# Functional analysis

Luka Horjak (luka1.horjak@gmail.com)

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Introduction Luka Horjak

## Introduction

These are my lecture notes on the course Functional analysis in the year 2023/24. The lecturer that year was prof. dr. Igor Klep.

The notes are not perfect. I did not write down most of the examples that help with understanding the course material. I also did not formally prove every theorem and may have labeled some as trivial or only wrote down the main ideas.

I have most likely made some mistakes when writing these notes – feel free to correct them.

Convexity Luka Horjak

### 1 Convexity

#### 1.1 Locally convex spaces

**Definition 1.1.1.** A topological vector space V is an  $\mathbb{F}$ -vector space that is also a topological space, such both addition and scalar multiplication are continuous.

**Definition 1.1.2.** Let V be an  $\mathbb{F}$ -vectors pace. A map  $p:V\to\mathbb{R}$  is a *seminorm* if the following holds:

- i)  $\forall x \in V : p(x) > 0$ ,
- ii)  $\forall \lambda \in \mathbb{F}, x \in V : p(\lambda x) = |\lambda| p(x),$
- iii)  $\forall x, y \in V : p(x+y) < p(x) + p(y)$ .

**Definition 1.1.3.** Let V be an  $\mathbb{F}$ -vector space and  $\mathcal{P}$  a family of seminorms on V. We define a topology  $\mathcal{T}$  on V with the sets

$$U(x_0, p, \varepsilon) = \{ x \in V \mid p(x - x_0) < \varepsilon \}$$

as a subbasis.

**Definition 1.1.4.** A topological vector space X is a *locally convex space* if its topology is generated by a family of seminorms  $\mathcal{P}$  satisfying

$$\bigcap_{p \in \mathcal{P}} \{ x \in X \mid p(x) = 0 \} = \{ 0 \}.$$

**Proposition 1.1.5.** A locally convex space X is Hausdorff.

*Proof.* Let  $x, y \in X$  be distinct points. Let  $p \in \mathcal{P}$  be a seminorm such that  $p(x - y) \neq 0$ . Then the sets

$$U = \left\{ z \in X \;\middle|\; p(z - x) < \frac{\varepsilon}{2} \right\} \quad \text{and} \quad V = \left\{ z \in X \;\middle|\; p(z - y) < \frac{\varepsilon}{2} \right\}$$

split the points x and y.

Remark 1.1.5.1. The converse is also true.

**Definition 1.1.6.** A partially ordered set I is upward directed if for all  $i', i'' \in I$  there exists some  $i \in I$  such that  $i \geq i'$  and  $i \geq i''$ .

**Definition 1.1.7.** A net is a pair  $((I, \leq), x)$ , where  $(I, \leq)$  is an upward directed set and  $x: I \to X$  is a function. We usually write  $(x_i)_{i \in I}$ .

**Remark 1.1.7.1.** Let  $(X, \mathcal{T})$  be a topological space and  $x_0 \in X$ . Partially order the set

$$\mathcal{U} = \{ U \subseteq X \mid x_0 \in U \land U \text{ is open} \}$$

with reverse inclusion. Then any choice function defines a net  $(x_U)_{U\in\mathcal{U}}$ .

<sup>&</sup>lt;sup>1</sup> Also linear topological space.

**Definition 1.1.8.** Let X be a topological space. A net  $(x_i)_{i\in I}$  converges so  $x\in X$  if for all open sets  $U\subseteq X$  with  $x\in U$  there exists some index  $i_0\in I$  such that for all  $i\geq i_0$  we have  $x_i\in U$ . We write

$$\lim_{i \in I} x_i = x.$$

**Definition 1.1.9.** A point  $x \in X$  is a *cluster point* of a net  $(x_i)_{i \in I}$  if for all open sets  $U \subseteq X$  with  $x \in U$  and index  $i_0 \in I$  there exists some index  $i \geq i_0$  such that  $x_i \in U$ .

**Proposition 1.1.10.** Let X be a topological space and  $A \subseteq X$ . Then  $x \in \overline{A}$  if and only if there exists a net  $(a_i)_{i \in I}$  in A such that

$$\lim_{i \in I} a_i = x.$$

*Proof.* Suppose a net  $(a_i)_{i\in I}$  converges to x. For any neighbourhood U of x and some  $i_0 \in I$  we have  $a_{i_0} \in U$ . Therefore,  $U \cap A \neq \emptyset$ .

Assume now that  $x \in \overline{A}$ . Again, define

$$\mathcal{U} = \{ U \subseteq X \mid x_0 \in U \land U \text{ is open} \}.$$

There is a choice function a such that  $a_U \in A$  for all U. The net  $(a_U)_{U \in \mathcal{U}}$  then converges to x.

