Electromagnetics and Differential Forms

Poincaré Lemmata and de Rham Cohomology

In today's lecture we talk about:

The Poincaré lemmata

De Rham cohomology

Simplicial homology

The theorem of de Rham

Duality paring between forms and chains

Let $\omega \in \mathcal{F}^p(M)$ be a p-form on a differentiable manifold M.

Let $c \in \mathcal{C}_p(M)$ be a p-chain on M.

The pairing
$$\langle \omega, c \rangle := \int_c \omega$$
 is

I) bilinear, $\lambda \in \mathbb{R}$

$$\langle \omega + \lambda \omega', c \rangle = \int_{c} \omega + \lambda \int_{c} \omega'$$

II) nondegenerate

$$\forall c \in \mathcal{C}_p(M) : \langle \omega, c \rangle = 0$$
$$\Rightarrow \omega = 0$$

 $\langle \omega, c \rangle$ is a duality paring between $\mathcal{F}^p(M)$ and $\,\mathcal{C}_p(M)$.

$$\langle \omega, c + \lambda c' \rangle = \int_{c} \omega + \lambda \int_{c'} \omega$$

$$\forall \omega \in \mathcal{F}^p(M) : \langle \omega, c \rangle = 0$$
$$\Rightarrow c = 0$$

Physical interpretation of chains and forms

Consider the duality paring

$$(\mathcal{F}^p(M), \mathcal{C}_p(M), \langle \cdot, \cdot \rangle)$$

Note that for $C_p(M)$, in order to be a vector space, one also has to admit formal linear combinations of simplices with real coefficients.

From a physical perspective:

Stokes' theorem revisited

We can express Stokes' theorem in terms of the duality paring:

d is the dual operator to ∂

$$\langle d\omega, c \rangle = \langle \omega, \partial c \rangle$$

$$\forall c \in \mathcal{C}_p(M)$$
$$\forall \omega \in \mathcal{F}^{p-1}(M)$$

This can be used as an alternative definition of the exterior derivative:

 $\mathrm{d}\omega$ is the p - form that gives the same response to any p - chain cas the (p-1)- form ω gives on the boundaries ∂c .

$$\partial \circ \partial = 0$$

$$d \circ d = 0$$

Also $\partial \circ \partial = 0 \implies d \circ d = 0$ holds as a necessity.

Classifications of forms and chains

closed p-forms

$$\mathcal{Z}^p(M) = \ker d_p$$

$$\forall \omega \in \mathcal{Z}^p(M) : d\omega = 0$$

exact p-forms

$$\mathcal{B}^p(M) = \operatorname{Im} d_{p-1}$$

$$\forall \omega \in \mathcal{B}^p(M) : \exists \Omega \in \mathcal{F}^{p-1}(M) : \omega = d\Omega$$

p-cycles

$$\mathcal{Z}_p(M) = \ker \partial_p$$

$$\forall c \in \mathcal{Z}_p(M): \ \partial c = 0$$

p-boundaries

$$\mathcal{B}_p(M) = \operatorname{Im} \partial_{p+1}$$

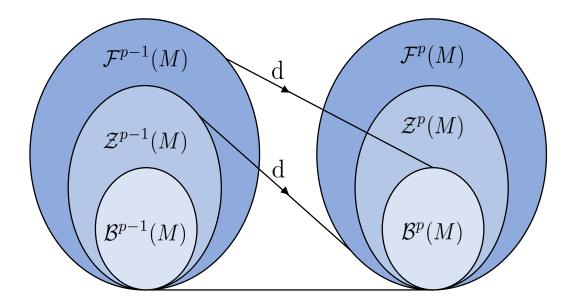
$$\forall c \in \mathcal{B}_p(M): \exists C \in \mathcal{C}_{p+1}(M): c = \partial C$$

First lemma of Poincaré

From the complex property $d \circ d = 0$ and $\partial \circ \partial = 0$ it follows directly

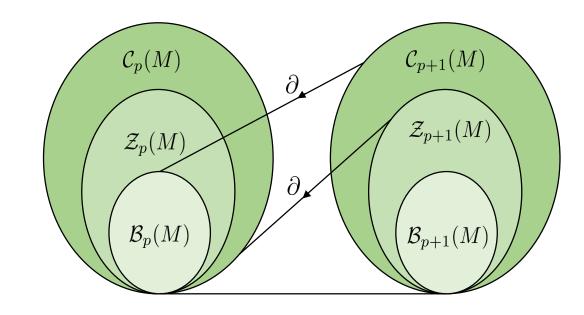
$$\mathcal{B}^p(M) \subseteq \mathcal{Z}^pM$$

Every exact form is closed.



$$\mathcal{B}_p(M) \subseteq \mathcal{Z}_p M$$

Every boundary is a cycle.



