

Matrix Representations

Aug. 25, 2016 ①

HW# 2 Due by Sep. 6

In the last lecture, we introduced kets, bras and operators.

Today, we show that they can be represented by column vectors, row vectors and matrices, respectively.

This is possible due to the closure or completeness relation, i.e.

$$I = \sum_{i=1}^N |a^{(i)}\rangle \langle a^{(i)}| \quad (i=1, 2, \dots, N)$$

Identity operator is the sum of each and every orthonormal eigenket and corresponding eigenbra, where "orthonormal" means

$$\langle a^{(i)} | a^{(j)} \rangle = \delta_{ij} = \begin{cases} 1 & (i=j) \\ 0 & (i \neq j) \end{cases}$$

e.g. In spin- $\frac{1}{2}$ system,

$$I = |+\rangle \langle +| + |-\rangle \langle -|,$$

where $\langle +|+\rangle = 1$, $\langle +|-\rangle = 0$, $\langle -|+\rangle = 0$, $\langle -|-\rangle = 1$.

To get these results, we may represent

"represented by"

$$|+\rangle \doteq \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$|-\rangle \doteq \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Dual Correspondence
(D.C.)

column vectors

$$\langle +| \doteq [1, 0]$$

$$\langle -| \doteq [0, 1]$$

row vectors

e.g. Inner products of bras & kets.

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$$\langle + | + \rangle = [1, 0] \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 1 \times 1 + 0 \times 0 = 1$$

$$\langle + | - \rangle = [1, 0] \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 1 \times 0 + 0 \times 1 = 0$$

Outer products of bras & kets.

$$| + \rangle \langle + | = \begin{bmatrix} 1 \\ 0 \end{bmatrix} [1, 0] = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$| - \rangle \langle + | = \begin{bmatrix} 0 \\ 1 \end{bmatrix} [1, 0] = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

$$I = | + \rangle \langle + | + | - \rangle \langle - | = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Similarly, in N-dimensional system,
ket vector representation:

$$| \alpha \rangle = \sum_{i=1}^N | a^{(i)} \rangle \underbrace{\langle a^{(i)} | \alpha \rangle}_{\alpha_i}$$

$$= \begin{bmatrix} \langle a^{(1)} | \alpha \rangle \\ \langle a^{(2)} | \alpha \rangle \\ \vdots \\ \langle a^{(N)} | \alpha \rangle \end{bmatrix} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_N \end{bmatrix}$$

$$| a^{(1)} \rangle = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \left. \vphantom{\begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}} \right\} \begin{array}{l} \text{N dim.} \\ \text{Column vector} \end{array}$$

$$| a^{(2)} \rangle = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}$$

$$\text{and } \langle a^{(1)} | = [1, 0, \dots, 0]$$

N dim row vector

$$\langle a^{(2)} | = [0, 1, \dots, 0]$$

bra vector representation:

$$\begin{aligned} \langle \beta | &= \langle \beta | \left(\sum_{i=1}^N | a^{(i)} \rangle \langle a^{(i)} | \right) = \sum_{i=1}^N \langle \beta | a^{(i)} \rangle \langle a^{(i)} | = \sum_{i=1}^N \underbrace{\langle a^{(i)} | \beta \rangle}_{\beta_i^*} \langle a^{(i)} | \\ &= [\langle a^{(1)} | \beta \rangle^*, \langle a^{(2)} | \beta \rangle^*, \dots, \langle a^{(N)} | \beta \rangle^*] = [\beta_1^*, \beta_2^*, \dots, \beta_N^*] \end{aligned}$$

Operator as outerproduct of bra & ket:

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$$X = |\alpha\rangle\langle\beta|$$

$$X|\beta\rangle = |\alpha\rangle \text{ if } \langle\beta|\beta\rangle = 1 \text{ (normalized ket)}$$

(X operator changes $|\beta\rangle$ state to $|\alpha\rangle$ state in ket space)

$$X \equiv \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_N \end{bmatrix} [\beta_1^*, \beta_2^*, \dots, \beta_N^*] = \begin{bmatrix} \alpha_1\beta_1^* & \alpha_1\beta_2^* & \dots & \alpha_1\beta_N^* \\ \alpha_2\beta_1^* & \alpha_2\beta_2^* & \dots & \alpha_2\beta_N^* \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_N\beta_1^* & \alpha_N\beta_2^* & \dots & \alpha_N\beta_N^* \end{bmatrix}$$

