

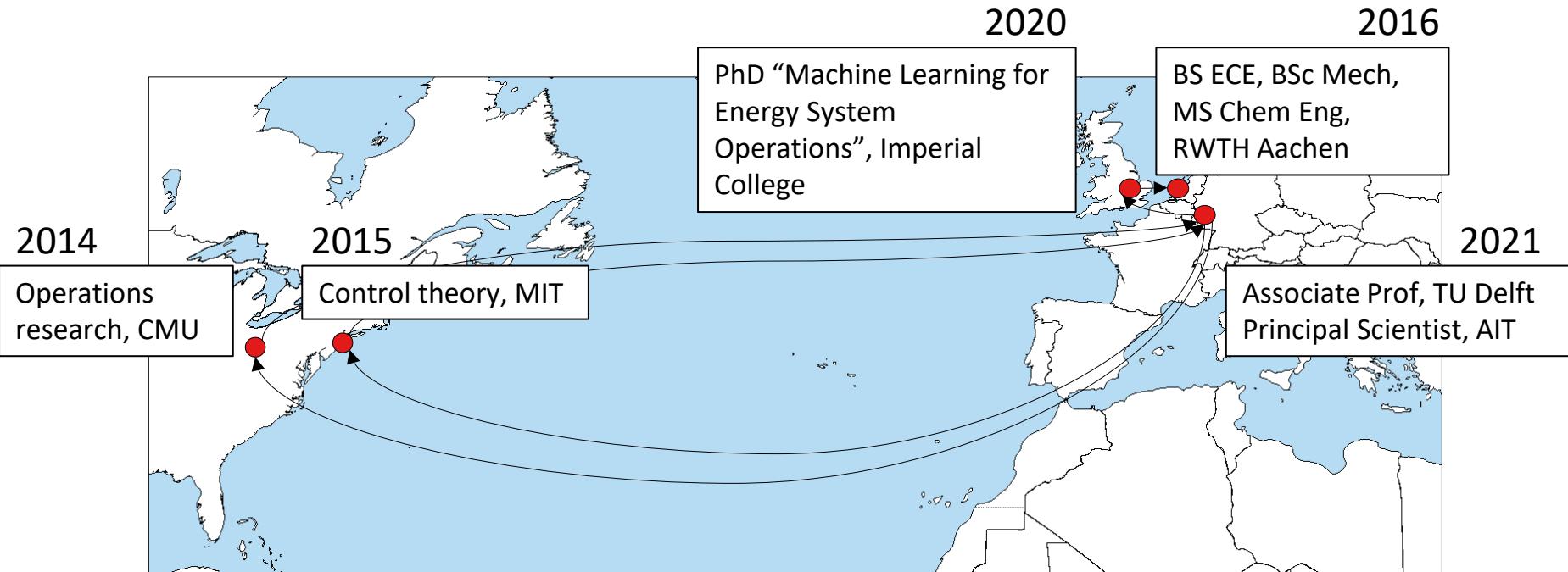
Power System Reliability with Deep Learning

ACM e-Energy'25

17-05

Prof. Dr. Jochen L. Cremer,
Associate Professor

Introduction



Delft AI Energy Lab

Mission & objective

- combine groundbreaking ML with the reliable theory of the physical energy system
- make energy systems sustainable, reliable, effective

Education

- EE4C12 ML for Electrical Engineering
- SET 3125 Machine Learning Workflows for Digital Energy Systems
- SC42150 Statistical Signal Processing
- SC42110 Dynamic Programming and Stochastic Control
- MOOC Digitalization of Intelligent and Integrated Energy Systems
- Crash course of "Data-science"



Team



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Outline

Reliability management and data in control rooms

1. Introduction to reliability management
2. Machine learning approaches
3. Security assessment with cost-sensitive supervised learning

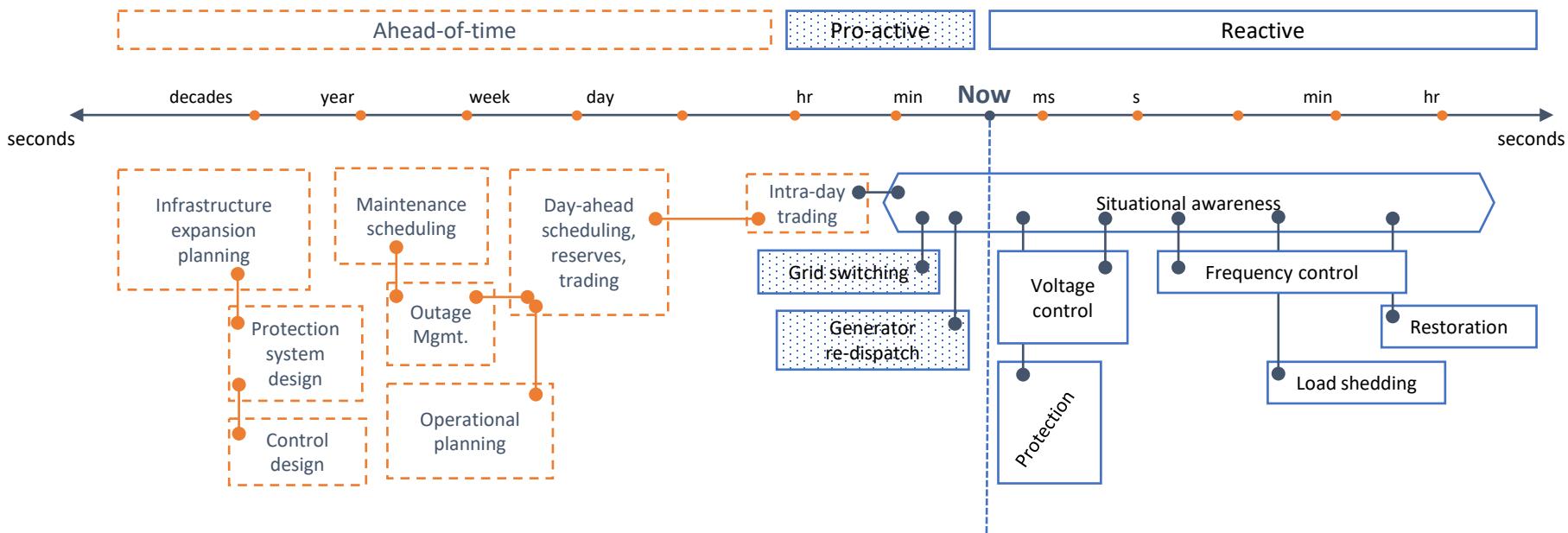
Learning models for secure system operation

