

$$\begin{aligned} 0 &= v_x (G_3 + sC_1) - v_1 sC_1 \quad (1) \\ 0 &= v_x (G_2 + G_1) - v_2 G_2 - v_1 G_1 \quad (2) \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \quad (1) \quad v_x = \frac{v_1 sC_1}{(G_3 + sC_1)}$$

reemplazo en (2)

$$0 = \frac{v_1 sC_1}{(G_3 + sC_1)} (G_2 + G_1) - v_2 G_2 - v_1 G_1 \Rightarrow$$

$$v_2 G_2 = v_1 \left[\frac{sC_1}{(G_3 + sC_1)} (G_2 + G_1) - G_1 \right]$$

$$\frac{v_2}{v_1} = \frac{1}{G_2} \left[\frac{sC_1 (G_2 + G_1)}{(G_3 + sC_1)} - G_1 \right]$$

$$\frac{v_2}{v_1} = \frac{1}{G_2} \frac{sC_1 G_2 + sC_1 G_1 - G_1 G_3 - G_1 sC_1}{G_3 + sC_1}$$

$$\frac{v_2}{v_1} = \frac{sC_1 G_2 - G_1 G_3}{G_3 G_2 + sC_1 G_2}$$

$$\text{donde } \left[K = \frac{R_2}{R_1} \right]$$

$$\left| \frac{v_2}{v_1} = \frac{s + \frac{1}{R_3 C_1}}{s + \frac{1}{R_2 C_1}} \right|$$

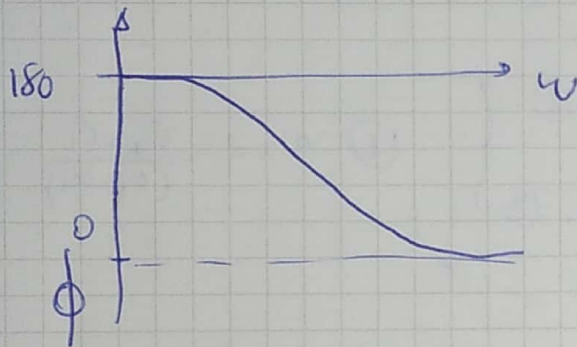
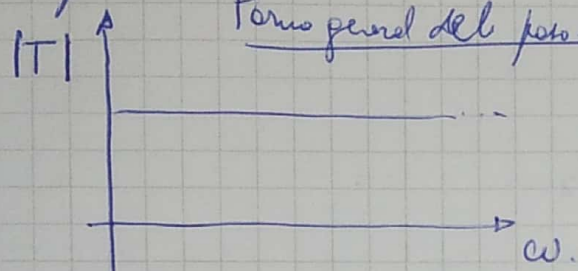
aprox el polo y el cero son

$$P_1 = \frac{1}{R_3 C_1}$$

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El filtro tiene la forma de un paso-todo

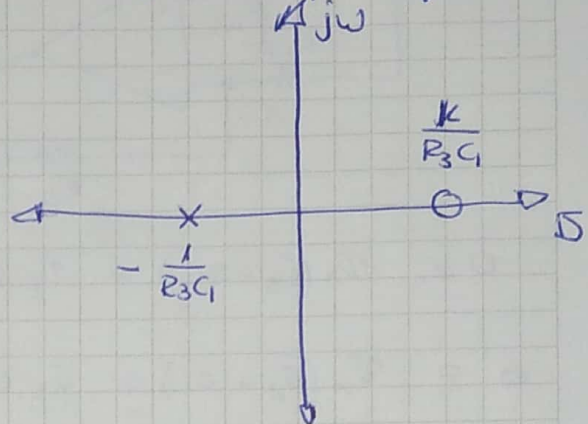
Forma general del paso-todo



Normalizando

$$T(s) = \frac{s - 1}{s + 1}$$

Diagrama de polos y ceros

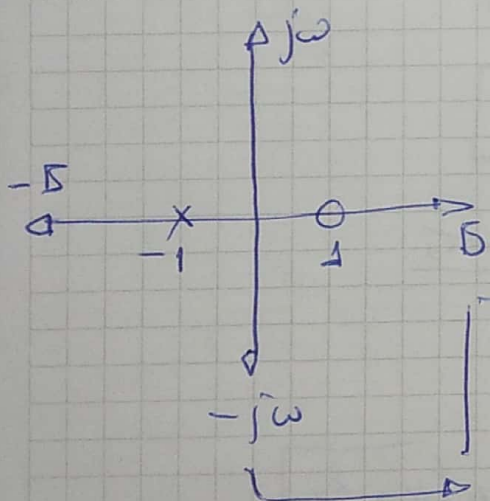


$$\left. \frac{\phi T(s)}{s} \right|_{s=j\omega} = \frac{\frac{-K}{R_3 C_1} + j\omega}{\frac{1}{R_3 C_1} + j\omega}$$

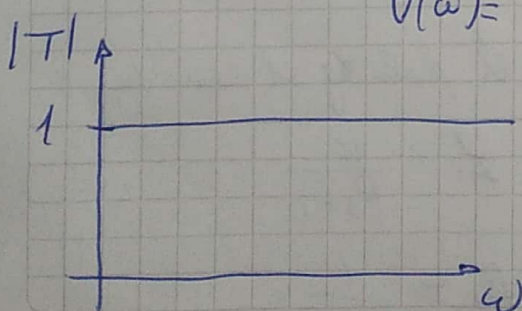
$$|T(j\omega)| = \frac{\sqrt{\omega^2 + \left(\frac{K}{R_3 C_1}\right)^2}}{\sqrt{\omega^2 + \left(\frac{1}{R_3 C_1}\right)^2}}$$

$$\theta(\omega) = \theta_n - \theta_d$$

$$= \tan^{-1}\left(\frac{\omega}{-\frac{K}{R_3 C_1}}\right) - \tan^{-1}\left(\frac{\omega}{\frac{1}{R_3 C_1}}\right)$$



$$T(j\omega) = \frac{\sqrt{(\omega/\omega_0)^2 + 1}}{\sqrt{(\omega/\omega_0)^2 + 1}} = 1 \quad \forall \omega$$



$$\theta(\omega) = \tan^{-1}\left(\frac{\omega/\omega_0}{-1}\right) - \tan^{-1}\left(\frac{\omega/\omega_0}{1}\right)$$

