

# Financial Econometrics I

## Lecture 4

Fu Ouyang

December 7, 2018

# Outline

Nonstationary ARMA Processes

Forecasting

# Stochastic and Deterministic Trends

Consider the following two processes:

- Stochastic trend:  $X_t = X_{t-1} + \epsilon_t$  (random walk) with  $\epsilon_t \stackrel{iid}{\sim} N(0, 1)$ .
- Deterministic trend:  $Y_t = 0.1t + \epsilon_t$  with  $\epsilon_t \stackrel{iid}{\sim} N(0, 1)$ .

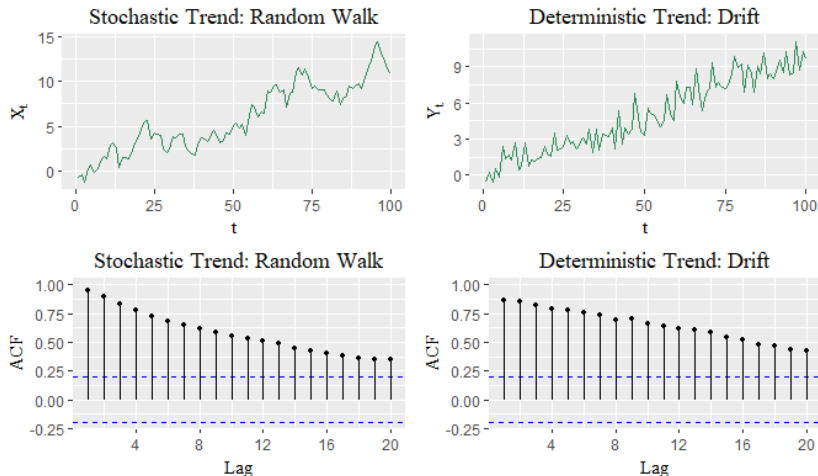
The two processes are both nonstationary as

- $Corr(X_t, X_{t+k}) = t/\sqrt{t(t+k)} > 0$ .
- $E(Y_t) = 0.1t$ .

It is obvious that  $Y_t$  has a deterministic trend  $0.1t$ . As for  $X_t$ , note that  $X_t = X_0 + \sum_{s=1}^t \epsilon_s$ , and so it has a stochastic trend  $\sum_{s=1}^t \epsilon_s$ . However, these two processes exhibit similar time series plots and ACF.

# Stochastic and Deterministic Trends

Figure 1: Stochastic Trend vs. Deterministic Trend



# Random Walks

A *random walk* (without drift) is defined as

$$X_t = X_{t-1} + \epsilon_t$$

where  $\epsilon_t \sim WN(0, \sigma^2)$ . Using backshift operator, we have

$$(1 - B) X_t = \epsilon_t \Leftrightarrow X_t = \sum_{j=0}^{\infty} \epsilon_{t-j}$$

It is easy to obtain that (assume  $\epsilon_t = 0$  for all  $t \leq 0$ )

$$Var(X_t) = \sum_{j=0}^{t-1} Var(\epsilon_{t-j}) = t\sigma^2, Cov(X_t, X_{t+k}) = Var(X_t) = t\sigma^2$$

$$Corr(X_t, X_{t+k}) = \frac{t\sigma^2}{\sqrt{t\sigma^2(t+k)\sigma^2}} = \frac{t}{\sqrt{t(t+k)}} \rightarrow 1, t \rightarrow \infty$$

# ARIMA Models

Let  $\nabla$  denote the *difference operator*, i.e.,

$$\nabla X_t \equiv X_t - X_{t-1}$$

and

$$\nabla^d X_t \equiv \nabla(\nabla^{d-1} X_t)$$

for all integer  $d \geq 1$ .

If  $\nabla^d X_t$  is a stationary ARMA( $p, q$ ),  $X_t$  is called an *autoregressive integrated moving average* (ARIMA) model denoted as  $X_t \sim \text{ARIMA}(p, d, q)$ .

