

# **Electromagnetics and Differential Forms**

Multivectors and Differential Forms

# In today's lecture we talk about:

- **Multivectors**
- Exterior product
- Differential p-forms
- First connections to classical vector analysis
- First connections to electromagnetism

# Multivectors

A multivector  $\eta$  in a point  $P \in M$  on a differentiable manifold is defined as an alternating multilinear map over the tangent space  $T_P M$ .

$$\eta : T_P M \times \cdots \times T_P M \rightarrow \mathbb{R}$$

$\mathbb{R}$ -linearity in every argument :  $\lambda, \mu \in \mathbb{R} \quad \xi, \xi' \in T_P M$

$$\eta(\dots, \mu\xi + \lambda\xi', \dots) = \mu\eta(\dots, \xi, \dots) + \lambda\eta(\dots, \xi', \dots)$$

Alternating property :  $\xi, \xi' \in T_P M$

$$\eta(\dots, \xi, \dots, \xi', \dots) = -\eta(\dots, \xi', \dots, \xi, \dots)$$

Vanishes if  
 $\xi = \xi'$

# Space of multivectors $\bigwedge^p T_P^* M$

The degree  $p$  of a multivector  $\eta$  is the number of arguments it takes.

The space of all multivectors of degree  $p$  at  $P \in M$  is denoted as :

$$\bigwedge^p T_P^* M$$

It can be given the structure of a vector space over  $\mathbb{R}$  by:

$$(\eta + \eta')(\xi_1, \dots, \xi_p) := \eta(\xi_1, \dots, \xi_p) + \eta'(\xi_1, \dots, \xi_p) \quad \forall \xi_i \in T_P M$$

$$(\lambda \eta)(\xi_1, \dots, \xi_p) := \lambda \eta(\xi_1, \dots, \xi_p) \quad \forall \lambda \in \mathbb{R} \quad \forall \xi_i \in T_P M$$

# Dimension of $\bigwedge^p T_P^* M$

Let  $T_P M$  be of dimension  $n$  and  $\eta \in \bigwedge^p T_P^* M$  any multivector of degree  $p$ .

Linearity in each slot  $\longrightarrow \eta$  is completely fixed by action on basis of  $T_P M$ .

Alternating property  $\begin{cases} \nearrow \eta \text{ is only nonzero if all basis vectors are different.} \\ \searrow \text{order of basis vectors only determines sign.} \end{cases}$

$$\Rightarrow \dim \bigwedge^p T_P^* M = \binom{n}{p}$$

The dimension is the number of options to draw  $p$  different basis vectors of  $T_P M$ , ignoring the order.

# Some examples of $\bigwedge^p T_P^*M$

$p$	$\bigwedge^p T_P^*M$	$\dim \bigwedge^p T_P^*M$
0	$\mathbb{R}$	1
1	$T_P^*M$	$n$
$> n$	$\{0\}$	0

← By definition

← There is only a finite number of such spaces that are non trivial.

Can we combine these spaces to an overall structure?

$$\bigwedge T_P^*M := \bigwedge^0 T_P^*M \oplus \bigwedge^1 T_P^*M \oplus \cdots \oplus \bigwedge^n T_P^*M$$

↑  
direct sum

What is the dimension of  $\bigwedge T_P^*M$  ?

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# Exterior product - definition

$$\begin{aligned} \wedge : \bigwedge^p T_P^* M \times \bigwedge^q T_P^* M &\rightarrow \bigwedge^{(p+q)} T_P^* M \\ (\omega, \eta) &\mapsto \omega \wedge \eta \end{aligned}$$

$$\omega \wedge \eta(\xi_1, \dots, \xi_{p+q}) = \frac{1}{p!q!} \sum_{\pi \in S^{p+q}} \text{sign}(\pi) \omega(\xi_{\pi(1)}, \dots, \xi_{\pi(p)}) \eta(\xi_{\pi(p+1)}, \dots, \xi_{\pi(p+q)})$$

$$\xi_i \in T_P M$$

$$S^{p+q} = \{ \pi : \{1, \dots, p+q\} \rightarrow \{1, \dots, p+q\} \mid \pi \text{ is permutation} \}$$

$$\text{sign}(\pi) = \begin{cases} 1 & \text{if } \pi \text{ is even} \\ -1 & \text{if } \pi \text{ is odd} \end{cases}$$

permutations ensure  
alternating property



# Exterior product - properties

Let  $\omega \in \bigwedge^p T_P^*M$ ,  $\eta, \eta' \in \bigwedge^q T_P^*M$ ,  $\rho \in \bigwedge^r T_P^*M$  and  $\lambda \in \mathbb{R}$  then