Converse lemma?

The following question arises:

Does the converse hold e.g. is every closed form exact and every cycle a boundary?

The answer is given by the **second lemma of Poincaré**:

Locally – **Yes, always**! To any point there always exist a open set on the manifold where this holds.

Globally – **It depends** on the topological properties of the manifold.

 \Rightarrow leads to discussion of homology and cohomology classes.

Contractible manifold

A differentiable manifold M is called **contractible** if there exists a differentiable map

such that

$$\psi: [0,1] \times M \to M$$

$$\psi(1, \cdot) = \mathrm{id}_M$$

$$\psi(0, \cdot) = \text{const.}$$

One can picture this as a continuous deformation to a point.

Examples:

contractible

non contractible

$$n\text{-ball} \qquad \text{convex domains} \\ \text{solid cylinder} \qquad \text{star-shaped domains} \\ \\ \text{in } \mathbb{R}^n \\ \\ \text{disconnected domains} \qquad n\text{-sphere} \\ \\ \text{disconnected domains} \qquad \text{cylindrical surface} \\$$

Second lemma of Poincaré

Let M be a **contractible** differentiable manifold, then it holds

that

$$\mathcal{B}^p(M) = \mathcal{Z}^p(M)$$

Every closed form is exact.

 Ω is called the potential to ω .

$$\mathcal{B}_p(M) = \mathcal{Z}_p(M)$$

Every cycle is a boundary.

$$d\omega = 0 \Rightarrow \exists \Omega \in \mathcal{F}^{p-1}(M) : \omega = d\Omega$$

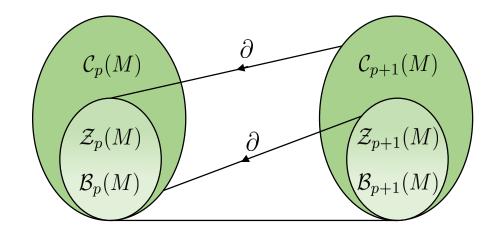
$$\mathcal{F}^{p-1}(M)$$

$$\mathcal{Z}^{p-1}(M)$$

$$\mathcal{Z}^{p}(M)$$

$$\mathcal{B}^{p}(M)$$

$$\partial c = 0 \Rightarrow \exists C \in \mathcal{C}_{p+1}(M) : c = \partial C$$



Lemma of Poincaré for star-shaped domains in \mathbb{R}^n

The **lemma of Poincaré** especially holds for $M \subset \mathbb{R}^n$ open and **star-shaped**.

A star-shaped domain contains all lines \overline{PQ} from the star point $P \in M$ to

a point $Q \in M$. We can construct an explicit contraction

$$\psi(t,Q) = P + t \overrightarrow{PQ}$$

In this special case:

- 1) One can explicitly construct, to a boundary c, a chain C such that $c = \partial C$ holds. \Rightarrow **Poincaré cone construction**
- 2) One can give an explicit formula for the potential Ω to a p -form ω .

The Poincaré cone construction in \mathbb{R}^3

Consider a 1-cycle $c \in \mathcal{C}_1(M)$, $M \subset \mathbb{R}^3$

A cone is constructed by the family

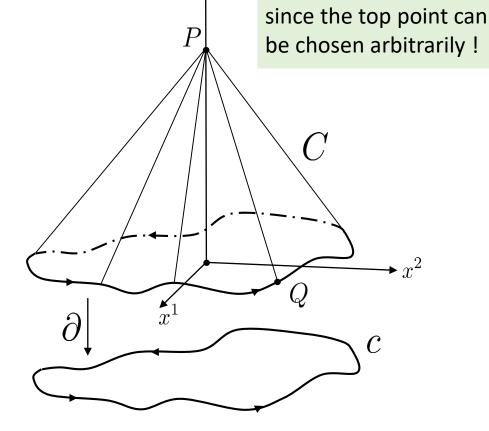
$$\psi_t := \psi(t,\cdot) : M \to M$$

as the set

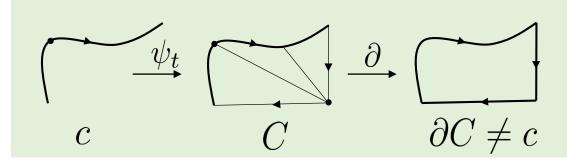
$$C = \{ \psi_t(Q) \mid t \in [0, 1], Q \in c \}$$

with properties

$$C \in \mathcal{C}_2(M)$$
 and $\partial C = c$



The cone is not unique



If C is not a cycle, this construction is in general not possible!

