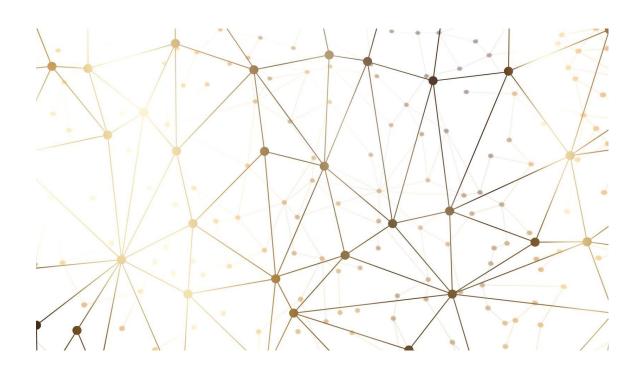
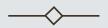
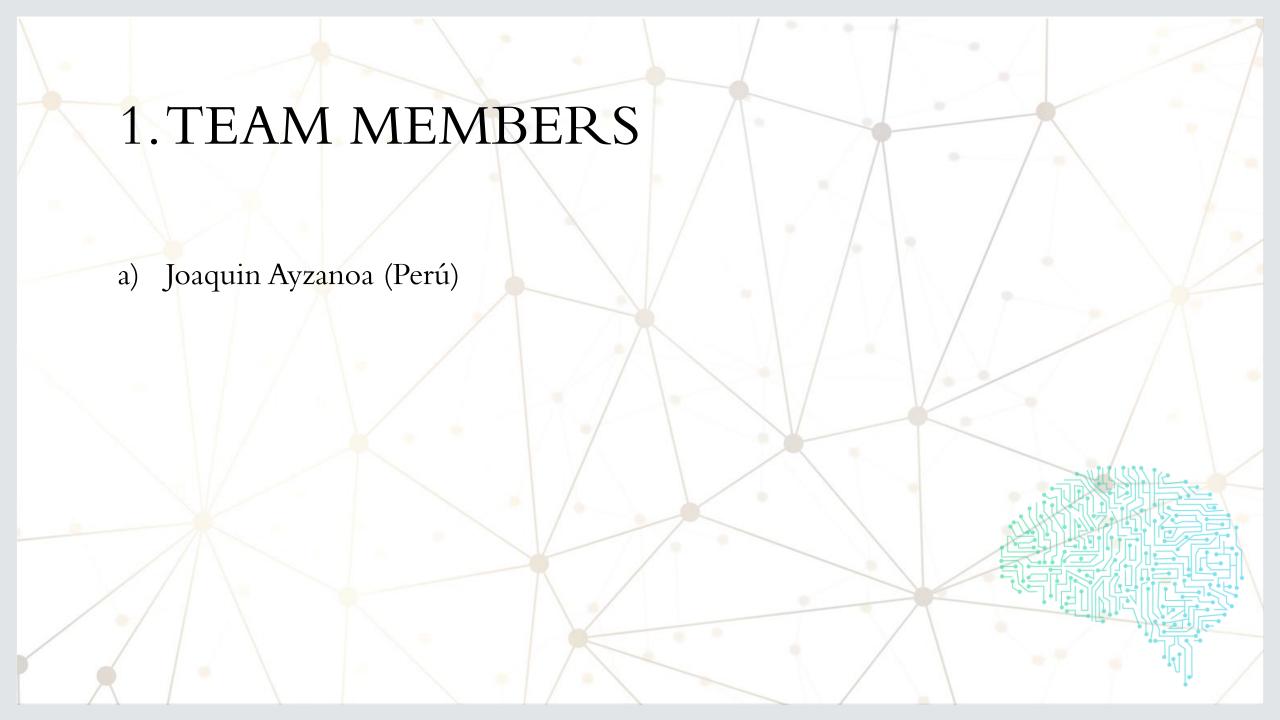
# fuse machines



BONE FRACTURE DETECTION

FUSE AI FELLOWSHIP 2023-2024





## 2. PROBLEM STATEMENT

a) A data set of bone fractures with which we want to train a machine learning model, specifically focusing on algorithms to automatically detect and classify bone fractures in X-ray images for better and fast registration for doctors and

patients.



a) Detect and classify bone fractures in X-ray images for better and fast registration for doctors and patients.

b) Deploy the ML model with an interface so it can predict the type of fracture when someone upload an image.

