

DEPARTMENT OF INFORMATICS ENGINEERING

Logic and Constraint Programming

Masters in Informatics and Computing Engineering 2022/2023 - 2nd Semester

Constraint Systems

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Agenda

- IBM ILOG CP Optimizer
- Docplex.CP
- Google OR Tools CP-SAT Solver
- Example Exercises

Constraint Systems

IBM ILOG CP Optimizer (CPLEX)

- ILOG was one of the first companies (late 80s, early 90s) with a commercial tool using Constraint Programming technology
 - ILOG Solver was used in many industrial successful cases, mostly in Europe at first, but also around the world later on
- It was then acquired by IBM (late 2000s)
 - Developments continue, and IBM ILOG CP Optimizer continues to be one of the foremost constraint programming tools, used with special success in scheduling problems

See https://www.ibm.com/analytics/cplex-cp-optimizer

• IBM ILOG CP Optimizer can be used directly from the IBM ILOG CPLEX Optimization Studio, using OPL (Optimization Programming Language), or using one of the available interfaces: C++, Java, C#/.Net, and Python (DOcplex)

- CPLEX Optimization Studio and OPL provide
 - Separation of concerns between model and data
 - Support for external data sources (e.g., Excel files)
 - Good support for arrays, ranges, tuples and sets
 - Support for integer decision variables (*dvar*), but also floating-point decision expressions (*dexpr*) (e.g. for use as a cost function)
 - Many scheduling-related constraints
 - Some other global constraints
 - Many more features

- IBM ILOG CP Optimizer provides elements to concisely represent complex scheduling problems:
 - Variables of type interval, with start, end, size and intensity attributes
 - Precedence constraints
 - Cumulative expressions to define resource constraints
 - Other elements to model sequencing, synchronization, and other constraints
 - Documentation center (v. 22.1.1)
 - Other documents
 - <u>CP Optimizer User's Manual</u>
 - OPL Language User's Manual
 - OPL Language Reference Manual
 - OPL Functions (Language Quick Reference)

Arithmetic Operations and Expressions

- Arithmetic operations
 - addition
 - subtraction
 - multiplication
 - scalar products
 - integer division
 - floating-point division
 - modular arithmetic

- Arithmetic expressions
 - standard deviation
 - minimum
 - maximum
 - counting
 - absolute value
 - element or index

See https://www.ibm.com/docs/en/icos/22.1.1?topic=expressions-arithmetic

Arithmetic and Logical Constraints

- Arithmetic constraints
 - equal to (==)
 - not equal to (!=)
 - strictly less than (<)
 - strictly greater than (>)
 - less than or equal to (<=)
 - greater than or equal to (>=)

- Logical constraints
 - Logical AND (&&)
 - Logical OR (||)
 - Logical NOT (!)
 - Logical XOR (!=)
 - Equivalence (==)
 - Imply (=>)

Scheduling Precedence Constraints

- endAtEnd
- endAtStart
- endBeforeEnd
- endBeforeStart
- startAtEnd
- startAtStart
- startBeforeEnd
- startBeforeStart

All can include a delay to further separate events

Other Scheduling Constraints

- alternative
- span
- synchronize
- isomorphism
- presenceOf
- first / last
- before / prev
- noOverlap
- <= / alwaysIn</pre>
- alwaysConstant / alwaysEqual / alwaysNoState

Other Specialized Constraints

- allDifferent
- allMinDistance
- pack
- distribute
- inverse
- lex

Variable and Value Selection

- Search phase can be guided in order to increase performance
 - Variable selection
 - What variable should we select next to attribute a value?
 - Value selection
 - What value should we try first for the selected variable?
- IBM ILOG CP Optimizer also supports different 'search types'
 - Depth-first
 - Restart
 - Multi-point
 - Iterative-diving

Variable Selection

- selectSmallest(eval)
- selectLargest(eval)
- selectRandomVar()

Where eval may be:

- cp.factory.domainSize()
- cp.factory.domainMin()
- cp.factory.domainMax()
- cp.factory.regretOnMin()
- cp.factory.regretOnMax()
- cp.factory.successRate()
- cp.factory.impact()
- cp.factory.localImpact()
- cp.factory.impactOfLastBranch()
- cp.factory.varIndex(dvar int[])
- cp.factory.explicitVarEval(dvar int[],int[])