The Poincaré potential construction [2, Ch. 11.5]

Consider the position vector field $x:M\subset\mathbb{R}^n\to T_PM\cong\mathbb{R}^n$, $Q\mapsto \overrightarrow{PQ}$ and the contraction maps $\psi_t:=\psi(t,\cdot):M\to M$

Define the cone integral operator

$$I: \mathcal{F}^{p}(M) \to \mathcal{F}^{p-1}(M)$$

$$\omega \mapsto \int_{0}^{1} \frac{1}{\tau} \mathbf{i}_{x} \mathrm{D} \psi_{\tau}^{*} \omega \, d\tau$$

It can be shown that: $d \circ I + I \circ d = id_M$

Therefore:
$$d\omega = 0 \implies \omega = d I \omega = d\Omega \implies$$

This gives an explicit formula to calculate the potential Ω on star-shaped domains

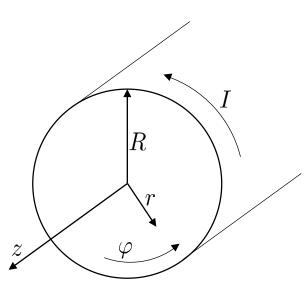
$$\Omega = I \omega$$

Cone integral operator in coordinates

Use a chart ϕ such that for the star point $\phi(P)=0$.

Vector potential of a long, densely wound round coil

Describe the problem in polar coordinates:



 $R \dots$ Radius of coil

I ... Current

n ... Winding density of coil

$$B = \mu_0 In \begin{cases} \frac{\partial}{\partial z} & \text{if} \quad r < R \\ 0 & \text{if} \quad r > R \end{cases}$$

$$\Rightarrow \mathcal{B} = {}^{2}B = \mu_{0} In \begin{cases} dr \wedge r d\varphi & \text{if } r < R \\ 0 & \text{if } r > R \end{cases}$$

Vector potential of a long, densely wound round coil

Cone integral operator in 2D cross-sectional area:

 $\begin{array}{ll} \text{polar coordinate} \\ \text{representation} \end{array} \colon \quad \tilde{\psi}_{\tau} : (r,\varphi) \mapsto (\tau r,\varphi) \quad \Rightarrow \quad \begin{array}{ll} \mathrm{D} \psi_{\tau}^* \mathrm{d} r = \mathrm{d}(\tau r) = \tau \mathrm{d} r \\ \mathrm{D} \psi_{\tau}^* \mathrm{d} \varphi = \mathrm{d} \varphi \end{array}$

$$D\psi_{\tau}^* \mathcal{B} = \mu_0 In \begin{cases} \tau^2 dr \wedge r d\varphi & \text{if } \tau r < R \\ 0 & \text{if } \tau r > R \end{cases}$$

$$\Rightarrow \int_{0}^{1} \frac{1}{\tau} \mathrm{D}\psi_{\tau}^{*} \mathcal{B} \, \mathrm{d}\tau = \mu_{0} In \int_{0}^{\min(1, \frac{R}{r})} \tau \, \mathrm{d}\tau \, \mathrm{d}r \wedge r \, \mathrm{d}\varphi$$
$$= \mu_{0} In \frac{r}{2} \min\left(1, \frac{R^{2}}{r^{2}}\right) \mathrm{d}r \wedge \mathrm{d}\varphi = \frac{1}{2} \int_{0}^{\min(1, \frac{R}{r})} \tau \, \mathrm{d}r \, \mathrm{d}r \wedge \mathrm{d}\varphi$$

In a last step we need to contract this 2-form with the position vector field \boldsymbol{x} .

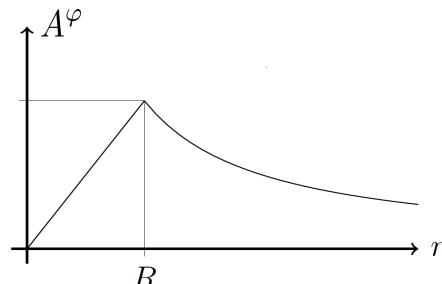
Vector potential of a long, densely wound round coil

Perform the contraction \mathbf{i}_x with position vector field $x \cong r \frac{\partial}{\partial r} + z \frac{\partial}{\partial z}$

$$\mathbf{i}_{x}(\mathrm{d}r \wedge \mathrm{d}\varphi)(\xi) = (\mathrm{d}r \wedge \mathrm{d}\varphi)(r\frac{\partial}{\partial r} + z\frac{\partial}{\partial z}, \xi) = (\mathrm{d}r \wedge \mathrm{d}\varphi)(r\frac{\partial}{\partial r}, \xi) \qquad \forall \xi \in \mathcal{X}(\mathbb{R}^{3})$$

$$= \begin{vmatrix} r & 0 \\ \mathrm{d}r(\xi) & \mathrm{d}\varphi(\xi) \end{vmatrix} = r\,\mathrm{d}\varphi(\xi)$$

$$\Rightarrow \mathcal{A} = I\mathcal{B} = \frac{\mu_0 In}{2} \underbrace{r d\varphi}_{r} \begin{cases} r & \text{if } r \leq R \\ \frac{R^2}{r} & \text{if } r \geq R \end{cases}$$
$$= \frac{1}{r} \frac{\partial}{\partial \varphi} = \frac{1}{r} e_{\varphi}$$



Existence of potentials and gauge transformations

The 2nd lemma of Poincaré guarantees the existence of potential forms if the domain of the form is topologically trivial.

