

# **CHAPTER 6**

## **Functions of Random Variables**

## Motivation

- All quantities used to estimate population parameters or to make decisions about a population are **functions of the  $n$  random observations** that appear in a sample.
- For example, we draw a random sample of  $n$  observations,  $y_1, y_2, \dots, y_n$ , from the population and employ the sample mean

$$\bar{y} = \frac{y_1 + y_2 + \dots + y_n}{n} = \frac{1}{n} \sum_{i=1}^n y_i$$

as an estimate for  $\mu$ .

- How good is this estimate?
  - Depends on the behavior of the random variables  $Y_1, Y_2, \dots, Y_n$  which affect on the distribution on

$$\bar{Y} = \frac{Y_1 + Y_2 + \dots + Y_n}{n} = \frac{1}{n} \sum_{i=1}^n Y_i$$

## Motivation

- A measure of the goodness of an estimate is the error of estimation, the difference between the estimate and the parameter estimated (for our example, the difference between  $y$  and  $\mu$ ).
- If we can determine **the probability distribution of the estimator  $\bar{Y}$**

$$\bar{Y} = \frac{Y_1 + Y_2 + \cdots + Y_n}{n} = \frac{1}{n} \sum_{i=1}^n Y_i$$

- which is a function of random variables.
- this probability distribution can be used to determine the probability that the error of estimation is less than or equal to  $B$ .
- To determine the probability distribution of  $n$  random variables,  $Y_1 + Y_2 + \cdots + Y_n$ , we must find the **joint probability distribution** for the random variables.
- We will assume that the random variables obtained through a **random sample**
  - $p(y_1, y_2, \dots, y_n) = p(y_1)p(y_2) \cdots p(y_n)$ .
  - $f(y_1, y_2, \dots, y_n) = f(y_1)f(y_2) \cdots f(y_n)$ .

### Motivation

- Consider random variables  $Y_1, Y_2, \dots, Y_n$  and a function  $U(Y_1, Y_2, \dots, Y_n)$ , denoted simply as  $U$ .
- Then three of the methods for finding the probability distribution of  $U$  are as follows:
  - The method of distribution functions:
  - The method of transformations
  - The method of moment-generating functions

## Procedure

### Distribution Function Method

Let  $U$  be a function of the random variables  $Y_1, Y_2, \dots, Y_n$ .

1. Find the region  $U = u$  in the  $(y_1, y_2, \dots, y_n)$  space.
2. Find the region  $U \leq u$ .
3. Find  $F_U(u) = P(U \leq u)$  by integrating  $f(y_1, y_2, \dots, y_n)$  over the region  $U \leq u$ .
4. Find the density function  $f_U(u)$  by differentiating  $F_U(u)$ . Thus,  $f_U(u) = \frac{dF_U(u)}{du}$ .

## The Method of Distribution Functions : Example

### EXAMPLE 6.1

A process for redefining sugar yields up to 1 ton of pure sugar per day, but the actual amount produced,  $Y$ , is a random variable because of machine breakdowns and other slowdowns. Suppose that  $Y$  has density function given by

$$f(y) = \begin{cases} 2y, & 0 \leq y \leq 1 \\ 0, & \text{elsewhere} \end{cases}.$$

The company is paid at the rate of \$300 per ton for the refined sugar, but it also has a fixed overhead cost of \$100 per day. Thus the daily profit, in hundreds of dollars, is  $U = 3Y - 1$ . Find the probability density function for  $U$ .

# The Method of Distribution Functions : Example

### SOLUTION 6.1

## The Method of Distribution Functions : Example

### EXAMPLE 6.2

In Example 5.4, we considered the random variables  $Y_1$  (the proportional amount of gasoline stocked at the beginning of a week) and  $Y_2$  (the proportional amount of gasoline sold during the week). The joint density function of  $Y_1$  and  $Y_2$  is given by

$$f(y) = \begin{cases} 3y_1, & 0 \leq y_2 \leq y_1 \leq 1 \\ 0, & \text{elsewhere} \end{cases}.$$

Find the probability density function for  $U = Y_1 - Y_2$ , the proportional amount of gasoline remaining at the end of the week. Use the density function of  $U$  to find  $E(U)$ .