4. Learning with domain knowledge
5. State estimation with graph neural networks
6. Weakly-supervised learning for secure operation
7. Challenges applying ML to reliability



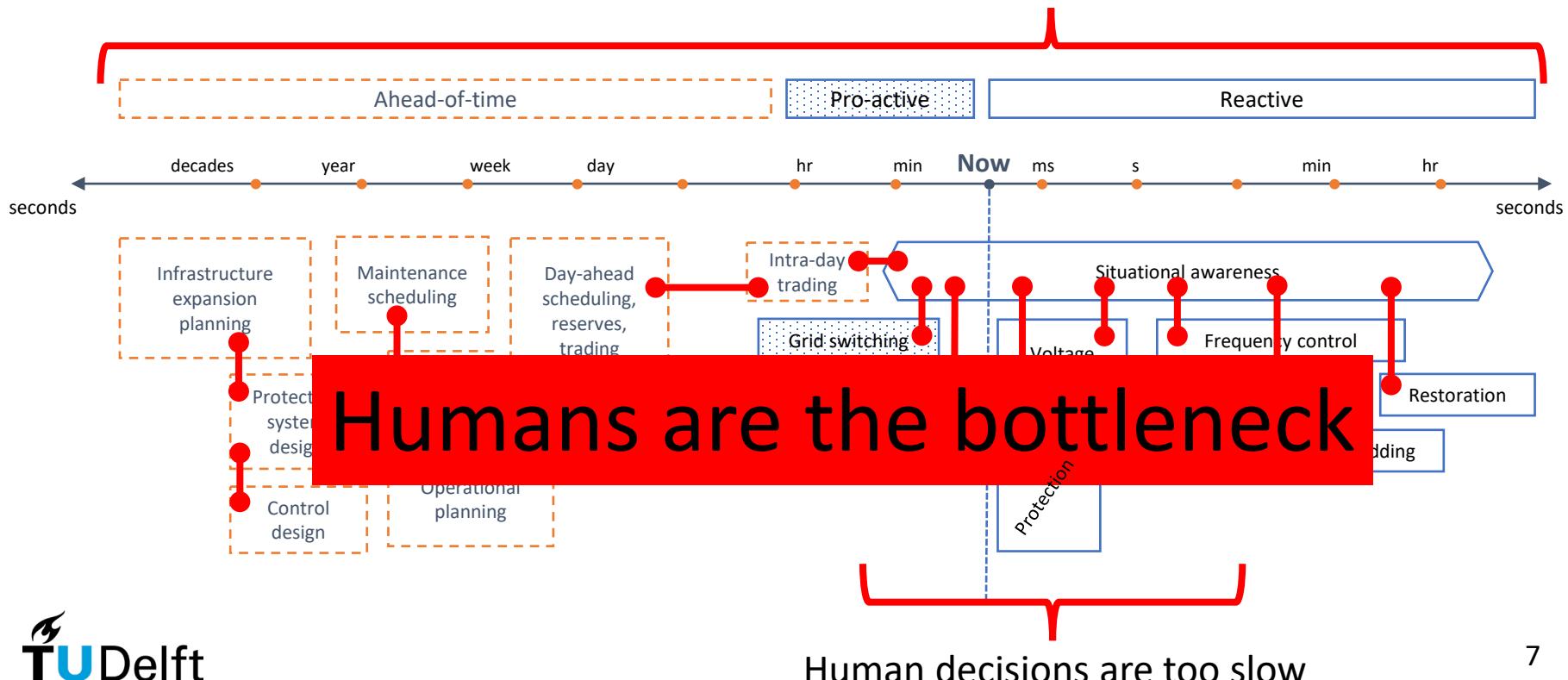
Experts are in charge to manually operate the power system based on experience and with the support of tools