**Example: ARIMA(0,1,1)**

$$X_t - X_{t-1} = \epsilon_t - \theta\epsilon_{t-1}, |\theta| < 1$$

where  $\epsilon_t \sim WN(0, \sigma^2)$ .

# ARIMA Models

## Example: ARIMA(0,1,1)

Using the backshift operator, it is easy to verify that  $X_t \sim \text{AR}(\infty)$  with coefficients  $(1 - \theta)\theta^k$ , i.e.,

$$X_t = (1 - \theta)(X_{t-1} + \theta X_{t-2} + \theta^2 X_{t-3} + \cdots) + \epsilon_t$$

Note that  $\sum_{k=0}^{\infty} (1 - \theta)\theta^k = 1$ . Hence the weights decay and sum up to 1.

The “best” predictor (in the mean square error sense) of  $X_{t+1}$  is

$$E(X_{t+1} | X_t, X_{t-1}, \dots) = (1 - \theta)(X_t + \theta X_{t-1} + \theta^2 X_{t-2} + \cdots)$$

which is called *exponential smoothing* and widely used in practice.

# Trend Removal

The slow decay of the sample ACF is often a signal for nonstationarity of a process due to either stochastic or deterministic trend.

For a process with only deterministic trend, e.g.,

$$Y_t = \beta_0 + \beta_1 t + e_t$$

One can run a linear regression and obtain the OLS estimate  $\hat{\beta}_1$  of  $\beta_1$  first, and then work on  $Z_t = Y_t - \hat{\beta}_1 t$ .

A more commonly used (and safer) method is differencing, i.e., working on ARIMA models. For example,

- Stochastic:  $X_t = X_{t-1} + \epsilon_t + \theta\epsilon_{t-1} \Rightarrow \nabla X_t = \epsilon_t + \theta\epsilon_{t-1} \sim \text{MA}(1)$ .
- Deterministic:  $Y_t = \beta t + e_t \Rightarrow \nabla Y_t = \beta + e_t - e_{t-1} \sim \text{MA}(1)$ .
- Quadratic deterministic trend:  $Y_t = \beta_1 t^2 + \beta_2 t + e_t \Rightarrow \nabla^2 Y_t \sim \text{MA}(2)$ .



# ADF Tests

Differencing is often used to restore stationarity and results in some ARIMA model for fitting of the data.

The *augmented Dickey-Fuller* (ADF) *test* is used to determine if differencing is necessary and/or identify the existence of a deterministic trend.

The ADF test is based on the following models:

- (Type 1)  $X_t = \alpha X_{t-1} + \beta_1 \nabla X_{t-1} + \cdots + \beta_p \nabla X_{t-p} + \epsilon_t$ .
- (Type 2)  $X_t = \mu + \alpha X_{t-1} + \beta_1 \nabla X_{t-1} + \cdots + \beta_p \nabla X_{t-p} + \epsilon_t$ .
- (Type 3)  $X_t = \mu + \beta_0 t + \alpha X_{t-1} + \beta_1 \nabla X_{t-1} + \cdots + \beta_p \nabla X_{t-p} + \epsilon_t$ .

The null hypothesis is  $H_0 : \alpha = 1$  (vs.  $H_1 : \alpha < 1$ ). Define the testing statistic

$$W = \frac{\hat{\alpha} - 1}{SE(\hat{\alpha})}$$

The according critical values can be found in page 25 of the textbook.

## ADF Tests

Random Walk						
	Type 1		Type 2		Type 3	
	ADF	p-value	ADF	p-value	ADF	p-value
$p = 0$	0.301	0.729	-1.460	0.536	-3.190	0.094
$p = 1$	0.280	0.723	-1.460	0.536	-3.320	0.071
$p = 2$	0.305	0.730	-1.630	0.472	-3.440	0.052

Deterministic Trend						
	Type 1		Type 2		Type 3	
	ADF	p-value	ADF	p-value	ADF	p-value
$p = 0$	-0.645	0.448	-2.470	0.147	-10.730	< 0.01
$p = 1$	0.482	0.781	-1.300	0.591	-6.770	< 0.01
$p = 2$	1.135	0.930	-1.080	0.668	-5.190	< 0.01

# Seasonality

Some financial time series are characteristic of periodic behavior. A typical example is the *seasonality*, i.e., the data exhibit seasonal pattern.