# 4. GITHUB REPOSITORY LINK

This is the link of the repository:

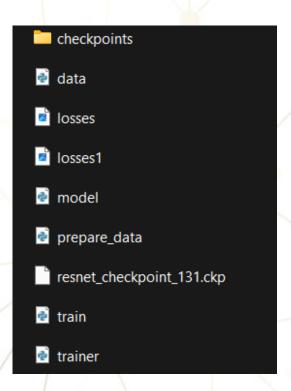
https://github.com/JoaquinAyzanoa/PortafolioJA/tree/main/Fracture%20Bone%20Detection

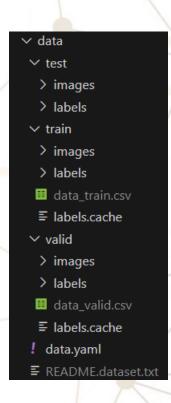




#### 5. RESNET MODEL

The Resnet model was created from scratch using pytorch, no pretrained model or downloaded model was used here.





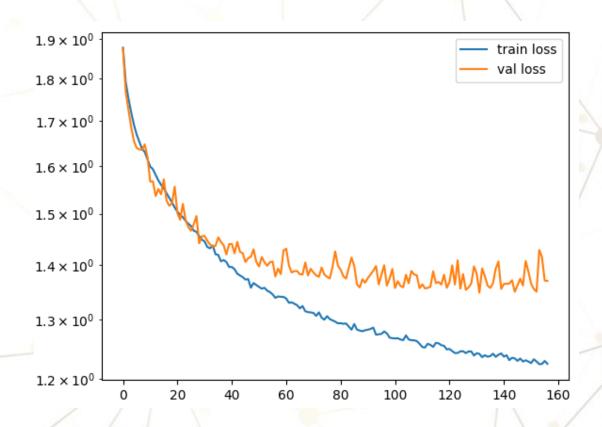
```
Fracture Bone Detection > Resnet Model > 🏺 model.py > {} nn
      import torch
      import torch.nn as nn
      import torch.nn.functional as F
      class ResBlock(nn.Module):
          def __init__(self, in_channels, out_channels, stride):
              super(ResBlock, self). init ()
              self.conv1 = nn.Conv2d(in channels, out channels, kernel size=3, stride=s
              self.bn1 = nn.BatchNorm2d(out channels)
              self.relu = nn.ReLU(inplace=True)
              self.conv2 = nn.Conv2d(out channels, out channels, kernel size=3, stride=
              self.bn2 = nn.BatchNorm2d(out channels)
              self.shortcut = nn.Sequential()
              if stride != 1 or in channels != out channels:
                  self.shortcut = nn.Sequential(
                      nn.Conv2d(in_channels, out channels, kernel size=1, stride=stride
                      nn.BatchNorm2d(out channels)
```

#### 5. RESNET MODEL

The Resnet model was created from scratch using pytorch, no pretrained model or downloaded model was used here.

```
Fracture Bone Detection > Resnet Model > 🌵 prepare_data.py > {} pd
      import glob
      import os
      import pandas as pd
      def prepare data(root, mode):
          file dataname = os.path.join(root, mode)
          file dataname = file dataname + f'/data {mode}.csv'
          if os.path.exists(file dataname):
                df = pd.read_csv(file_dataname, delimiter=';')
                print(f'data {mode}.csv' +' already exists')
              files = sorted(glob.glob(os.path.join(root, mode) + '/images/*.jpg'))
              df= pd.DataFrame(columns=['filename','label', 'coords'])
              for file in files:
                  text file = file.replace(".jpg", ".txt").replace("images", "labels")
                  with open(text file, mode="r") as f:
                               lines = f.readlines()
                               for line in lines:
                                   values = [float(value) for value in line.split()]
                                  label = int(values[0])
                                   coords = values[1:]
                                   row data = [file]
```

```
# set up data loading for the training and validation set each using t.utils.dat
     train dataset = ChallengeDataset(train data, mode='train')
     val dataset = ChallengeDataset(val data, mode='val')
     train dataloader = t.utils.data.DataLoader(train dataset, batch size=48, shuffle=
     val dataloader = t.utils.data.DataLoader(val dataset, batch size=48, shuffle=Fal
     # create an instance of our ResNet model
     resnet model = model.ResNet()
     resnet model.to(device)
     # set up a suitable loss criterion (you can find a pre-implemented loss function
     # set up the optimizer (see t.optim)
     # create an object of type Trainer and set its early stopping criterion
     criterion = t.nn.CrossEntropyLoss() # Assuming it's a multi class classificatio
     optimizer = t.optim.Adam(resnet model.parameters(), lr=0.00001)
     trainer = Trainer(model=resnet model, crit=criterion, optim=optimizer,
                       train dl=train dataloader, val test dl=val dataloader,
                       cuda=True, early stopping patience=25)
40
     #trainer.restore checkpoint(79)
     res = trainer.fit(epochs=200)
```



