

# CSC 212: Data Structures and Abstractions

## Dynamic (Growing / Resizing) Arrays

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# Quick notes

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- **Review** Pointers and Dynamic Memory Allocation
- Programming Assignment 1
  - ✓ Due tonight (9/16)
  - ✓ Submit up to 3 days late @ 10% penalty per day late
- Programming Assignment 2
  - ✓ Recommend learning vector of pairs `std::vector<std::pair>>`
  - ✓ Introducing at the end of this lecture

# Arrays

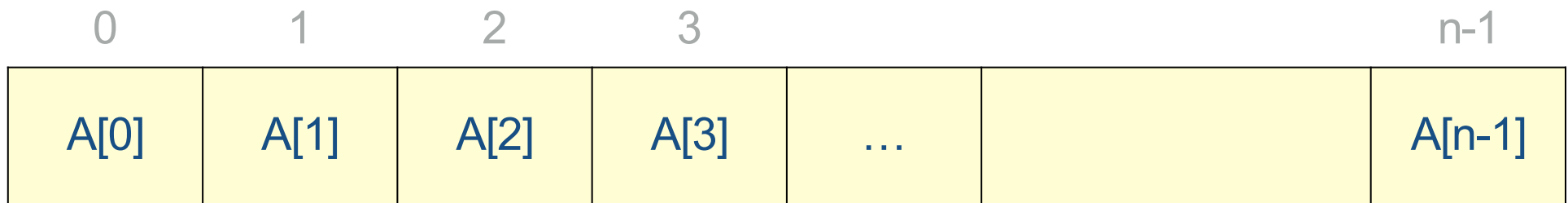
# Arrays

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- An array is a **contiguous** sequence of elements of the **same type**
- Each element can be accessed using its **index**

array name: A

array length: n



all elements of the same data type

# Declaration

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// array declaration by specifying size

```
int myarray1[100];
```

// can also declare an array of user specified

// size (must be const for many compilers!)

```
int n = 8;
```

```
int myarray2[n];
```

// can declare and initialize elements

```
double arr[] = { 10.0, 20.0, 30.0, 40.0};
```

// compiler figures the right size

// a different way

```
int arr[5] = { 1, 2, 3};
```

// compiler creates an array of length 5 and

// initializes first 3 elements

# Static arrays

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- So far ... we have seen examples of arrays, **allocated in the stack** (fixed length)

```
// array declaration by specifying size
```

```
int myarray1[100];
```

- You can allocate memory dynamically, **allocated in the heap** (still fixed length)

```
int *myarray = new int[100];
```

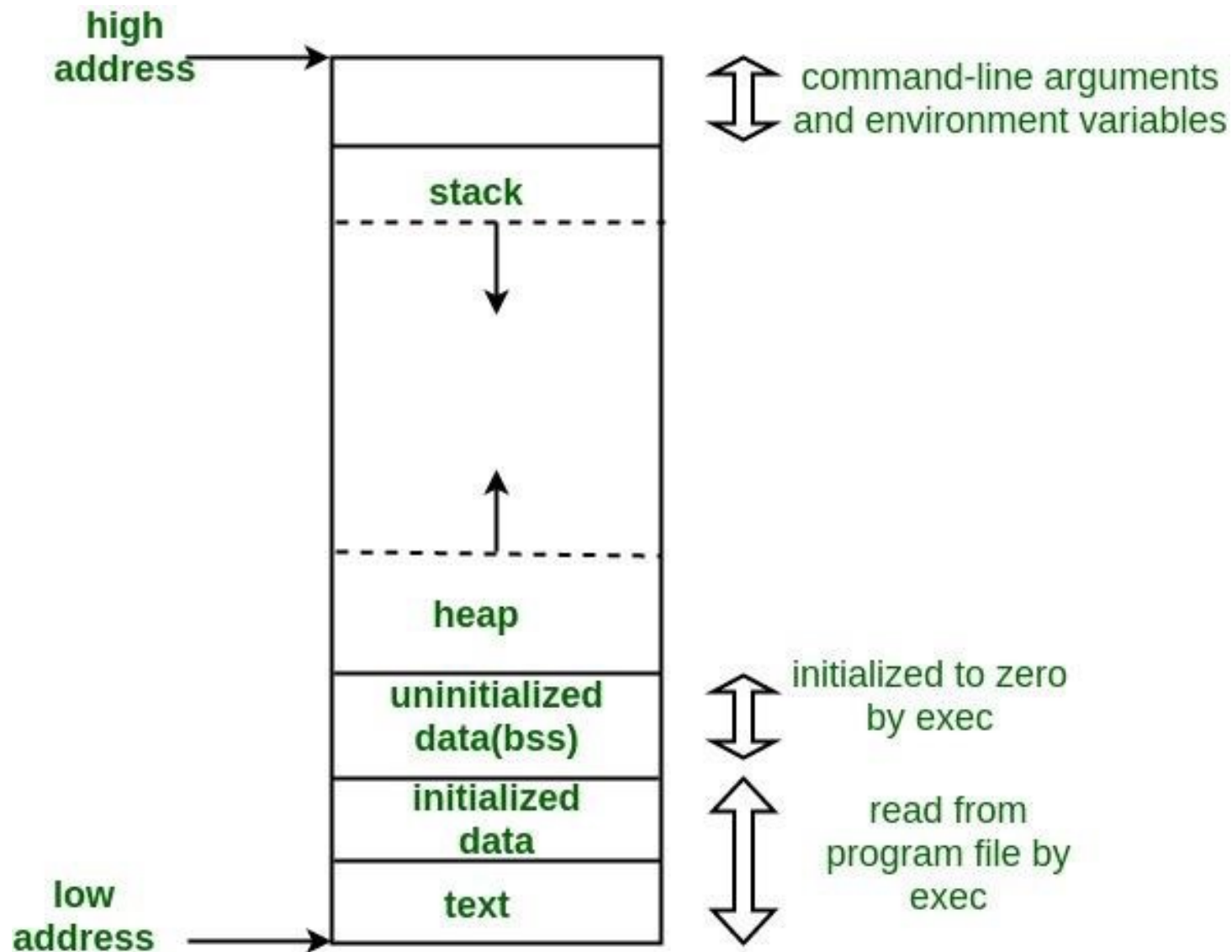
```
// ...
```

```
// work with the array
```

```
// ...
```

```
delete [] myarray;
```