# The Method of Distribution Functions : Example

### SOLUTION 6.2

### The Method of Distribution Functions : Example

#### EXAMPLE 6.3

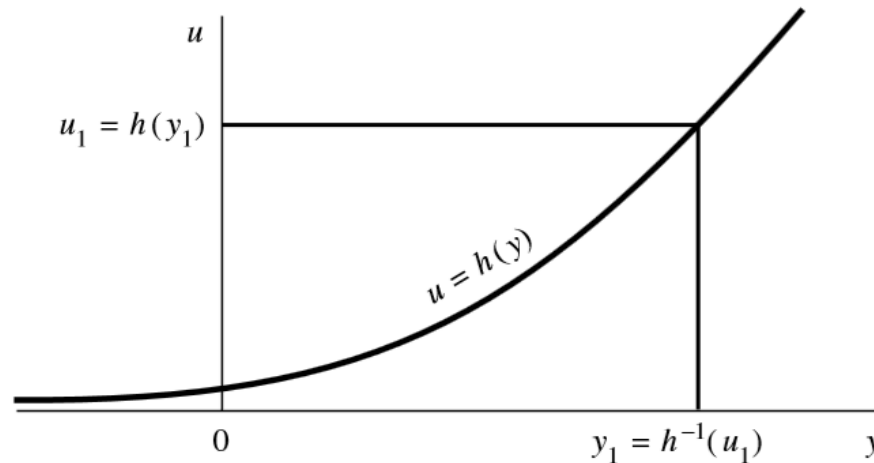
Let  $(Y_1, Y_2)$  denote a random sample of size  $n = 2$  from the uniform distribution on the interval  $(0,1)$ . Find the probability density function for  $U = Y_1 + Y_2$ .

# The Method of Distribution Functions : Example

### SOLUTION 6.3

## Motivation

- Through the distribution function approach, we can arrive at a simple method of writing down the density function of  $U = h(Y)$ , provided that  $h(y)$  is either decreasing or increasing.



$$P(U \leq u) = P[h(Y) \leq u] = P\{h^{-1}[h(Y)] \leq h^{-1}(u)\} = P[Y \leq h^{-1}(u)]$$

$$F_U(u) = F_Y[h^{-1}(u)].$$

- Then differentiating with respect to  $u$ , we have

$$f_U(u) = \frac{dF_U(u)}{du} = \frac{dF_Y[h^{-1}(u)]}{du} = f_Y(h^{-1}(u)) \frac{d[h^{-1}(u)]}{du}$$

## Procedure

### Summary of the Transformation Method

Let  $U = h(Y)$ , where  $h(y)$  is either an increasing or decreasing function of  $y$  for all  $y$  such that  $f_Y(y) > 0$ .

1. Find the inverse function,  $y = h^{-1}(u)$ .

2. Evaluate  $\frac{dh^{-1}}{du} = \frac{d[h^{-1}(u)]}{du}$ .

3. Find  $f_U(u)$  by

$$f_U(u) = f_Y[h^{-1}(u)] \left| \frac{dh^{-1}}{du} \right|.$$

## The Method of Transformations : Example

### EXAMPLE 6.6

In Example 6.1, we worked with a random variable  $Y$  (amount of sugar produced) with a density function given by

$$f(y) = \begin{cases} 2y, & 0 \leq y \leq 1 \\ 0, & \text{elsewhere} \end{cases}.$$

We were interested in a new random variable (profit) given by  $U = 3Y - 1$ . Find the probability density function for  $U$  by the transformation method.

### The Method of Transformations : Example

#### SOLUTION 6.6

## The Method of Transformations : Example

### EXAMPLE 6.7

Let  $Y$  have the probability density function given by

$$f(y) = \begin{cases} 2y, & 0 \leq y \leq 1 \\ 0, & \text{elsewhere} \end{cases}.$$

Find the density function of  $U = -4Y + 3$ .