**Proposition 1.1.11.** Let X and Y be topological spaces and  $f: X \to Y$  a map. Then, f is continuous in  $x_0 \in X$  if and only if

$$\lim_{i \in I} f(x_i) = f(x_0)$$

for all nets  $(x_i)_{i\in I}$  that converge to  $x_0$ .

*Proof.* Suppose that f is continuous at  $x_0$ . Take an open neighbourhood U of  $f(x_0)$ . Then there must exist some  $i_0 \in I$  such that for all  $i \geq i_0$  we have  $x_i \in f^{-1}(U)$ , therefore  $f(x_i) \in U$ .

Now suppose f is discontinuous at  $x_0$ . Let

$$\mathcal{U} = \{ U \subseteq X \mid x_0 \in U \land U \text{ is open} \}$$

and  $V \subseteq Y$  be an open set such that  $f(x_0) \in V$  and  $x_0$  is not an interior point of  $f^{-1}(V)$ . Now using the discontinuity of f, for all  $U \in \mathcal{U}$  choose  $x_U \in U$  such that  $f(x_U) \notin V$ . Trivially the net  $(x_V)_{V \in \mathcal{V}}$  converges to  $x_0$ , but

$$\lim_{V \in \mathcal{V}} f(x_V) \neq f(x_0).$$

**Proposition 1.1.12.** The following statements are true:

- i) A net  $(x_i)_{i\in I}$  in a locally convex space converges to  $x_0$  if and only if the net  $(p(x_i x_0))_{i\in I}$  converges to 0 for all  $p \in \mathcal{P}$ .
- ii) The topology in a locally convex space X is the coarsest topology in which all the maps  $x \mapsto p(x x_0)$  are continuous for all  $x_0 \in X$  and  $p \in \mathcal{P}$ .

Proof.

i) If  $(x_i)_{i\in I}$  converges to  $x_0$ , just apply the proposition 1.1.11. Suppose that all the nets  $(p(x_i - x_0))_{i\in I}$  converge to 0. Choose an open set from the local basis of  $x_0$ . It is given by

$$U = \{ x \in X \mid \forall k \le n \colon p_k(x - x_0) < \varepsilon \}.$$

But as all nets  $(p_k(x_i - x_0))_{i \in I}$  converge to 0, there is some index  $i_k \in I$  such that for all  $i \geq i_k$  we have  $p_k(x_i - x_0) < \varepsilon$ . Now just take  $i_0$  to be an upper bound of  $i_k$ . For all  $i \geq i_0$  we then have  $x_i \in U$ .

ii) Obvious.  $\Box$ 

**Definition 1.1.13.** For all  $f \in X^*$  define a seminorm  $p_f : X \to \mathbb{R}$  as  $p_f(x) = |f(x)|$ . The family  $\mathcal{P} = \{p_f \mid f \in X^*\}$  induces the *weak topology* on X. We denote the weak topology with  $\sigma(X, X^*)$ .

**Remark 1.1.13.1.** The space X with the topology  $\sigma(X, X^*)$  is a locally convex space by the Hahn-Banach theorem.<sup>2</sup>

**Definition 1.1.14.** Let X be a normed space. For all  $x \in X$  we define a seminorm  $p_x \colon X^* \to \mathbb{R}$  as  $p_x(f) = |f(x)|$ . The family  $\mathcal{P} = \{p_x \mid x \in X\}$  induces the weak-\* topology on  $X^*$ . We denote the weak-\* topology with  $\sigma(X^*, X)$ .

**Remark 1.1.14.1.** The weak topology on  $X^*$  is finer than the weak-\* topology, as X can be isometrically mapped into  $X^{**}$  with the map  $x \mapsto (f \mapsto f(x))$ .

<sup>&</sup>lt;sup>2</sup> Introduction to functional analysis, corollary 2.2.5.2.

#### 1.2 Banach-Alaoglu theorem

**Theorem 1.2.1** (Banach-Alaoglu). Let X be a normed space. Then the closed unit ball in  $X^*$ 

$$(X^*)_1 = \{ f \in X^* \mid ||f|| \le 1 \}$$

is compact in the weak-\* topology on  $X^*$ .

*Proof.* Assign a disk to all  $x \in X$  as  $D_x = \{z \in \mathbb{F} \mid |z| \leq ||x||\}$  with the euclidean topology. Define

$$P = \prod_{x \in X} D_x$$

with the product topology. The space P is then compact by Tychonoff's theorem. Now define the map  $\Phi: (X^*)_1 \to P$  with  $\Phi(f) = (f(x))_{x \in X}$ . This map is injective.