One can use the seasonal difference to remove the seasonal effect, e.g.,

$$\nabla_4 X_t \equiv (1 - B^4)X_t = X_t - X_{t-4}$$

More generally, seasonal difference with periodicity  $m$  applies the operator  $\nabla_m \equiv (1 - B^m)$ .

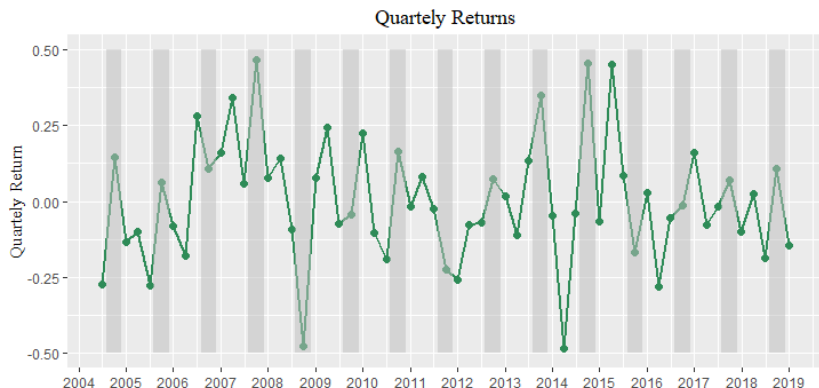
Stochastic trend, deterministic trend and seasonality can be removed simultaneously, e.g.,

$$(1 - B^4)(1 - B)X_t = (X_t - X_{t-4}) - (X_{t-1} - X_{t-5})$$

The resulting series then can be fitted directly to an ARMA model.

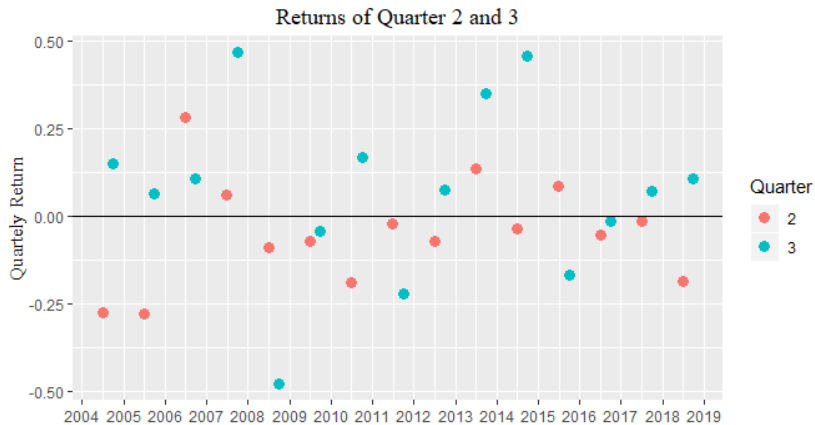
# Seasonality

Figure 2: Periodic Behavior (Seasonality)



# Seasonality

Figure 3: Periodic Behavior (Seasonality)



# Outline

Nonstationary ARMA Processes

Forecasting

# Forecasting

One of the primary goals in time series analysis is to forecast the future values based on the historical data.

Consider predicting  $X_{T+k}$  for  $k \geq 1$  based on  $X^T \equiv \{X_T, X_{T-1}, \dots, X_1\}$ .