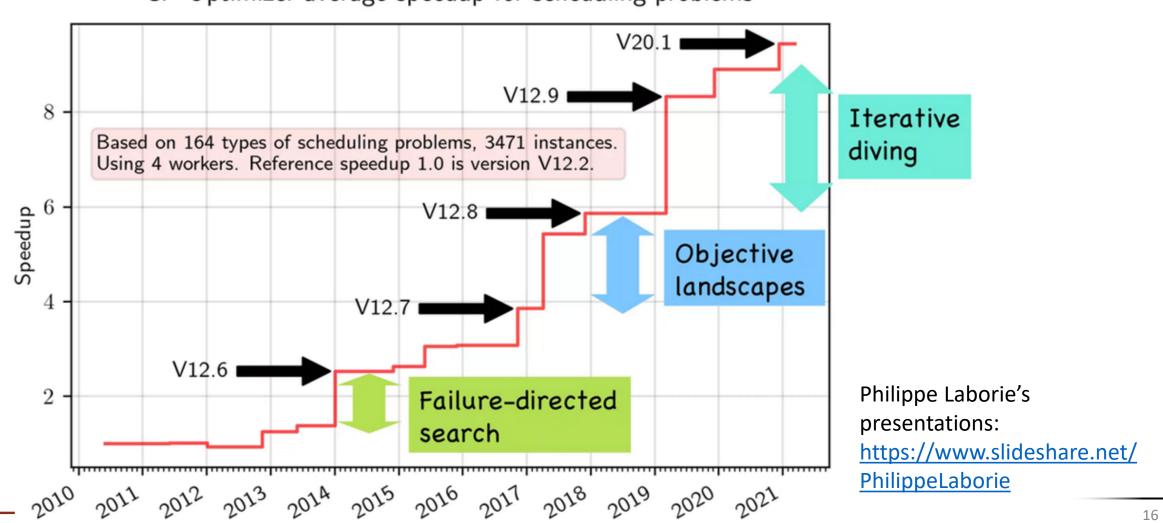
Value Selection

- selectSmallest(eval)
- selectLargest(eval)
- selectRandomValue()

Where eval may be:

- cp.factory.value()
- cp.factory.valueImpact()
- cp.factory.valueSuccessRate()
- cp.factory.valueIndex(int[])
- cp.factory.explicitValueEval(int[],int[])

CP Optimizer average speedup for scheduling problems



DOcplex.CP

Constraint Systems

DOcplex

- Python interface to IBM ILOG CP Optimizer
 - Provides access to both mathematical programming modeling and constraint programming modeling
 - Can work with local installation of CPLEX or connect to the cloud

See http://ibmdecisionoptimization.github.io/docplex-doc/

Typical Program Structure

- Import Solver module from docplex.cp.model import CpoModel
- Declare modelmodel = CpoModel()
- Add Variables to the model
- Add Constraints to the model
- Solve the model solution = model.solve() solution = model.solve(TimeLimit=120)

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• Creating a single integer variable

```
varName = model.integer_var(MinValue, MaxValue, "VarNameInModel")
```

Integer variables can also be created with explicit domains

```
varName = model.integer_var(name="VarNameInModel", domain=(1,3,5,7,9))
varName = model.integer_var(name="VarNameInModel", domain=(1, (3,7), 9))
```

Creating a list of integer variables at once

```
varsName = model.integer_var_list(NVars, MinVal, MaxVal, "VarsNameInModel")
```

• An explicit domain can also be used as with a single variable

```
vars = model.integer_var_list(NVars, name="VarsName", domain=(1,3,5,7,9) )
```

Creating a single interval variable

varName = model.interval_var(Start, End, Length, "VarNameInModel")

- Intervals can also be created as optional (optional=True)
- There is a distinction between interval Length and Size
 - Length is the duration of the interval if the intensity is always 100%
 - Size is the actual duration of the interval (can be higher than Length if intensity is sometimes below 100%)
 - The intensity is a stepwise function that can describe efficiency over time
- Lists of intervals can also be created at once

- In addition to integers and intervals, DOcplex also has:
 - Binary variables (and binary variable lists) (these are equivalent to integer variables with domain [0, 1])

```
varName = model.binary_var("VarNameInModel")
varsName = model.binary_var_list(Size, "VarNameInModel")
```

Sequence variables (they represent a sequence of intervals)
 varName = model.sequence_var(ListOfIntervals, "VarNameInModel")

You can also create dictionaries of (integer, interval or binary)
 variables in addition to lists

varsName = model.integer_var_dict(Keys, MinVal, MaxVal, "VarsNameInModel")

 Variable names are optional, but they are useful when visualizing (printing) the solution

- The *add(Expr)* method allows adding expressions to the model, which can be constraints, objectives, search phases, ...
 - Arithmetic expressions
 - Logical expressions
 - Constraints
 - Objectives (minimize / maximize)
 - Search phases (variable / value selectors)

See http://ibmdecisionoptimization.github.io/docplex-doc/cp/docplex-doc/cp/docplex.cp.modeler.py.html for a list of expressions and constraints

• Examples:

```
model.add( model.all_diff(ListOfVars) )
model.add( sumVar == model.sum(ListOfVars) )
model.add( nValuesVar == model.count_different(ListOfVars) )
model.add( model.distribute(Occurrences, ListOfVars, Values) )
model.add ( model.minimize(VarName) )
model.add(
  model.search_phase(varchooser=model.select_smallest(model.domain_size()),
  valuechooser=model.select_smallest(model.value()) ) )
```

