Tello SDK

1.3.0.0

1. OVERVIEW

The Tello SDK connects to the aircraft through a Wi-Fi UDP port, allowing users to control the drone with text commands. Click here to download the Tello3.py file.

2. ARCHITECTURE

Use Wi-Fi to establish communication between Tello and PC, Mac or Mobile device

Send Command & Receive Response

Tello IP: 192.168.10.1 UDP PORT:8889 <<- ->> PC/Mac/Mobile

Remark1: Set up a UDP client on PC, Mac or Mobile device to send and receive message from Tello via the same port.

Remark2: Send "command" command to Tello via UDP PORT 8889 to initiate Tello's SDK mode, before sending all other commands.

Receive Tello State

Tello IP: 192.168.10.1 ->> PC/Mac/Mobile UDP Server: 0.0.0.0 UDP PORT:8890

Remark3: Set up a UDP server on PC, Mac or Mobile device and listen the message from IP 0.0.0.0 via UDP PORT 8890. Do Remark2 to start receiving state data if you haven't.

Receive Tello Video Stream

Tello IP: 192.168.10.1 ->> PC/Mac/Mobile UDP Server: 0.0.0.0 UDP PORT:11111

Remark4: Set up a UDP server on PC, Mac or Mobile device and listen the message from IP 0.0.0.0 via UDP PORT 11111.

<u>Remark5</u>: Do Remark2 if you haven't. Then send "streamon" command to Tello via UDP PORT 8889 to start the streaming.

3. TELLO COMMAND TYPES AND RESULTS

This SDK includes three basic command types.

• Control Commands (xxx)

- returns "ok" if the command is executed successfully
- returns "error" or an informative result code if unsuccessful

• Read Commands (xxx?)

• returns the current value of the sub-parameter(s).

• Set Command (xxx a) will attempt to set a new sub-parameter value(s)

- returns "ok" if the command is executed successfully
- returns "error" or an informative result code if unsuccessful

4. TELLO COMMANDS

Control Commands

| Command | Description | Possible Response |
|---------|----------------|-------------------|
| command | entry SDK mode | ok |
| | | error |

| Command | Description | Possible Response |
|---------|--------------------|-------------------|
| takeoff | Tello auto takeoff | ok |
| | | error |

| Command | Description | Possible Response |
|---------|-----------------|-------------------|
| land | Tello auto land | ok |
| | | error |

| Command | Description | Possible Response |
|----------|---------------------|-------------------|
| streamon | Set video stream on | ok |
| | | error |

| Command | Description | Possible Response |
|-----------|----------------------|-------------------|
| streamoff | Set video stream off | ok |
| | | error |

| Command | Description | Possible Response |
|-----------|-----------------------------|-------------------|
| emergency | Stop all motors immediately | ok |
| | | error |

| Command | Description | Possible Response |
|---------|---------------------------------|-------------------|
| up x | Tello fly up with distance x cm | ok |
| | x: 20-500 | error |

| Command | Description | Possible Response |
|---------|-----------------------------------|-------------------|
| down x | Tello fly down with distance x cm | ok |
| | x: 20-500 | error |

| Command | Description | Possible Response |
|---------|-----------------------------------|-------------------|
| left x | Tello fly left with distance x cm | ok |
| | x: 20-500 | error |

| Command | Description | Possible Response |
|---------|------------------------------------|-------------------|
| right x | Tello fly right with distance x cm | ok |
| | x: 20-500 | error |

| Command | Description | Possible Response |
|-----------|-----------------------------------|-------------------|
| forward x | Tello fly forward with distance x | ok |
| | cm | error |
| | x: 20-500 | |

| Command | Description | Possible Response |
|---------|-----------------------------------|-------------------|
| back x | Tello fly back with distance x cm | ok |
| | x: 20-500 | error |

| Command | Description | Possible Response |
|---------|---------------------------------|-------------------|
| cw x | Tello rotate x degree clockwise | ok |
| | x: 1-3600 | error |