#### **TERMINAL**

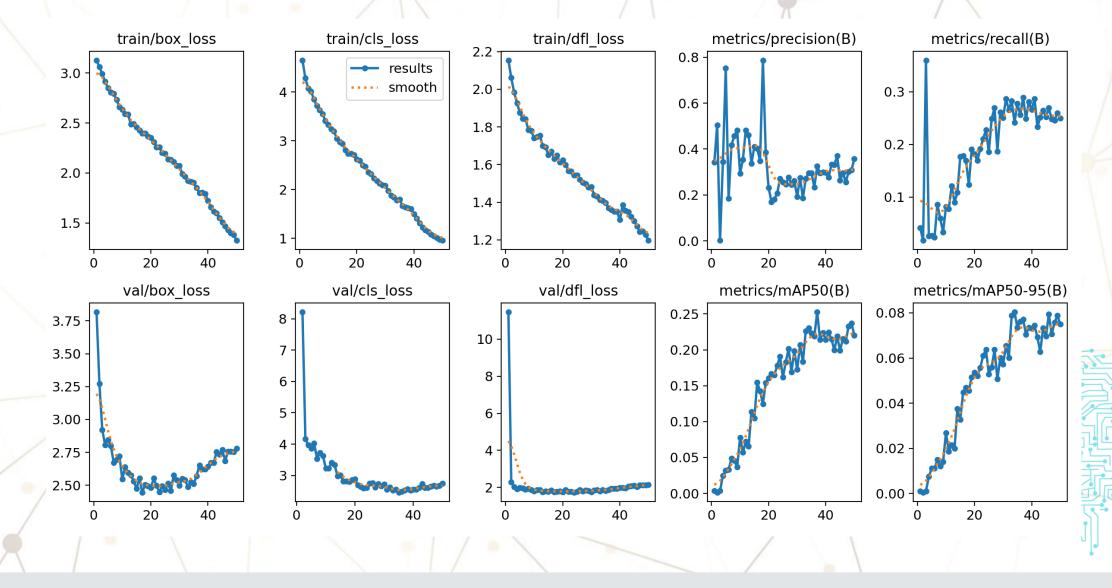
```
Epoch 130/200: Train Loss: 1.2447, Val Loss: 1.3684, F1 Score: 0.7963
Epoch 131/200: Train Loss: 1.2428, Val Loss: 1.3483, F1 Score: 0.8056
Epoch 132/200: Train Loss: 1.2381, Val Loss: 1.3751, F1 Score: 0.7709
Epoch 133/200: Train Loss: 1.2427, Val Loss: 1.3700, F1 Score: 0.7849
Epoch 134/200: Train Loss: 1.2407, Val Loss: 1.3798, F1 Score: 0.7667
Epoch 135/200: Train Loss: 1.2460, Val Loss: 1.4967, F1 Score: 0.6689
Epoch 136/200: Train Loss: 1.2396, Val Loss: 1.3573, F1 Score: 0.7905
Epoch 137/200: Train Loss: 1.2312, Val Loss: 1.3677, F1 Score: 0.7814
Epoch 138/200: Train Loss: 1.2327, Val Loss: 1.3985, F1 Score: 0.7460
Epoch 139/200: Train Loss: 1.2372, Val Loss: 1.3769, F1 Score: 0.7764
Epoch 140/200: Train Loss: 1.2328, Val Loss: 1.3675, F1 Score: 0.7830
Epoch 141/200: Train Loss: 1.2302, Val Loss: 1.4016, F1 Score: 0.7574
Epoch 142/200: Train Loss: 1.2360, Val Loss: 1.3950, F1 Score: 0.7550
Epoch 143/200: Train Loss: 1.2355, Val Loss: 1.3733, F1 Score: 0.7756
Epoch 144/200: Train Loss: 1.2303, Val Loss: 1.4430, F1 Score: 0.7138
Epoch 145/200: Train Loss: 1.2395, Val Loss: 1.3915, F1 Score: 0.7705
Epoch 146/200: Train Loss: 1.2372, Val Loss: 1.3624, F1 Score: 0.7839
Epoch 147/200: Train Loss: 1.2335, Val Loss: 1.3638, F1 Score: 0.7819
Epoch 148/200: Train Loss: 1.2293, Val Loss: 1.4029, F1 Score: 0.7375
Epoch 149/200: Train Loss: 1.2357, Val Loss: 1.4042, F1 Score: 0.7306
Epoch 150/200: Train Loss: 1.2290, Val Loss: 1.3804, F1 Score: 0.7608
Epoch 151/200: Train Loss: 1.2305, Val Loss: 1.4086, F1 Score: 0.7491
Epoch 152/200: Train Loss: 1.2302, Val Loss: 1.3770, F1 Score: 0.7741
Epoch 153/200: Train Loss: 1.2270, Val Loss: 1.3767, F1 Score: 0.7921
Epoch 154/200: Train Loss: 1.2288, Val Loss: 1.3628, F1 Score: 0.7973
Epoch 155/200: Train Loss: 1.2262, Val Loss: 1.3854, F1 Score: 0.7686
Epoch 156/200: Train Loss: 1.2275, Val Loss: 1.3872, F1 Score: 0.7690
Early stopping after 156 epochs without improvement.
```