- Several properties and functions can be used to obtain information from variables, useful in specifying constraints
 - From integer variables we can determine:
 - The lower and upper bounds of the domain: varName.lb, varName.ub
 - The domain of the variable: varName.get_domain()
 - Whether a value is contained in the domain: varName.domain_contains(Value)
 - Whether the variable is binary: varName.is_binary()
 - And also set the domain of a variable
 - The domain is represented in the same manner as when declaring an integer variable given a domain

See http://ibmdecisionoptimization.github.io/docplex-doc/cp/docplex.cp.expression.CpoIntVar

- Interval variables also provide much information and functionality:
 - Obtaining interval start, end, length, size, intensity, etc.: varName.get_start(), varName.get_end(), varName.get_length(), varName.get_size(), ...
 - Setting interval start, end, length, size, intensity, etc. using either intervals or specifying minimum and/or maximum values: varName.set_start(Interval), varName.set_end(Interval), varName.set_length(Interval), varName.set_start_min(Value), varName.set_start_max(Value), ...
 - Determining whether the interval is optional, present or absent: varName.is_optional(), varName.is_absent(), varName.is_present(), ...
 - Setting interval as optional, present or absent: varName.set_optional(),
 varName.set_absent(), varName.set_present(), ...

See http://ibmdecisionoptimization.github.io/docplex-doc/cp/docplex-doc/cp/docplex.cp.expression.py.html#docplex.cp.expression.CpoIntervalVar

Google OR-Tools CP-SAT Solver

Constraint Systems

Google OR-Tools CP-SAT Solver

- OR-Tools provides many functionalities
 - Dedicated algorithms for specific problems (e.g. knapsack problem)
 - Includes a CP-SAT Solver
 - External interfaces (Python, C++, Java, .Net)
 - Several global constraints
 - Very good performance
 - eg, very good results in the MiniZinc Challenge

Google OR-Tools CP-SAT Solver

- Google OR-Tools provides elements to concisely represent several problems:
 - Boolean and Integer Variables
 - Intervals (and Optional Intervals)
 - Constants

- For more information
 - OR-Tools Constraint Programming
 - Python CP-SAT Reference

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Typical Program Structure

- Import SAT-CP module from ortools.sat.python import cp_model
- Declare modelmodel = cp_model.CpModel()
- Add Variables to the model
- Add Constraints to the model
- Declare the solver and solve the model solver = cp_model.CpSolver() status = solver.Solve(model)

Variable Types

- Constants
 - model.NewConstant(Value)
- Booleans
 - model.NewBoolVar(Name)
- Integers
 - model.NewIntVar(Lower Bound, Upper Bound, Name)
 - model.NewIntVarFromDomain(Domain, Name)
- Intervals
 - model.NewIntervalVar(Start, Duration, End, Name)
 - model.NewOptionalIntervalVar(Start, Dur, End, Is Present, Name)

Domains

Domains can be constructed from lists of Values or Intervals

```
dom = cp_model.Domain.FromValues([1,3,5,7,9])
dom = cp_model.Domain.FromIntervals([[1-5], [7,7], [9,9]])
```

There are some methods to obtain information about a domain

```
dom.IsEmpty()
dom.Size()
dom.Min()
dom.Max()
dom.Contains(Value)
```

There are also useful domain manipulation methods

```
dom.UnionWith( anotherDomain )
dom.IntersectionWith( anotherDomain )
```

Constraints

- Constraints over linear expressions
 - Add(Linear Expression)
 - AddLinearConstraint(Linear Expression, Lower, Upper) [Low<= Expr<= Up]
 - AddLinearExpressionInDomain(Linear Expression, Domain)
- Propositional Constraints
 - AddBoolAnd(Literals)
 - AddBoolOr (Literals)
 - AddBoolXOr (Literals)
 - AddImplication(Antecedent, Consequent)
 - Negation: *Var.Not()* [for Boolean variables]
- Absolute and Modulo
 - AddAbsEquality(Value, Variable) [Value = abs(Variable)]
 - AddModuloEquality(Value, Variable, Modulo) [Value = Variable % Modulo]

Constraints

- Division and Multiplication
 - AddDivisionEquality(Value, Numerator, Denominator)
 - AddMultiplicationEquality(Value, List of Variables)
- Sum, Term and Scalar Product
 - Sum(Expressions)
 - Term(Expression, Coefficient)
 - ScalProd(Expressions, Coefficients)
- Minimum and Maximum
 - AddMaxEquality(Max Value, Variables)
 - AddMinEquality(Min Value, Variables)
- Domain Mapping
 - AddMapDomain(Variable, List of Bools, Offset)

