Heisenberg Equation Od: 11,2018 HW#5 Due by Oct. 18 In the last lecture, we discussed how the different picture of handling quantum dynamics could arise using the computation of expectation values in the spin precession problem; e.g. $\langle S_x \rangle_t = \langle \alpha, t | S_x | \alpha, t \rangle$ = Lx, t=0 Ut) Sx U(t) (x,t=0) Estate ket inschrödinger picture. time-evoluted
operator inflerences
picture initial stationary State ket as the Heisenberg picture state ket $= \langle x | S_x^H(t) | x \rangle$ Heigenberg State pet This works of course due to the Associativity of Multiplication.

The reason for this change of picture is to get a close connection with the classical physics, where the state kets & bras are not introduced atall, Physical observable are functions of time in C.M. Thus, define 10/4 = 10/, t=0/8 so that 12, t = U(t) 12 (Unitary transf. of state kets) Similarly, AH) (t) = Ut (t) A(s) Utt). This leads to the independence of pictures for the expectation value of an observable A. < xit | A k, t> = < x | A (t) | x }

ä

Now, let's find the equation of motion (3) for A(H) (b) by differentiating it over the time. 1 AH) (t) = 3 Uts A(s) Uts + Uts A(s) 3 Uts) - I WH From the 2000 H UCH) = it [und As) H Un - with As wer) = th [AH), H], where one should note H = WEH WO = H Heisenberg picture (1th Oth) original Hamiltonian Hamiltonian Thus, we get Heisenberg Equation of motion (4) As His independent on time have

one can think that this commutation at the same time

Classical Correspondence for AHH) and Hise. dAA(a,p) = EA, H) One may understand the C.M. equation of motion from the following consideration with Hamiltonic equation $\frac{dA(8,P)}{dt} = \frac{\partial A}{\partial 9} \frac{1}{9} + \frac{\partial$

Spin-Precession in Heisenberg Picture Here, we drop the "(H)" notation to denote Heisenberg picture for simplicity of notation. H= W Sz. dSz = I [Sz, H] = 0 Thus, Sz(t) = Sz(o) and H is indep. of time as expected. $\frac{dS_{x}}{dt} = \frac{1}{2} \left[S_{x}, H \right]$ $=\frac{\omega}{\pi \kappa} \left[S_{X}, S_{z} \right]$ ith €132 Sy = - WSy d Sy = In [Sy, H] = 0 [Sy, Sz] 14 (231, Sx)

= WSx.

In summary, we get $\frac{dS_x}{dt} = -\omega S_y \text{ and } \frac{dS_y}{dt} = \omega S_x$ while Sz is stationary. To decouple Sx and Sy separately, let's raise the order of differentiation. $\frac{dS_x}{dt^2} = -\omega \frac{dS_y}{dt} = -\omega^2 S_x$ One can denve these Similarly, results using just commutations See Baker Hausdorf Lemma Lecture note. $\frac{d^2S_y}{dt^2} = -\omega^2 S_y.$ Thus, the solutions are given by Sx(t) = corwt Sx(0) - sinut Sy(0) Sylt) = sin wt Sxlo) + con wt Sy (a) We may represent these solutions in matrices.

Sxlt) = $\frac{1}{2}$ [count-ismut o] = $\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$ [$\frac{1}{2}$ [$\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$] $\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}{2}$ [$\frac{1}{2}$] $\frac{1}$

Heisenberg Operators as Outer Products of (8)
Bras & Kets. As we've done in Schrödinger picture, we may write Sx = \frac{1}{2} |Sx+> < Sx+1 - \frac{1}{2} |Sx> < Sx-1 = 誓(1+><-1+1-><+1), In Heisenberg picture, Sx (H) = Ut (H) Sx U(H) = \f[\(\ta\)(\s,+)(\s,+)(\s,+)(\ta) - (ut(t) (sx-) (<sx-1 Utt) (= 当[15x+, t) + Sx+, t] -15x th + 5x+, t] where the base kets and bras in Heisenberg picture changes in time although the state ket does not.

As $|S_{x+}, t\rangle_{H} = \mathcal{U}^{\dagger}(H)|S_{x+}\rangle$, ika 15x+,th=ika Ut 15x+> = - H W(H) (Sx+) = -H 15,+,+>H, where Ut (t) = other and the negative sign in front of H appears in Heisenberg picture equation for the base ket. In general, Utola> = 1a,t>H and it at |a,t>H = -H |a,t>H Schnödingen Picture Heisenberg Picture

15y+>

10,t \ and syleno = 2

10,t \ and syleno = 2

Appendix: Baker-Hausdorf Lemma (See 5, (2.3.47) p.95.) ρίθλ Α Ε- iGλ = Α + iλ[G, A] + iλ [G, A] + in [G, [G, [G, A]]] Example Sxtt) = UT(t) Sx(0) U(t) = Cht Sx(0) Cht $= e^{iS_{z}(\omega t)} S_{x}(0) e^{-iS_{z}(\omega t)}$ $=S_{\chi}(0)+i(\underline{wt})[S_{z}(0)]+\frac{i^{2}(\underline{wt})^{2}}{2!}$ -(ix)3 E312 Sy(0) $S_{\chi}(0)\left(1-\frac{(\omega t)^{2}+(\omega t)^{4}}{4!}-\frac{(\omega t)^{4}}{4!}-\frac{(\omega t)^{4}+(\omega t)^{4}+(\omega t)^{4}}{4!}-\frac{(\omega t)^{4}+(\omega t)^{4}}{4!}-\frac{(\omega t)^{4}+(\omega t)^{4}}{4!}-\frac{(\omega t)$ cout Sx10) - sin wit Sy (0)