In other words:

$$\Omega \in \mathcal{F}^{p-1}(M): \quad \omega = \mathrm{d}\Omega \quad \omega \in \mathcal{F}^p(M) \quad \text{is solvable if M is contractible.}$$

The solution is **not unique**!

$$\forall \lambda \in \mathcal{F}^{p-2}(M) \quad \mathrm{d}(\Omega + \mathrm{d}\lambda) = \mathrm{d}\Omega + \mathrm{d}\circ\mathrm{d}\lambda = \mathrm{d}\Omega = \omega$$

$$\Rightarrow \ \mathrm{d}\Omega \to \mathrm{d}(\Omega + \mathrm{d}\lambda) \quad \text{gauge transformation}$$

The choice of a different apex in the Poincaré cone construction leads also to a different gauge.

2nd lemma of Poincaré in classical vector analysis [10]

If the open set $U \subset \mathbb{R}^3$ is contractible then for sufficiently smooth vector fields and functions it holds that:

- 1) To every vector field E on U with $\operatorname{\mathbf{curl}} E = 0$ there exists a function Φ such that $E = -\operatorname{grad} \Phi$.
- 2) To every vector field B on U with $\mathbf{div}B=0$ there exists a vector field A such that $B=\mathbf{curl}\,A$.

3) To every function f there exists a vector field F such that $f = \operatorname{div} F$.

In today's lecture we talk about:

The Poincaré lemmata

De Rham cohomology

Simplicial homology

The theorem of de Rham

Cohomologous forms

Two closed p-forms $\omega_1, \omega_2 \in \mathcal{Z}^p(M)$ are called **cohomologous** if they only differ by an exact p-form $d\Omega$.

$$\omega_1 \sim \omega_2 \qquad \Leftrightarrow \quad \exists \Omega \in \mathcal{F}^{p-1}(M) : \omega_1 - \omega_2 = \mathrm{d}\Omega$$

This defines an equivalence relation.

$$\Rightarrow \mathcal{B}^p(M) = \operatorname{Im} \operatorname{d}_{p-1}$$

$$= [0] \qquad \text{is the equivalence class of all closed}$$
 $p\text{-forms cohomologous to 0}.$

Cohomology groups

The quotient space

$$H^p(M) := \mathcal{Z}^p(M)/\mathcal{B}^p(M)$$

is called the p-th de Rham cohomology group/space.

It is the set of all equivalence classes $[\omega]$ of the relation of last slide.

 $H^p(M)$ can be given the structure of an Abelian group or vector space over $\mathbb R$ by :

$$[\omega] + [\omega'] := [\omega + \omega'] \qquad \forall \omega, \omega' \in \mathcal{Z}^p(M)$$
$$\lambda[\omega] := [\lambda\omega] \qquad \forall \lambda \in \mathbb{R}$$

Homotopy invariance of cohomology [2, Ch. 11.2]

Let M, N be differentiable manifolds.

Two differentiable maps $f,g:M\to N$ are called **differentiably homotopic** if there exists a differentiable map

$$h:[0,1] imes M o N$$
 such that $h(0,\cdot)=f$ and $h(1,\cdot)=g$

If f,g:M o N are differentiably homotopic maps, then

$$\mathrm{D}f^* = \mathrm{D}g^* : H^p(N) \to H^p(M)$$

holds for all p, e.g.

$$[Df^*\omega] = [Dg^*\omega] \qquad \forall \omega \in \mathcal{Z}^p(N)$$

Betti numbers (cohomology)

The dimension of the p-th de Rham cohomology space

$$b^p := \dim H^p(M)$$

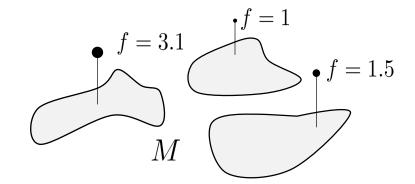
is called the p-th **Betti number** of M.