A complex process

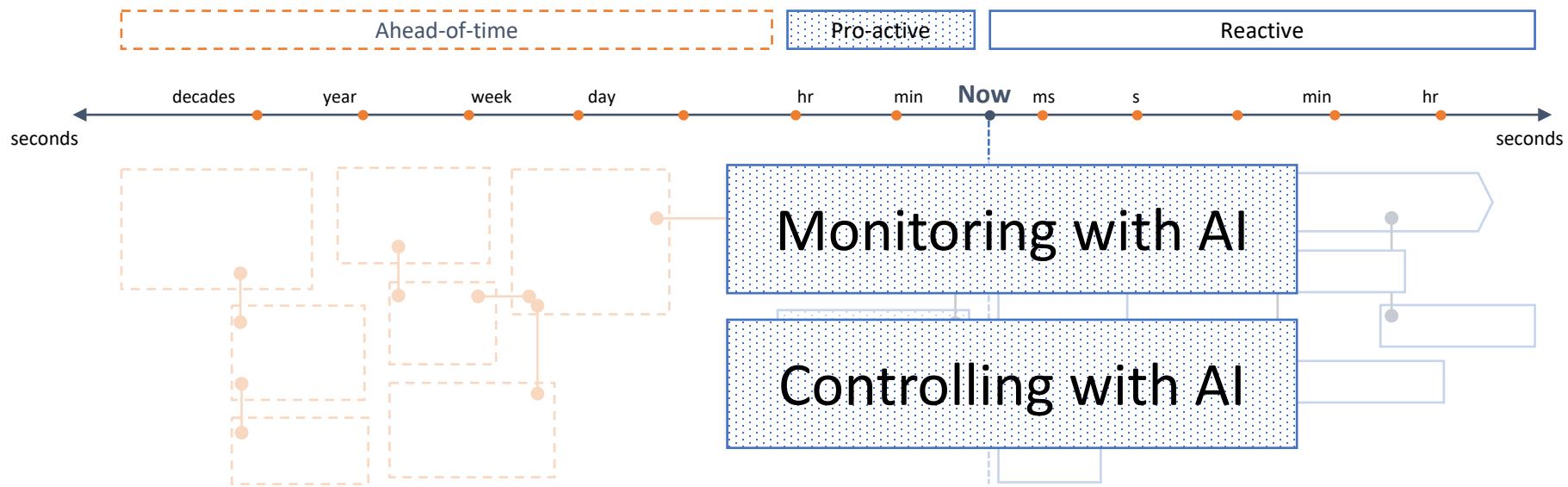


What's the issue?

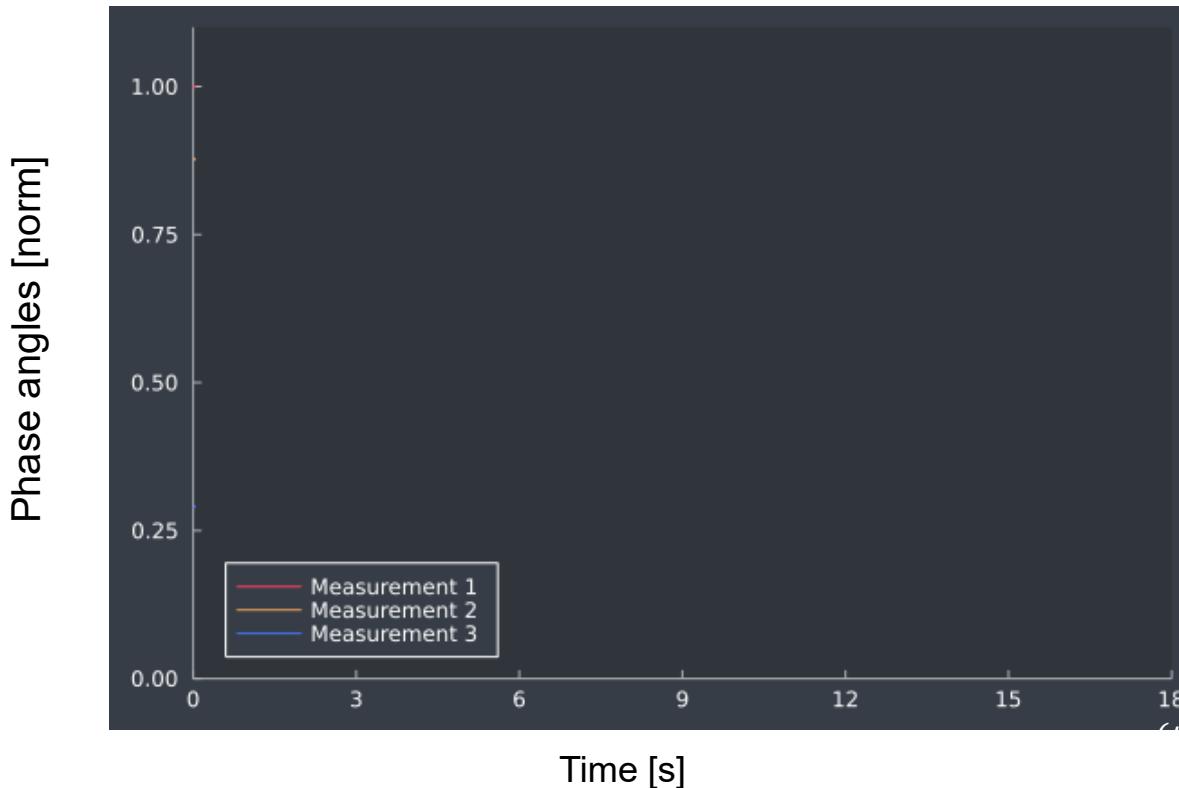
Interdependencies
challenge manual rules