$\omega \wedge \eta$  is a multivector of degree  $p + q$  over  $T_P M$ .

$$\omega \wedge \eta = (-1)^{pq} \eta \wedge \omega$$

Graded commutative law

$$(\omega \wedge \eta) \wedge \rho = \omega \wedge (\eta \wedge \rho)$$

Associative law

$$\omega \wedge (\eta + \lambda \eta') = \omega \wedge \eta + \lambda (\omega \wedge \eta')$$

Distributive law

Proofs may be done as exercise (easier in coordinate representation)

# Exterior algebra (Cartan algebra, Graßmann algebra)

The tuple  $\left(\bigwedge T_P^*M, +, \cdot, \wedge\right)$  has the structure of an exterior algebra.

$$\begin{aligned}\bigwedge T_P^*M &:= \bigwedge^0 T_P^*M \oplus \bigwedge^1 T_P^*M \oplus \cdots \oplus \bigwedge^n T_P^*M \\ &= \left\{ (\omega_0, \dots, \omega_n) \mid \omega_p \in \bigwedge^p T_P^*M \right\}\end{aligned}$$

- + component wise vector addition
- component wise scalar multiplication
- $\wedge$  exterior product (generalize definition via distributive law)

This is purely formal and will come naturally when looking at the basis representations  $\Rightarrow$  no influence on practical calculations

# Exterior product of covectors

Let  $\eta^i \in T_P^*M$  and  $\xi_i \in T_P M$  with  $1 \leq i \leq p \leq n$ . Then it holds

$$(IH) \quad \eta^1 \wedge \cdots \wedge \eta^p(\xi_1, \dots, \xi_p) = \det \begin{pmatrix} \eta^1(\xi_1) & \cdots & \eta^1(\xi_p) \\ \vdots & \ddots & \vdots \\ \eta^p(\xi_1) & \cdots & \eta^p(\xi_p) \end{pmatrix}$$

*Proof by induction:*

$$(IB) : \quad p = 2$$

$$(IS) : \quad p \rightarrow p + 1 \quad \longleftarrow \quad \text{Will be based on Laplace theorem for determinants}$$

IH ... Induction Hypothesis

IB ... Induction Base

IS ... Induction Step

# Exterior product of covariant vectors – IB

Induction base (IB) for  $p = 2$ :

$$\begin{aligned}\eta^1 \wedge \eta^2(\xi_1, \xi_2) &= \frac{1}{1!1!} \sum_{\pi \in S^2} \text{sign}(\pi) \eta^1(\xi_{\pi(1)}) \eta^2(\xi_{\pi(2)}) \\ &= \eta^1(\xi_1) \eta^2(\xi_2) - \eta^1(\xi_2) \eta^2(\xi_1) \\ &= \det \begin{pmatrix} \eta^1(\xi_1) & \eta^1(\xi_2) \\ \eta^2(\xi_1) & \eta^2(\xi_2) \end{pmatrix}\end{aligned}$$