- b^p gives the number of essentially different closed p- forms on M.
- These numbers are topological invariants, they depend only on the topology of the manifold.
- $b^p < \infty$ holds for finite dimensional, compact manifolds.

$$\omega = 0$$
 for $p > n$

$$H^p(M)=0$$
 for $p<0$ and $p>n=\dim M$.

$$H^0(M):=\mathcal{Z}^0(M)=\{f\in\mathcal{C}^\infty(M)\mid \mathrm{d} f=0\}\cong\mathbb{R}^c \qquad \text{Piecewise constant functions on }M.$$



Here c is the number of connected components of ${\cal M}$.

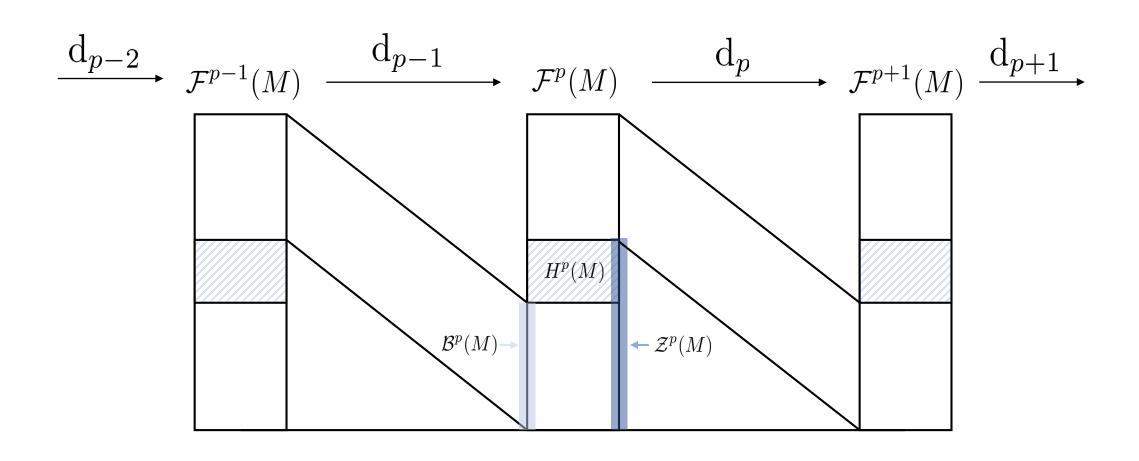
$$b^0 := \dim H^0(M) = c$$

$$H^0(\mathbb{R}^n)\cong\mathbb{R}$$
 $H^p(\mathbb{R}^n)=0$ for $p>0$

This follows directly from the 2nd lemma of Poincaré.

The de Rham complex of ${\cal M}$

The sequence $(\mathcal{F}^p(M), d_p)$ is called the **de Rham complex** of M.



The 2nd lemma of Poincaré revisited

The 2nd lemma of Poincaré can also be stated in terms of de Rham cohomology groups:

M is a contractible manifold.

$$\Leftrightarrow H^0(M) \cong \mathbb{R}$$

$$H^p(M) = 0 \text{ for } p > 0$$

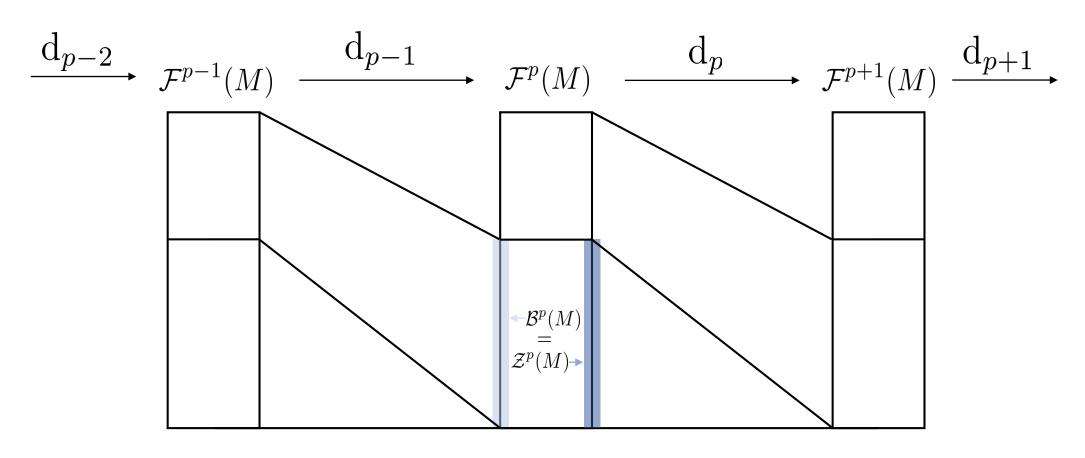
Manifolds with the Betti numbers

$$b^0 = 1 \qquad \text{and} \qquad b^p = 0 \quad \text{for } p > 0$$

are called topologically trivial.

