

# Financial Econometrics

## Lecture 4

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# Outline

Nonstationary and Long Memory ARMA Processes

Fitting ARMA Models

Model Diagnostics: Residual Analysis

# Random Walks

A random walk (without drift) is defined as

$$X_t = X_{t-1} + \epsilon_t$$

where  $\epsilon_t \sim WN(0, \sigma^2)$ . Using backshift operator, we have

$$(1 - B) X_t = \epsilon_t \Leftrightarrow X_t = \sum_{j=0}^{\infty} \epsilon_{t-j}$$

It is easy to obtain that (assume  $\epsilon_t = 0$  for all  $t \leq 0$ )

$$Var(X_t) = \sum_{j=0}^{t-1} Var(\epsilon_{t-j}) = t\sigma^2, Cov(X_t, X_{t+k}) = Var(X_t) = t\sigma^2$$

$$Corr(X_t, X_{t+k}) = \frac{t\sigma^2}{\sqrt{t\sigma^2(t+k)\sigma^2}} = \frac{t}{\sqrt{t(t+k)}} \rightarrow 1, t \rightarrow \infty$$

# ARIMA Models

Let  $\nabla$  denote the *difference operator*, i.e.,

$$\nabla X_t \equiv X_t - X_{t-1}$$

and

$$\nabla^d X_t \equiv \nabla(\nabla^{d-1} X_t)$$

for all integer  $d \geq 1$ .

If  $\nabla^d X_t$  is a stationary ARMA( $p, q$ ),  $X_t$  is called an *autoregressive integrated moving average* (ARIMA) model denoted as  $X_t \sim \text{ARIMA}(p, d, q)$ .

**Example: ARIMA(0,1,1)**

$$X_t - X_{t-1} = \epsilon_t - \theta\epsilon_{t-1}, |\theta| < 1$$

where  $\epsilon_t \sim WN(0, \sigma^2)$ .

# ARIMA Models

## Example: ARIMA(0,1,1)

Using the backshift operator, it is easy to verify that  $X_t \sim \text{AR}(\infty)$  with coefficients  $(1 - \theta)\theta^k$ , i.e.,

$$X_t = (1 - \theta)(X_{t-1} + \theta X_{t-2} + \theta^2 X_{t-3} + \cdots) + \epsilon_t$$

Note that  $\sum_{k=0}^{\infty} (1 - \theta)\theta^k = 1$ . Hence the weights decay and sum up to 1.

The “best” predictor (in the mean square error sense) of  $X_{t+1}$  is

$$E(X_{t+1} | X_t, X_{t-1}, \dots) = (1 - \theta)(X_t + \theta X_{t-1} + \theta^2 X_{t-2} + \cdots)$$

which is called *exponential smoothing* and widely used in practice.

See time series simulated from random walk and ARIMA(0,1,1) [[R code](#)].

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# Least Square Estimation for AR( $p$ ) Models

Consider the AR( $p$ ) model

$$X_t = b_0 + b_1 X_{t-1} + \cdots + b_p X_{t-p} + \epsilon_t, \epsilon_t \sim WN(0, \sigma^2)$$

With observations  $\{X_t\}_{t=1}^T$ , we can estimate parameters  $b \equiv (b_0, b_1, \dots, b_p)$  via a linear regression:

$$\hat{b} \equiv (\hat{b}_0, \hat{b}_1, \dots, \hat{b}_p) = \arg \min_{b \in \mathbb{R}^{p+1}} \sum_{t=p+1}^T (X_t - b_0 - b_1 X_{t-1} - \cdots - b_p X_{t-p})^2$$

which is called the *least square estimator* (LSE) for  $b$ .

Note that both  $\hat{b}$  and  $\widehat{Var}(\hat{b})$  have explicit expressions. Hypothesis tests can be conducted easily.

# Least Square Estimation for AR( $p$ ) Models

Once  $\hat{b}$  is obtained, we can compute the LSE for  $\sigma^2$  by

$$\hat{\sigma}^2 = \frac{1}{T - 2p - 1} \sum_{t=p+1}^T \left( X_t - \hat{b}_0 - \hat{b}_1 X_{t-1} - \cdots - \hat{b}_p X_{t-p} \right)^2$$

where the divider is  $T - 2p - 1$  because the effective sample size is  $T - p$  and the number of parameters is  $p + 1$ .



# Least Square Estimation for ARMA( $p, q$ ) Model

Consider the ARMA( $p, q$ ) model

$$X_t = b_0 + b_1 X_{t-1} + \cdots + b_p X_{t-p} + \epsilon_t + a_1 \epsilon_{t-1} + \cdots + a_q \epsilon_{t-q}$$

where  $\epsilon_t \sim WN(0, \sigma^2)$  and  $\epsilon_{p+1-k}$  is assumed to be 0 for all  $1 \leq k \leq q$ .