# Exterior product of covariant vectors – IS

Induction step (IS) for  $p \rightarrow p + 1$ :

$$\begin{aligned} (\eta^1 \wedge \cdots \wedge \eta^p) \wedge \eta^{p+1}(\xi_1, \dots, \xi_p, \xi_{p+1}) &= \\ &= \frac{1}{p!1!} \sum_{\pi \in S^{p+1}} \text{sign}(\pi) \eta^1 \wedge \cdots \wedge \eta^p(\xi_{\pi(1)}, \dots, \xi_{\pi(p)}) \eta^{p+1}(\xi_{\pi(p+1)}) \\ &= \sum_{\tilde{\pi} \in \tilde{S}^{p+1}} \text{sign}(\tilde{\pi}) \eta^1 \wedge \cdots \wedge \eta^p(\xi_{\tilde{\pi}(1)}, \dots, \xi_{\tilde{\pi}(p)}) \eta^{p+1}(\xi_{\tilde{\pi}(p+1)}) \end{aligned}$$

sign change of p-form due to swap of arguments is canceled out

where

$$\tilde{S}^{p+1} := \{ \tilde{\pi} : (1, \dots, p, p+1) \mapsto (i_1, \dots, i_p, i_{p+1}) \mid i_1 < \cdots < i_p \}$$

# Exterior product of covariant vectors – IS cont.

$$\sum_{\tilde{\pi} \in \tilde{S}^{p+1}} \text{sign}(\tilde{\pi}) \eta^1 \wedge \cdots \wedge \eta^p(\xi_{\tilde{\pi}(1)}, \dots, \xi_{\tilde{\pi}(p)}) \eta^{p+1}(\xi_{\tilde{\pi}(p+1)})$$



$$= \sum_{j=1}^{p+1} (-1)^{p+1+j} \eta^1 \wedge \cdots \wedge \eta^p(\xi_1, \dots, \widehat{\xi_j}, \dots, \xi_{p+1}) \eta^{p+1}(\xi_j)$$

The hat indicates to skip this argument

IH

$$= \sum_{j=1}^{p+1} (-1)^{p+1+j} \det \begin{pmatrix} \eta^1(\xi_1) & \cdots & \widehat{\eta^1(\xi_j)} & \cdots & \eta^1(\xi_{p+1}) \\ \vdots & & & & \vdots \\ \eta^p(\xi_1) & \cdots & \widehat{\eta^p(\xi_j)} & \cdots & \eta^p(\xi_{p+1}) \end{pmatrix} \eta^{p+1}(\xi_j)$$

□

# Notation - strictly ordered multi-indices

The tuple  $J := (j_1 j_2 \dots j_p)$  is called a multi-index.

$$M_{j_1 j_2 \dots j_p} = M_J$$

A multi-index is called strictly ordered if  $j_1 < j_2 < \dots < j_p$  holds.

For the set of all strictly ordered multi-indices, denoted by

$$\mathcal{J}_p^n := \{(j_1 \dots j_p) \mid 1 \leq j_1 < j_2 < \dots < j_p \leq n\}$$

it holds

$$\#\mathcal{J}_p^n = \binom{n}{p}$$

# Basis of $\bigwedge^p T_P^* M$

Let  $(e_i)_{i=1}^n \subset T_P M$  be a basis of the tangent space and  $(\varepsilon^i)_{i=1}^n \subset T_P^* M$  the dual basis.

We define for  $J \in \mathcal{J}_p^n$  the multivectors of degree  $p$  :

$$\varepsilon^J = \varepsilon^{j_1 \dots j_p} := \varepsilon^{j_1} \wedge \dots \wedge \varepsilon^{j_p}$$

The family  $(\varepsilon^J)_{J \in \mathcal{J}_p^n}$  forms a basis of  $\bigwedge^p T_P^* M$  :

$$\forall \eta \in \bigwedge^p T_P^* M : \quad \eta = \sum_{J \in \mathcal{J}_p^n} \eta_J \varepsilon^J \quad \text{where} \quad \eta_J = \eta(e_{j_1}, \dots, e_{j_p})$$



# Linear independence of the $\varepsilon^J$

Let  $(i_1, \dots, i_p) = I \in \mathcal{J}_p^n$  and  $(j_1, \dots, j_p) = J \in \mathcal{J}_p^n$  be strictly ordered multi-indices.

$$\varepsilon^{j_1 \dots j_p}(e_{i_1}, \dots, e_{i_p}) = \sum_{\pi \in S^p} \text{sign}(\pi) \varepsilon^{j_1}(e_{\pi(i_1)}) \cdots \varepsilon^{j_p}(e_{\pi(i_p)})$$

Leibniz formula for  
determinants

$$= \sum_{\pi \in S^p} \text{sign}(\pi) \delta_{\pi(i_1)}^{j_1} \cdots \delta_{\pi(i_p)}^{j_p}$$

$$= \delta_{i_1}^{j_1} \cdots \delta_{i_p}^{j_p} =: \delta_I^J$$

$\Rightarrow \varepsilon^J$  are linear independent.