Denote by  $X_T(k)$  the predictor for  $X_{T+k}$ . When  $X_T(k)$  minimizes the *mean squared predictive error* (MSPE), i.e.,

$$X_T(k) = \arg \inf_{f \in \mathcal{F}} E[(X_{T+k} - f(X^T))^2]$$

$X_T(k)$  is called the *least squares predictor*. It is not hard to show that

$$X_T(k) = E[X_{T+k} | X^T]$$

when  $E[X_{T+k} | X^T] = \beta_0 + \beta_1 X_1 + \dots + \beta_T X_T$ ,  $X_T(k)$  is called the *best linear predictor*.

# Forecasting AR(1) Processes

Consider an AR(1) model:

$$X_t = bX_{t-1} + \epsilon_t$$

where  $|b| < 1$  and  $\epsilon_t \sim WN(0, \sigma^2)$ . Assume the unpredictable condition (mean independence)

$$E[\epsilon_t | X_{t-1}, X_{t-2}, \dots] = 0$$

Let  $E_T[\cdot] \equiv E[\cdot | \Omega_T]$  be the conditional expectation given the information up to time  $T$ ,  $\Omega_T$ . Here  $\Omega_T = \{X_T, X_{T-1}, \dots\}$ .

Then the one-step ahead predictor and its MSPE are

$$X_T(1) = E_T[bX_T + \epsilon_{T+1}] = bX_T$$

$$\text{MSPE}[X_T(1)] = E[(X_{T+1} - X_T(1))^2] = E(\epsilon_{T+1}^2) = \sigma^2$$



# Forecasting AR(1) Processes

More generally, for any  $k \geq 1$ , by recursive substitution,

$$X_{T+k} = b^k X_T + \epsilon_{T+k} + b\epsilon_{T+k-1} + \cdots + b^{k-1}\epsilon_{T+1}$$

Then

$$X_T(k) = E_T[b^k X_T + \epsilon_{T+k} + b\epsilon_{T+k-1} + \cdots + b^{k-1}\epsilon_{T+1}] = b^k X_T$$

and

$$\begin{aligned}\text{MSPE}[X_T(k)] &= E[(X_{T+k} - X_T(k))^2] \\ &= E[(\epsilon_{T+k} + b\epsilon_{T+k-1} + \cdots + b^{k-1}\epsilon_{T+1})^2] \\ &= (1 + b^2 + \cdots + b^{2(k-1)})\sigma^2\end{aligned}$$

Hence

$$X_{T+k} \stackrel{a}{\sim} N(X_T(k), (1 + b^2 + \cdots + b^{2(k-1)})\sigma^2)$$

# Forecasting AR(1) Processes

## Summary for AR(1) Forecasting

$$X_T(k) = b^k X_T$$

$$\text{MSPE}[X_T(k)] = (1 + b^2 + \dots + b^{2(k-1)})\sigma^2$$

$$X_{T+k} \stackrel{a}{\sim} N(X_T(k), (1 + b^2 + \dots + b^{2(k-1)})\sigma^2)$$

When  $k$  increases (long term forecasting),

- $\text{MSPE}[X_T(k)] \nearrow$ .
- $X_T(k) \xrightarrow{p} 0 = E(X_{T+k})$ , as  $k \rightarrow \infty$ .
- $\text{MSPE}[X_T(k)] \rightarrow \sigma^2/(1 - b^2) = \text{Var}(X_{T+k})$ , as  $k \rightarrow \infty$ .

In practice, both  $b$  and  $\sigma^2$  are replaced by their estimates.

# Forecasting ARMA( $p, q$ ) Processes

Consider a causal and invertible ARMA( $p, q$ ) model

$$X_t - b_1 X_{t-1} - \cdots - b_p X_{t-p} = \epsilon_t + a_1 \epsilon_{t-1} + \cdots + a_q \epsilon_{t-q}$$

where  $\epsilon_t \sim WN(0, \sigma^2)$  and  $E(\epsilon_t | X_{t-1}, X_{t-2}, \dots) = 0$ .