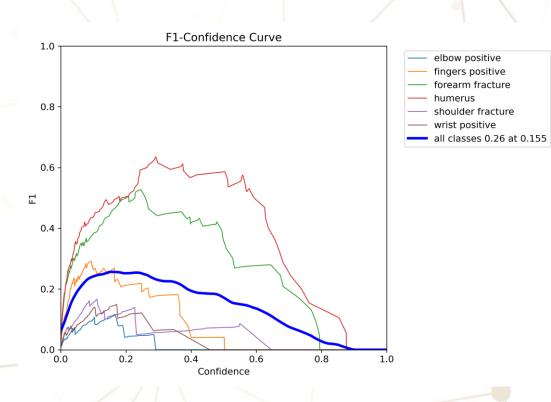


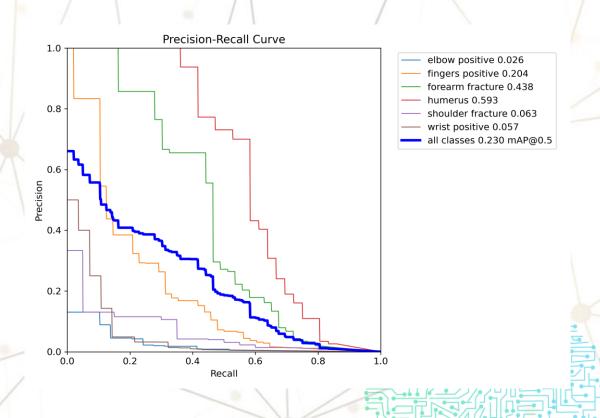
# 6.YOLO-V8 FOR OBJECT DETECTION

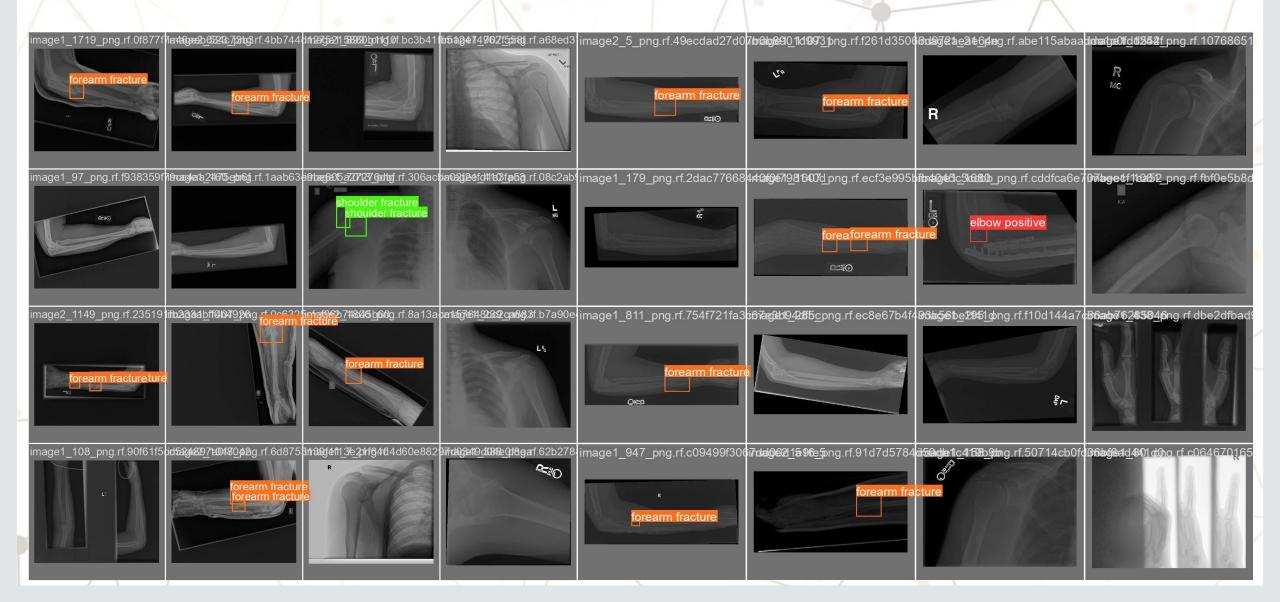
The YoloV8 model is a pretrained model downloaded from the library "Ultralytics". The YoloV8 was finetuned to bone fracture detection task.

