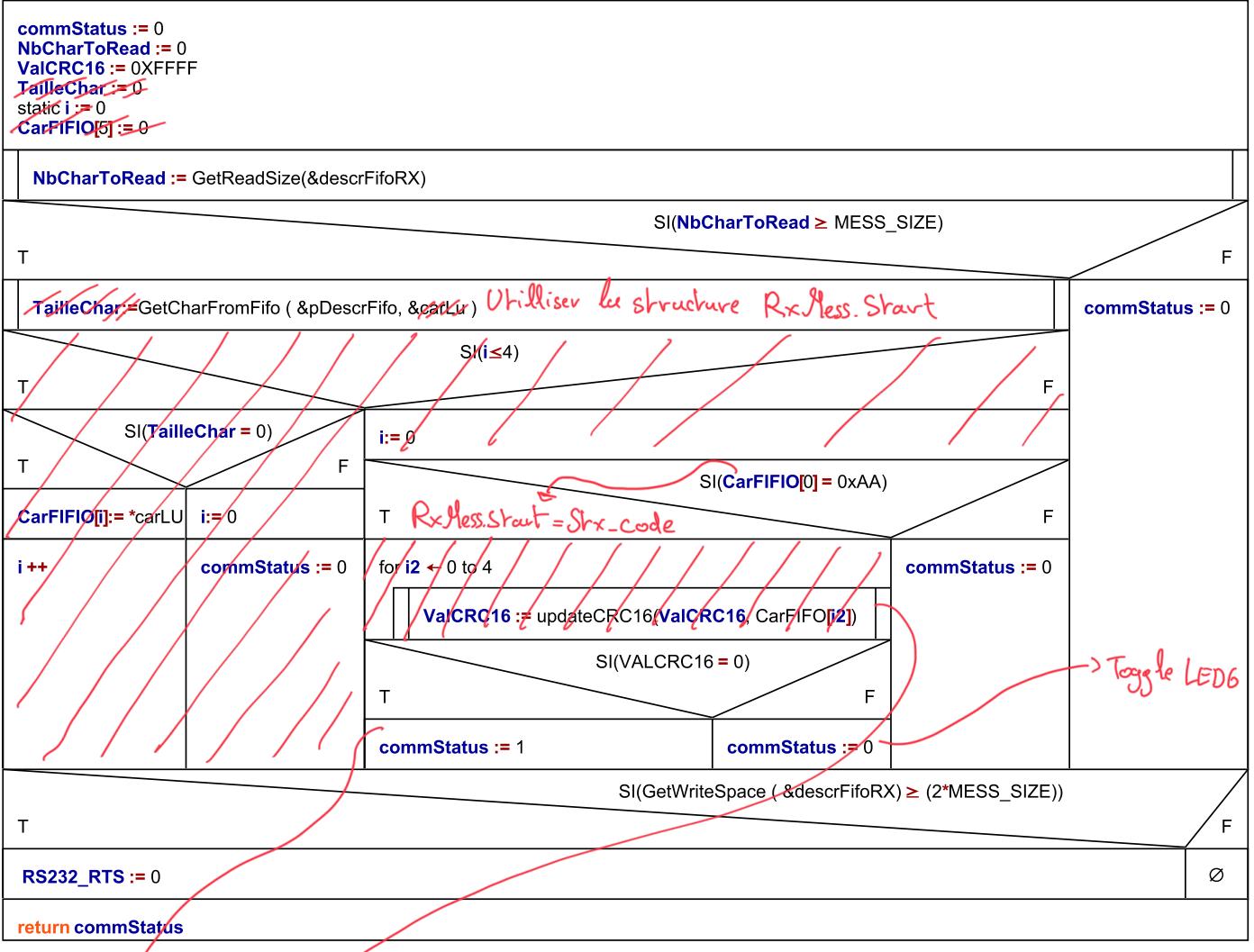


```
int GetMessage(S_pwmSettings *pData)
```



Handwritten notes at the bottom left:

- `Envie de RxMess.Angle à la struct pData -> Speed Setting Angle Setting`
- `ValCrc16 = updateCrc16(ValCrc16, RxMess.Start)`
- `GetCharFromFifo(&descrFifoRX, &RxMess.Speed)`
- `ValCrc16 = updateCrc16(ValCrc16, RxMess.Speed)`
- `Refaire pour les DATA Rx Mess. Angle Hsb-Crc Lsb-Crc`