# Spanning property of the $\varepsilon^J$

Let  $(e_{j_1}, \dots, e_{j_p})$  with  $(j_1 \dots j_p) = J \in \mathcal{J}_p^n$  be a test tuple, where the  $(e_i)_{i=1}^n \subset T_P M$  are a basis of tangent space.

Let  $\eta \in \bigwedge^p T_P^* M$  be any multivector of degree  $p$ .

Due to linearity and the alternating property,  $\eta$  is completely defined by its action on all test tuples.

$$\eta_J = \eta_{j_1 \dots j_p} := \eta(e_{j_1}, \dots, e_{j_p})$$

# Spanning property of the $\varepsilon^J$ - continued

Lets define a multivector

$$\tilde{\eta} := \sum_{I \in \mathcal{J}_p^n} \eta_I \varepsilon^I$$

but then

$$\begin{aligned} \tilde{\eta}(e_{j_1}, \dots, e_{j_p}) &:= \sum_{I \in \mathcal{J}_p^n} \eta_I \varepsilon^I(e_{j_1}, \dots, e_{j_p}) \\ &= \sum_{I \in \mathcal{J}_p^n} \eta_I \delta_J^I = \eta_J = \eta(e_{j_1}, \dots, e_{j_p}) \end{aligned}$$

and therefore  $\tilde{\eta} = \eta$ : hence any  $\eta$  can be represented that way.



# Wrap up: Multivectors

An alternating multilinear map  $\eta : T_P M \times \cdots \times T_P M \rightarrow \mathbb{R}$  is called a **multivector** at  $P \in M$  on the manifold  $M$ .

Let  $\phi(P) = (x^1, \dots, x^n)$  be local coordinates for a neighborhood  $U \ni P$ .

$\Rightarrow \varepsilon^J = dx^{j_1}|_P \wedge \cdots \wedge dx^{j_p}|_P$  is a basis of  $\bigwedge^p T_P^* M$

$\Rightarrow \eta = \sum_{J \in \mathcal{J}_p^n} \eta_{j_1 \dots j_p} dx^{j_1}|_P \wedge \cdots \wedge dx^{j_p}|_P$  is a unique representation.  
(with respect to a chart)

$\bigwedge^p T_P^* M$  is the space of multivectors of degree  $p$  at  $P \in M$ .

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# (Smooth) Differential $p$ -forms

A smooth differential  $p$ -form  $\omega$  on  $M$  is a local operator

$$\omega : \underbrace{\mathcal{X}(M) \times \cdots \times \mathcal{X}(M)}_{p \text{ times}} \rightarrow \mathcal{C}^\infty(M)$$

Space of smooth  
Vector fields

Smoothness is buried in the  
target space

$\mathcal{C}^\infty(M)$ -linearity in every argument :  $f, g \in \mathcal{C}^\infty(M) \quad v, v' \in \mathcal{X}(M)$

$$\omega(\dots, fv + gv', \dots) = f\omega(\dots, v, \dots) + g\omega(\dots, v', \dots)$$

Alternating property :  $v, v' \in \mathcal{X}(M)$

$$\eta(\dots, v, \dots, v', \dots) = -\eta(\dots, v', \dots, v, \dots)$$

Vanishes if  
 $v = v'$

# Space of all $p$ -forms

$\mathcal{F}^p(M)$  denotes the space of all smooth differential  $p$ -forms on  $M$ .