Constraints

- All Different
 - AddAllDifferent(List of Variables)
- Element
 - AddElement(Index, List of Variables, Value)
- Allowed and Forbidden Assignments
 - AddAllowedAssignments(List of Variables, List of Tuples)
 - AddForbiddenAssignments(List of Variables, List of Tuples)
- Circuit
 - AddCircuit(List of Arcs)
 - Arcs are tuples (Source Node, Destination Node, Literal)
- Cumulative
 - AddCumulative(Intervals, Demands, Capacity)

Constraints

- Reservoir
 - AddReservoirConstraint(Times, Demands, Min, Max)
 - AddReservoirConstraintWithActive(Times, Demands, Actives, Min, Max)
- Automaton
 - AddAutomaton(Transitions Variables, Start State, Final States, Transitions)
 - Transitions is a list of tuples (From State, Variable Value, Destination State)
- Inverse
 - AddInverse(Variables, Inverse Variables)
- No Overlapping Constraints
 - AddNoOverlap(List of Intervals)
 - AddNoOverlap2D(X Intervals, Y Intervals)

Other Features

- Reified Constraints
 - Constraint.OnlyEnforceIf(Literal or List of Literals)
- Optimization
 - Minimize(Objective)
 - Maximize(Objective)
- Search Strategy
 - AddDecisionStrategy(Variables, Variable Strategy, Value Strategy)

Solver Features

- Timeout
 - solver.parameters.max_time_in_seconds = 10.0
- Solve
 - Solve(Model)
 - SearchForAllSolutions(Model, Callback)
 - SolveWithSolutionCallback(Model, Callback)
- Statistics
 - NumBooleans
 - NumBranches
 - NumConflicts
 - ObjectiveValue
 - UserTime
 - WallTime
 - Value(Variable or Expression)

Example Exercises

Constraint Systems

Example Exercises

- 3x3 Magic Square
- Wedding Table
- Lazy Mailman
- Map Coloring
- Bus Company

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3x3 Magic Square

- Solve the 3x3 Magic Square
 - Fill the square with values from 1 to 9
 - All cells must have a different value
 - The sum of each line, column or diagonal must be the same

А	В	С
D	E	F
G	Η	I

3x3 Magic Square – (SICStus) Prolog Model

```
:-use module(library(clpfd)).
magicSquare:-
         Vars = [C1, C2, C3, C4, C5, C6, C7, C8, C9],
         domain(Vars, 1, 9),
         all distinct(Vars),
         C1 + C2 + C3 \# = Soma,
                                        % Rows
         C4 + C5 + C6 \# = Soma,
         C7 + C8 + C9 \# = Soma,
         C1 + C4 + C7 \# Soma,
                                        % Cols
         C2 + C5 + C8 \# = Soma,
         C3 + C6 + C9 \# = Soma,
         C1 + C5 + C9 \# = Soma,
                                        % Diagonals
         C3 + C5 + C7 #= Soma,
         C1 #< C3, C3 #< C7,
                                        % Symmetry-breaking constraints
          labeling([], Vars),
         write(Vars).
```

3x3 Magic Square – OPL Model

```
using CP;
dvar int numbers[1..9] in 1..9;
dvar int summ in 6..24;
                                     //int summ = 15; // Given by n (n^2 + 1)/2 (more efficient)
constraints
    allDifferent(numbers);
                                                       // Rows
    numbers[1] + numbers[2] + numbers[3] == summ;
    numbers[4] + numbers[5] + numbers[6] == summ;
    numbers[7] + numbers[8] + numbers[9] == summ;
                                                       // Cols
    numbers[1] + numbers[4] + numbers[7] == summ;
    numbers[2] + numbers[5] + numbers[8] == summ;
    numbers[3] + numbers[6] + numbers[9] == summ;
    numbers[1] + numbers[5] + numbers[9] == summ;
                                                       // Diagonals
    numbers[3] + numbers[5] + numbers[7] == summ;
                                                        // Symmetry-breaking constraints
    numbers[1]<numbers[3];</pre>
    numbers[3]<numbers[7];
```

3x3 Magic Square – DOcplex.CP Model

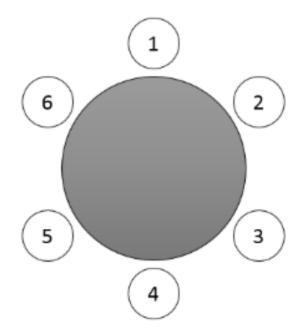
```
model = CpoModel()
Square = model.integer var list(9, 1, 9, "Squares")
Sum = model.integer var(6, 24, "Sum")
                                                          # Sum = 15
for i in range(3):
    model.add( Square[i*3] + Square[i*3+1] + Square[i*3+2] == Sum )
                                                                           # Row i
    model.add( Square[i] + Square[3+i] + Square[6+i] == Sum )
                                                                           # Col i
model.add( Square[0] + Square[4] + Square[8] == Sum )
                                                                    # Diagonal \
model.add( Square[6] + Square[4] + Square[2] == Sum )
                                                                    # Diagonal /
model.add( model.all diff(Square) )
model.add( Square[0] < Square[2] )
                                                          # Symmetry-breaking constraints
model.add( Square[2] < Square[6] )
solution = model.solve()
if solution:
    solution.print solution()
```