"represented by" $N \times N$ matrix

$$\begin{aligned} \text{Tr } X &= \alpha_1\beta_1^* + \alpha_2\beta_2^* + \dots + \alpha_N\beta_N^* \\ &= [\beta_1^*, \beta_2^*, \dots, \beta_N^*] \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_N \end{bmatrix} \end{aligned}$$

$$X_{ij} = \alpha_i\beta_j^* = \langle\alpha|\beta\rangle$$

\nearrow i'th row \nwarrow j'th column.

$$\text{Tr } X \equiv \sum_i X_{ii}$$

Trace definition

$$= \langle\beta|\alpha\rangle$$

Theorem: If $X = |\alpha\rangle\langle\beta|$, then $\text{Tr } X = \langle\beta|\alpha\rangle$.

Adjoint operator dual to operator X is denoted by

$$X^\dagger = |\beta\rangle\langle\alpha| \text{ if } X = |\alpha\rangle\langle\beta|.$$

$$\langle\beta|X^\dagger = \langle\alpha| \text{ is dual correspondent to } X|\beta\rangle = |\alpha\rangle$$

(X^\dagger operator change $\langle\beta|$ state to $\langle\alpha|$ state in bra space)

$$X^\dagger = \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_N \end{bmatrix} [\alpha_1^*, \alpha_2^*, \dots, \alpha_N^*] = \begin{bmatrix} \beta_1 \alpha_1^* & \beta_1 \alpha_2^* & \dots & \beta_1 \alpha_N^* \\ \beta_2 \alpha_1^* & \beta_2 \alpha_2^* & \dots & \beta_2 \alpha_N^* \\ \vdots & \vdots & \ddots & \vdots \\ \beta_N \alpha_1^* & \beta_N \alpha_2^* & \dots & \beta_N \alpha_N^* \end{bmatrix} \quad (4)$$

Transpose of X is denoted by

$$X^T = \begin{bmatrix} \alpha_1 \beta_1^* & \alpha_2 \beta_1^* & \dots & \alpha_N \beta_1^* \\ \alpha_1 \beta_2^* & \alpha_2 \beta_2^* & \dots & \alpha_N \beta_2^* \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_N \beta_N^* & \alpha_2 \beta_N^* & \dots & \alpha_N \beta_N^* \end{bmatrix}$$

$$(X^\dagger)_{ij} = \beta_i \alpha_j^*$$

\nearrow i th row \nwarrow j th column.

$$(X^T)_{ij} = \alpha_j \beta_i^*$$

\nearrow i th row \nwarrow j th column.

Thus, $X^\dagger = (X^T)^*$

i.e. Adjoint operation is equivalent to transpose and complex conjugation.

$$(X^\dagger)_{ij} = X_{ji}^*$$

$$\beta_i \alpha_j^* = (\alpha_j \beta_i^*)^* = \beta_i \alpha_j^*$$

Note also

$$X_{ij} = \langle a^{(i)} | X | a^{(j)} \rangle = \langle a^{(i)} | \alpha \rangle \langle \beta | a^{(j)} \rangle = \alpha_i \beta_j^*$$

$$(X^\dagger)_{ij} = \langle a^{(i)} | X^\dagger | a^{(j)} \rangle = \langle a^{(j)} | X | a^{(i)} \rangle^* = X_{ji}^*$$

$$\langle a^{(j)} | \beta \rangle \langle \alpha | a^{(i)} \rangle = \beta_j \alpha_i^* = (\alpha_i \beta_j^*)^* \rightarrow X_{ji}^*$$

In general,

$$\langle \alpha | (X_1 X_2 \dots X_n) | \beta \rangle^* = \langle \beta | X_n^\dagger X_{n-1}^\dagger \dots X_2^\dagger X_1^\dagger | \alpha \rangle$$

If $X = X^\dagger$, then X is self-adjoint (5)
 or X is called as Hermitian Operator.

$$X_{ij} = X_{ji}^* \text{ or } X_{ij}^* = X_{ji}$$

Thus, the diagonal elements of Hermitian Operator are real as $X_{ii} = X_{ii}^*$.

It implies that the eigenvalues of Hermitian Operator are real.

Observables are Hermitian Operators for this reason.

