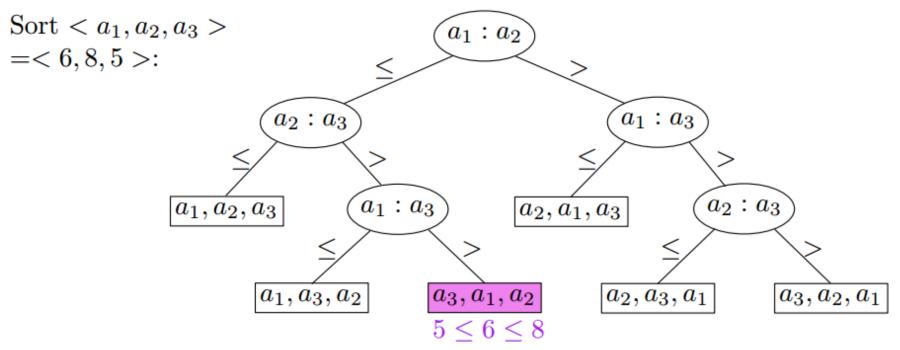
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Worst-case running time = height of tree

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### Corollary

Heapsort and merge sort are asymptotically optimal comparison-based sorting algorithms.

## Can we do better?

Are there sorting algorithms which are not based on comparisons? Do they beat the  $\Omega(n \log n)$  lower bound?

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Counting sort (计数排序)

Radix sort (基数排序)

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- Introduction to Part II
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  - For example, if 17 elements are less than x, then x belongs in output position 18.

## **Counting Sort**

Counting-Sort(A,B,k)

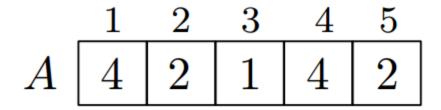
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Input: A[1...n] where A[j] \in \{1, 2, ..., k\}
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end
for j \leftarrow 1 to n do
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for j \leftarrow n \ to \ 1 \ do
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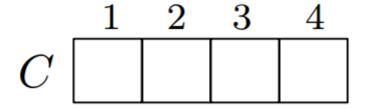
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# **Example: Counting Sort**





