Data Science

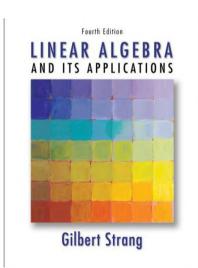
Linear Algebra

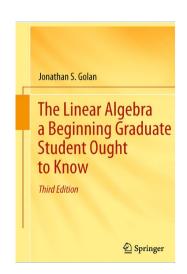
Basic and practical reminder

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Linear Algebra

- Representation spaces
- Applied Linear Algebra
- Matrix Calculus





Academic Linear Algebra

A vector space is a space of vectors with linear operations

Linear mapping f: V -> V
$$f(xM+BV) = \lambda f(x)$$

 A vector space can be equipped with a inner product, resulting in a pre-Hilbert space

Implications

→ Main implication: inner product vs projection

→ Main implication: coordinates in Shauder basis ≡

- → Main implication: representations spaces
 - → Vectors -> elements
 - → Matrices ma ling
 - → Matrix calculus

Example

Given a process f that transform my input (x,y,z) into (x',y',z') such that:

$$x' = -55x + 11y + 45z$$

 $y' = 130x - 26y - 103z$
 $z' = -100x + 20y + 81z$

Is f linear? \equiv

What if I apply f twice $(f \circ f)$?

What if I apply f 99 times (f^{99}) ?

What if I apply f 100 times (f^{100})?

Apply f twice

Search and replace:

$$x'' = -55x' + 11y' + 45z'$$
 = $-45x + 9y + 37z$
 $y'' = 130x' - 26y' - 103z'$ = $-230x + 46y + 185z$
 $z'' = -100x' + 20y' + 81z'$ = z

And continue?

More elegant solution?

$$f: \mathbb{R}^3 \to \mathbb{R}^3$$
 represented by matrix

And $f \circ f$

$$A^{2} = \begin{bmatrix} -45 & 9 & 37 \\ -250 & 46 & 185 \\ 0 & 0 & 1 \end{bmatrix}$$

So let's compute A⁹⁹

$$A^{2} = \begin{bmatrix} -45 & 9 & 37 \\ -250 & 46 & 85 \\ 0 & 0 & \end{bmatrix} \qquad A^{3} = \bigcirc$$

Can we rather use Linear Algebra??



Look at A

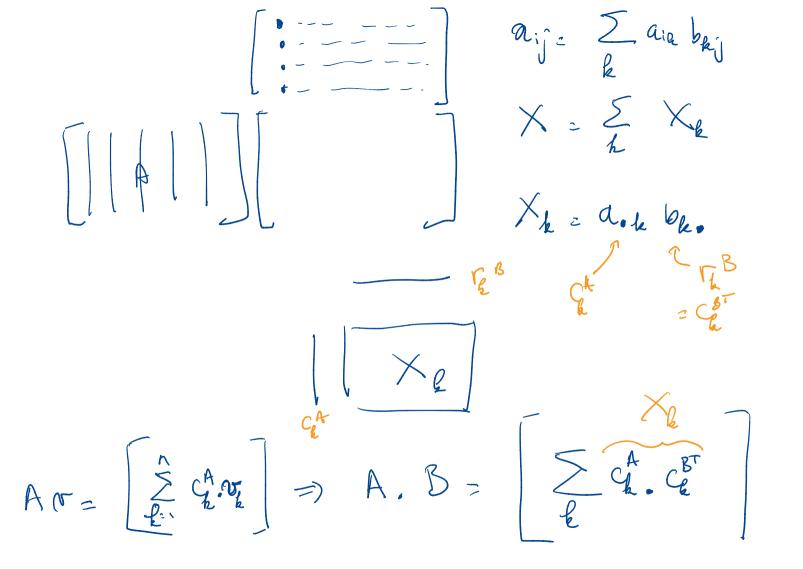
What does the facts that

$$c1 + c2 + c3 = \begin{bmatrix} 4 \\ 4 \\ 4 \end{bmatrix}$$

tell us? Anything else?

So what is A^{99} ? And what is A^{100} ?

A=
$$\begin{bmatrix} -55 & 11 & 15 \\ 150 & -26 & -105 \end{bmatrix}$$
 $\begin{bmatrix} r_1 \\ -100 & 20 & 81 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ -100 & 20 & 81 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_2 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_3 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_2 \\ r_4 \end{bmatrix}$ $\begin{bmatrix} r_1 \\ r_4$



The Fundamental Theorem of Linear Algebra

Gilbert Strang

 $\dim R(A) = \dim R(A^T)$ and $\dim R(A) + \dim N(A) = n$.

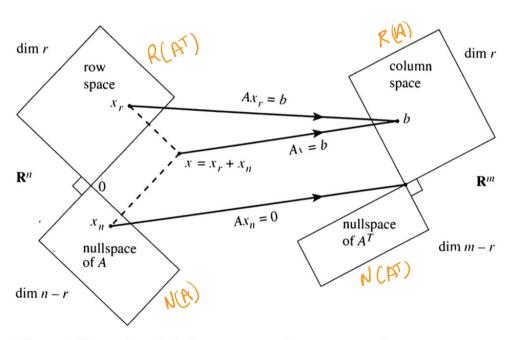


Figure 1. The action of A: Row space to column space, nullspace to zero.

What did we see?

- f can be represented by a matrix A -> Base Change
- A has rank 2 (Since C₂ = -5 C₁ π λ₂ = 0)
- U is a orthogonal matrix
- The Trace of A is invariant (so is the Det)
- A has a "eigenvalue" and a "eigenvector"

Ask yourselves:

- Why the above? How can I use that?
- What is the Range of a linear application?
- What is the Kernel of a linear application?
- What are their dimensions?

Any Question ? Anything (un) clear?