Let  $(f_i)_{i\in I}$  be a net in  $(X^*)_1$  that weak-\* converges to  $f\in X^*$ . Equivalently, we have

$$\lim_{i \in I} f_i(x) = f(x)$$

for all  $x \in X$ . By the definition of the product topology we have

$$\lim_{i \in I} \Phi(f_i) = \Phi(f).$$

Therefore,  $\Phi$  is continuous. Analogously,  $\Phi^{-1}$ : im  $\Phi \to (X^*)_1$  is continuous.

Suppose that  $(\Phi(f_i))_{i\in I}$  converges to some  $p \in P$ . By the definition of the product topology this means that  $f_i(x)$  converges to  $p_x$  for all  $x \in X$ . Define a map  $f: X \to \mathbb{F}$  given by  $f(x) = p_x$ . Then, f is linear and bounded with  $||f|| \le 1$ . Thus  $p = \Phi(f) \in \operatorname{im}(\Phi)$ , therefore,  $\Phi((X^*)_1)$  is closed. As  $(X^*)_1$  is homeomorphic to its image which is compact, it is also compact.

Corollary 1.2.1.1. Every Banach space X is isometrically isomorphic to a closed subspace C(K) for some compact Hausdorff space K.

*Proof.* Choose  $K = (X^*)_1$  with the weak-\* topology. By Banach-Alaoglu, K is compact and Hausdorff. Now define the map  $\Delta \colon X \to K$  with  $\Delta(x) = (f \mapsto f(x))$ . Now observe that

$$\|\Delta(x)\|_{\infty} = \sup_{g \in K} |\Delta(x)(g)| = \sup_{g \in K} |g(x)| = \|x\|$$

by Hahn-Banach.<sup>3</sup>

<sup>&</sup>lt;sup>3</sup> Introduction to functional analysis, corollary 2.2.5.1.

#### 1.3 Minkowski gauge

**Definition 1.3.1.** Let X be a  $\mathbb{F}$ -vector space. A set  $A \subseteq is$ 

- i) balanced, if for all  $x \in A$  and  $\alpha \in \mathbb{F}$  with  $|\alpha| \leq 1$  we have  $\alpha x \in A$ ,
- ii) absorbing, if for all  $x \in A$  there exists some  $\varepsilon > 0$  such that for all  $t \in (0, \varepsilon)$  we have  $tx \in A$ ,
- iii) absorbing in  $a \in A$  if A a is absorbing.

**Theorem 1.3.2.** Let X be a  $\mathbb{F}$ -vector space and  $V \subseteq X$  a convex, balanced and absorbing in each of its points. Then there exists a unique seminorm p such that

$$V = \{ x \in X \mid p(x) < 1 \} .$$

*Proof.* As A is convex, we can define the *Minkowski gauge* 

$$p_V(x) = \inf \left\{ t \ge 0 \mid x \in tV \right\}.$$

It is of course well defined, as A is absorbing. We can check that

$$p_{V}(\alpha x) = \inf \left\{ t \ge 0 \mid x \in \frac{t}{\alpha} V \right\}$$

$$= \inf \left\{ t \ge 0 \mid x \in \frac{t}{|\alpha|} V \right\}$$

$$= |\alpha| \cdot \inf \left\{ \frac{t}{|\alpha|} \ge 0 \mid x \in \frac{t}{|\alpha|} V \right\}$$

$$= |\alpha| p_{V}(x)$$

as A is balanced. Therefore,  $p_V$  is homogeneous. As  $p_V$  is sublinear,<sup>4</sup> it is a seminorm. It follows that<sup>5</sup>

$$V = \{ x \in X \mid p_V(x) < 1 \} .$$

Suppose that

$$V = \{ x \in X \mid q(x) < 1 \}$$

for some seminorm  $q \neq p_V$ . But then we have  $p_V(x) \neq q(x)$  for some  $x \in X$ , therefore there exists some  $t \in \mathbb{R}$  such that  $p_V(tx) > 1 > q(tx)$  or  $q(tx) > 1 > p_V(tx)$ .

<sup>&</sup>lt;sup>4</sup> Introduction to functional analysis, proposition 2.3.3.

<sup>&</sup>lt;sup>5</sup> Introduction to functional analysis, remark 2.3.4.1.