Automation first realised where urgently needed

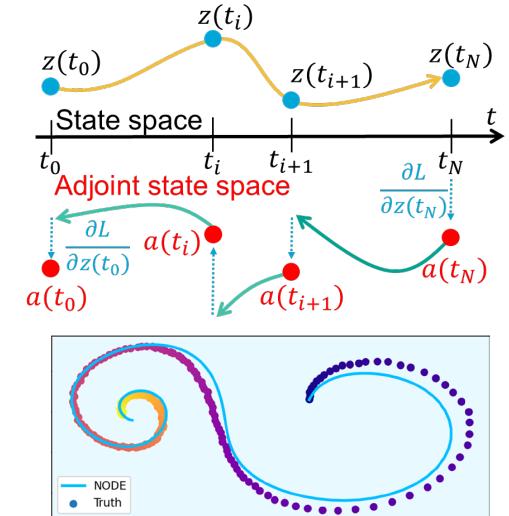


Real-time security assessment of disturbances



Mert Karaçelebi

Neural ordinary differential equations



[1] Mert Karaçelebi, Jochen L. Cremer "Online Neural Dynamics Forecasting for Power System Security", *International Journal of Electrical Power & Energy Systems* 2025

[2] Mert Karaçelebi, Jochen L. Cremer, "Predicting Power System Frequency with Neural Ordinary Differential Equations", *12th Bulk Power System Dynamics and Control Symposium and Sustainable Energy, Grids and Networks Journal*, 2025

Why do system operators require reliability monitoring?



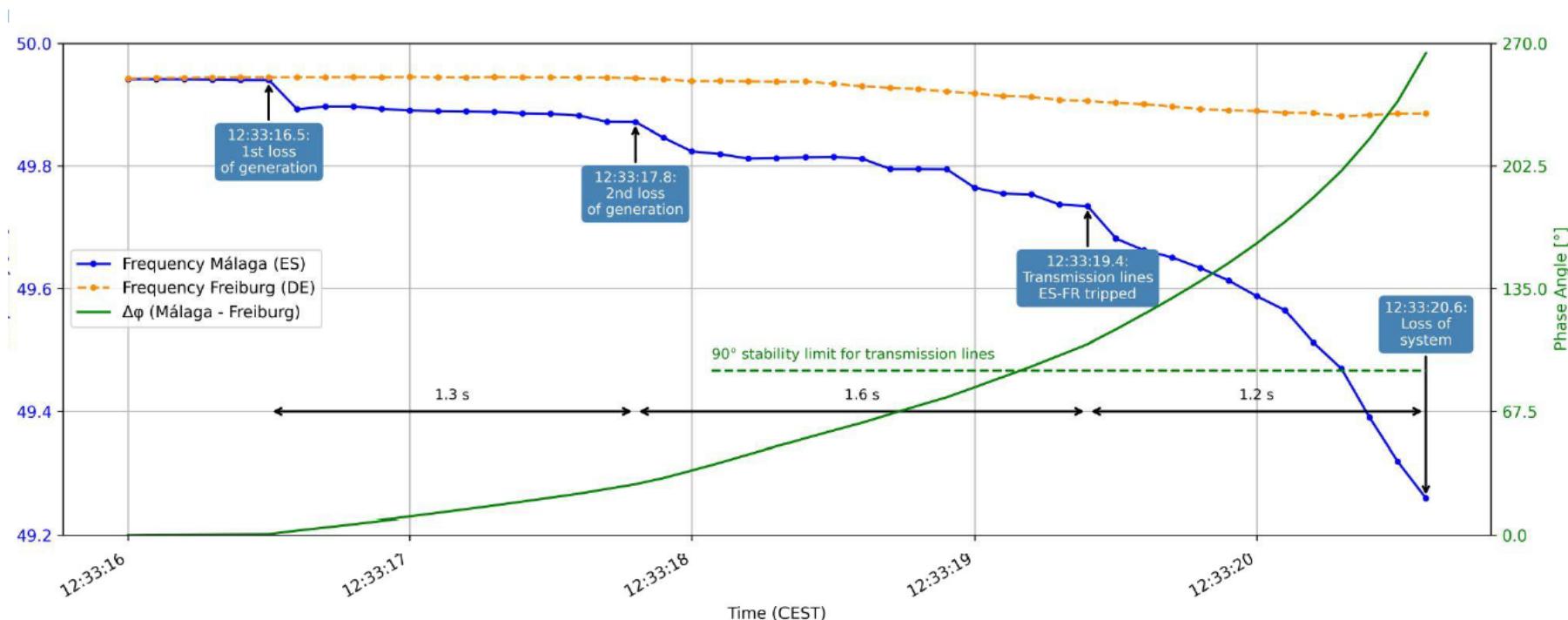
Houston, Texas 07 Feb 2021



Houston, Texas 16 Feb 2021

- Damages from the blackouts were estimated at **\$195 billion [3]**
- **Seconds away** from a total power blackout in Texas