Consider an observable A (e.g. A could be S_z or ^{any} spin observable.)

$$\underset{\text{eigenket}}{A} \underset{\text{eigenvalue}}{|a^{(i)}\rangle} = a^{(i)} |a^{(i)}\rangle \quad (i=1, 2, \dots, N)$$

$$A = A \cdot I = A \left(\sum_{i=1}^N |a^{(i)}\rangle \langle a^{(i)}| \right) = \sum_{i=1}^N A |a^{(i)}\rangle \langle a^{(i)}|$$

$$= \sum_{i=1}^N a^{(i)} |a^{(i)}\rangle \langle a^{(i)}| = \begin{bmatrix} a^{(1)} & & 0 \\ & a^{(2)} & \\ 0 & & \ddots \\ & & & a^{(N)} \end{bmatrix}$$

$$A^\dagger = \begin{bmatrix} a^{(1)*} & & \\ & a^{(2)*} & \\ & & \ddots \\ & & & a^{(N)*} \end{bmatrix}$$

$$\langle a^{(i)} | A | a^{(j)} \rangle = a^{(j)} \langle a^{(i)} | a^{(j)} \rangle$$

$$\rightarrow \langle a^{(i)} | A^\dagger | a^{(j)} \rangle = \langle a^{(i)} | A | a^{(j)} \rangle^* = a^{(j)*} \langle a^{(i)} | a^{(j)} \rangle$$

$$a^{(i)*} \delta_{ij} = a^{(j)*} \delta_{ij} \Rightarrow (a^{(i)} - a^{(j)*}) \delta_{ij} = 0$$

As $A^\dagger = A$ for an observable, $a^{(i)*} = a^{(j)}$ or all the eigenvalues are real.

Also, $\langle a^{(i)} | a^{(j)} \rangle = \delta_{ij}$ and thus if $a^{(i)} \neq a^{(j)}$ then $\langle a^{(i)} | a^{(j)} \rangle = 0$ and the eigenkets $|a^{(i)}\rangle$ and $|a^{(j)}\rangle$ are orthogonal.

See the theorem written in page (5) of previous lecture note on Aug. 23.

Spin- $\frac{1}{2}$ System as an example

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$$\left. \begin{aligned} S_z |+\rangle &= \frac{\hbar}{2} |+\rangle \\ S_z |-\rangle &= -\frac{\hbar}{2} |-\rangle \end{aligned} \right\} S_z = S_z \cdot I = S_z (|+\rangle\langle+| + |-\rangle\langle-|)$$
$$= S_z |+\rangle\langle+| + S_z |-\rangle\langle-|$$
$$= \frac{\hbar}{2} |+\rangle\langle+| - \frac{\hbar}{2} |-\rangle\langle-|$$
$$= \frac{\hbar}{2} (|+\rangle\langle+| - |-\rangle\langle-|)$$
$$\doteq \frac{\hbar}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

Note

$$|+\rangle\langle+| = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$
$$|-\rangle\langle-| = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Similarly,

$$\left. \begin{aligned} S_x |S_x+\rangle &= \frac{\hbar}{2} |S_x+\rangle \\ S_x |S_x-\rangle &= -\frac{\hbar}{2} |S_x-\rangle \end{aligned} \right\} S_x = \frac{\hbar}{2} |S_x+\rangle\langle S_x+| - \frac{\hbar}{2} |S_x-\rangle\langle S_x-|$$

However,

$$|S_x+\rangle = \frac{1}{\sqrt{2}} |+\rangle + \frac{1}{\sqrt{2}} |-\rangle \doteq \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$
$$|S_x-\rangle = -\frac{1}{\sqrt{2}} |+\rangle + \frac{1}{\sqrt{2}} |-\rangle \doteq \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

Note

$$I = |S_x+\rangle\langle S_x+| + |S_x-\rangle\langle S_x-|$$
$$= \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} + \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} + \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$S_x = \frac{\hbar}{2} (|S_x+\rangle\langle S_x+| - |S_x-\rangle\langle S_x-|)$$
$$\doteq \frac{\hbar}{2} \left(\begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} - \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \right) = \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

How about S_y ?

$$\left. \begin{aligned} S_y |S_y^+\rangle &= \frac{\hbar}{2} |S_y^+\rangle \\ S_y |S_y^-\rangle &= -\frac{\hbar}{2} |S_y^-\rangle \end{aligned} \right\} S_y = \frac{\hbar}{2} (|S_y^+\rangle \langle S_y^+| - |S_y^-\rangle \langle S_y^-|)$$

because $I = |S_y^+\rangle \langle S_y^+| + |S_y^-\rangle \langle S_y^-|$

$$\text{As } |S_y^+\rangle = \frac{1}{\sqrt{2}} |+\rangle + \frac{i}{\sqrt{2}} |-\rangle \doteq \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{i}{\sqrt{2}} \end{bmatrix}$$

$$|S_y^-\rangle = \frac{1}{\sqrt{2}} |+\rangle - \frac{i}{\sqrt{2}} |-\rangle \doteq \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \end{bmatrix},$$

$$|S_y^+\rangle \langle S_y^+| = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{i}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & -\frac{i}{2} \\ \frac{i}{2} & \frac{1}{2} \end{bmatrix}$$

$$|S_y^-\rangle \langle S_y^-| = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{i}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{i}{2} \\ -\frac{i}{2} & \frac{1}{2} \end{bmatrix}$$

$$|S_y^+\rangle \langle S_y^+| + |S_y^-\rangle \langle S_y^-| = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

as it should be.