# Memory layout of C/C++ programs



Live coding demo (static  
arrays — stack and heap)



C++ (gcc 4.8, C++11)  
**EXPERIMENTAL!** [known limitations](#)

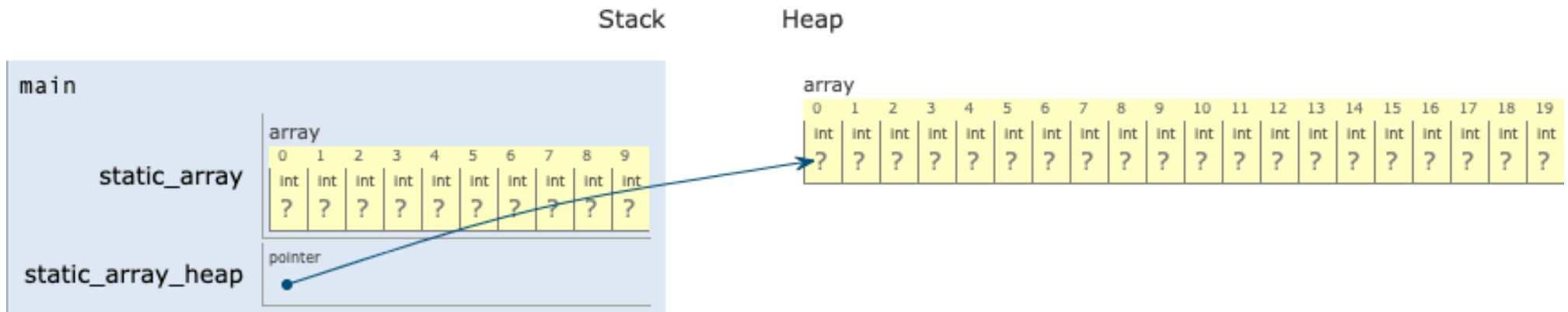
```
1  int main() {  
2      float var1;  
3      double var2;  
4      int static_array[10];  
→ 5      int *static_array_heap = new int [20];  
6      // ...  
7      // work with the array  
8      // ...  
→ 9      delete [] static_array_heap;  
10 }
```

[Edit this code](#)

→ line that just executed

→ next line to execute

[View this code in PythonTutor!](#)



# A few notes ...

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- Creating variables in the stack:
  - ✓ variables are automatically created and freed
  - ✓ variables only exist while the function is running
  - ✓ faster and good for small local variables
- Allocating memory in the heap:
  - ✓ memory is allocated at runtime
  - ✓ programmer is responsible for allocating / deallocating memory
  - ✓ variables can be accessed globally (in the program)
  - ✓ memory may become fragmented
  - ✓ slower but good for large variables

# What if ... ?

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- We don't know the max size of an array before running the program
  - ✓ user specified inputs/decisions
  - ✓ e.g. read an image or video and display
- The sequence changes over time (during the execution of the program)
  - ✓ e.g. you develop a text editor and represent the sequence of characters as an array

Which data structure (studied so far) would you use on each case?

# Dynamic Arrays (resizing, growing)

# Dynamic Arrays

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- Dynamically allocated arrays that change their size over time
  - ✓ can **grow** automatically
  - ✓ can **shrink** automatically
- Operations on arrays (we could have more, but these are enough for the purposes of this lecture)
  - ✓ **append**
  - ✓ **remove\_last**
  - ✓ **get** —  $\Theta(1)$
  - ✓ **set** —  $\Theta(1)$

# First try ...

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- Start with an empty array
- For every **append**:
  - ✓ increase the size of the array by 1 then write the new element
- For every **remove\_last**:
  - ✓ remove the last element and then decrease the size of the array by 1
- Demo ...