By defining binary operations  $\forall \omega, \omega' \in \mathcal{F}^p(M) \quad \forall f \in C^\infty(M)$

$$(\omega + \omega')(v_1, \dots, v_p) := \omega(v_1, \dots, v_p) + \omega'(v_1, \dots, v_p) \quad \forall v_i \in \mathcal{X}(M)$$

$$(f\omega)(\xi_1, \dots, \xi_p) := f \omega(\xi_1, \dots, \xi_p) \quad \forall v_i \in \mathcal{X}(M)$$

$\mathcal{F}^p(M)$  can be given the structure of a module over  $C^\infty(M)$ .

# Exterior algebra for $p$ -forms

The exterior product is defined similarly as for multivectors, but with vector fields as arguments.

$$\wedge : \mathcal{F}^p(M) \times \mathcal{F}^q(M) \rightarrow \mathcal{F}^{p+q}(M)$$

It shares the same properties as for multivectors.

$$\begin{aligned} \mathcal{F}(M) &:= \mathcal{F}^0(M) \oplus \mathcal{F}^1(M) \oplus \dots \oplus \mathcal{F}^n(M) \\ &= \left\{ (\omega_0, \dots, \omega_n) \mid \omega_p \in \mathcal{F}^p(M) \right\} \end{aligned} \quad \begin{array}{l} \text{is the space of all differential} \\ \text{forms on } M. \end{array}$$

$(\mathcal{F}(M), +, \cdot, \wedge)$  has the structure of an exterior algebra.



# $p$ -forms as family of multivectors

Differential  $p$ -form  $\rightarrow$  family of multivectors  $(\omega_P)_{P \in M}$ .

$$\omega_P \in \bigwedge^p T_P^* M : \omega_P(\xi_1, \dots, \xi_p) = \omega(v_{\xi_1}, \dots, v_{\xi_p})|_P \quad \forall \xi_i \in T_P M$$

where  $v_{\xi_i} \in \mathcal{X}(M) : v_{\xi_i}|_P = \xi_i$

$v_{\xi_i}$  is a smooth  
continuation of  $\xi_i$

- $\Rightarrow$  When seen from this point of view,  $p$ -forms behave like multivectors when restricting to a point on the manifold.
- $\Rightarrow$  Properties of exterior product or basis representation follow directly.

# $p$ -forms – Basis representation

Let  $\phi(P) = (x^1, \dots, x^n)$  be local coordinates for a open set  $U \subset M$ .

Any  $p$ -form  $\omega \in \mathcal{F}^p(M)$  on  $M$  can locally be represented by

$$\omega = \sum_{J \in \mathcal{J}_p^n} \omega_J \, dx^{j_1} \wedge \dots \wedge dx^{j_p}$$

$$\text{where } \omega_J = \omega \left( \frac{\partial}{\partial x^{j_1}}, \dots, \frac{\partial}{\partial x^{j_p}} \right) \in \mathcal{C}^\infty(M)$$

This representation is unique (except for the choice of a chart).

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# Classical vector analysis

We look at the space  $(\mathbb{R}^3, \cdot, \times)$

Euclidean scalar product

cross product

That's a lot of additional structure which goes beyond a pure manifold !

$\Rightarrow$  Is a metric and therefore topological space (induced metric)

$\Rightarrow \text{id} : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is a global chart (flat manifold)

$\Rightarrow \psi : (0, \infty) \times [0, 2\pi) \times \mathbb{R} \rightarrow \mathbb{R}^3 \setminus \{0\}$  is another parametrization  
 $(r, \varphi, z) \mapsto (r \cos \varphi, r \sin \varphi, z)$  (cylindrical coordinates)

# Translation isomorphisms – coordinate-free [\[1\]](#)

In  $(\mathbb{R}^3, \cdot, \times)$  we may identify scalar/vector fields with differential forms.