3x3 Magic Square – OR-Tools Python Model

```
model = cp model.CpModel()
List = [ model.NewIntVar(1, 9, 'v'+str(x+1)) for x in range(9) ]
Sum = model.NewIntVar(6, 24, "Sum")
                                                   # Sum = model.NewConstant(15)
for i in range(3):
    model.Add(List[i*3] + List[i*3+1] + List[i*3+2] == Sum)
                                                                     # Rows
    model.Add(List[i] + List[3+i] + List[6+i] == Sum)
                                                                     # Cols
model.Add(List[0] + List[4] + List[8] == Sum)
                                                           # Diagonal \
model.Add(List[6] + List[4] + List[2] == Sum)
                                                           # Diagonal /
model.AddAllDifferent(List)
# model.Add( List[0] < List[2] )
                                                 # Symmetry-breaking constraints
# model.Add( List[2] < List[6] )
solver = cp model.CpSolver()
status = solver.Solve(model)
```

Wedding Table

- We want to sit six people in a round table such that some constraints are met:
 - Adam and Bernadette should sit together
 - Christina and Emmet should sit together
 - Emmet and Francis should NOT sit together
 - Adam and Emmet should NOT sit together
- Try to make the model flexible so as to adapt to different problem sizes
- Try to improve performance by avoiding symmetries



Wedding Table – (SICStus) Prolog Model

• List with the place each person is sitting at

```
wedTable(TableSize, Adj, Dist):-
         % Example input:
                   TableSize = 6, Adj = [1-2, 3-5], Dist = [5-6, 1-5],
         %
          length(PersonSeat, TableSize),
         domain(PersonSeat, 1, TableSize),
         all distinct(PersonSeat),
          processAdj(TableSize, PersonSeat, Adj),
          processDist(TableSize, PersonSeat, Dist),
         element(1, PersonSeat, 1),
                                                 % Avoid Rotate Symmetry
         element(2, PersonSeat, S),
                                                 % Avoid Mirror Symmetry
         element(TableSize, PersonSeat, L),
         S #< L,
          labeling([], PersonSeat),
         write(PersonSeat).
```

Adam 1
Bernadette 2
Christina 3
Dina 4
Emmet 5
Francis 6

Wedding Table – (SICStus) Prolog Model

Constraints

```
processAdj( TableSize, PersonSeat, []).
processAdj(TableSize, PersonSeat, [F-S|Adj]):-
          element(F, PersonSeat, FP),
          element(S, PersonSeat, SP),
          abs(FP-SP) #= 1 # \sqrt{abs(FP-SP)} #= TableSize-1,
          processAdj(TableSize, PersonSeat, Adj).
processDist( TableSize, PersonSeat, []).
processDist(TableSize, PersonSeat, [F-S|Dist]):-
          element(F, PersonSeat, FP),
          element(S, PersonSeat, SP),
          abs(FP-SP) \# = 1, abs(FP-SP) \# = TableSize-1,
          processDist(TableSize, PersonSeat, Dist).
```

Wedding Table – OPL Model

List with the place each person is sitting at and problem input

```
using CP;
int TableSize = 6;
dvar int PersonSeat [1..TableSize] in 1..TableSize;
tuple Pair {
    int First;
    int Second;
};
int NAdjacencies = 2;
int NDistances = 2;
Pair adj [1..NAdjacencies] = [ <1, 2>, <3, 5> ];
Pair dist [1..NDistances] = [ <5, 6>, <1, 5> ];
```

Adam	1
Bernadette	2
Christina	3
Dina	4
Emmet	5
Francis	6

Wedding Table – OPL Model

Constraints

 The model can work with any problem size (table size, number of constraints), merely by adjusting input

Wedding Table – OPL Model

- Removal of symmetries
 - We can add some constraints to limit the number of symmetrical solutions, thus improving the performance of the solver

Wedding Table – DOcplex.CP Model

• List with the place each person is sitting at

```
TableSize = 6;
Adjacents = [ [1, 2], [3, 5] ]
Distants = [ [5, 6], [1, 5] ]

model = CpoModel()

PersonSeat = model.integer_var_list(TableSize, 1, TableSize, "PersonSeat")
model.add( model.all_diff(PersonSeat) )

distances = []
```