# Analyzing the cost (grow by 1)

- Count array accesses (reads and writes) of adding first  $n$  elements
  - will ignore the cost of allocating / deallocating arrays

n	append	copy

each row indicates the number of **reads and writes** necessary for appending an element into an **existing array of length n**

$$n + \sum_{i=0}^{n-1} 2i = n + n^2 - n$$

$$\Theta(n^2)$$



# Lets try again ...

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- If array is **full**, create an array of **twice the size**
  - ✓ **repeated doubling**
- If array is **one-quarter full**, **halve the size**
  - ✓ more efficient
  - ✓ **why not halving when array is one-half full?**

append - remove - append - remove - append - remove...

- Demo ...



# Analyzing the cost (doubling the array)

- Count array accesses (reads and writes) of adding first  $n = 2^i$  elements
  - will ignore the cost of allocating/deallocating arrays

n	append	copy

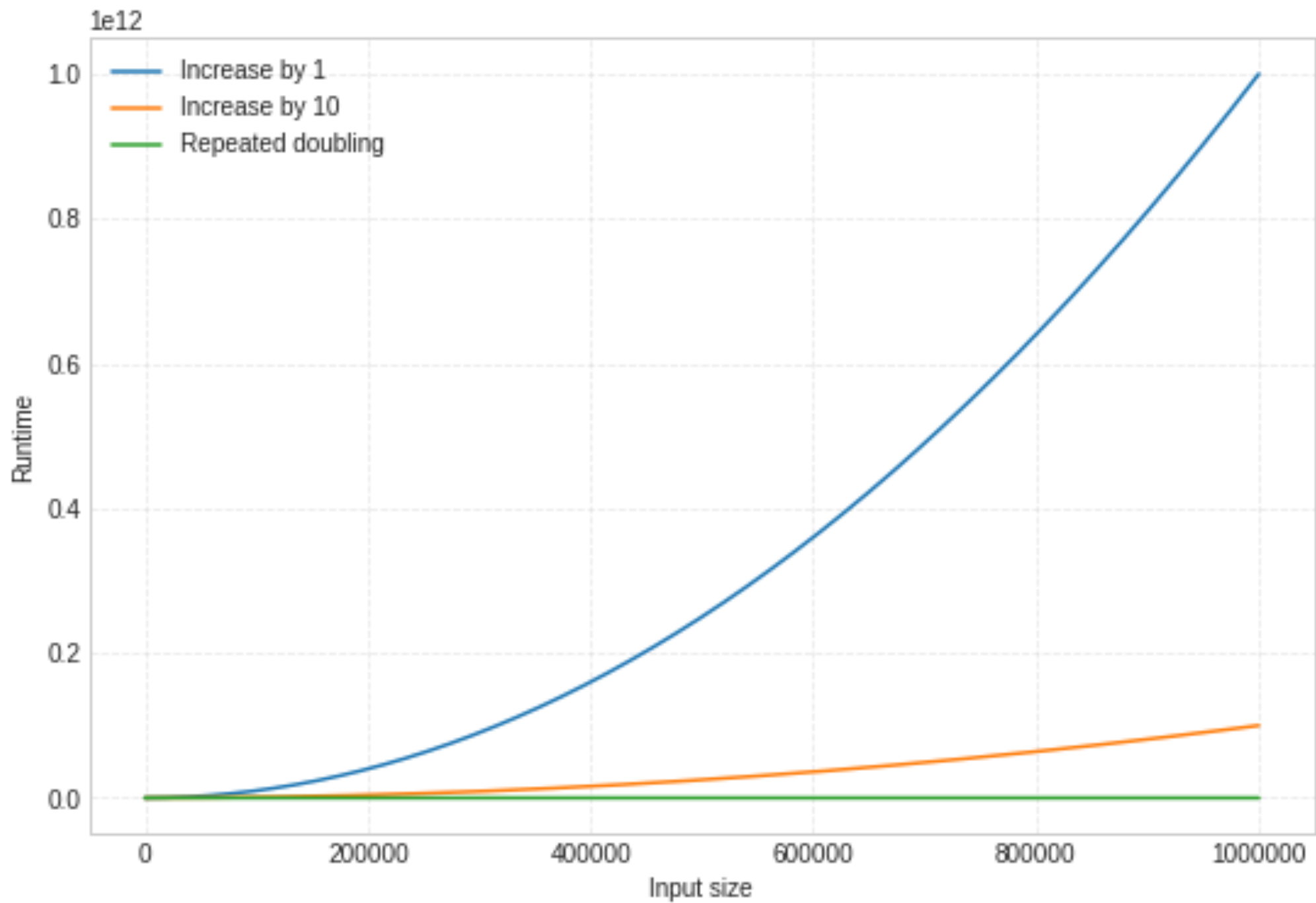
each row indicates the number of **reads and writes** necessary for appending an element into an **existing array of length n**

$\log n$

$$n + \sum_{i=1}^{\log n} 2^i = n + 2^{\log n + 1} - 1$$

$$\Theta(n)$$

$$\sum_{i=0}^n c^i = \frac{c^{n+1} - 1}{c - 1}$$



# Worst-case and average-case

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- Analysis for appending **a single element** using increase-by-1
- Analysis for appending **a single element** using repeated doubling