Power blackout 28 April 2025 Spain/Portugal

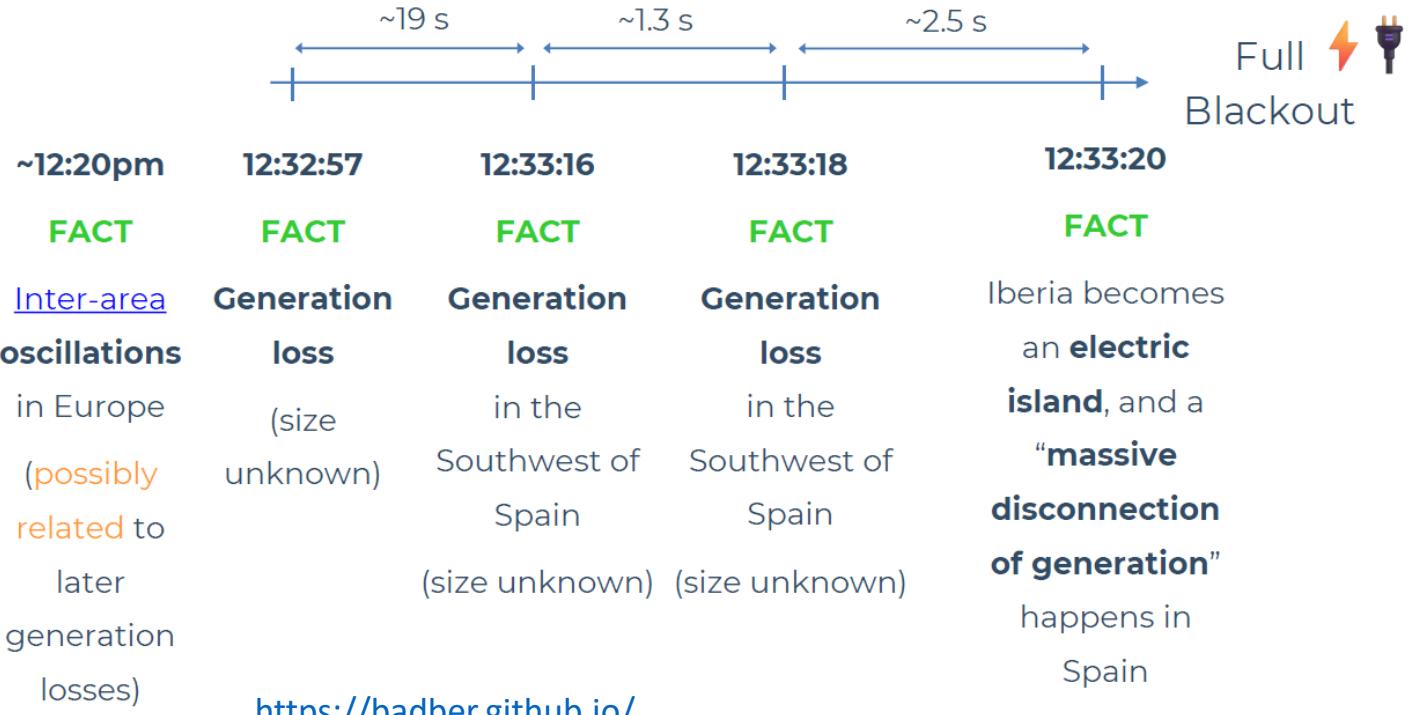




N-2?

► 28th of April 2025 (CET)