Adam 1
Bernadette 2
Christina 3
Dina 4
Emmet 5
Francis 6

Wedding Table – DOcplex.CP Model

Constraints and symmetry removal

```
for pair in Adjacents:
    distances.append(model.integer var(domain=(-TableSize+1, -1, 1, TableSize-1),
                                            name="d"+str(pair[0])+str(pair[1]) ))
    model.add( PersonSeat[ pair[0]-1 ] - PersonSeat[ pair[1]-1 ] == distances[-1] )
for pair in Distants:
    model.add(PersonSeat[pair[0]-1] - PersonSeat[pair[1]-1]!= 1)
    model.add(PersonSeat[ pair[0]-1 ] - PersonSeat[ pair[1]-1 ] != -1)
    model.add(PersonSeat[ pair[0]-1 ] - PersonSeat[ pair[1]-1 ] != TableSize-1)
    model.add(PersonSeat[pair[0]-1] - PersonSeat[pair[1]-1]!= -TableSize+1)
model.add( PersonSeat[0] == 1)
model.add( PersonSeat[1] < PersonSeat[TableSize-1] )
solution = model.solve()
if solution:
    solution.print solution()
```

Wedding Table – OR-Tools Python Model

• List with the place each person is sitting at

```
TableSize = 6;
Adjacents = [ [1, 2], [3, 5] ]
Distants = [ [5, 6], [1, 5] ]

PersonSeat = [TableSize]  # To use 1-based indexes

model = cp_model.CpModel()

for i in range(TableSize):
    PersonSeat.append( model.NewIntVar(1, TableSize, "p"+str(i+1)) )

model.AddAllDifferent(PersonSeat[1:])
```

Adam 1
Bernadette 2
Christina 3
Dina 4
Emmet 5
Francis 6

Wedding Table – OR-Tools Python Model

Constraints and symmetry removal

```
distances = []
                            # Aux var with possible adjacency distance values for each adjacent pair
for pair in Adjacents:
    distances.append(model.NewIntVarFromDomain(cp model.Domain.FromValues([-TableSize+1,
         -1, 1, TableSize-1]), "d"+str(pair[0])+str(pair[1]) ))
    model.Add( PersonSeat[ pair[0] ] - PersonSeat[ pair[1] ] == distances[-1] )
for pair in Distants:
    model.Add(PersonSeat[pair[0]] - PersonSeat[pair[1]]!= 1)
    model.Add(PersonSeat[pair[0]] - PersonSeat[pair[1]]!= -1)
    model.Add(PersonSeat[pair[0]] - PersonSeat[pair[1]]!= TableSize-1)
    model.Add(PersonSeat[pair[0]] - PersonSeat[pair[1]]!= -TableSize+1)
model.Add( PersonSeat[1] == 1)
                                                # Remove some symmetries
model.Add( PersonSeat[2] < PersonSeat[TableSize] )</pre>
solver = cp_model.CpSolver()
status = solver.Solve(model)
```

Lazy Mailman

- A lazy mailman with few letters to deliver has set a goal of taking as long as possible to deliver the mail in the last street of his round
 - It is a straight street, with ten houses, all ten meters apart from each other
 - He always walks at ten meters per minute, and wants to finish at house 6 (the person living there always offers him coffee and cake).
 - He has a (greedy) solution, starting in house 1, then going to house 10, then house 2, ..., and finally 6, which results in 45 minutes (9+8+7+6+5+4+3+2+1)
 - Model this problem using constraint programming to find a better solution (one that takes even longer than 45 minutes)
 - Note: consider that the mailman enters the street orthogonally and time starts counting from the first house he visits

Lazy Mailman – (SICStus) Prolog Model

• List of visited houses (order of visit)

```
lazy:-
         Size = 10,
          length( HouseOrder, Size ),
          domain( HouseOrder, 1, Size ),
          all_distinct( HouseOrder ),
          element(Size, HouseOrder, 6),
          calcDistance( HouseOrder, Distance ),
          Distance #> 45,
          labeling([maximize(Distance)], HouseOrder),
          write( HouseOrder-Distance ).
calcDistance( [Last], 0).
calcDistance( [F, N|R], Distance):-
         Step \#= abs(F - N),
         calcDistance([N|R], NDist),
          Distance #= NDist + Step.
```

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Lazy Mailman – OPL Model

• List of visited houses (order of visit)

```
using CP;
dvar int houseOrder [1..10] in 1..10;

dexpr float distance = sum(i in 1..9) abs(houseOrder[i+1] - houseOrder[i]);
maximize distance;

subject to {
    allDifferent(houseOrder);
    houseOrder[10] == 6;
    distance >= 45;
}
```

Lazy Mailman – OPL Model

 Possible improvement: execute block with instructions to change variable and value choice methods and/or search type