								Pytho
	ull	J <del>-1</del> 0	<b>40</b> -	01302	V1270	01233	0,0757	
Epoch	GPU mem	box loss	cls loss	dfl loss	Instances	Size		
49/50	5.51G	1.381	0.975	1.226	11	320:	100% 227/22	27 [01:
	Class	Images	Instances	Box(P	R	mAP50	mAP50-95):	100% 1
	all	348	204	0.309	0.26	0.237	0.0789	
Epoch	GPU_mem	box_loss	cls_loss	dfl_loss	Instances	Size		
50/50	5.5G	1.325	0.9576	1.197	7	320:	100% 227/22	27 [01:
	Class	Images	Instances	Box(P	R	mAP50	mAP50-95):	100% 1
	all	348	204	0.357	0.25	0.22	0.0749	
a onache com	nloted in	1 212 hours						
otimizer str	ipped from	runs/detec	t/train/wei	-				
ptimizer str ptimizer str	ipped from ipped from	runs/detec runs/detec	t/train/weiį t/train/weiį	ghts/best.p				
ptimizer str ptimizer str alidating ru	ipped from ipped from ns/detect/	runs/detec runs/detec train/weigh	t/train/wei t/train/wei ts/best.pt.	ghts/best.p		Tesla T4,	15102MiB)	
ptimizer str ptimizer str alidating ru ltralytics Y	ipped from ipped from ns/detect/ OLOv8.1.27	runs/detec runs/detec train/weigh	t/train/wei t/train/wei ts/best.pt. -3.10.12 tor	ghts/best.p  .ch-2.1.0+cu	t, 136.7MB			
ptimizer str ptimizer str ptimizer str plidating ru ltralytics Y	ipped from ipped from ns/detect/ OLOv8.1.27	runs/detec runs/detec train/weigh Python- 268 layers,	t/train/wei t/train/wei ts/best.pt. -3.10.12 tor	ghts/best.p  .ch-2.1.0+cu	t, 136.7MB u121 CUDA:0 (			100% 1
ptimizer str ptimizer str ptimizer str plidating ru ltralytics Y	ipped from ipped from ns/detect/t0LOv8.1.27	runs/detec runs/detec train/weigh Python- 268 layers,	t/train/wei t/train/wei ts/best.pt. -3.10.12 tor 68130309 pa	ghts/best.p  ch-2.1.0+cu arameters,	t, 136.7MB u121 CUDA:0 ( 0 gradients,	257.4 GFL	OPs .	100% 1
otimizer str ptimizer str alidating ru ltralytics Y odel summary	ipped from ipped from ns/detect/t OLOv8.1.27 (fused): 2 Class	runs/detectruns/detectrain/weigh Python Reference Pages Pages	t/train/wei t/train/wei ts/best.pt. -3.10.12 tor 68130309 pa Instances	ghts/best.p  ch-2.1.0+cu arameters, Box(P	t, 136.7MB u121 CUDA:0 ( 0 gradients, R 0.242	257.4 GFL mAP50	OPs mAP50-95):	100% 1
etimizer stroptimizer stroptimizer stroption stroption of the stroption of	ipped from ipped from ns/detect/f OLOv8.1.27 (fused): 7 Class all	runs/detectruns/detectrain/weigh Python- 268 layers, Images 348	t/train/wei; t/train/wei; ts/best.pt. -3.10.12 tor 68130309 pa Instances 204	ghts/best.p  ch-2.1.0+cu arameters, Box(P 0.296	t, 136.7MB u121 CUDA:0 ( 0 gradients, R 0.242 0.0345	257.4 GFL mAP50 0.23	OPs mAP50-95): 0.0802 0.0094	100% 1
ptimizer str ptimizer str alidating ru ltralytics Y odel summary elbow fingers	ipped from ipped from ns/detect/t OLOv8.1.27 (fused): 7 Class all positive	runs/detectruns/detectrain/weigh Python- 268 layers, Images 348 348	t/train/wei; t/train/wei; ts/best.pt. -3.10.12 tor 68130309 pa Instances 204 29	ghts/best.p  ch-2.1.0+cu arameters, Box(P 0.296 0.0521	t, 136.7MB u121 CUDA:0 ( 0 gradients, R 0.242 0.0345 0.146	257.4 GFL mAP50 0.23 0.0265 0.204	OPs mAP50-95): 0.0802 0.0094 0.0617	100% 1
ptimizer str ptimizer str alidating ru ltralytics Y odel summary elbow fingers forearm	ipped from ipped from ns/detect/f OLOV8.1.27 (fused): 2 Class all positive positive fracture humerus	runs/detectruns/detectrain/weight Python- 268 layers, Images 348 348	t/train/wei; t/train/wei; ts/best.pt. -3.10.12 tor 68130309 ps Instances 204 29 48	ghts/best.p  ch-2.1.0+cu arameters, Box(P 0.296 0.0521 0.389 0.538 0.442	t, 136.7MB  J121 CUDA:0 ( 0 gradients,	257.4 GFL mAP50 0.23 0.0265 0.204 0.438 0.593	OPs mAP50-95): 0.0802 0.0094 0.0617 0.175 0.204	100% 1
odel summary elbow fingers forearm shoulder	ipped from ipped from ns/detect/f OLOV8.1.27 (fused): 2 Class all positive positive fracture	runs/detectruns/detectrain/weight Python- 268 layers, Images 348 348 348	t/train/weigt/train/weigts/best.pt3.10.12 tor 68130309 pa Instances 204 29 48 43	ghts/best.p  ch-2.1.0+co arameters, Box(P 0.296 0.0521 0.389 0.538	t, 136.7MB  J121 CUDA:0 ( 0 gradients,	257.4 GFL mAP50 0.23 0.0265 0.204 0.438	OPs mAP50-95): 0.0802 0.0094 0.0617 0.175 0.204	100% 1