$$S_y \doteq \frac{\hbar}{2} \left(\begin{bmatrix} \frac{1}{2} & -\frac{i}{2} \\ \frac{i}{2} & \frac{1}{2} \end{bmatrix} - \begin{bmatrix} \frac{1}{2} & \frac{i}{2} \\ -\frac{i}{2} & \frac{1}{2} \end{bmatrix} \right) = \frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

~~The~~ Summary, we get

$$S_z \doteq \frac{\hbar}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, S_y \doteq \frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, S_x \doteq \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

Define $\vec{S} \equiv \frac{\hbar}{2} \vec{\sigma}$, where

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$$\sigma_x = \sigma_1 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \sigma_y = \sigma_2 = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}, \sigma_z = \sigma_3 = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

Pauli matrices.

$\{\sigma_1, \sigma_2, \sigma_3\}$ forms $SU(2)$ algebra. (2 dim. $SU(2)$ group elements $U = e^{i\vec{\sigma} \cdot \vec{\theta}}$)

$$\sigma_i \sigma_j = \delta_{ij} + i\epsilon_{ijk} \sigma_k$$

special

$$\text{Tr } \vec{\sigma} = 0$$

$$\det[e^{i\vec{\sigma} \cdot \vec{\theta}}] = e^{i(\text{Tr } \vec{\sigma}) \cdot \vec{\theta}} = e^0 = 1$$

unitary

$$\vec{\sigma}^\dagger = \vec{\sigma}$$

$$U^\dagger = (e^{i\vec{\sigma} \cdot \vec{\theta}})^\dagger = e^{-i\vec{\sigma} \cdot \vec{\theta}} = e^{i\vec{\sigma} \cdot \vec{\theta}}$$

$$U^\dagger U = e^{-i\vec{\sigma} \cdot \vec{\theta}} e^{i\vec{\sigma} \cdot \vec{\theta}} = e^0 = I$$

$SU(2)$ algebra
Commutator

$$[\sigma_i, \sigma_j] = \sigma_i \sigma_j - \sigma_j \sigma_i = 2i\epsilon_{ijk} \sigma_k$$

Anticommutator

$$\{\sigma_i, \sigma_j\} = \sigma_i \sigma_j + \sigma_j \sigma_i = 2\delta_{ij}$$

e.g. $[\sigma_x, \sigma_y] = 2i\sigma_z$
 S_x and S_y are not compatible

$$\sigma_i^2 = I$$

$$\underline{Ex} \cdot \sigma_x \sigma_z \sigma_x = \sigma_x (i\sigma_y) = i\sigma_x \sigma_y = -\sigma_z$$

Group Element Example

Rotation of spin- $\frac{1}{2}$ system around z-axis by an angle ϕ : $e^{-\frac{iS_z \phi}{\hbar}} = e^{-\frac{i\sigma_z \phi}{2}}$

$$e^{-i\sigma_z \frac{\phi}{2}} = I - i\sigma_z \left(\frac{\phi}{2}\right) + \frac{1}{2!} \left[-i\sigma_z \left(\frac{\phi}{2}\right)\right]^2 + \dots$$

$$= I \left\{ 1 - \frac{1}{2!} \left(\frac{\phi}{2}\right)^2 + \frac{1}{4!} \left(\frac{\phi}{2}\right)^4 + \dots \right\} - i\sigma_z \left\{ \frac{\phi}{2} - \frac{1}{3!} \left(\frac{\phi}{2}\right)^3 + \dots \right\}$$

$$= I \cos \frac{\phi}{2} - i\sigma_z \sin \frac{\phi}{2}; \text{ In general, rotation around } \hat{n}\text{-axis by angle } \theta: e^{-i\vec{\sigma} \cdot \hat{n} \frac{\theta}{2}} = \cos \frac{\theta}{2} - i\vec{\sigma} \cdot \hat{n} \sin \frac{\theta}{2}$$