### The Method of Transformations : Example

#### SOLUTION 6.7

## The Method of Transformations : Example

### EXAMPLE 6.8

Let  $Y_1$  and  $Y_2$  have a joint density function given by

$$f(y_1, y_2) = \begin{cases} e^{-(y_1+y_2)} & 0 \leq y_1, 0 \leq y_2 \\ 0, & \text{elsewhere} \end{cases}.$$

Find the density function for  $U = Y_1 + Y_2$ .

### The Method of Transformations : Example

#### SOLUTION 6.8

### Motivation

The roles of Moments:

- Moments can be used as numerical descriptive measures to describe the data that we obtain in an experiment
- Moments can be used in a theoretical sense to prove that a random variable possesses a particular probability distribution
  - If two random variables  $Y$  and  $Z$  possess identical moment-generating functions, then  $Y$  and  $Z$  possess identical probability distributions.

### Procedure

#### Summary of the Moment-Generating Functions Method

Let  $U$  be a function of the random variables  $Y_1, Y_2, \dots, Y_n$ .

1. Find the moment-generating function for  $U, m_U(t)$ .
2. Compare  $m_U(t)$  with other well-known moment-generating functions. If  $m_U(t) = m_V(t)$  for all values of  $t$ , Theorem 6.1 implies that  $U$  and  $V$  have identical distributions.

# Uniqueness of Moment-Generating Functions

### THEOREM 6.1

Let  $m_X(t)$  and  $m_Y(t)$  denote the moment-generating functions of random variables  $X$  and  $Y$ , respectively. If both moment-generating functions exist and  $m_X(t) = m_Y(t)$  for all values of  $t$ , then  $X$  and  $Y$  have the same probability distribution.

#### **Proof:**

Far beyond the scope of this course.

## The Method of Moment-Generating Functions : Example

### EXAMPLE 6.10

Suppose that  $Y$  is a normally distributed with mean  $\mu$  and variance  $\sigma^2$ . Show that

$$Z = \frac{Y - \mu}{\sigma}$$

has a *standard normal* distribution, a normal distribution with mean 0 and variance 1.

# Finding Moments using Moment Generating Function : Examples

### EXAMPLE 4.16

Let  $g(Y) = Y - \mu$ , where  $Y$  is a normally distributed random variable with mean  $\mu$  and variance  $\sigma^2$ . Find the moment-generating function for  $g(Y)$ .



## Finding Moments using Moment Generating Function : Examples

### SOLUTION 4.16

# The Method of Moment-Generating Functions : Example

### SOLUTION 6.10

### The Method of Moment-Generating Functions : Example

#### EXAMPLE 6.11

Let  $Z$  be a normally distributed random variable with mean 0 and variance 1. Use the method of moment-generating functions to find the probability distribution of  $Z^2$ .

## The Method of Moment-Generating Functions : Example

### SOLUTION 6.11

# Moment-Generating Functions of Sum of Random Variables

**THEOREM 6.2**

Let  $Y_1, Y_2, \dots, Y_n$  be independent random variables with moment-generating function  $m_{Y_1}(t), m_{Y_2}(t), \dots, m_{Y_n}(t)$ , respectively. If  $U = Y_1 + Y_2 + \dots + Y_n$ , then

$$m_U(t) = m_{Y_1}(t) \times m_{Y_2}(t) \times \dots \times m_{Y_n}(t).$$

**Proof:**

## The Method of Moment-Generating Functions : Example

### EXAMPLE 6.12

The number of customer arrivals at a checkout counter in a given interval of time possesses approximately a Poisson probability distribution (see Section 3.8). If  $Y_1$  denotes the time until the first arrival,  $Y_2$  denotes the time between the first and second arrival,  $\dots$ , and  $Y_n$  denotes the time between the  $(n - 1)$ st and  $n$ th arrival, then it can be shown that  $Y_1, Y_2, \dots, Y_n$  are independent random variables, with the density function for  $Y_i$  given by

$$f_{Y_i}(y_i) = \begin{cases} \frac{1}{\theta} e^{-y_i/\theta}, & y_i > 0 \\ 0, & \text{otherwise} \end{cases}.$$

[Because the  $Y_i$ , for  $i = 1, 2, \dots, n$ , are exponentially distributed, it follows that  $E(Y_i) = \theta$ ; that is,  $\theta$  is the average time between arrivals.] Find the probability density function for the waiting time from the opening of the counter until the  $n$ th customer arrives. (If  $Y_1, Y_2, \dots$  denote successive interarrival times, we want the density function of  $U = Y_1 + Y_2 + \dots + Y_n$ .)

