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bnr...label of object, p_md...processing mode, part...partition, ro_rg...ro-range, ref_1...reference line, cas...case of object, n_pix...minimal length of line, c_ld...correct line detection, sek...type of line sequence, c_pos...correct position, c_sek...correct line sequence, c_adj_1...correct adjustment of lines,*manually derived line orientation, x_y...additional lines of other orientation than main, es...extract single building, ld...line detection, sl...sequence of lines, al...adj of line, ic...intersect corners, ac...adj of corner coordinates.

bnr	p_md	part	ro_rg	ref_l	cas	n_pix	c_ld	sek	c_pos	c_sek	c_adj_l	lines	spObj
4	demo	-	-	1	extr_wd	-	-	-	Y	-	-	39,18,1,192	-
4	auto	-	-	1	extr_wd	-	ı	-	Y	-	-	39,18,1,192	-
5	auto	0	1	1	100_all	11	Y	Mpts	Y	1	Y	61,44,41,80,1,13	-
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bnr	p_md	part	ro_rg	ref_l	cas	n_pix	c_ld	c_sek	c_pos	c_sek	c_adj_l	lines	spObj