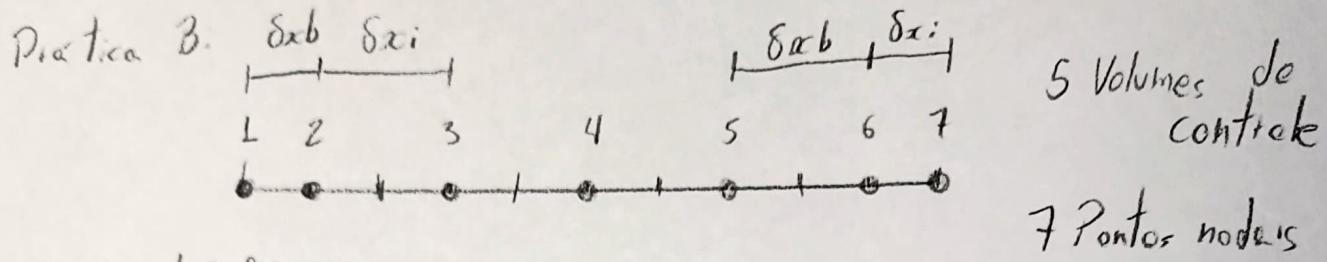


PMT09 - Lista de Exercícios 4

João Gabriel Clarindo

$$\frac{d}{dx} \left(h \frac{dT}{dx} \right) = 0 \quad \text{Condução 1D em RP sem afecção}$$



$$T(0) = 150^\circ\text{C}$$

$$T(x=L) = 50^\circ\text{C}$$

Pontos nodais internos: #3, #4 e #5

$$\left(h \frac{dT}{dx} \right)_e - \left(h \frac{dT}{dx} \right)_{w'} = 0$$

$$\frac{h_e}{\Delta x_e} \frac{T_E - T_P}{\Delta x_e} - \frac{h_w}{\Delta x_w} \frac{T_P - T_W}{\Delta x_w} = 0$$

Sabendo que $h_e = h_w$ (h constante) e $\Delta x_e = \Delta x_w$ (malha uniforme)

$$\frac{h}{\Delta x} \cdot T_E - \frac{h}{\Delta x} \cdot T_P - \frac{h}{\Delta x} \cdot T_P + \frac{h}{\Delta x} \cdot T_W = 0$$

$$\frac{2h}{\Delta x} \cdot T_P - \frac{h}{\Delta x} \cdot T_E - \frac{h}{\Delta x} \cdot T_W = 0$$

$$\Rightarrow \alpha_p \cdot T_p + \alpha_E \cdot T_E + \alpha_W \cdot T_W$$

onde:

$$\alpha_E = \alpha_W = \frac{h}{\Delta x} \quad \text{e} \quad \underline{\alpha_p = \alpha_W + \alpha_E}$$

Pontos no domínio

$$\#3 \quad q_3 \cdot T_3 = q_4 \cdot T_4 + q_2 \cdot T_2$$

$$\#4 \quad q_4 \cdot T_4 = q_5 \cdot T_5 + q_3 \cdot T_3$$

$$\#5 \quad q_5 \cdot T_5 = q_6 \cdot T_6 + q_4 \cdot T_4$$

Parâmetros do problema

$$\begin{cases} h = 25 \text{ W/mK} \\ \delta_x = 0,2 \end{cases}$$

Substituindo os valores nas equações:

$$\#3 \quad 250 \cdot T_3 = 125 \cdot T_4 + 125 \cdot T_2$$

$$\#4 \quad 250 \cdot T_4 = 125 \cdot T_5 + 125 \cdot T_3$$

$$\#5 \quad 250 \cdot T_5 = 125 \cdot T_6 + 125 \cdot T_4$$

Pontos de Fronteira:

- $x=0$: extremidade esquerda (Dirichlet)

$$\left(h \cdot \frac{\partial T}{\partial x} \right)_i - \left(h \cdot \frac{\partial T}{\partial x} \right)_b = 0$$

$$h_i \frac{(T_3 - T_2)}{\delta x_i} - h_b \frac{(T_2 - T_L)}{\delta x b} = 0$$

$$\frac{h_i}{\delta x_i} \cdot T_3 - \frac{h_i}{\delta x_i} \cdot T_2 - \frac{h_b}{\delta x b} \cdot T_2 + \frac{h_b}{\delta x b} \cdot T_L = 0$$

Sendo $\frac{\delta x_i}{2} = \delta x b$ e $h_i = hb$

$$\left(\frac{h}{\delta x} + \frac{h}{\left(\frac{\delta x}{2}\right)} \right) \cdot T_2 = \frac{h}{\delta x} T_3 + \frac{h}{\left(\frac{\delta x}{2}\right)} T_1 = 0$$