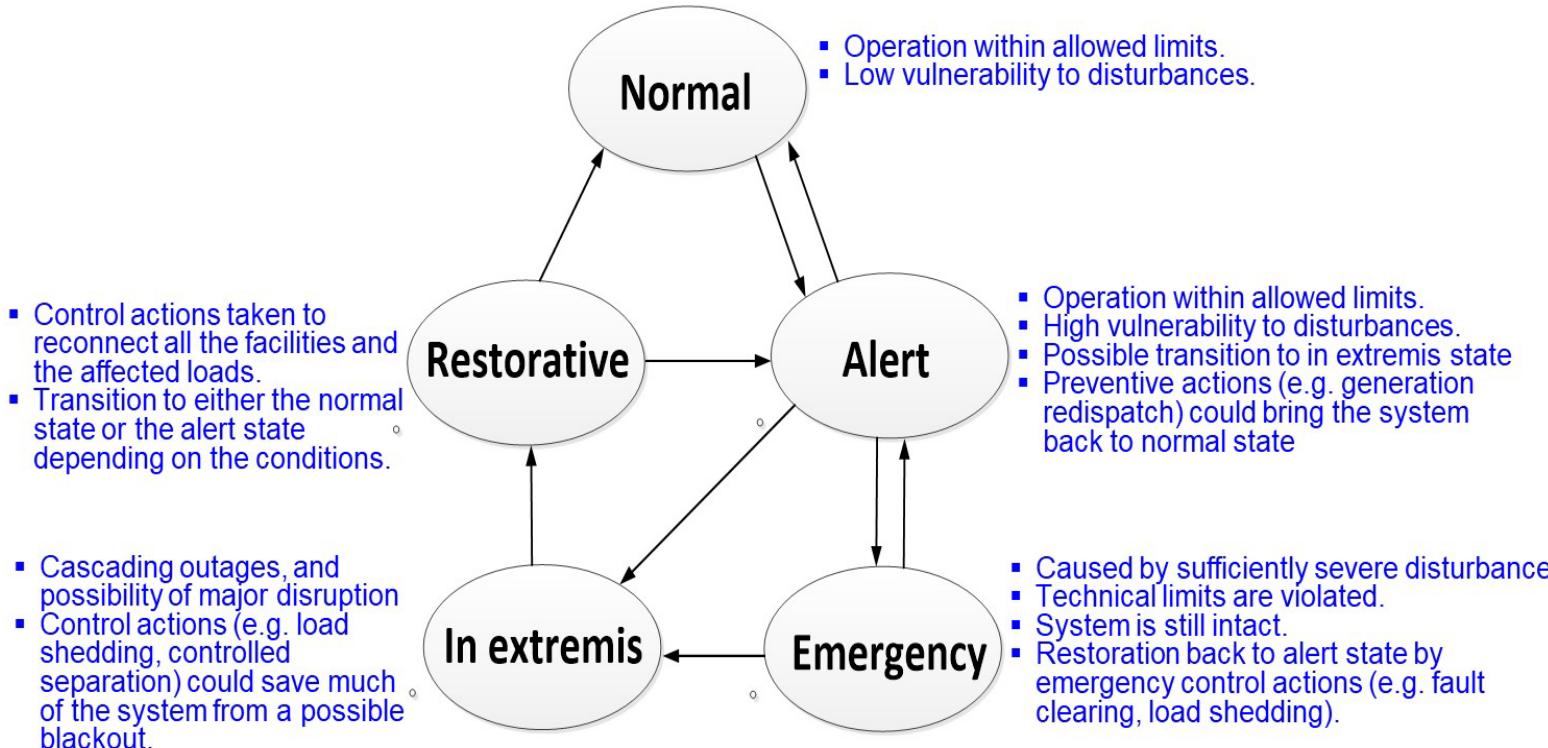
Luis Badesa



Power system reliability

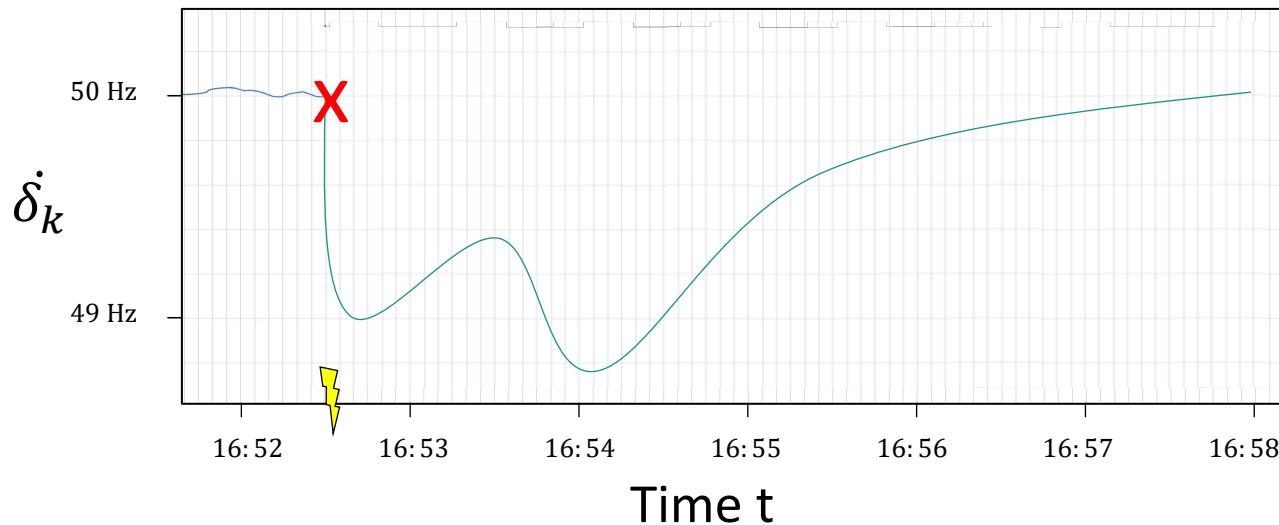
“...is the probability that an electrical power system can perform a required function under given conditions for a given time interval.”

Operating states of power systems



Conventional (offline) dynamic security assessment

Simulating time-response



Numerical integration

ODE system

$$\begin{cases} \dot{x} = f(x, t, x_0) \\ x_0 = (P_k^{16h}, Q_k^{16h}) \end{cases}$$