#### 1.4 Applications of the Hahn-Banach theorem

**Theorem 1.4.1** (Hahn-Banach). Suppose X is a locally convex space and  $A, B \subseteq X$  are disjoint convex sets. If B is compact, there exists a functional  $f \in X^*$  that separates A from B – there exist  $\alpha, \beta \in \mathbb{R}$  such that for all  $a \in A$  and  $b \in B$  we have

$$\operatorname{Re} f(a) \le \alpha < \beta \le \operatorname{Re} f(b).$$

**Theorem 1.4.2.** Suppose X is a locally convex space and  $A \subseteq X$  is a convex space. Then the closure of A is the same as the closure in the weak topology.

*Proof.* The set  $\overline{A}$  is of course a subset of the closure of A in the weak topology. Now choose a point  $x \notin \overline{A}$ . There exists a functional  $f \in X^*$  and numbers  $\alpha, \beta \in \mathbb{R}$  such that

$$\operatorname{Re} f(a) \le \alpha < \beta \le \operatorname{Re} f(x)$$

for all  $a \in \overline{A}$ . But then

$$\overline{A} \subseteq \{y \in X \mid \operatorname{Re} f(y) < \alpha\} = (\operatorname{Re} f)^{-1} ((-\infty, \alpha]) = C,$$

where C is closed in the weak topology. It follows that the closure of A in the weak topology is a subset of C. As  $x \notin C$ , we get the desired equality.

Corollary 1.4.2.1. A convex set is a locally convex space if and only if it is weakly closed.

**Proposition 1.4.3.** Let X be a topological vector space and  $f: X \to \mathbb{F}$  a linear functional. The following statements are equivalent:

- i) The functional f is continuous.
- ii) The functional f is continuous in 0.
- iii) The functional f is continuous in some point  $x_0 \in X$ .
- iv) The set  $\ker f$  is closed.
- v) The function  $x \mapsto |f(x)|$  is a continuous seminorm.

If X is a locally compact space and  $\mathcal{P}$  is the family of seminorms defining the topology on X, the above conditions are also equivalent to

$$|f(x)| \le \sum_{k=1}^r \alpha_k p_k(x)$$

for some  $\alpha_k \in \mathbb{R}^+$  and  $p_k \in \mathcal{P}$ .

*Proof.* The proof of the equivalence of the first 5 statements is the same as for normed spaces. Suppose now that

$$|f(x)| \le \sum_{k=1}^r \alpha_k p_k(x).$$

Let  $(x_i)_{i\in I}$  be a net in X that converges to 0. Then

$$0 \le |f(x_i)| \le \sum_{k=1}^r \alpha_k p_k(x_i),$$

which converges to 0. It follows that f is continuous at 0.

Now suppose that f is continuous at 0. The set

$$f^{-1}\left(\mathring{\mathcal{B}}(0,1)\right) = \{x \in X \mid |f(x)| < 1\}$$

contains an open neighbourhood B of the point 0. We can write

$$B = \bigcap_{j=1}^{r} U(0, p_j, \varepsilon).$$

Take  $x \in X$ . For  $\delta > 0$  be such that

$$p_j\left(x \cdot \frac{\varepsilon}{\delta + \sum p_j(x)}\right) = \frac{\varepsilon}{\delta + \sum p_j(x)} \cdot p_j(x) < \varepsilon,$$

therefore,

$$\left| f\left( x \cdot \frac{\varepsilon}{\delta + \sum p_j(x)} \right) \right| < 1,$$

which can be rearranged to

$$|f(x)| < \frac{1}{\varepsilon} \cdot \sum_{j=1}^{r} p_j(x) + \frac{\delta}{\varepsilon}.$$

Taking a limit, we get the desired inequality.

**Theorem 1.4.4** (Riesz-Markov). Let X be a compact Hausdorff space and  $\Phi \in \mathcal{C}(X) \check{\mathbf{A}} *$ . Then there exists a unique regular Borel measure  $\mu$  such that

$$\Phi(f) = \int_{X} f \, d\mu$$

for all  $f \in \mathcal{C}(X)$ . Furthermore, we have  $\|\Phi\| = \|\mu\| = |\mu|(X)$ .

**Proposition 1.4.5.** Let X be a completely regular space. Endow the space  $\mathcal{C}(X)$  with the topology induced by the seminorms  $\{p_K \mid K \subseteq X \text{ is compact}\}$ . If  $L \in \mathcal{C}(X)^*$ , then there exists a compact set  $K \subseteq X$  and a regular Borel measure on K such that

$$L(f) = \int_{K} f \, d\mu$$

for all  $f \in \mathcal{C}(X)$ . Conversely, every such  $(K, \mu)$  defines a functional  $L \in \mathcal{C}(X)^*$ .