Let  $M \subset \mathbb{R}^3$  be an open set in  $\mathbb{R}^3$  and  $u, v, w \in \mathcal{X}(M)$

$$\begin{aligned} {}^1. & : \mathcal{X}(M) \rightarrow \mathcal{F}^1(M) \\ & a \mapsto {}^1a \end{aligned}$$

$${}^1a(v) := a \cdot v$$

$$\begin{aligned} {}^2. & : \mathcal{X}(M) \rightarrow \mathcal{F}^2(M) \\ & b \mapsto {}^2b \end{aligned}$$

$${}^2b(u, v) := b \cdot (u \times v)$$

$$\begin{aligned} {}^3. & : \mathcal{C}^\infty(M) \rightarrow \mathcal{F}^3(M) \\ & c \mapsto {}^3c \end{aligned}$$

$${}^3c(u, v, w) := c \, u \cdot (v \times w)$$

# Cross product as exterior product

Let  $a, b \in \mathcal{X}(M)$  be any vector fields.

$${}^2(a \times b) = {}^1a \wedge {}^1b$$

*Proof :*

$$\begin{aligned} {}^2(a \times b)(v_1, v_2) &= (a \times b) \cdot (v_1 \times v_2) \\ &= (a \cdot v_1)(b \cdot v_2) - (a \cdot v_2)(b \cdot v_1) \\ &= \det \begin{pmatrix} a \cdot v_1 & a \cdot v_2 \\ b \cdot v_1 & b \cdot v_2 \end{pmatrix} \\ &= \det \begin{pmatrix} {}^1a(v_1) & {}^1a(v_2) \\ {}^1b(v_1) & {}^1b(v_2) \end{pmatrix} = {}^1a \wedge {}^1b(v_1, v_2) \end{aligned}$$

# Example: Vector fields as 1-forms

Since  $(\mathbb{R}^3, \cdot, \times)$  is a Hilbert space the isomorphic property of the translation follows from the Riesz representation theorem.

Let  $(e_i)_{i=1}^3 \subset \mathbb{R}^3$  be a basis and  $(\varepsilon^i)_{i=1}^3$  the dual basis. Then the translation isomorphism is written as

$${}^1a = (a \cdot e_1)\varepsilon^1 + (a \cdot e_2)\varepsilon^2 + (a \cdot e_3)\varepsilon^3$$

*Proof :*

$${}^1a(v) = a \cdot v = (a \cdot e_i)v^i = (a \cdot e_i)\varepsilon^i(v)$$

# Vector fields as 1-forms – different coordinates

Cartesian coordinates

$$\frac{\partial}{\partial x} \quad \frac{\partial}{\partial y} \quad \frac{\partial}{\partial z}$$

$$a = a_x \frac{\partial}{\partial x} + a_y \frac{\partial}{\partial y} + a_z \frac{\partial}{\partial z}$$

$${}^1a = a_x dx + a_y dy + a_z dz$$

cylindrical coordinates

use orthonormal dual bases

$$\frac{\partial}{\partial r} \quad \frac{1}{r} \frac{\partial}{\partial \varphi} \quad \frac{\partial}{\partial z}$$

$$a = a_r \frac{\partial}{\partial r} + a_\varphi \frac{1}{r} \frac{\partial}{\partial \varphi} + a_z \frac{\partial}{\partial z}$$

$${}^1a = a_r dr + a_\varphi r d\varphi + a_z dz$$



# Example: Vector fields as 2-forms

Let  $(e_i)_{i=1}^3 \subset \mathbb{R}^3$  be a direct orthonormal basis and  $(\varepsilon^i)_{i=1}^3$  the dual basis. Then the translation isomorphism is written as

$${}^2b = (b \cdot e_1)\varepsilon^2 \wedge \varepsilon^3 + (b \cdot e_2)\varepsilon^3 \wedge \varepsilon^1 + (b \cdot e_3)\varepsilon^1 \wedge \varepsilon^2$$

Note it is (3, 1)  
not (1, 3)

*Proof:*

${}^2b$  is an alternating multilinear 2-form over a 3D space.