De Rham complex for topologically trivial manifolds

The sequence $(\mathcal{F}^p(M), d_p)$ is called **exact** in the case of topologically trivial manifolds.



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Homologous chains

Two p-cycles $c_1, c_2 \in \mathcal{Z}_p(M)$ are called **homologous** if they only differ by a boundary ∂C_{p+1} .

$$c_1 \sim c_2 \qquad \Leftrightarrow \quad \exists C \in \mathcal{C}_{p+1}(M) : c_1 - c_2 = \partial C$$

This defines an equivalence relation.

$$\Rightarrow \ \mathcal{B}_p(M) = \mathrm{Im} \ \partial_{p+1}$$

$$= [0] \qquad \text{Boundaries are said to}$$
 be "homologous to zero".

Homology groups

The quotient space

$$H_p(M) := \mathcal{Z}_p(M)/\mathcal{B}_p(M)$$

is called the p-th simplicial homology group/space.

It is the set of all equivalence classes [c] of the relation of last slide.

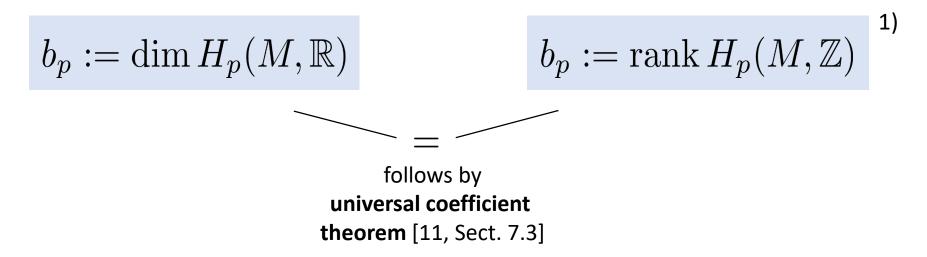
 $H_p(M)$ can be given the structure of an Abelian group or vector space

$$[\omega] + [\omega'] := [\omega + \omega'] \qquad \forall \omega, \omega' \in \mathcal{Z}_p(M)$$

$$\lambda[\omega] := [\lambda \omega] \qquad \forall \lambda \left\{ \begin{array}{l} \in \mathbb{Z} \ \Rightarrow \ \text{group structure only} \ \Rightarrow \ H_p(M, \mathbb{Z}) \\ \in \mathbb{R} \ \Rightarrow \ \text{vector space over} \ \mathbb{R} \ \Rightarrow \ H_p(M, \mathbb{R}) \end{array} \right.$$

Betti numbers (homology)

We define the p-th **Betti number** of M in terms of homology as



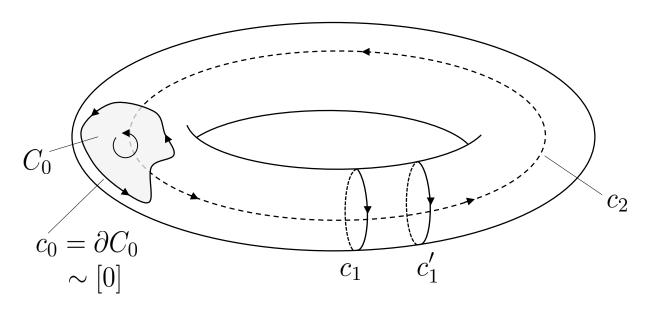
Their intuitive meaning can be better understood in terms of groups.

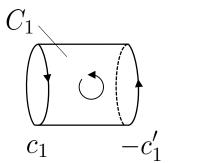
For de Rham's theorem we need $H_p(M)$ to have a vector space structure.

¹⁾ Precisely: The rank of the free Abelian part, neglecting the torsion subgroup [12, Sect. 3.4.3]

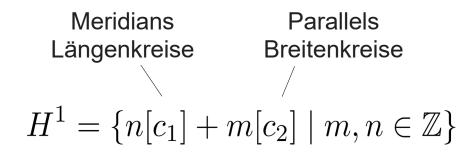
Example: Homology of a torus

Let M be a torus, $\dim M=2$.





$$c_1 - c_1' = \partial C_1$$



 $3[c_1] + 2[c_2]$ can be interpreted as closed curves that are wound around the torus

3 times like c_1

2 times like c_2

Betti numbers

 $b_0=1$ manifold is connected $b_1=2$ number of "loops" $b_2=1$ number of "cavities"

Example: Betti numbers

For practical computations see [14]