# The Method of Moment-Generating Functions : Example

### SOLUTION 6.12

# Moment-Generating Functions of Sum of Random Variables

## THEOREM 6.3

Let  $Y_1, Y_2, \dots, Y_n$  be independent normally distributed random variables with  $E(Y_i) = \mu_i$  and  $V(Y_i) = \sigma_i^2$ , for all  $i = 1, 2, \dots, n$ , and let  $a_1, a_2, \dots, a_n$  be constants. If

$$U = \sum_{i=1}^n a_i Y_i = a_1 Y_1 + a_2 Y_2 + \cdots + a_n Y_n,$$

then  $U$  is a normally distributed random variable with

$$E(U) = \sum_{i=1}^n a_i \mu_i = a_1 \mu_1 + \cdots + a_n \mu_n$$

and

$$V(U) = \sum_{i=1}^n a_i^2 \sigma_i^2 = a_1^2 \sigma_1^2 + \cdots + a_n^2 \sigma_n^2.$$



# Moment-Generating Functions of Sum of Random Variables

**Proof:**

## Moment-Generating Functions of Sum of Random Variables

### THEOREM 6.4

Let  $Y_1, Y_2, \dots, Y_n$  be independent normally distributed random variables with  $E(Y_i) = \mu_i$  and  $V(Y_i) = \sigma_i^2$ , for all  $i = 1, 2, \dots, n$ , and define  $Z_i$  by

$$Z_i = \frac{Y_i - \mu_i}{\sigma_i}, \quad i = 1, 2, \dots, n.$$

Then  $\sum_{i=1}^n Z_i^2$  has a  $\chi^2$  distribution with  $n$  degrees of freedom.

**Proof:**

# Moment-Generating Functions of Sum of Random Variables

**Proof:**

## The Bivariate Transformation Method

### The Bivariate Transformation Method

Suppose that  $Y_1$  and  $Y_2$  are continuous random variables with joint density function  $f_{Y_1, Y_2}(y_1, y_2)$  and that for all  $(y_1, y_2)$ , such that  $f_{Y_1, Y_2}(y_1, y_2) > 0$ ,

$$u_1 = h_1(y_1, y_2) \quad \text{and} \quad u_2 = h_2(y_1, y_2)$$

is a one-to-one transformation from  $(y_1, y_2)$  to  $(u_1, u_2)$  with inverse

$$y_1 = h_1^{-1}(u_1, u_2) \quad \text{and} \quad y_2 = h_2^{-1}(u_1, u_2).$$

If  $h_1^{-1}(u_1, u_2)$  and  $h_2^{-1}(u_1, u_2)$  have continuous partial derivatives with respect to  $u_1$  and  $u_2$  and *Jacobian*

$$J = \det \begin{bmatrix} \frac{\partial h_1^{-1}}{\partial u_1} & \frac{\partial h_1^{-1}}{\partial u_2} \\ \frac{\partial h_2^{-1}}{\partial u_1} & \frac{\partial h_2^{-1}}{\partial u_2} \end{bmatrix} = \frac{\partial h_1^{-1}}{\partial u_1} \frac{\partial h_2^{-1}}{\partial u_2} - \frac{\partial h_2^{-1}}{\partial u_1} \frac{\partial h_1^{-1}}{\partial u_2} \neq 0,$$

then the joint density of  $U_1$  and  $U_2$  is

$$f_{U_1, U_2}(u_1, u_2) = f_{Y_1, Y_2}(h_1^{-1}(u_1, u_2), h_2^{-1}(u_1, u_2)) |J|,$$

where  $|J|$  is the absolute value of the Jacobian.