$\Rightarrow$  Calculate the 3 independent components in basis representation

$${}^2b(e_2, e_3) = b \cdot (e_2 \times e_3) = b \cdot e_1$$

$${}^2b(e_3, e_1) = b \cdot (e_3 \times e_1) = b \cdot e_2$$

$${}^2b(e_1, e_2) = b \cdot (e_1 \times e_2) = b \cdot e_3$$

# Example: scalar fields as 3-forms

Let  $(e_i)_{i=1}^3 \subset \mathbb{R}^3$  be a direct orthonormal basis and  $(\varepsilon^i)_{i=1}^3$  the dual basis. Then the translation isomorphism is written as

$${}^3c = c \ \varepsilon^1 \wedge \varepsilon^2 \wedge \varepsilon^3$$

*Proof:*

${}^3c$  is an alternating multilinear 3-form over a 3D space.

$\Rightarrow$  Only one independent component in basis representation.

$${}^3c(e_1, e_2, e_3) = c \ e_1 \cdot (e_2 \times e_3) = c$$

# Translation isomorphisms – In coordinates

In  $(\mathbb{R}^3, \cdot, \times)$  we may identify scalar/vector fields with differential forms.  
Let  $M \subset \mathbb{R}^3$  be an open set and  $(e_i)_{i=1}^3$  a direct orthonormal basis of  $\mathbb{R}^3$ .

$$1. : \mathcal{X}(M) \rightarrow \mathcal{F}^1(M)$$

$$a \mapsto {}^1a = (a \cdot e_1)\varepsilon^1 + (a \cdot e_2)\varepsilon^2 + (a \cdot e_3)\varepsilon^3$$

dual basis

$$2. : \mathcal{X}(M) \rightarrow \mathcal{F}^2(M)$$

$$b \mapsto {}^2b = (b \cdot e_1)\varepsilon^2 \wedge \varepsilon^3 + (b \cdot e_2)\varepsilon^3 \wedge \varepsilon^1 + (b \cdot e_3)\varepsilon^1 \wedge \varepsilon^2$$

$$3. : \mathcal{C}^\infty(M) \rightarrow \mathcal{F}^3(M)$$

$$c \mapsto {}^3c = c \varepsilon^1 \wedge \varepsilon^2 \wedge \varepsilon^3$$

# Dot product as exterior product

Let  $a, b \in \mathcal{X}(M)$  be any vector fields.

$${}^3(a \cdot b) = {}^1a \wedge {}^2b$$

*Proof:*

use Cartesian coordinate representation for  $a$  and  $b$ .

$$\begin{aligned} {}^3(a \cdot b) &= (a_x b_x + a_y b_y + a_z b_z) dx \wedge dy \wedge dz \\ &= (a_x dx + a_y dy + a_z dz) \wedge (b_x dy \wedge dz + b_y dz \wedge dx + b_z dx \wedge dy) \\ &= {}^1a \wedge {}^2b \end{aligned}$$

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# Electric field as 1-form

Consider a charge  $q$  moving along a trajectory  $C(\lambda)$  parametrized over  $\lambda$  in electric field  $E$ .

At point  $P = C(\lambda_0)$  we have the vector tangent to the curve

$$\xi = \frac{\partial}{\partial \lambda} \in T_P \mathbb{R}^3$$

The notion of a tangent vector and of differentiation in a given direction coincide

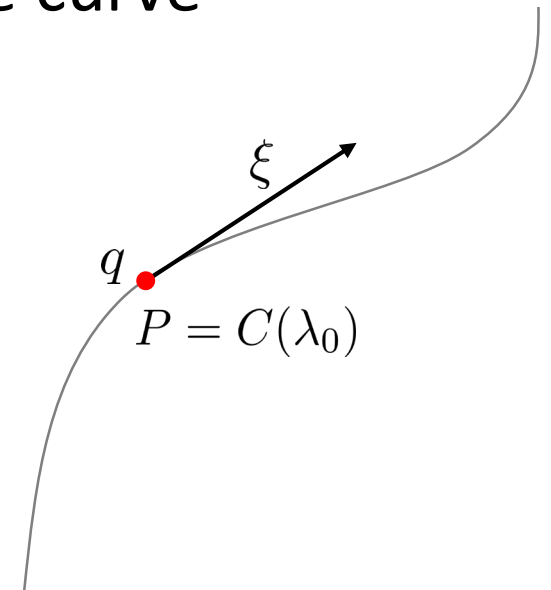
We express the work per charge

$$\frac{W(\lambda)}{q} = \frac{W(\lambda_0)}{q} + (\lambda - \lambda_0) \underbrace{E(P) \cdot \xi}_{^1E(\xi)} + \mathcal{O}(\lambda^2)$$

