

# Load balancing algorithm running on Open RAN RIC

Hyeon-Min Yoo  
dept. Electronics and Information  
Convergence Engineering  
KyungHee University  
Yong-In, Republic of Korea  
yhm1620@khu.ac.kr

Jong-Seok Rhee  
dept. Electronics and Information  
Convergence Engineering  
KyungHee University  
Yong-In, Republic of Korea  
howrhee@khu.ac.kr

Seok-Young Bang  
dept. Electronics and Information  
Convergence Engineering  
KyungHee University  
Yong-In, Republic of Korea  
qkdtjr97@khu.ac.kr

Een-Kee Hong  
dept. Electronics and Information  
Convergence Engineering  
KyungHee University  
Yong-In, Republic of Korea  
ekhong@khu.ac.kr

**Abstract**— The O-RAN alliance has received attention by presenting an O-RAN architecture. They standardizes wireless interfaces to solve the compatibility problem between multi-vendor of existing radio access network (RAN) architecture. They also disclose an open source framework, which is applicable to programmable base station equipment. In this paper, we analyze the xApp and the near-real time RAN intelligent controller (RIC) serviced by the O-RAN-compatible SD-RAN platform, developed by the open networking foundation (ONF), and address simple simulation results.

**Keywords**— O-RAN, SD-RAN, xApp, Near-RT RIC

## I. INTRODUCTION

In February 2018, five global telecom operators (AT&T, China Mobile, Deutsche Telekom, NTT DOCOMO and Orange) launched O-RAN alliance to realize an open radio access network (RAN) including openness and intelligent for the 5G era [1]. O-RAN alliance has designed O-RAN architecture and encourages the equipment vendors to develop their equipment in accordance with this standard for enabling the interoperability. The components and functions of the O-RAN architecture include [2]:

- *RAN intelligent controller (RIC)*: A controller that manages and controls network. The non-real time RIC (non-RT RIC) is responsible for functions with a control latency of more than 1 second, and the near-real time RIC (near-RT RIC) for functions with 10 millisecond to 1 second. The non-RT RIC is managed by service management and organization (SMO), and mainly performs functions based on artificial intelligence and big data such as traffic pattern and QoS prediction. The near-RT RIC performs real-time radio resource management functions such as handover and load balancing. It is connected to a number of RANs (i.e., O-CUs), and transfers collected data to non-RT RIC.
- *O-RU/O-DU/O-CU*: In O-RAN architecture, the base station (eNB, gNB) was disaggregated into O-CU, O-DU, and O-RU. The O-CU is directly connected to the near-RT RIC. The O-DU and O-RU are connected by open fronthaul interfaces, each performing the functions of the upper physical layer and the lower physical layer [3].
- *xApp*: An application running on Near-RT RIC. An xApp performs the specific intelligent function. In other words, some

RAN functions such as handover and load balancing can be executed in the near-RT RIC as an xApp.

To expand an O-RAN architecture ecosystem, various projects design RANs that follow this structure and disclose them as open sources [4]. Among the projects, the Open Networking Foundation (ONF) has developed and released the SD-RAN platform including cloud-native near-RT RIC and xApp that follow O-RAN architecture [5]. They also support software development kits (SDKs) so that users can develop the xApp themselves. In this paper, we analyze the open source xApp, near-RT RIC, and RAN simulator provided by SD-RAN platform, and introduce the development method of xApp and the simulation results.

## II. NEAR-RT RIC, XAPPS, AND RAN SIMULATOR

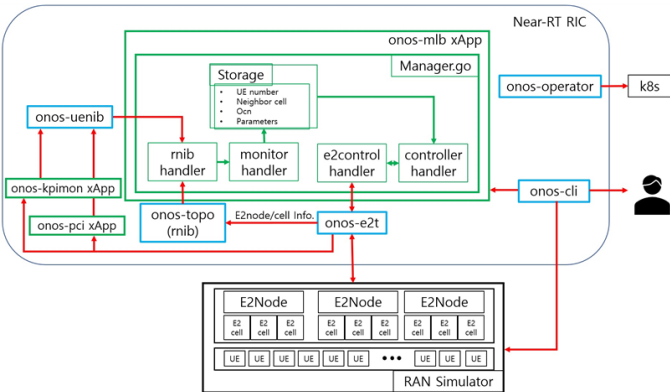


Fig. 1. Structure of xApp, RAN simulator, and near-RT RIC

Fig. 1 shows the structure of onos-mlb (mobility load balancing) xApp, RAN simulator, near-RT RIC released by ONF as an open source. It also includes the interface of onos-mlb xApp for communicating with other xApps, RAN simulator, and packages in the Near-RT RIC. Fig. 1 represents xApp in green, Near-RT RIC packages in blue, and RAN simulator in black line.