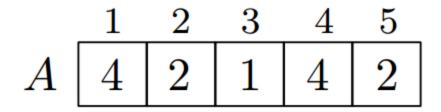


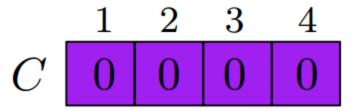
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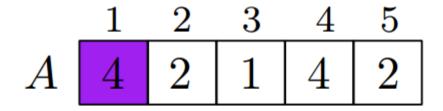
for 
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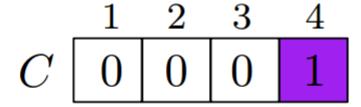
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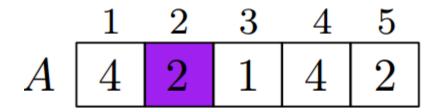
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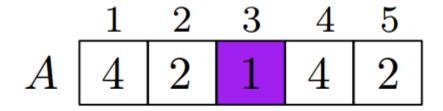
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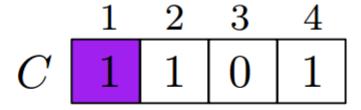
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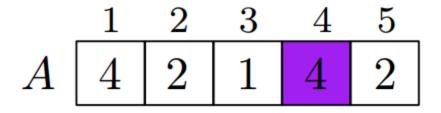
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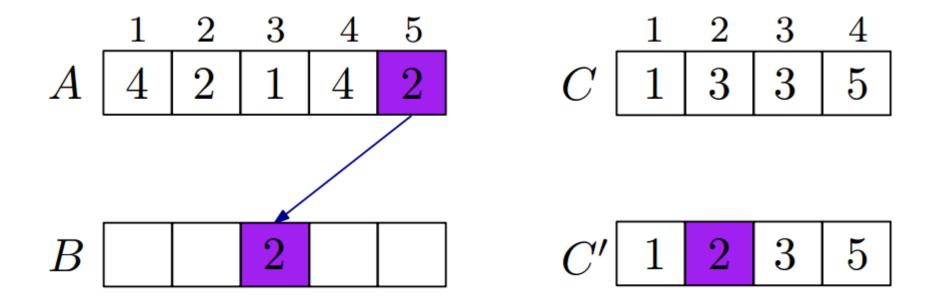
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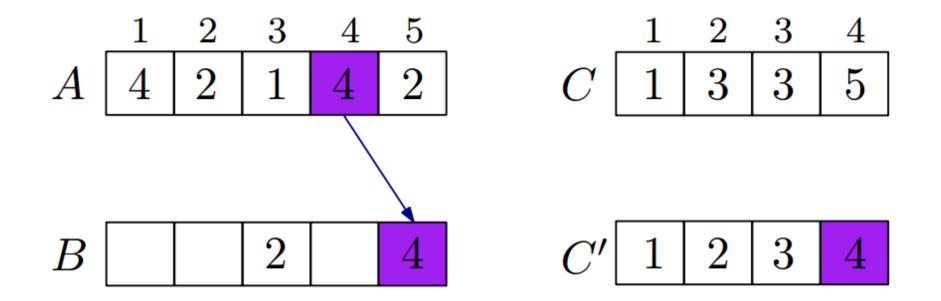
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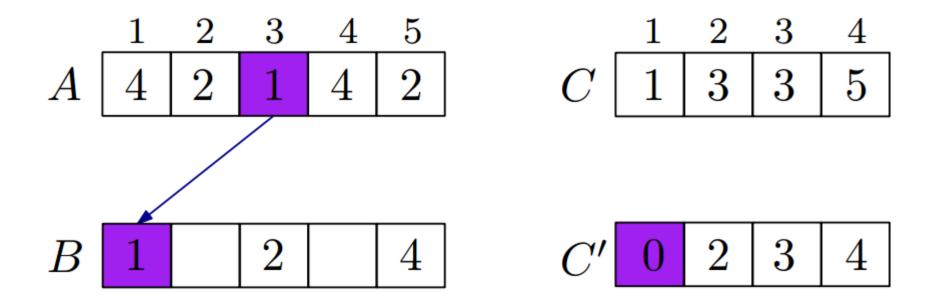
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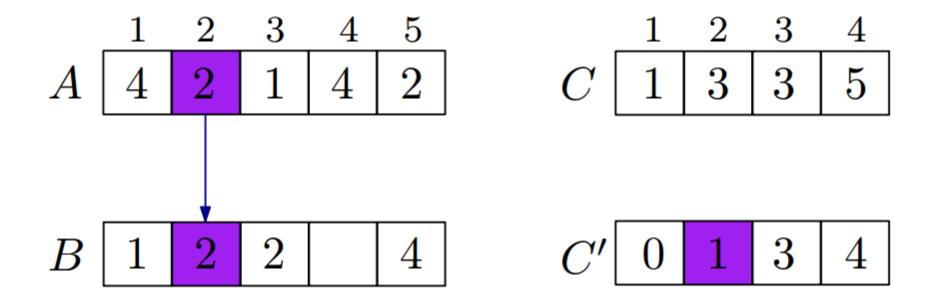
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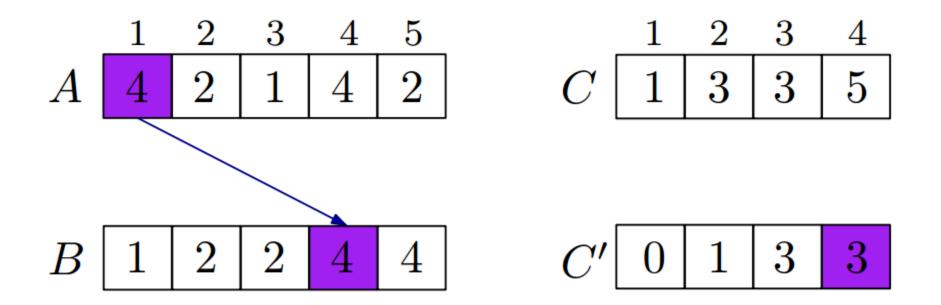
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  |C[i] \leftarrow C[i] + C[i-1]; //C[i] = |\{key \le i\}|
