

# JOANA FONSECA

PHD IN ROBOTICS AND CONTROL



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Recently finished my Ph.D. in KTH, Sweden, in control, motion planning, and decision-making for underwater robots. Developed software solutions using Adaptive Sampling and Gaussian Processes. Used data from sensor measurements, satellite imagery, and numerical models. Looking forward to working with you!

## PUBLICATIONS

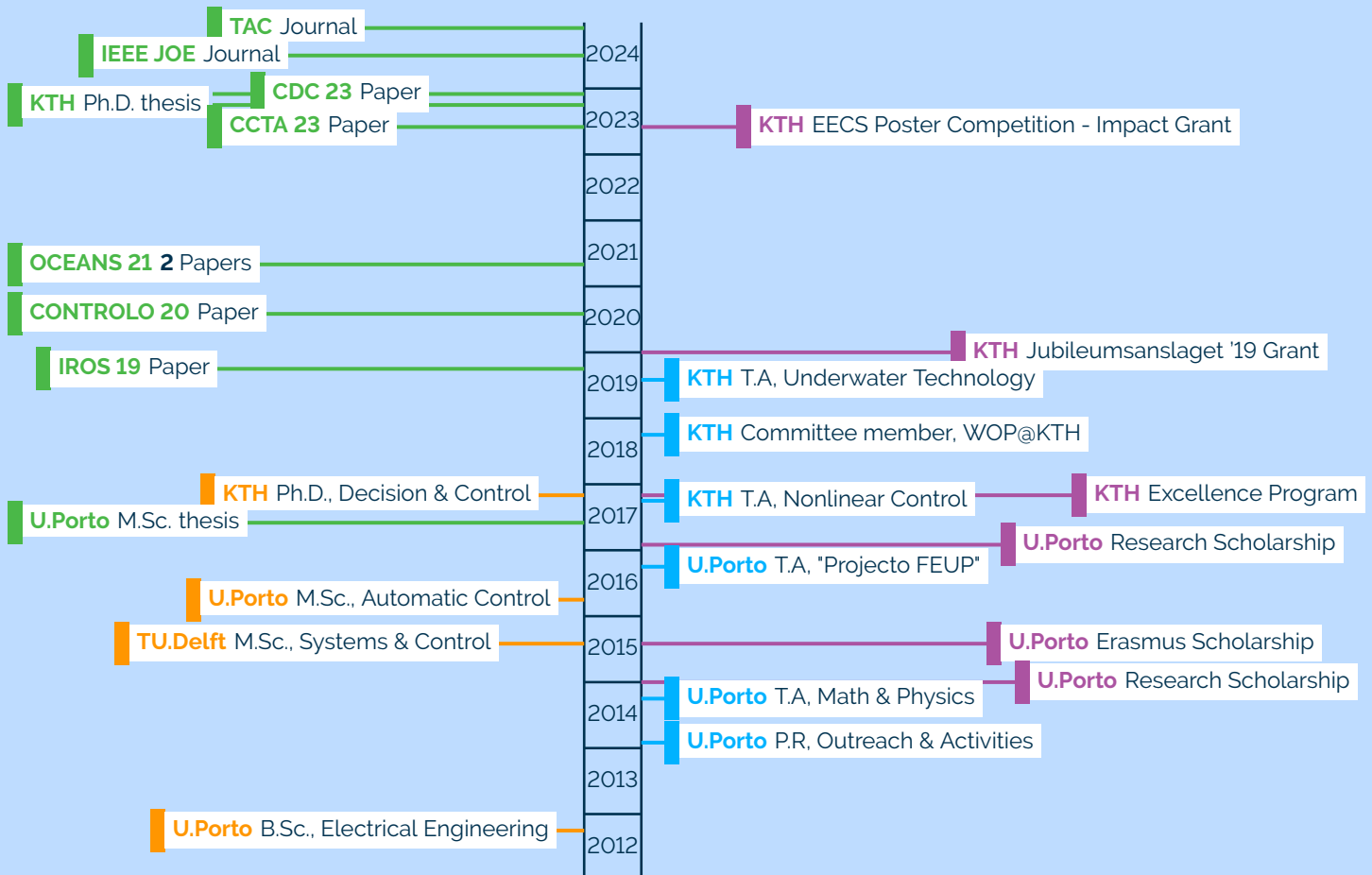
## EDUCATION

START DATE

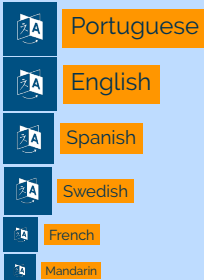
## EXPERIENCE

START DATE

## AWARDS



## LANGUAGES



## INTERESTS



## PROGRAMMING