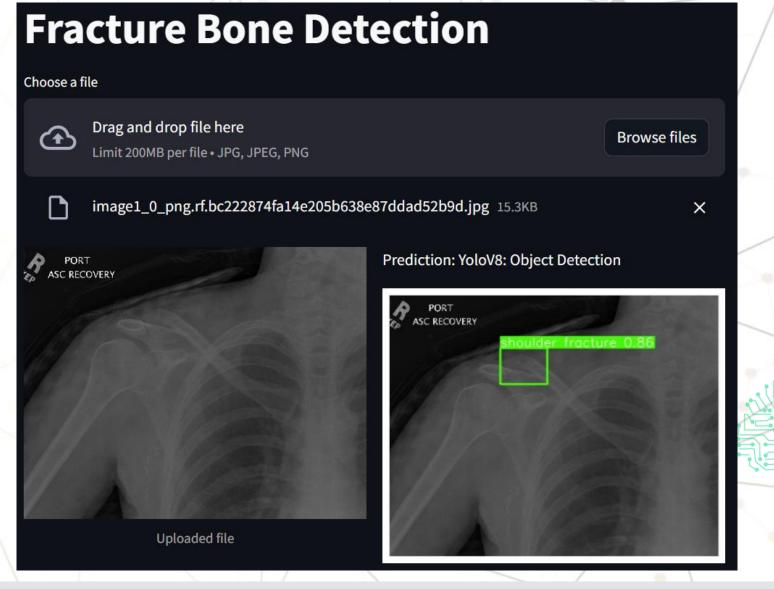








# 6.2 Results with Streamlit and FastAPI

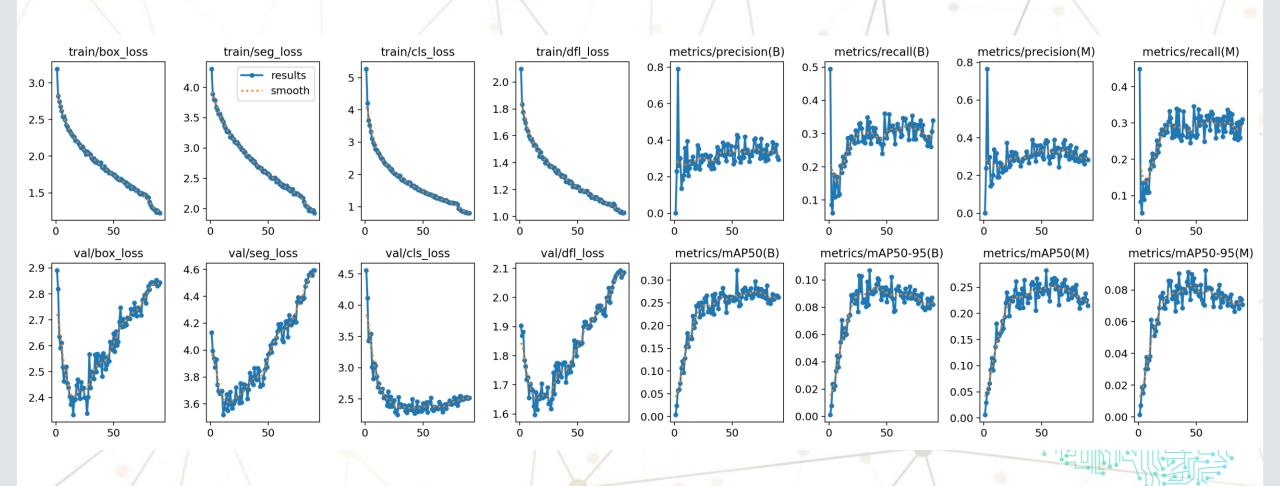


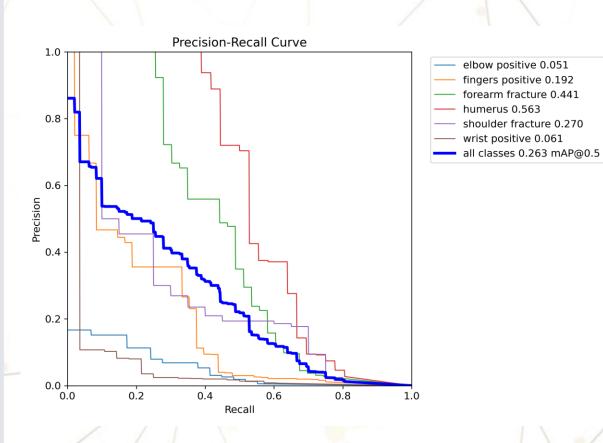
#### 7. YOLO-V8 WITH INSTANCE SEGMENTATION