Topological trivial manifolds:

$$b_0 = 1$$
 , $b_k = 0 \ \forall k > 0$

n - sphere:

$$b_0 = b_n = 1$$
, $b_k = 0 \ \forall k \notin \{1, n\}$

n - torus:

$$b_k = \left(\begin{array}{c} n \\ k \end{array}\right)$$

Hollow n- ball:

$$b_0 = b_{n-1} = 1$$
, $b_k = 0 \quad \forall k \notin \{1, n-1\}$

Homeomorphic to (n-1)-sphere imes line segment

For topological spaces X, Y it holds

$$b_k(X \times Y) = \sum_{\lambda + \mu = k} b_\lambda(X) b_\mu(Y)$$
 \rightarrow Künneth formula [12, eq. (6.45)]

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Consequences of Stokes's theorem (1)

The integral of an **exact form** $\omega \in \mathcal{B}^p(M)$ over a **cycle** $c \in \mathcal{Z}_p(M)$ vanishes.

Proof:

$$\int_{c} \omega = \int_{c} d\Omega = \int_{\partial c} \Omega = 0$$

Consequences of Stokes's theorem (2)

The integral of a **closed form** $\omega \in \mathcal{Z}^p(M)$ over a **boundary** $c \in \mathcal{B}_p(M)$ vanishes.

Proof:

$$\int_{c} \omega = \int_{\partial C} \omega = \int_{C} d\omega = 0$$

Consequences of Stokes's theorem (3)

The integral of a **closed form** $\omega \in \mathcal{Z}^p(M)$ over a **cycle** $c \in \mathcal{Z}_p(M)$ depends only on the homology class of the cycle.

Proof:

Let
$$c \sim c'$$
 , then $\exists C \in \mathcal{C}_{p+1}(M) : c - c' = \partial C$

$$\Rightarrow \int_{c} \omega - \int_{c'} \omega = \int_{c-c'} \omega = \int_{\partial C} \omega = \int_{C} d\omega = 0$$

Consequences of Stokes's theorem (4)

The integral of a **closed form** $\omega \in \mathcal{Z}^p(M)$ over a **cycle** $c \in \mathcal{Z}_p(M)$ depends only on the cohomology class of the form.

Proof:

Let
$$\omega \sim \omega'$$
, then $\exists \Omega \in \mathcal{F}^{p-1}(M): \ \omega - \omega' = \mathrm{d}\Omega$

$$\Rightarrow \int_{c} \omega - \int_{c} \omega' = \int_{c} \omega - \omega' = \int_{c} d\Omega = \int_{\partial c} \Omega = 0$$

The theorem of de Rham [4, Thm. 3.6]

Follows from the previous four consequences of Stokes' theorem.

The following bilinear mapping is well defined and non-degenerate.



$$\langle \cdot, \cdot \rangle : H^p(M) \times H_p(M, \mathbb{R}) \to \mathbb{R}$$

$$([\omega], [c]) \mapsto \int_c \omega$$

Important consequences:

$$H^p(M) \cong H_p(M, \mathbb{R})^* \ \forall p \ge 0$$

 $b_p = \dim H^p(M) = \dim H_p(M, \mathbb{R})$

Corollary: Existence of potentials

The **periods of a** p-form $\omega \in \mathcal{F}^p(M)$ are the values of the pairing

$$\langle \omega, c \rangle = \int_c \omega$$
 , where $c \in \mathcal{Z}_p(M)$

From the theorem of de Rham it follows:

$$\omega \in \mathcal{B}^p(M) \qquad \Leftrightarrow \quad \langle \omega, c \rangle = 0 \quad \forall c \in \mathcal{Z}_p(M)$$

 ω is an exact form e.g. there exist a \Leftrightarrow All periods of ω vanish. potential form Ω

Proof: Existence of potentials corollary

i) Consider $\omega \in \mathcal{Z}^p(M)$

$$\omega \in \mathcal{B}^p(M)$$

$$\overset{\text{(class definition)}}{\Leftrightarrow} [\omega] = 0$$

$$\Leftrightarrow^{\text{(non-degeneracy)}} \langle [\omega], [c] \rangle = 0 \qquad \forall [c] \in H_p(M)$$

(well definedness)
$$\langle \omega, c \rangle = 0$$
 $\forall c \in \mathcal{Z}_p(M)$

ii) Consider $\omega \in \mathcal{F}^p(M)$

$$\langle \omega, c \rangle = 0 \qquad \forall c \in \mathcal{Z}_p(M)$$

 $\Rightarrow \langle \omega, c \rangle = 0 \qquad \forall c \in \mathcal{B}_p(M)$

$$\Rightarrow \langle \omega, \partial C \rangle = 0 \quad \forall C \in \mathcal{C}_{p+1}(M)$$

$$\Rightarrow \langle d\omega, C \rangle = 0 \quad \forall C \in \mathcal{C}_{p+1}(M)$$

$$\Rightarrow \omega \in \mathcal{Z}^p(M)$$

iii)
$$\omega \in \mathcal{B}^p(M) \subset \mathcal{Z}^p(M) \stackrel{\text{(i)}}{\Rightarrow} \langle \omega, c \rangle = 0 \quad \forall c \in \mathcal{Z}_p(M)$$

iv)
$$\omega \in \mathcal{F}^p(M)$$
 and $\langle \omega, c \rangle = 0 \ \forall c \in \mathcal{Z}_p(M) \overset{\text{(ii + i)}}{\Rightarrow} \ \omega \in \mathcal{B}^p(M)$