The ONF's xApp is written in Go language. There is no class in Go, so the method must be declared separately after declaring the structure. It has *Go routine*, which plays a similar role to C++'s *thread*. It also has *channel*, which transfers data between

routines. In xApp, *manager* controls the behavior of xApp and declares *handlers* with structure. The handlers communicate with packages in near-RT RIC and RAN simulator using *Go routine* and *channel*. RAN simulator is implemented in software and replaces the actual hardware, O-CUs, O-DUs, and O-RUs. O-DU and O-CU are integrated to E2Node, O-RU is substitutes for E2Cell.

Near-RT RIC includes some packages for executing xApps. onos-e2t (e2 termination) is a package located at the bottom of the near-RT RIC, which serves as a proxy for the interface between RAN simulator's E2Node and other near-RT RIC packages, xApp. E2t exchanges messages with E2Node of RAN simulator and forwards the information of RAN simulator to the database package and e2control handler of the xApp. The databases defined in O-RAN architecture include onos-uenib and onos-topo (also called *rnib*, radio network information base). onos-topo stores information about E2Nodes and E2Cells, and onos-uenib stores information about the user equipments (UEs) and its neighbor cells. These databases can obtain the information from onos-kpimon (key performance indicator monitoring) xApp and onos-pci (physical cell id) xApp. onos-kpimon collects information on the number of UEs connected to each E2Cell, and onos-pci gets information on the neighbor cell of each UE by interacting with RAN simulator. In other words, for the execution of onos-mlb xApp, it is necessary to execute these xApps.

The two databases transfer the information on number of UEs and neighbor cell of each UE to the onos-mlb xApp's *rnib handler*, and *monitoring handler* monitors this information and stores it in the xApp's storage.  $O_{cn}$  is a handover parameter for load balancing. *Controller handler* reports on the situation of each E2Node and E2cell from the *e2control handler*, and  $O_{cn}$  value is changed depending on their situation. If a E2cell serves more UEs than currently set overload threshold (%), load balancing is performed by increasing the  $O_{cn}$  value to take place more frequent handover to the neighbor cell. *Controller handler* transmits a message about the changed value to E2Node of RAN simulator through *e2control handler*.

Parameters are also required for load balancing. They include overload threshold,  $\Delta O_{cn}$ , which is the interval of increment and decrement of  $O_{cn}$ , and *interval*, which is the update time interval of the  $O_{cn}$ . These values will be stored directly in the storage by the *manager*. The onos-cli (command line interface) is an interface that allows users to input commands in onos-mlb. The onos-operator builds cloud native xApp and packages of near-RT RIC on Kubernetes. It also monitors the built elements and performs functions such as scheduling resources or entering the necessary configuration for deploying.

### III. SIMULATION RESULT

The xApp is built to an image through the Docker file, and this image is deployed and executed in the Kubernetes (k8s) (Fig. 2). The image of onos-mlb xApp is deployed in Kubernetes by helm command, and images of RAN simulator, onos-pci, and onos-kpimon xApp are also deployed together. *Helm* is a command for installing *charts* for running xApp and deploys images to user-specified namespaces. We built elements in

namespace named 'riab', and Fig. 3 shows the results. In Fig. 3, we can identify that near-RT RIC packages, xApps, and RAN simulators have been deployed successfully in the riab namespace.



Fig. 2. Deployment and execution of xApp

```

vagrant@sd-ran-vm: ~/sd-ran-helm-charts/sd-ran$ kubectl get po -n riab
NAME                                READY   STATUS    RESTARTS   AGE
onos-cli-744d864c6b-fbnfr           1/1     Running   0           62s
onos-config-757d5fb76d-lzbsk        4/4     Running   0           62s
onos-consensus-store-0              1/1     Running   0           62s
onos-e2t-6b9646874c-mcf2l           3/3     Running   0           62s
onos-kpimon-598cb8f9d6-flb7x        2/2     Running   0           62s
onos-mlb-555947c954-5rcht           2/2     Running   0           62s
onos-pci-5f756dff4d-fvt4x           2/2     Running   0           62s
onos-topo-644c49f767-j2wgt          3/3     Running   0           62s
onos-uenib-b7cdc8898-qsrqs          3/3     Running   0           62s
ran-simulator-6cf659cd64-6mms       1/1     Running   0           62s
  
```

Fig. 3. The xApps and packages of near-RT RIC deployed on riab namespace

TABLE I. SIMULATION PARAMETERS

Parameters	Value
Number of UEs	10
Number of E2Nodes	2
Number of E2Cells	6
overload threshold	80 %
Delta $O_{cn}$	3 dB
interval	10 s