*Proof.* Suppose that

$$L(f) = \int_{K} f \, d\mu$$

for some compact set K and measure  $\mu$ . Then we have

$$|L(f)| = \left| \int_{K} f \, d\mu \right| \le \|\mu\| \cdot \sup_{K} |f| = \|\mu\| \cdot p_{K}(f),$$

so L is continuous.

Let now  $L \in \mathcal{C}(X)^*$ . We can therefore write

$$|L(f)| \le \sum_{k=1}^r \alpha_k p_{K_j}(f)$$

for some compact sets  $K_j$ . We can simplify the above to

$$|L(f)| \le \alpha \cdot p_K(f),$$

where

$$K = \bigcup_{j=1}^{r} K_j.$$

Note that if we have  $f \in \mathcal{C}(X)$  and  $f|_K = 0$ , it follows that L(f) = 0. Now define  $F: \mathcal{C} \to \mathbb{F}$  as follows; for any  $g \in \mathcal{C}$  choose an extension  $\widetilde{g} \in \mathcal{C}(X)$  of g and set

$$F(g) = L(\widetilde{g}).$$

This map is well defined by the above observation. We can check that F is indeed linear. Note that

$$\left|F(g)\right| = \left|L\left(\widetilde{g}\right)\right| \leq \alpha \cdot p_{K}\left(\widetilde{g}\right) = \alpha \cdot \left\|g\right\|_{\infty,K},$$

therefore, F is continuous. By the Riesz-Markov theorem there exists a regular Borel measure  $\mu$  on K such that

$$F(g) = \int_{K} g \, d\mu.$$

If  $f \in \mathcal{C}(X)$ , we have  $g = f|_K \in \mathcal{C}(K)$ , so

$$L(f) = F(g) = \int_{K} g \, d\mu.$$

#### 1.5 Krein-Milman theorem

**Definition 1.5.1.** Let X be a vector space and  $C \subseteq X$  a convex subset.

- i) A non-empty convex subset  $F \subseteq C$  is a face if for all  $t \in (0,1)$  and  $x,y \in C$  satisfying  $tx + (1-t)x \in F$ , we also have  $x,y \in F$ .
- ii) A point  $x \in C$  is an extreme point if  $\{x\} \subseteq C$  is a face. We denote the set of extreme points of C by ext C.

**Definition 1.5.2.** For a vector space X and  $A \subseteq X$  define the *convex hull* of A as

$$\operatorname{co} A = \left\{ \sum_{i=1}^{n} \alpha_{i} x_{i} \;\middle|\; n \in \mathbb{N} \land \alpha_{j} \in \mathbb{R}_{\geq 0} \land \sum_{i=1}^{n} \alpha_{i} = 1 \land x_{i} \in A \right\}.$$

If X is a topological vector space, define the closed convex hull as

$$\overline{\operatorname{co}} A = \overline{\operatorname{co} A}.$$

**Proposition 1.5.3.** The set co A is the smallest convex set that contains A. The set  $\overline{\operatorname{co}} A$  is the smallest closed set that contains A.

*Proof.* The only nontrivial part of the proof is convexity of the set  $\overline{\operatorname{co}} A$ . Let  $(x_i)_{i\in I}$  and  $(y_i)_{i\in I}$  be two nets that converge to x and y, where  $x,y\in\overline{\operatorname{co}} A$ . For any  $t\in(0,1)$  we have

$$tx + (1-t)y = \lim_{i \in I} (tx_i + (1-t)y_i) \in \overline{\operatorname{co}} A.$$

**Lemma 1.5.4.** Let X be a topological vector space and  $C \subseteq X$  be a non-empty compact convex subset. Then for any  $\phi \in X^*$  the set

$$F = \left\{ x \in C \mid \operatorname{Re} \phi(x) = \min_{C} \operatorname{Re} \phi \right\}$$

is a closed face of C.

*Proof.* As C is a compact set, the set F is obviously non-empty. Also note that, as a preimage of a closed point, F is a closed set. Convexity of F follows from linearity of  $\phi$ . Suppose that  $tx + (1-t)y \in F$ . As

$$\min_{C} \operatorname{Re} \phi = \operatorname{Re} \phi(tx + (1-t)y) = t\phi(x) + (1-t)\phi(y) \ge \min_{C} \operatorname{Re} \phi,$$

it follows that  $x, y \in F$ . By definition, F is a face.

**Theorem 1.5.5** (Krein-Milman). Let X be a locally convex space and  $C \subseteq X$  a non-empty convex compact subset. Then

$$C = \overline{\operatorname{co}} (\operatorname{ext} C)$$
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