# Motivation

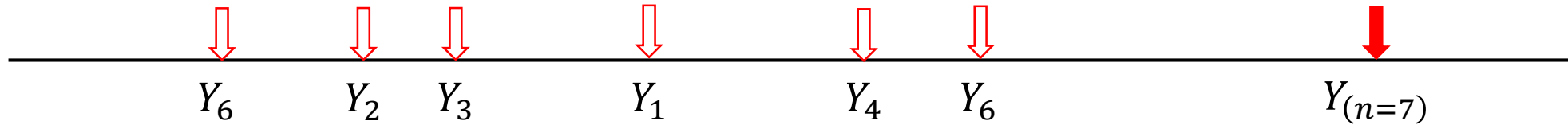
- Many functions of random variables of interest in practice depend on **the relative magnitudes of the observed variables**.
- For instance, we may be interested in
  - the fastest time in an automobile race or
  - the heaviest mouse among those fed on a certain diet.
- Thus, we often order observed random variables according to their magnitudes. The resulting ordered variables are called order statistics.



## Derivations

- Formally, let  $Y_1, Y_2, \dots, Y_n$  denote independent continuous random variables with distribution function  $F(y)$  and density function  $f(y)$ .
- We denote the ordered random variables  $Y_i$  by  $Y_{(1)}, Y_{(2)}, \dots, Y_{(n)}$ , where  $Y_{(1)} \leq Y_{(2)} \leq \dots \leq Y_{(n)}$ .
  - $Y_{(1)} = \min(Y_1, Y_2, \dots, Y_n)$
  - $Y_{(n)} = \max(Y_1, Y_2, \dots, Y_n)$

## Derivations



- The event  $(Y_{(n)} \leq y)$  will occur if and only if the events  $(Y_i \leq y)$  occur for every  $i = 1, 2, \dots, n$ . That is,

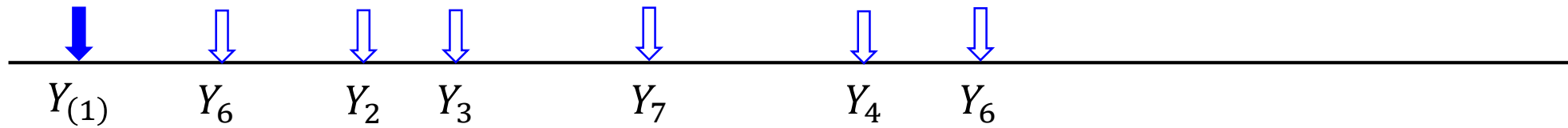
$$P(Y_{(n)} \leq y) = P(Y_1 \leq y, Y_2 \leq y, \dots, Y_n \leq y)$$

$$F_{Y_{(n)}}(y) = P(Y_{(n)} \leq y) = P(Y_1 \leq y)P(Y_2 \leq y) \cdots P(Y_n \leq y) = [F(y)]^n.$$

- Letting  $g_{(n)}(y)$  denote the density function of  $Y_{(n)}$ , we see that, on taking derivatives of both sides

$$g_{(n)}(y) = n[F(y)]^{n-1}f(y)$$

## Derivations



- The distribution function of  $Y_{(1)}$  is

$$P(Y_{(1)} \leq y) = 1 - P(Y_{(1)} > y)$$

- Because  $Y_{(1)}$  is the minimum of  $Y_1, Y_2, \dots, Y_n$ , it follows that the event  $(Y_{(1)} > y)$  occurs if and only if the events  $(Y_i > y)$  occur for  $i = 1, 2, \dots, n$ .
- Because the  $Y_i$  are independent and  $P(Y_i > y) = 1 - F(y)$  for  $i = 1, 2, \dots, n$ , we see that

$$\begin{aligned} F_{Y_{(1)}}(y) &= P(Y_{(1)} \leq y) = 1 - P(Y_{(1)} > y) \\ &= 1 - P(Y_1 > y, Y_2 > y, \dots, Y_n > y) \\ &= 1 - [P(Y_1 > y)P(Y_2 > y) \cdots P(Y_n > y)] \\ &= 1 - [1 - F(y)]^n. \end{aligned}$$

$$g_{(1)}(y) = n[1 - F(y)]^{n-1} f(y).$$



## Order Statistics : Example

### EXAMPLE 6.16

Electronic components of a certain type have a length of life  $Y$ , with probability density given by

$$f(y) = \begin{cases} (1/100)e^{-y/100}, & y > 0 \\ 0, & \text{elsewhere} \end{cases}.$$

(Length of life is measured in hours.) Suppose that two such components operate independently and in series in a certain system (hence, the system fails when either component fails). Find the density function for  $X$ , **the length of life of the system**.