The parameter and its value used in the simulation are summarized in Table 1. We run a simulation in onos-cli bash shell. The RAN simulator has ten UEs, and two E2Nodes with Entity IDs 5153 and 5154, respectively. Each E2Node manages three E2Cells. In Fig. 4, Each UE is identified by IMSI (International Mobile Subscriber Identity) and CRNTI (Cell Radio Network Temporary Identifier).

```

onos-cli-744d864c6b-8kzdt:~$ onos ransim get ues
IMSI      Serving Cell  CRNTI  Admitted  RRC
3126003   13842601454c002  90125  false     RRCSTATUS_CONNECTED
3301494   138426014550002  90126  false     RRCSTATUS_CONNECTED
5003707   138426014550003  90130  false     RRCSTATUS_IDLE
1039102   138426014550002  90132  false     RRCSTATUS_CONNECTED
3182986   138426014550003  90133  false     RRCSTATUS_IDLE
5827266   138426014550003  90127  false     RRCSTATUS_IDLE
4010129   138426014550002  90128  false     RRCSTATUS_IDLE
2833359   138426014550003  90129  false     RRCSTATUS_IDLE
5092721   13842601454c002  90131  false     RRCSTATUS_IDLE
9640497   13842601454c002  90134  false     RRCSTATUS_CONNECTED
  
```

Fig. 4. IMSI and CRNTI of UEs

Fig. 5 shows the information provided by onos-kpimon xApp. The RRC.Conn.Avg is the average number of UEs serviced by each E2Cell over time. The RRC.Conn.Max means the maximum number of UEs that can be accommodated by each E2Cell. If the ratio of RRC.Conn.Avg to the RRC.Conn.Max of a E2Cell is higher than the overload threshold, the E2Cell increases the  $O_{cn}$  value to handover UEs to other cells more frequent.

```
onos-cli-744d864c8b-bswmz-$ onos kpimon list metrics
```

Node ID	Cell Object ID	Cell Global ID	Time	PRC.Conn.Avg	PRC.Conn.Max
e2:1/5153	13842601454001	1454001	07:55:04.0	0	4
e2:1/5153	13842601454002	1454002	07:55:04.0	3	5
e2:1/5153	13842601454003	1454003	07:55:04.0	0	0
e2:1/5154	138426014550001	14550001	07:55:04.0	3	5
e2:1/5154	138426014550002	14550002	07:55:04.0	2	2
e2:1/5154	138426014550003	14550003	07:55:04.0	0	1

Fig. 5. Simulation result of onos-kpimon xApp

Fig. 6 shows the change in the  $O_{cn}$  value in onos-mlb xApp. A 14550002 E2cell belonging to 5154 E2Node is serving more than 80 percent of allowed UE. So, it increases the  $O_{cn}$  value between its neighbor cells by 3 dB to make handover more frequent. Since the other cells are serving fewer UEs, we can confirm that they lower their  $O_{cn}$  by 3 dB to reduce the handover.

```
onos-cli-744d864c8b-Bkzdt-$ onos mlb list ocn
```

sCell node ID	sCell PLMN ID	sCell cell ID	sCell object ID	nCell PLMN ID	nCell cell ID	OCN [dB]
e2:1/5153	138426	1454001	13842601454001	138426	1454002	0.0
e2:1/5153	138426	1454001	13842601454001	138426	1454003	0.0
e2:1/5153	138426	1454001	13842601454001	138426	14550001	0.0
e2:1/5153	138426	1454002	13842601454002	138426	1454001	3.0
e2:1/5153	138426	1454002	13842601454002	138426	1454003	3.0
e2:1/5153	138426	1454002	13842601454002	138426	14550002	3.0
e2:1/5153	138426	1454003	13842601454003	138426	1454001	0.0
e2:1/5153	138426	1454003	13842601454003	138426	1454002	0.0
e2:1/5153	138426	1454003	13842601454003	138426	14550003	0.0
e2:1/5154	138426	14550001	138426014550001	138426	1454001	3.0
e2:1/5154	138426	14550001	138426014550001	138426	14550002	3.0
e2:1/5154	138426	14550001	138426014550001	138426	14550003	3.0
e2:1/5154	138426	14550002	138426014550002	138426	1454002	0.0
e2:1/5154	138426	14550002	138426014550002	138426	14550001	3.0
e2:1/5154	138426	14550003	138426014550003	138426	1454003	0.0
e2:1/5154	138426	14550003	138426014550003	138426	14550001	3.0
e2:1/5154	138426	14550003	138426014550003	138426	14550002	3.0

Fig. 6. Simulation result of onos-mlb xApp

#### IV. CONCLUSION

In this paper, we introduce the SD-RAN platform and structure of xApp following the O-RAN architecture. We also show the execution method and simulation results of xApps. SD-RAN has not yet developed SMO, so the function of non-

RT RIC with big data/machine learning is not yet available. It is expected that more functions can be simulated after SMO is developed in the future. In addition, the development of xApps that perform new functions and contribution to the open source project would be interesting studies, and it can promote the commercialization of O-RAN architecture in the future.

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