The invertible condition implies that  $X_t$  can be represented as an AR( $\infty$ ) process:

$$X_t = \epsilon_t + \sum_{j=1}^{\infty} \varphi_j X_{t-j}$$

where all  $\varphi_j$  are determined (exclusively) by  $(a_1, \dots, a_q, b_1, \dots, b_p)$ . Hence,  $\epsilon^t$  can be recovered by  $X^t$  for all  $t$  and

$$\epsilon_T(k) \equiv E_T(\epsilon_{T+k}) = 0 \cdot \mathbf{1}[k \geq 1] + \epsilon_{T+k} \cdot \mathbf{1}[k \leq 0]$$

# Forecasting ARMA( $p, q$ ) Processes

Recall that

$$X_{T+1} = b_1 X_T + \cdots + b_p X_{T+1-p} + \epsilon_{T+1} + a_1 \epsilon_T + \cdots + a_q \epsilon_{T+1-q}$$

then the one-step ahead predictor is

$$\begin{aligned} X_T(1) &\equiv E_T(X_{T+1}) \\ &= b_1 X_T + \cdots + b_p X_{T+1-p} + a_1 \epsilon_T + \cdots + a_q \epsilon_{T+1-q} \end{aligned}$$

whose MSPE is

$$\text{MSPE}[X_T(1)] = E[(X_{T+1} - X_T(1))^2] = E(\epsilon_{T+1}^2) = \sigma^2$$

In practice, assume  $X_t = 0$  for all  $t \leq 0$ , and then recover  $\epsilon^T$  using  $X^T$ .

# Forecasting ARMA( $p, q$ ) Processes

More generally, for all  $k \geq 1$ ,

$$\begin{aligned} X_{T+k} \\ = b_1 X_{T+k-1} + \cdots + b_p X_{T+k-p} + \epsilon_{T+k} + a_1 \epsilon_{T+k-1} + \cdots + a_q \epsilon_{T+k-q} \end{aligned}$$

$$\begin{aligned} X_T(k) &\equiv E_T(X_{T+k}) \\ &= b_1 X_T(k-1) + \cdots + b_p X_T(k-p) + a_1 \epsilon_T(k-1) + \cdots + a_q \epsilon_T(k-q) \end{aligned}$$

To compute  $\text{MSPE}[X_T(k)]$ , one can appeal to the causality assumption, i.e.,  $X_t$  admits an  $\text{MA}(\infty)$  representation:

$$X_t = \epsilon_t + \sum_{j=1}^{\infty} \psi_j \epsilon_{t-j}$$

where  $\psi_j$  are determined by  $(a_1, \dots, a_q, b_1, \dots, b_p)$ .

# Forecasting ARMA( $p, q$ ) Processes

Then

$$X_{T+k} = \epsilon_{T+k} + \sum_{j=1}^{\infty} \psi_j \epsilon_{T+k-j}$$

$$X_T(k) = \sum_{j=k}^{\infty} \psi_j \epsilon_{T+k-j}$$

Hence

$$\text{MSPE}[X_T(k)] = E[(X_{T+k} - X_T(k))^2] = \sigma^2 \left( 1 + \sum_{j=1}^{k-1} \psi_j^2 \right)$$

# Forecasting ARMA( $p, q$ ) Processes

## Summary for ARMA( $p, q$ ) Forecasting

$$X_T(k) = \sum_{j=k}^{\infty} \psi_j \epsilon_{T+k-j}$$

$$\text{MSPE}[X_T(k)] = \sigma^2 \left( 1 + \sum_{j=1}^{k-1} \psi_j^2 \right)$$

When  $k$  increases (long term forecasting),

- $\text{MSPE}[X_T(k)] \nearrow$ .
- $X_T(k) \xrightarrow{p} 0 = E(X_{T+k})$ , as  $k \rightarrow \infty$ .
- $\text{MSPE}[X_T(k)] \rightarrow \text{Var}(X_{T+k})$ , as  $k \rightarrow \infty$ .

# Example: Forecasting Daily Gold Prices

Figure 4: Forecasting ARMA Models

