The mechanics of transformations

We briefly introduced transformations in <u>the overview of the Prepare the data step of the Recipe for ML (Prepare data Overview.ipynb)</u>.

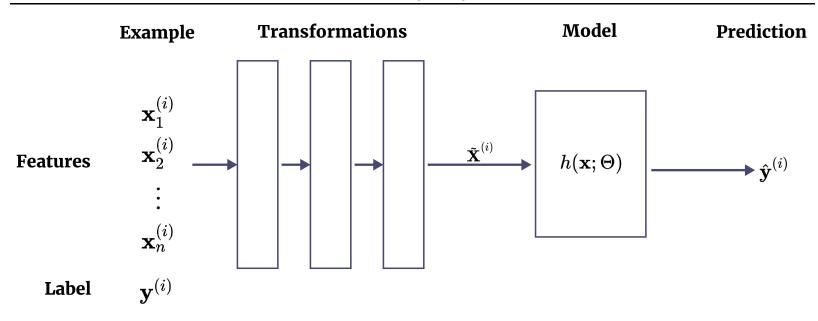
We recap the key points:

Fitting transformations

Feature engineering, or transformations

- takes an example: vector $\mathbf{x^{(i)}}$ with n features
- produces a new vector $\tilde{\mathbf{x}}^{(\mathbf{i})}$, with n' features

We ultimately fit the model with the transformed training examples.



- · Missing data inputation
- ·Standardization
- $\cdot \, {\sf Discretization}$
- $\cdot \, \text{Categorical variable encoding} \\$

Transformations have parameters $\Theta_{\mathrm{transform}}$ distinct from the model's parameters Θ .

- Example: Missing data imputation for a feature substitutes the mean/median feature value
- ullet $\Theta_{transform}$ stores this value

Our prediction is thus

$$egin{array}{lll} \hat{\mathbf{y}} &=& h_{\Theta}(ilde{\mathbf{x}}) \ &=& h_{\Theta}(\,T_{\Theta_{ ext{transform}}}(\mathbf{x})\,) \end{array}$$

Transformations can be applied to the target as well. For example

- One Hot Encoding a categorical target for a Classification task
- Scaling the target (e.g., pixel intensities from a range $[0\dots 255]$ to a range $[-1\dots +1]$)

If we transform the target y into new units, the predicted \hat{y} will also be in the new units

- If we want to report our prediction in original units
- We must be able to invert the transformation

For example:

- Logistic Regression transforms the target into Log Odds
- We want to report our prediction in terms of one class of the Categorical variable

Apply transformations consistently

Suppose you transform your raw training set

$$\langle \mathbf{X}, \mathbf{y}
angle$$

to

$$\langle \mathbf{X}', \mathbf{y}' \rangle$$

In order to satisfy the Fundamental Assumption of Machine Learning

- you must apply the **identical** transformation to
- validation examples
- test examples

By wrapping up all your transformations in an sklean Pipeline

- you can ensure that your transformations are applied consistently to each example
- regardless of its source

But remember

- ullet the transformation parameters $\Theta_{\mathrm{transform}}$
- are fit to the **training examples** only
- never re-fit to test examples

One simple way to remember this

- assume you can look at your test examples only **one at a time** rather than as a collection
- it doesn't make sense to "fit" a transformation on a singleton

Transformed targets: remember to invert your prediction!

Suppose you transform your raw training set

 $\langle \mathbf{X}, \mathbf{y}
angle$

to

$$\langle \mathbf{X}', \mathbf{y}'
angle$$

where f is the transformation applied to targets

$$\mathbf{y}' = f(\mathbf{y})$$

The units of y change from u (e.g., dollars) to u' (e.g., dimensionless z-score)

Then your model's predictions

$$\hat{\mathbf{y}}'$$

are in units of u' **not** u.

You must **invert** the transformed predicted target $\hat{\mathbf{y}}'$ back to units of u

$$\hat{\mathbf{y}} = f^{-1}(\hat{\mathbf{y}}')$$

For example

$$\mathbf{y}\mapsto rac{\mathbf{y}-\mu}{\sigma}$$

where μ,σ are the mean and standard deviation of the $\emph{training}$ examples ${f y}$

Then

$$\hat{\mathbf{y}}' \mapsto \sigma * \hat{\mathbf{y}}' + \mu$$

sklearn transformers provide an inverse_transform method to facilitate this.

Transformers in sklearn

A transformer in sklearn provides the following methods

- ullet fit: using training examples, compute $\Theta_{transform}$
- transform: map an example $[\mathbf{x^{(i)}}, \mathbf{y^{(i)}}]$ into transformed example $[\tilde{\mathbf{x}^{(i)}}, \tilde{\mathbf{y}^{(i)}}]$
- inverse_transform: map a transformed example $[\tilde{\mathbf{x}}^{(i)}, \tilde{\mathbf{y}}^{(i)}]$ back to its source example $[\mathbf{x}^{(i)}, \mathbf{y}^{(i)}]$

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In [3]: print("Done")
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Done