Utilizando o 2º Enfoque:

$$a_p \cdot T_p = a_E T_E + b$$

$$a_2 \cdot T_2 = a_3 \cdot T_3 + b$$

onde:

$$a_3 = \frac{h}{\delta x}, \quad a_2 = a_3 + \frac{h}{\left(\frac{\delta x}{2}\right)} \quad e \quad b = \frac{h}{\left(\frac{\delta x}{2}\right)} \cdot T_1$$

Substituindo os valores de h e δx :

$$\textcircled{2} \quad 375 \cdot T_2 = 125 \cdot T_3 + 37500$$

Extremidade da direita ($\alpha = L$)

$$a_6 \cdot T_6 = a_5 \cdot T_5 + b \quad \text{onde:}$$

$$a_6 = a_5 + \frac{h}{\left(\frac{\delta x}{2}\right)}, \quad a_5 = \frac{h}{\delta x} \quad e \quad b = \frac{h}{\left(\frac{\delta x}{2}\right)} \cdot T_7$$

$$\textcircled{6} \quad 375 \cdot T_6 = 125 \cdot T_5 + 12500$$

Sistema linear de equações algébricas

$$\textcircled{2} \quad 375 \cdot T_2 = 125 \cdot T_3 + 37500$$

$$\textcircled{3} \quad 250 \cdot T_3 = 125 \cdot T_4 + 125 \cdot T_2$$

$$\textcircled{4} \quad 250 \cdot T_4 = 125 \cdot T_5 + 125 \cdot T_3$$

$$\textcircled{5} \quad 250 \cdot T_5 = 125 \cdot T_6 + 125 \cdot T_4$$

$$\textcircled{6} \quad 375 \cdot T_6 = 125 \cdot T_5 + 12500$$

Forma Matricial

$$[A] \cdot [T] = [B]$$

$$\begin{bmatrix} 375 & -125 & 0 & 0 & 0 \\ -125 & 250 & -125 & 0 & 0 \\ 0 & -125 & 250 & -125 & 0 \\ 0 & 0 & -125 & 250 & -125 \\ 0 & 0 & 0 & -125 & 375 \end{bmatrix} \cdot \begin{bmatrix} T_2 \\ T_3 \\ T_4 \\ T_5 \\ T_6 \end{bmatrix} = \begin{bmatrix} 37500 \\ 0 \\ 0 \\ 0 \\ 12500 \end{bmatrix}$$

Solução do sistema

↳ Algoritmo TDMA

Passo 1: Calcular P_2 e Q_2 :

$$P_2 = \frac{b_2}{a_2} = \frac{125}{375} = \frac{1}{3}$$

$$Q_2 = \frac{d_2}{a_2} = \frac{37500}{375} = 100$$

Passo 2: Calcular os pares (P_i, Q_i) com i de 3 a $(N-1)$:

$$P_3 = \frac{b_3}{a_3 - c_3 \cdot P_2} = \frac{125}{250 - 125 \cdot \left(\frac{1}{3}\right)} = 0,6$$

$$Q_3 = \frac{d_3 + c_3 \cdot Q_2}{a_3 - c_3 \cdot P_2} = \frac{0 + 125 \cdot 100}{250 - 125 \cdot 0,6} = 60$$

$$P_4 = \frac{b_4}{a_4 - c_4 \cdot P_3} = \frac{125}{250 - 125 \cdot 0,6} = 0,714$$

$$Q_4 = \frac{d_4 + c_4 \cdot Q_3}{a_4 - c_4 \cdot P_3} = \frac{0 + 125 \cdot 60}{250 - 125 \cdot 0,6} = 42,857$$

$$P_5 = \frac{b_5}{a_5 - c_5 \cdot P_4} = \frac{125}{250 - 125 \cdot 0,714} = 0,778$$

$$Q_5 = \frac{d_5 + c_5 \cdot Q_4}{a_5 - c_5 \cdot P_4} = \frac{0 + 125 \cdot 42,857}{250 - 125 \cdot 0,714} = 33,326$$

$$P_6 = \frac{b_6}{a_6 - c_6 \cdot P_s} = 0$$

$$Q_6 = \frac{d_6 + c_6 \cdot Q_s}{a_6 - c_6 \cdot P_s} = \frac{12500 + 0 \cdot 33,326}{375 - 0 \cdot 0,778} = 60$$

Passo 3:

$$T_6 = Q_6 = \underline{\underline{60^\circ C}}$$

Passo 4:

$$T_5 = P_s \cdot T_6 + Q_s \Rightarrow T_5 = \underline{\underline{80^\circ C}}$$

$$T_4 = P_4 \cdot T_5 + Q_4 \Rightarrow T_4 = \underline{\underline{100^\circ C}}$$

$$T_3 = P_3 \cdot T_4 + Q_3 \Rightarrow T_3 = \underline{\underline{120^\circ C}}$$

$$T_2 = P_2 \cdot T_3 + Q_2 \Rightarrow T_2 = \underline{\underline{140^\circ C}}$$