Lazy Mailman – DOcplex.CP Model

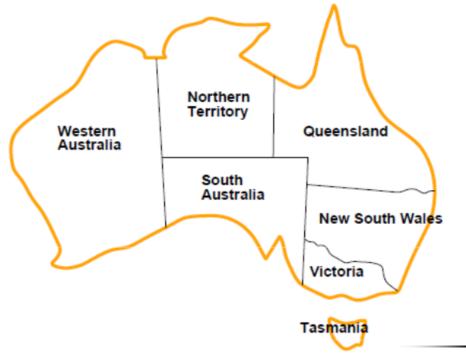
```
model = CpoModel()
NHouses = 10
houses = model.integer var list(NHouses, 1, NHouses, "Houses")
model.add( model.all diff(houses) )
model.add( houses[NHouses-1] == 6 )
distances = model.integer var list(NHouses-1, 1, NHouses, "Distances")
for i in range(0, NHouses-1):
    model.add( distances[i] == model.abs( houses[i+1] - houses[i] ) )
dist = model.integer var(0, NHouses * NHouses, "Dist")
model.add( dist == model.sum(distances) )
model.add( model.maximize(dist) )
solution = model.solve(TimeLimit=120)
if solution:
    solution.print solution()
```

Lazy Mailman – OR-Tools Python Model

```
model = cp model.CpModel()
NHOUSES = 10
houses = [ model.NewIntVar(1, NHOUSES, 'h'+str(i)) for i in range(1, NHOUSES+1) ]
model.AddAllDifferent(houses)
model.AddElement(NHOUSES-1, houses, 6)
travelTime = []
for i in range(NHOUSES-1):
    tempVar = model.NewIntVar( -NHOUSES, NHOUSES, 'o'+str(i) )
    model.Add( tempVar == houses[i+1] - houses[i] );
    travelTime.append( model.NewIntVar(1, NHOUSES, 'd'+str(i)) )
    model.AddAbsEquality( travelTime[-1], tempVar )
dist = model.NewIntVar(0, NHOUSES*NHOUSES, "Dist")
model.Add( dist == sum(travelTime) )
model.Maximize(dist)
solver = cp model.CpSolver()
status = solver.Solve(model)
```

Map Coloring

- Map Coloring is a classic problem, with the goal of coloring a map with N different colors such that no two adjacent areas have similar colors.
 - Solve the problem for Australia using the minimum amount of colors possible (and at most 5 colors)



Map Coloring – (SICStus) Prolog Model

```
mapColor:-
          length(StateColors, 7),
          domain(StateColors, 1, 5),
          % StateNames = ['WA', 'NT', 'SA', 'Q', 'NSW', 'V', 'T'],
          StateAdjacencies = [1-2, 1-3, 2-3, 2-4, 3-4, 3-5, 3-6, 4-5, 5-6],
          processAdj(StateColors, StateAdjacencies),
          maximum(MaxColor, StateColors),
          labeling([minimize(MaxColor)], StateColors),
          write(StateColors).
processAdj( StateColors, []).
processAdj(StateColors, [F-S|Adj]):-
          element(F, StateColors, FC),
          element(S, StateColors, SC),
          FC \# \subseteq SC
          processAdj(StateColors, Adj).
```

Map Coloring – OPL Model

```
using CP;
int NStates = 7;
//string StateNames[1..NStates] = ["WA", "NT", "SA", "Q", "NSW", "V", "T"];
tuple Pair{ int first; int second; }
{Pair} StateAdjacencies = {<1,2>, <1,3>, <2,3>, <2,4>, <3,4>, <3,5>, <3,6>, <4,5>, <5,6>};
int MaxColors = 5;
dvar int StateColors[1..NStates] in 1..MaxColors;
minimize max(i in 1..NStates) StateColors[i];
subject to
    forall(<a, b> in StateAdjacencies)
         StateColors[a] != StateColors[b];
```

Map Coloring – DOcplex.CP Model

```
model = CpoModel()
NStates = 7
StateNames = ["WA", "NT", "SA", "Q", "NSW", "V", "T"];
StateAdjacencies = [(1,2), (1,3), (2,3), (2,4), (3,4), (3,5), (3,6), (4,5), (5,6)]
MaxColors = 5
StateColors = model.integer var list(NStates, 1, MaxColors, "StateColors")
for a, b in StateAdjacencies:
    model.add(StateColors[a-1] != StateColors[b-1])
AllColors = list( range(1, MaxColors+1) )
ColorCounts = model.integer var list(MaxColors, 0, NStates, "ColorCounts")
model.add( model.distribute(ColorCounts, StateColors, AllColors) )
model.add( model.maximize( model.count(ColorCounts, 0) ) )
solution = model.solve(TimeLimit=120)
if solution:
    solution.print solution()
```

Map Coloring – OR-Tools Python Model

```
MaxColors = 5
NStates = 7
StateNames = ["WA", "NT", "SA", "Q", "NSW", "V", "T"]
StateAdjacencies = [(1,2), (1,3), (2,3), (2,4), (3,4), (3,5), (3,6), (4,5), (5,6)]
StateColors = [ model.NewIntVar(1, MaxColors, 'State' + str(i)) for i in range(NStates) ]
for a, b in StateAdjacencies:
    model.Add(StateColors[a-1] != StateColors[b-1])
model.Minimize( max(StateColors) )
solver = cp model.CpSolver()
status = solver.Solve(model)
```