Let  $a \equiv (a_1, \dots, a_q)$  and  $b \equiv (b_0, b_1, \dots, b_p)$ . We can compute the LSE for  $(a, b)$  using the iterative algorithm below:

## Iterative Linear Approximation

(1) Start from initial values of  $\epsilon_{p+1-q} = 0, \dots, \epsilon_p = 0$ . For  $t \geq p+1$ , Define

$$\epsilon_t(a, b) = X_t - b_0 - \sum_{j=1}^p b_j X_{t-j} - \sum_{l=1}^q a_l \epsilon_{t-l}(a, b)$$

# Least Square Estimation for ARMA( $p, q$ ) Model

## Iterative Linear Approximation

- (2) Compute the following iterative estimator with some starting values  $(a, b) = (\bar{a}, \bar{b})$ :

$$\begin{aligned} & (\hat{a}_k, \hat{b}_k) \\ &= \arg \min_{a, b} \sum_{t=p+1}^T [\epsilon_t(\hat{a}_{k-1}, \hat{b}_{k-1})]^2 \\ &= \arg \min_{a, b} \sum_{t=p+1}^T [X_t - b_0 - \sum_{j=1}^p b_j X_{t-j} - \sum_{l=1}^q a_l \epsilon_{t-l}(\hat{a}_{k-1}, \hat{b}_{k-1})]^2 \end{aligned}$$

for  $k = 1, 2, \dots$ , where  $\epsilon_t(\cdot)$  is defined in (1).

- (3) Repeat (2) till  $(\hat{a}_k, \hat{b}_k) \approx (\hat{a}_{k-1}, \hat{b}_{k-1})$ .

# Gaussian Maximum Likelihood Estimation

If we assume  $\epsilon_t \stackrel{iid}{\sim} N(0, \sigma^2)$ , then  $\theta \equiv (a, b, \sigma^2)$  can be more efficiently estimated using the Gaussian maximum likelihood estimation, and the resulting estimator is called the *maximum likelihood estimator* (MLE).

Consider a general ARMA( $p, q$ ) model:

$$X_t = b_0 + b_1 X_{t-1} + \cdots + b_p X_{t-p} + \epsilon_t + a_1 \epsilon_{t-1} + \cdots + a_q \epsilon_{t-q}$$

Let  $X^t \equiv (X_1, \dots, X_t)$  for all  $1 \leq t \leq T$ . We define the likelihood function for the model as

$$\begin{aligned} L(\theta) &\equiv f(X^T; \theta) \\ &= f(X_T; \theta | X^{T-1}) \times f(X_{T-1}; \theta | X^{T-2}) \times \cdots \times f(X_{p+1}; \theta | X^p) \times f(X^p) \end{aligned}$$

Taking log and dropping the “constant” term  $\log f(X^p)$  leads to the log-likelihood function for the model.

# Gaussian Maximum Likelihood Estimation

$$l(\theta) \equiv \log L(\theta) - \log f(X^p) = \sum_{t=p+1}^T \log f(X_t; \theta | X^{t-1})$$

Given  $\epsilon_t \stackrel{iid}{\sim} N(0, \sigma^2)$ ,  $f(X_t; \theta | X^{t-1})$  has explicit expression. Then we can employ a Newton-Raphson algorithm to compute the Gaussian MLE via the following optimization procedure:

$$\hat{\theta} = \arg \max_{\theta} l(\theta) = \arg \max_{\theta} \sum_{t=p+1}^T \log f(X_t; \theta | X^{t-1})$$

The covariance matrix of  $\hat{\theta}$  can be consistently estimated as

$$\widehat{Var}(\hat{\theta}) = -\ddot{l}(\hat{\theta})^{-1}$$

where  $\ddot{l}(\cdot)$  is the Hessian matrix of the log-likelihood function  $l(\cdot)$ .

# Gaussian Maximum Likelihood Estimation

Under mild conditions,

- Gaussian MLE is consistent and asymptotically normal.
- Gaussian MLE is often used when  $\epsilon_t$  is not normal. The resulting estimator is called *quasi-MLE*.
- Gaussian MLE is more efficient than LSE as it makes (and make uses of) stronger assumption.
- Statistical inference on  $g(\hat{\theta})$  can be done using the *Delta method* when  $g(\cdot)$  is differentiable.

$$\widehat{Var}(g(\hat{\theta})) \approx -\dot{g}(\hat{\theta})' \ddot{l}(\hat{\theta})^{-1} \dot{g}(\hat{\theta})$$

where  $\dot{g}(\cdot)$  is the gradient or Jacobian of  $g(\cdot)$ .

Now let's apply LSE and MLE to an empirical example [[R code](#)].

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# Model Diagnostics

Model Diagnostics is important as it can help check if the specification of a time series model is appropriate.

The key idea is straightforward: if a  $ARMA(p, q)$  model is adequate for an observed data, the residuals

$$\hat{\epsilon}_t = X_t - \sum_{j=1}^p \hat{b}_j X_{t-j} - \sum_{l=1}^q \hat{a}_l \hat{\epsilon}_{t-l}, t = p+1, \dots, T$$

with  $\hat{\epsilon}_{p+1-q} = 0, \dots, \hat{\epsilon}_p = 0$  should behave like white noise.

## Residual Analysis

Visual diagnostics

- Residual plot, i.e., plotting  $\hat{\epsilon}_t$  (more often standardized,  $\hat{\epsilon}_t / \widehat{SE}(\hat{\epsilon}_t)$ ) against time  $t$ .

# Model Diagnostics

## Residual Analysis

- Plot  $\hat{\epsilon}_t$  against the fitted values  $\hat{X}_t$ .
- ACF, PACF, EACF.
- QQ plots for diagnosing normality assumption.

Statistical tests for white noise

- Perform the Ljung-Box tests for white noise.

The `tsdiag()` function coming with R is designed for conducting time series diagnostics [[R code](#)].