Forward Euler

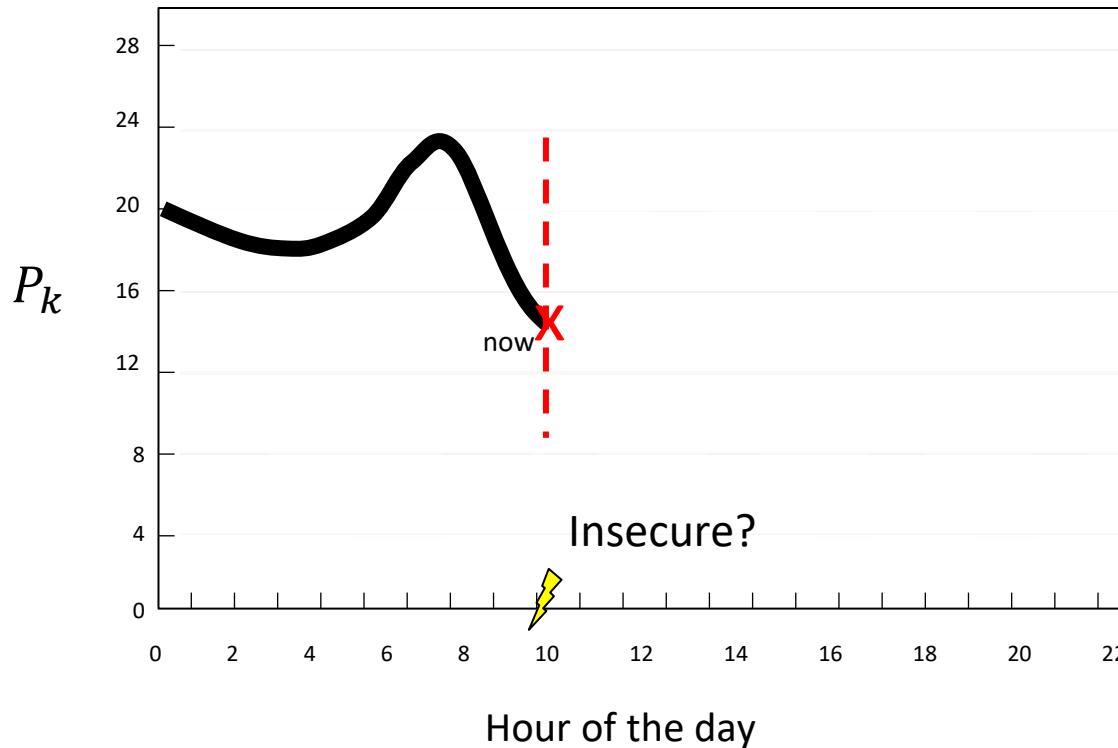
$$x_{k+1} = x_k + h f(x_k, t_k)$$

slow for large systems

Real-time dynamic security assessment

Objective: predicting security in real-time

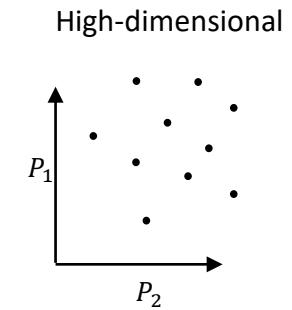
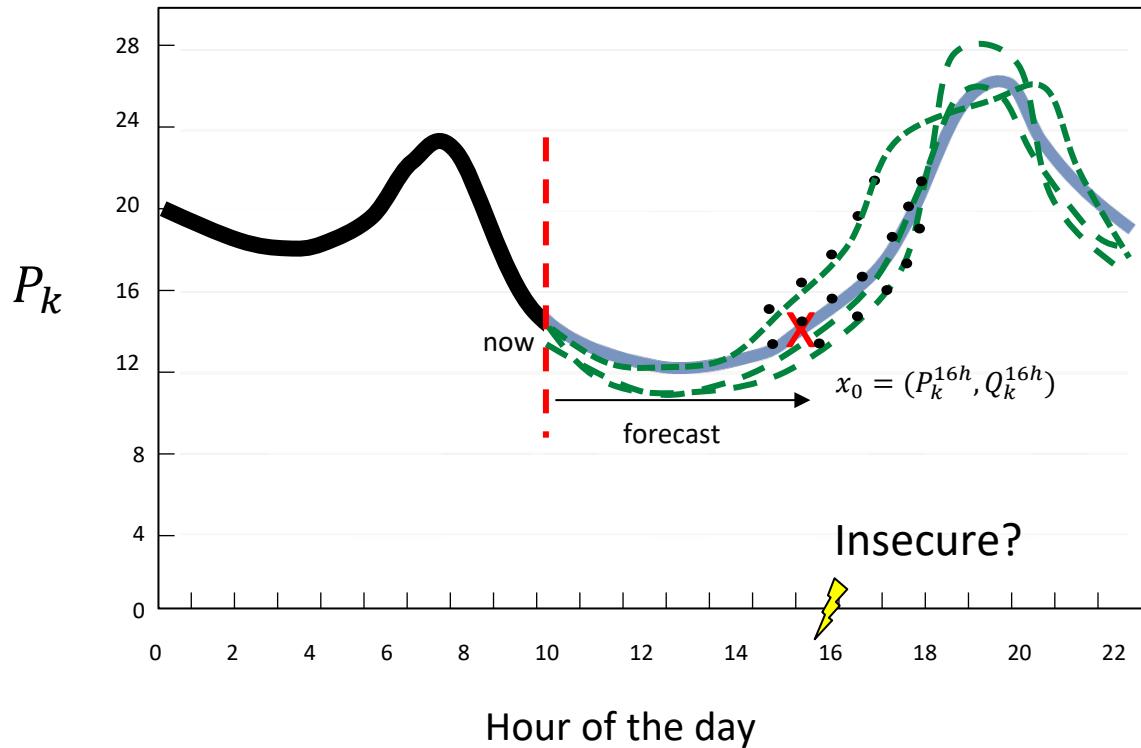
In response, use corrective actions in (near) real-time