$$^1E(\xi) \Rightarrow$$

$$\mathcal{E} = ^1E$$

model electric field as 1-form in the first place



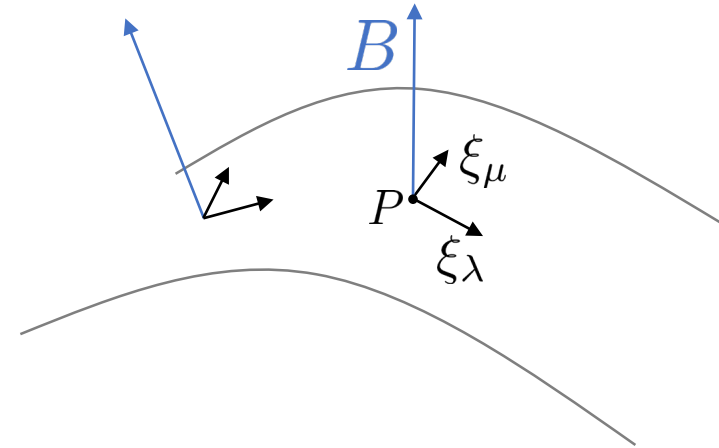
The equation for the work is invariant under reparametrization

# Magnetic flux density as 2-form

Consider a curved surface  $S(\lambda, \mu)$ , parametrized by  $\lambda$  and  $\mu$ .  
Consider a magnetic flux density  $B$ .

At a point  $P = S(\lambda_0, \mu_0)$  there are two tangent vectors,

$$\xi_\lambda = \frac{\partial}{\partial \lambda} \in T_P \mathbb{R}^3, \quad \xi_\mu = \frac{\partial}{\partial \mu} \in T_P \mathbb{R}^3$$



Magnetic flux through a parallelogram spanned by  $\xi_\lambda, \xi_\mu$

$$\Phi(\lambda, \mu) = (\lambda - \lambda_0)(\mu - \mu_0) \underbrace{B(P) \cdot (\xi_\lambda \times \xi_\mu)}_{\text{model magnetic flux density as 2-form in the first place}} + \mathcal{O}(\lambda^2, \mu^2)$$

model magnetic flux density  
as 2-form in the first place

$${}^2B(\xi_\lambda, \xi_\mu)$$

$\Rightarrow$

$$\mathcal{B} = {}^2B$$

# Scalar densities as 3-forms

Consider a parallelepiped spanned by 3 vectors  $u \xi_1, v \xi_2, w \xi_3 \in \mathbb{R}^3$  at the point  $P$ , where  $u, v, w \in \mathbb{R}^+$ .

One can identify  $\xi_1, \xi_2, \xi_3 \in T_P \mathbb{R}^3 \cong \mathbb{R}^3$

The charge within this parallelepiped is given by

$$Q(u, v, w) = u v w \underbrace{\rho(P) (\xi_1 \cdot (\xi_2 \times \xi_3))}_{\text{model charge density as 3-form in the first place}} + \mathcal{O}(u^2, v^2, w^2)$$

Charge density as scalar field

model charge density  
as 3-form in the first place

$${}^3\rho(\xi_1, \xi_2, \xi_3) \Rightarrow Q = {}^3\rho$$



# Wrap up – electromagnetic quantities as forms

			physical dim.
$\mathcal{E} = {}^1E$	electric field	1 – form	U
$\mathcal{H} = {}^1H$	magnetic field		I
$\mathcal{B} = {}^2B$	magnetic flux density	2 – form	UT
$\mathcal{D} = {}^2D$	electric displacement field		IT
$\mathcal{J} = {}^2J$	electric current density		I
$\mathcal{Q} = {}^3\rho$	electric charge density	3 – form	IT

# Literature

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