Holiday Bus Company

- A bus company has several buses that can be used to ferry several groups of tourists to their vacation destination.
- Different buses have different capacities, and each group of tourists has a different size.
- The goal is to allocate groups of tourists to buses such that:
 - Each group is not separated (the entire group travels in the same bus)
 - The number of used buses is minimized (each bus may ferry several groups)
- Example problem input:
 - 4 buses with capacities of 11, 14, 10, 20
 - 5 groups of sizes 5, 5, 7, 4, 3

Holiday Bus Company – (SICStus) Prolog Model

```
busCompany:-
    Buses = [11, 14, 10, 20],
    length(Buses, NBuses),
    Groups = [5, 5, 7, 4, 3],
    length(Groups, NGroups),
    create_items(Groups, Items, AssignedBuses),
    domain(AssignedBuses, 1, NBuses),
    create bins(Buses, 1, Bins),
    bin packing(Items, Bins),
    nvalue(UsedBuses, AssignedBuses),
    labeling([minimize(UsedBuses)], AssignedBuses),
    write(UsedBuses-AssignedBuses).
create_items([], [], []).
create items([Size | Gs], [item(Bin, Size) | Items], [Bin | IDs]):-
         create items(Gs, Items, IDs).
```

Holiday Bus Company – OPL Model

```
using CP;
// Buses (Bin maxLoads)
int NBuses = 4;
int MaxLoads[1..NBuses] = [11, 14, 10, 20];
int MaxMaxLoad = max(i in 1..NBuses) MaxLoads[i];
dvar int Loads[1..NBuses] in 0..MaxMaxLoad;
// Groups (Item weights)
int NGroups = 5;
int Weights[1..NGroups] = [5, 5, 7, 4, 3];
// Attribution (Packing)
dvar int PackIDs [1..NGroups] in 1..NBuses;
// Used Buses (Non-zero)
dvar int NonZero in 1..NBuses;
```

```
minimize NonZero;
subject to
{
    forall(i in 1..NBuses)
        Loads[i] <= MaxLoads[i];
    pack(Loads, PackIDs, Weights, NonZero);
}</pre>
```

Holiday Bus Company – DOcplex.CP Model

```
model = CpoModel()
# Groups (Weights)
NGroups = 5
Weights = [5, 5, 7, 4, 3]
# Buses (MaxLoads)
NBuses = 4
MaxLoads = [11, 14, 10, 20]
MaxMaxLoad = max(MaxLoads)
Loads = model.integer var list(NBuses, 0, MaxMaxLoad, "Loads")
# Attribution (Packing)
PackIDs = model.integer var list(NGroups, 1, NBuses, "PackIDs")
# Used Buses (Non-zero)
NonZero = model.integer var(1, NBuses, "NonZero")
```

Holiday Bus Company – DOcplex.CP Model

```
for i in range(NBuses):
    model.add( Loads[i] <= MaxLoads[i] )

model.add( model.pack(Loads, PackIDs, Weights, NonZero) )

model.add( model.minimize(NonZero) )

solution = model.solve( TimeLimit=120 )

if solution:
    solution.print_solution()</pre>
```

Holiday Bus Company – OR-Tools Python Model

- The new CP-SAT Solver lacks several global constraints that could be very useful:
 - pack, nvalue, global_cardinality (distribute), count, ...
- The original CP Solver has some of these constraints
 - Documentation on the original CP solver available online at https://developers.google.com/optimization/reference/python/constraint_solver/pywrapcp#solver_3

Holiday Bus Company – OR-Tools Python Model

```
model = cp model.CpModel()
NGroups = 5
Weights = [5, 5, 7, 4, 3]
NBuses = 4
MaxLoads = [11, 14, 10, 20]
Loads = [model.NewIntVar(0, MaxLoads[i], "Loads"+str(i)) for i in range(NBuses)]
# Attribution (0-1 Matrix)
Attribution = [ [model.NewIntVar(0, 1, "Attr"+str(i)+str(j) ) for i in range(NBuses)] for j in range(NGroups)]
# Groups are exactly on one Bus
for i in range(NGroups):
    model.Add( 1 == sum(Attribution[i][j] for j in range(NBuses)))
```

Holiday Bus Company – OR-Tools Python Model

```
def add_count_eq(vars, value, count, model):
    boolvars = []
    for var in vars:
        boolvar = model.NewBoolVar('')
        model.Add(var == value).OnlyEnforceIf(boolvar)
        model.Add(var != value).OnlyEnforceIf(boolvar.Not())
        boolvars.append(boolvar)
    model.Add(count == sum(boolvars))
```

Q & A



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