### Order Statistics : Example

#### SOLUTION 6.16

## Order Statistics : Example

### EXAMPLE 6.17

Suppose that the components in Example 6.16 operate in parallel (hence, the system does not fail until both components fail). Find the density function for  $X$ , the length of life of the system.

### Order Statistics : Example

#### SOLUTION 6.17

## Density of Order Statistics

### THEOREM 6.5

Let  $Y_1, Y_2, \dots, Y_n$  be independent identically distributed continuous random variables with common distribution function  $F(y)$  and common density function  $f(y)$ . If  $Y_{(k)}$  denotes the  $k$ th-order statistics, then the density function of  $Y_{(k)}$  is given by

$$g_{(k)}(y_k) = \frac{n!}{(k-1)!(n-k)!} [F(y_k)]^{k-1} [1 - F(y_k)]^{n-k} f(y_k), \quad y_k \in (-\infty, \infty).$$

If  $j$  and  $k$  are two integers such that  $1 \leq j < k \leq n$ , the joint density of  $Y_{(j)}$  and  $Y_{(k)}$  is given by

$$\begin{aligned} & g_{(j)(k)}(y_j, y_k) \\ &= \frac{n!}{(j-1)!(k-1-j)!(n-k)!} [F(y_j)]^{j-1} [F(y_k) - F(y_j)]^{k-1-j} [1 - F(y_k)]^{n-k} f(y_j) f(y_k), \\ & -\infty < y_j < y_k < \infty. \end{aligned}$$

**Proof: Omitted.**

## Order Statistics : Example

### EXAMPLE 6.18

Suppose that  $Y_1, Y_2, \dots, Y_5$  denotes a random sample from a uniform distribution defined on the interval  $(0,1)$ . That is,

$$f(y) = \begin{cases} 1, & 0 \leq y \leq 1 \\ 0, & \text{elsewhere} \end{cases}$$

Find the density function for the second-order statistic. Also, give the joint density function for the second- and fourth- order statistics.

## Order Statistics : Example

## SOLUTION 6.18

The distribution function associated with each of the  $Y$ 's is

$$F(y) = \begin{cases} 0, & y < 0 \\ y, & 0 \leq y \leq 1. \\ 1, & y > 1 \end{cases}$$

From Theorem 6.5, with  $n = 5, k = 2$ ,

$$\begin{aligned} g_{(2)}(y_2) &= \frac{5!}{(2-1)!(5-2)!} [F(y_2)]^{2-1} [1 - F(y_2)]^{5-2} f(y_2), & -\infty < y_2 < \infty \\ &= \begin{cases} 20y_2(1 - y_2)^3, & 0 \leq y_2 \leq 1 \\ 0, & \text{elsewhere} \end{cases} \end{aligned}$$

The preceding density is a beta density with  $\alpha = 2$  and  $\beta = 4$ .

## Order Statistics : Example

**SOLUTION 6.18**

The joint density of the second- and fourth- order statistics is readily obtained from Theorem 6.5, with  $j = 2$ ,  $k = 4$ , and  $n = 5$ ;

$$\begin{aligned}
 & g_{(2)(4)}(y_2, y_4) \\
 &= \frac{5!}{(2-1)!(4-2-1)!(5-4)!} [F(y_2)]^{2-1} [F(y_4) - F(y_2)]^{4-2-1} [1 - F(y_4)]^{5-4} f(y_2) f(y_4), \\
 & \quad -\infty < y_2 < y_4 < \infty \\
 &= \begin{cases} 5! y_2 (y_4 - y_2) (1 - y_4), & 0 \leq y_2 < y_4 \leq 1 \\ 0, & \text{elsewhere} \end{cases}
 \end{aligned}$$