Integrability condition and gauge freedom

Consider the equation

$$\omega = \mathrm{d}\Omega \qquad \omega \in \mathcal{F}^p(M)$$

The integrability condition

$$\langle \omega, c \rangle = 0 \quad \forall c \in \mathcal{Z}_p(M)$$

The integrability condition is necessary **and** sufficient

$$d\omega = 0$$
only necessary

guarantees the existence of a particular solution $\Omega' \in \mathcal{F}^{p-1}(M)$.

General solution:

$$\Omega=\Omega'+\underline{\mathrm{d}\lambda+\Gamma}\quad\text{with}\quad\lambda\in\mathcal{F}^{p-2}(M)\,\text{, }\Gamma\in[\Omega-\Omega']\in H^{p-1}(M)$$
 gauge freedom

Example: Magnetic vector potential

Let $\mathcal{B} \in \mathcal{F}^2(M)$ be the magnetic flux density 2-form.

From Maxwell's equation in integral form it follows

$$\langle \mathcal{B}, \partial V \rangle = \int_{\partial V} \mathcal{B} = 0 \qquad \Rightarrow \qquad \langle \mathcal{B}, A \rangle = 0 \quad \forall A \in \mathcal{B}_2(M)$$

We can generalize this to:

Then the theorem of de Rham implies

$$\exists \mathcal{A} \in \mathcal{F}^1(M) : \mathcal{B} = d\mathcal{A}$$

$$\langle \mathcal{B}, A \rangle = 0 \quad \forall A \in \mathcal{Z}_2(M)$$

2-boundaries

No magnetic monopoles

Maxwell's equation in **integral form** can be formulated to guarantee the existence of potentials, **even for topological non trivial manifolds**.

Example: Magnetic vector potential, hollow sphere

Consider $M=B_R(0)\setminus B_{\varepsilon}(0)$ and spherical coordinates (r,θ,φ) with the orthonormal basis fields $\frac{\partial}{\partial r}$, $\frac{1}{r}\frac{\partial}{\partial \theta}$, $\frac{1}{r\sin\theta}\frac{\partial}{\partial \theta}$ and dual forms $\mathrm{d} r$, $r\mathrm{d} \theta$, $r\sin\theta\,\mathrm{d} \varphi$.

Consider the magnetic flux density of a "hidden monopole"

 $b_2(M) = 1$ Not every closed 2-form is exact !

$$B = \frac{c}{4\pi} \frac{1}{r^2} \frac{\partial}{\partial r}$$
, $R > r > \varepsilon > 0$, $c \neq 0$.

This flux density satisfies Gauss's law for magnetism in differential form

$$B = \frac{c}{4\pi} \frac{1}{r^2} \frac{\partial}{\partial r} \longrightarrow \mathcal{B} = {}^{2}B = \frac{c}{4\pi} \sin \theta \, d\theta \wedge d\varphi \longrightarrow \frac{d\mathcal{B} = 0}{\text{div}B = 0}$$

Example: Magnetic vector potential, hollow sphere

Consider now a sphere $S_{\rho}(0)$ with $R > \rho > \varepsilon$. Then

$$\langle \mathcal{B}, S_{\rho}(0) \rangle = \int_{S_{\rho}(0)} \mathcal{B} = \int_{[0,\pi] \times [0,2\pi]} \frac{c}{4\pi} \sin \theta \, d\theta \wedge d\varphi = \int_{0}^{2\pi} \int_{0}^{\pi} \frac{c}{4\pi} \sin \theta \, d\theta \, d\varphi = c \neq 0$$

But then $\exists A \in \mathcal{F}^1(M) : \mathcal{B} = dA$ is **impossible**, despite $d\mathcal{B} = 0$, since

$$0 \neq c = \langle \mathcal{B}, S_{\rho}(0) \rangle = \langle d\mathcal{A}, S_{\rho}(0) \rangle = \langle \mathcal{A}, \partial S_{\rho}(0) \rangle = 0$$

The vanishing of periods requires $\langle \mathcal{B}, S_R(0) \rangle = 0$ and rules out this situation !

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