 end
for j \leftarrow n \ to \ 1 \ do
   B[C[A[j]]] \leftarrow A[j];
C[A[j]] \leftarrow C[A[j]] - 1;
end
 return B;
```











Counting-Sort(A,B,k)

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Input: A[1...n] where A[j] \in \{1, 2, ..., k\}
Output: B[1...n], sorted
let C[1...k] be a new array;
for i \leftarrow 1 to k do
C[i] \leftarrow 0; //O(k)
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Total: O(n+k)

If k = O(n), then counting sort takes O(n) time.

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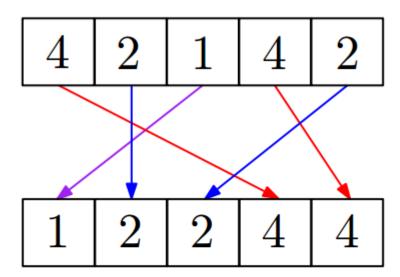
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- Note that counting sort is not a comparison-based sorting algorithm.
- In fact, it makes no comparison at all!

# Stable Sorting

Counting sort is a stable sort

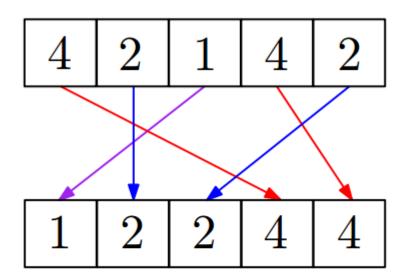
it preserves the input order among equal elements.



# Stable Sorting

Counting sort is a stable sort

it preserves the input order among equal elements.



#### Exercise

What other sorts have this property?

## Outline

- Introduction to Part II
- Heapsort Problem
  - Priority Queues
  - (Binary) Heap
  - Heapsort
- Lower Bound for Sorting
- Sorting in Linear Time
  - Counting Sort
  - Radix Sort