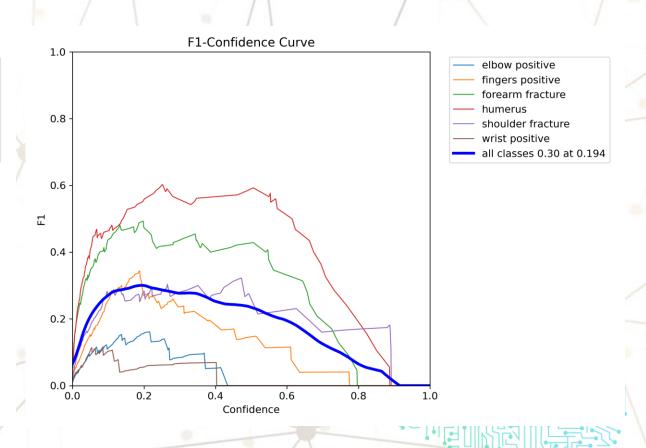
The YoloV8-SEG model is a pretrained model downloaded from the library "Ultralytics". The YoloV8 was finetuned to bone fracture instance segmentation.

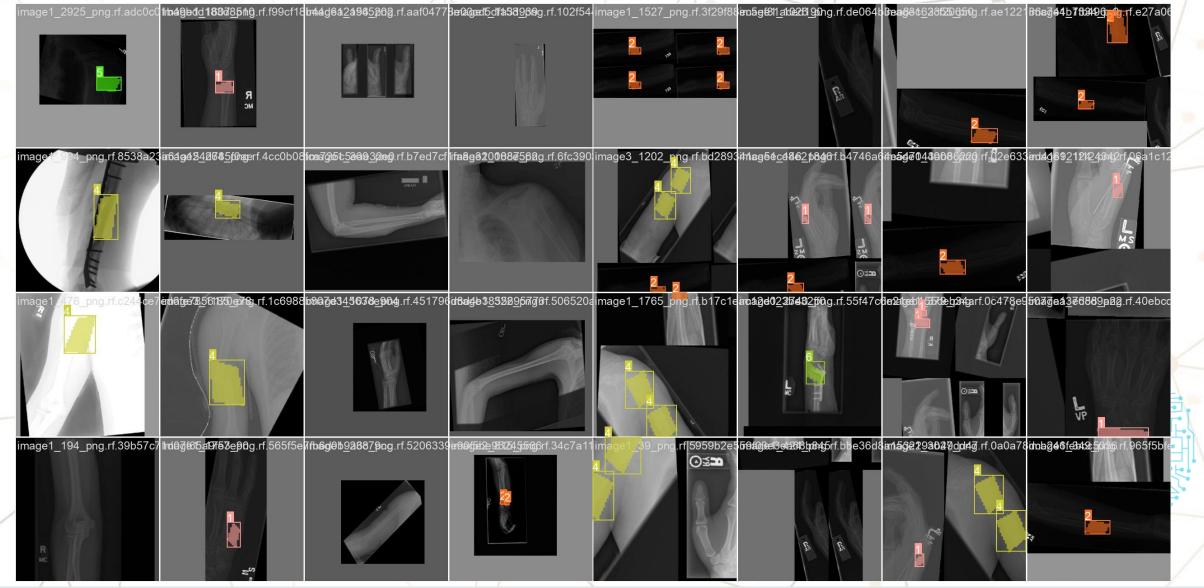
```
# Run inference on an image with YOLO
!yolo detect train data='./data.yaml' model=yolov8n-seg.pt epochs=90 imgsz=320 device=0
Downloading <a href="https://github.com/ultralytics/assets/releases/download/v8.1.0/yolov8n-seg.pt">https://github.com/ultralytics/assets/releases/download/v8.1.0/yolov8n-seg.pt</a> to 'yolov8n-seg.pt'...
100% 6.73M/6.73M [00:00<00:00, 24.7MB/s]
WARNING A conflicting 'task=detect' passed with 'task=segment' model. Ignoring 'task=detect' and updating to 'task=segment' to match model
Ultralytics YOLOv8.1.29 

✓ Python-3.10.12 torch-2.2.1+cu121 CUDA:0 (Tesla T4, 15102MiB)
engine/trainer: task=segment, mode=train, model=yolov8n-seg.pt, data=./data.yaml, epochs=90, time=None, patience=100, batch=16, imgsz=320,
2024-03-20 22:10:23.819812: E external/local xla/xla/stream executor/cuda/cuda dnn.cc:9261] Unable to register cuDNN factory: Attempting to
2024-03-20 22:10:23.819872: E external/local xla/xla/stream executor/cuda/cuda fft.cc:607] Unable to register cuFFT factory: Attempting to
2024-03-20 22:10:23.832882: E external/local xla/xla/stream executor/cuda/cuda blas.cc:1515] Unable to register cuBLAS factory: Attempting
Overriding model.yaml nc=80 with nc=7
                                params module
                                                                                        arguments
                    from n
                                        ultralytics.nn.modules.conv.Conv
                                                                                        [3, 16, 3, 2]
                                 4672 ultralytics.nn.modules.conv.Conv
                                                                                        [16, 32, 3, 2]
                                        ultralytics.nn.modules.block.C2f
                                                                                        [32, 32, 1, True]
                                        ultralytics.nn.modules.conv.Conv
                                                                                        [32, 64, 3, 2]
                                 18560
                                        ultralytics.nn.modules.block.C2f
                                                                                        [64, 64, 2, True]
                                        ultralytics.nn.modules.conv.Conv
                                                                                        [64, 128, 3, 2]
                                197632 ultralytics.nn.modules.block.C2f
                                                                                        [128, 128, 2, True]
                                295424 ultralytics.nn.modules.conv.Conv
                                                                                        [128, 256, 3, 2]
                                        ultralytics.nn.modules.block.C2f
                                                                                        [256, 256, 1, True]
                                        ultralytics.nn.modules.block.SPPF
                                                                                        [256, 256, 5]
```

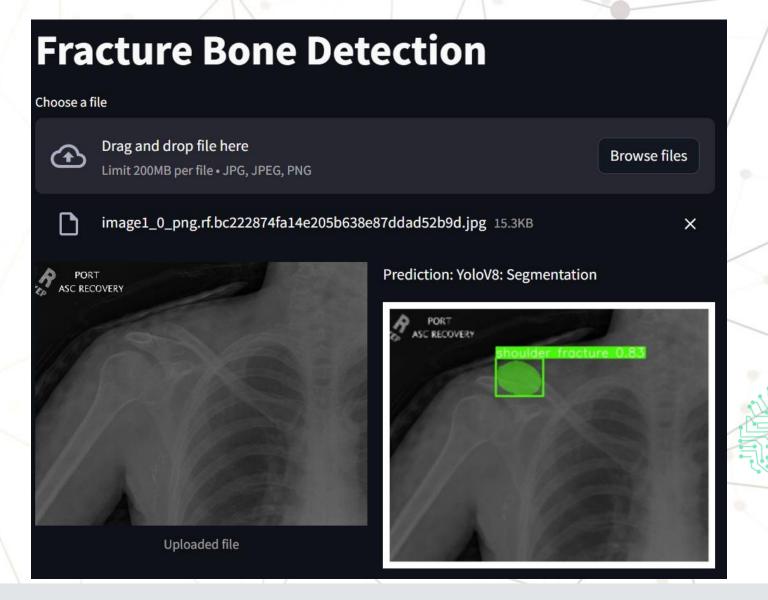






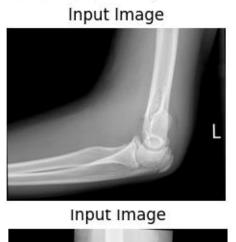


# 7.3 Results with Streamlit and FastAPI

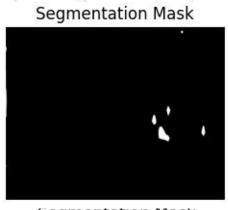


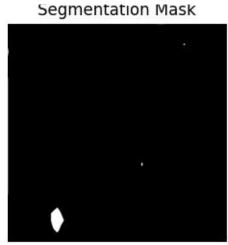
# 8. Conclusions

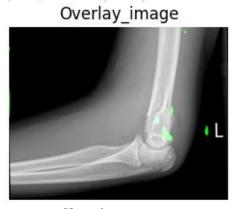
1. Resnet strugle to make instance segmentation as is shown bellow:



Input Image











## 8. Conclusions

- 2. Using Resnet with FastAPI has a lower response time in the server.
- 3. Using Yolo model has a relative higher response time in the server using streamlit and FastAPI.
- 4. Segmentation using YOLO could be improve by fine-tuning the model for more epochs or with more data for the training.
- 5. The deployment of the models on the server was successfully completed.