```
2 3 2 9
```

Sort on least significant digit first using stable sort



2 3 2 9

5 4 5 7

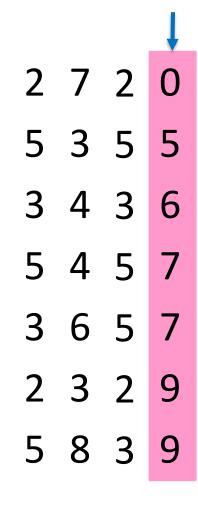
3 6 5 7

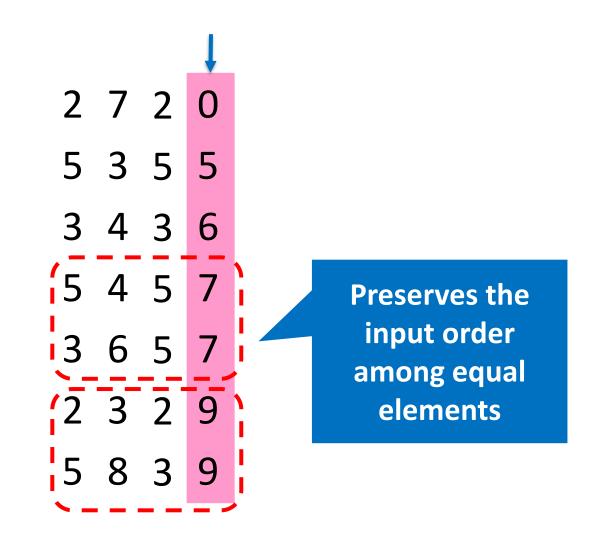
5 8 3 9

3 4 3 6

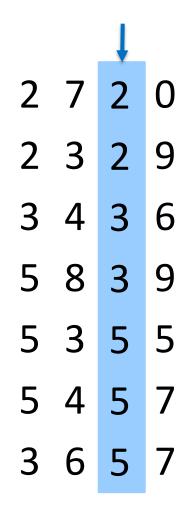
2 7 2 0

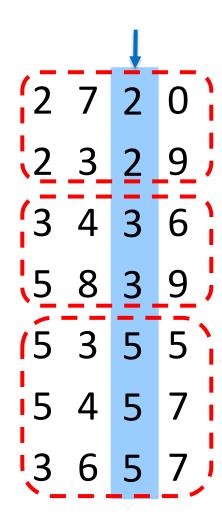
5 3 5 5



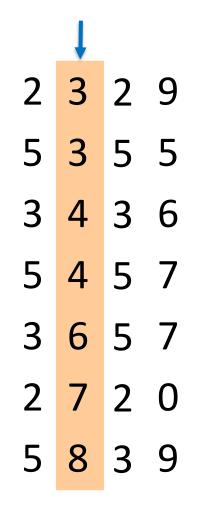


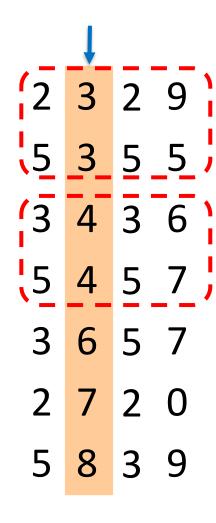
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2 7 2 0
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3 4 3 6
5 4 5 7
3 6 5 7
2 3 2 9
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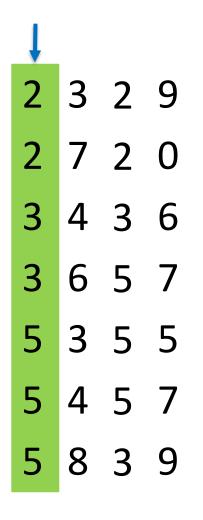


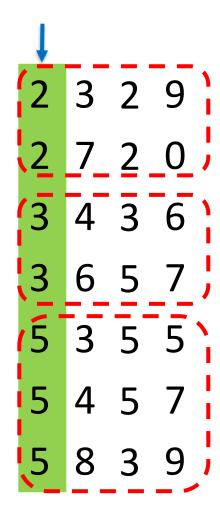
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5 8 3 9
5 3 5 5
5 4 5 7
3 6 5 7
```





```
2 3 2 9
5 3 5 5
3 4 3 6
5 4 5 7
3 6 5 7
2 7 2 0
5 8 3 9
```





```
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```

### Radix Sort: Correctness

## Induction on digit position

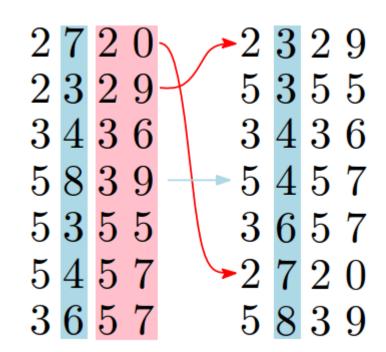
- Assume that the numbers are sorted by their loworder i-1 digits
- Sort on digit i

2	7	2	0	2	3	2	9
2	3	2	9	5	3	5	5
3	4	3	6	3	4	3	6
5	8	3	9	<b></b> 5	4	5	7
5	3	5	5	3	6	5	7
5	4	5	7	2	7	2	0
3	6	5	7	5	8	3	9

### Radix Sort: Correctness

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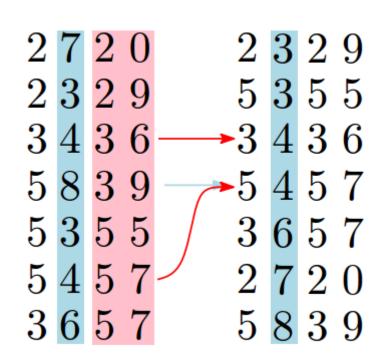
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## Radix Sort: Correctness

### Induction on digit position

- Assume that the numbers are sorted by their loworder i-1 digits
- Sort on digit i
  - Two numbers that differ on digit i are correctly sorted by their low-order i digits
  - Two numbers equal on digit I are put in the same order as the input → correctly sorted by their low-order i digits



#### Lemma

Given n d-digit numbers in which each digit can take on up to k possible values, radix sort correctly sorts these numbers in O(d(n+k)) time if the stable sort it uses takes O(n+k) time.

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- each number can be viewed as having O(b) digits of log n bits each
- running time is  $O(d(n + k)) = O(b(n + 2^{\log n})) = O(bn)$
- since b is a constant, the running time is O(n)

dank u Tack ju faleminderit Asante ipi Tak mulţumesc

Salamat! Gracias
Terima kasih Aliquam

Merci Dankie Obrigado
köszönöm Grazie

Aliquam Go raibh maith agat
děkuji Thank you

gam