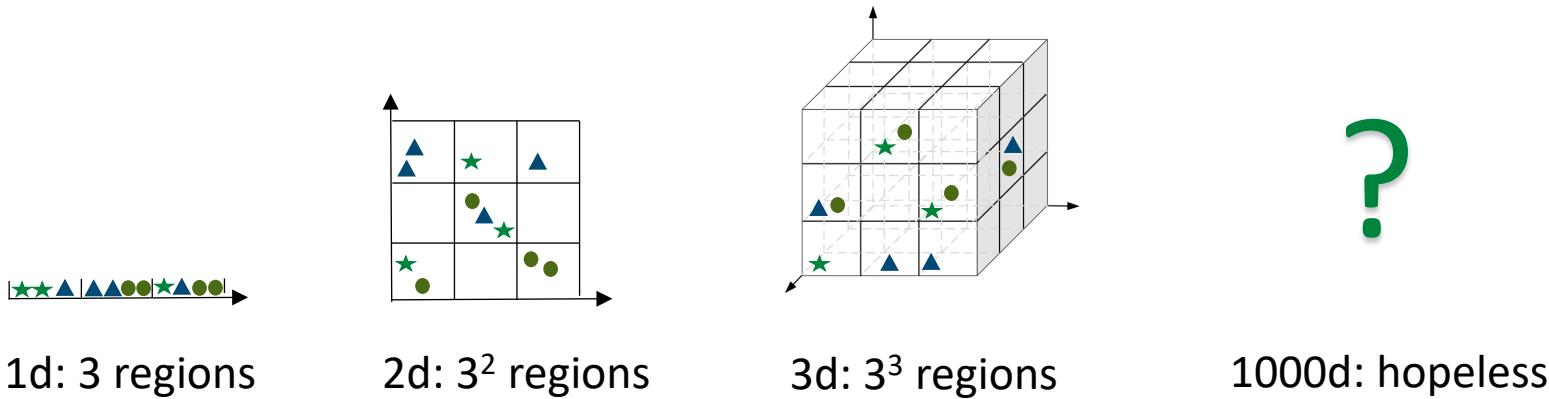
(Preventive) real-time dynamic security assessment

For N-1 security

Preventive actions

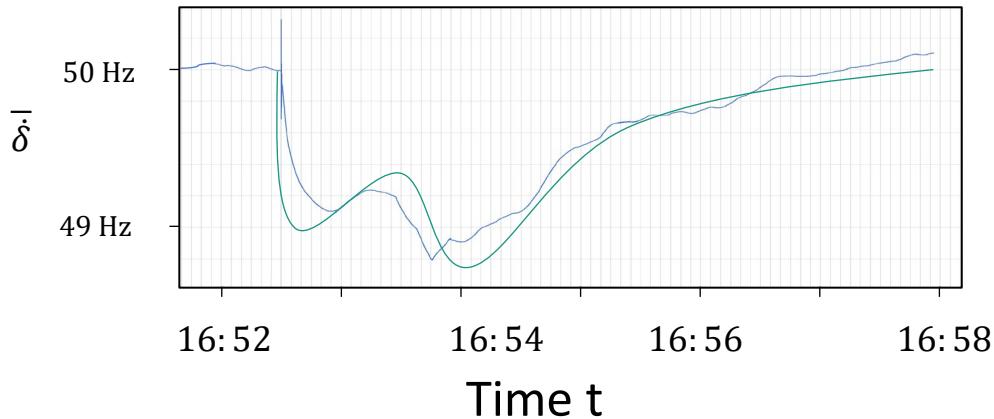


Curse of Dimensionality



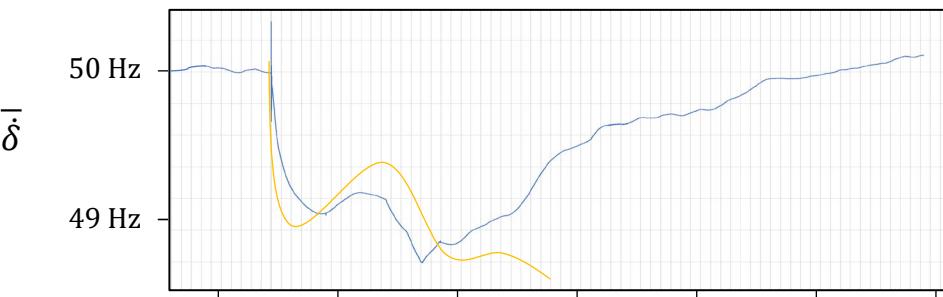
As dimensionality grows: fewer samples per region.

Security of power systems



secure

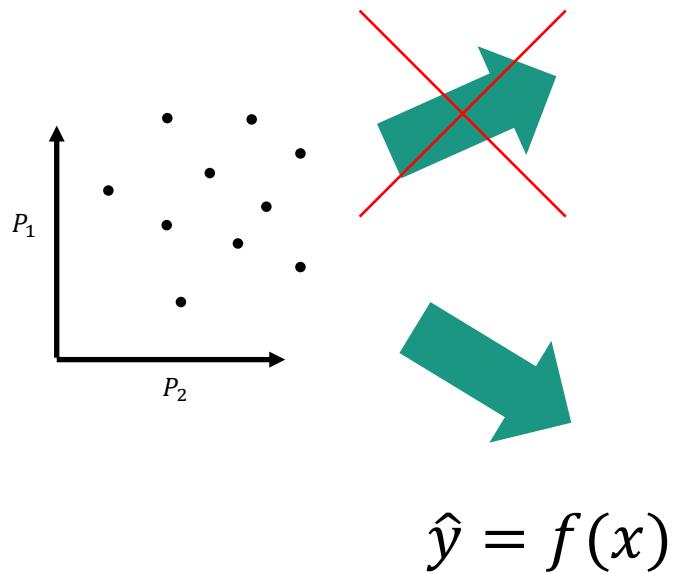
$$y = 0$$



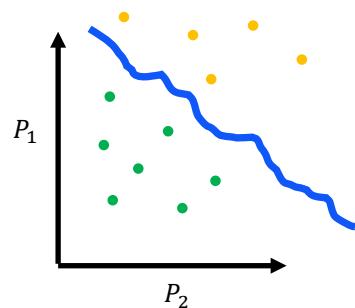
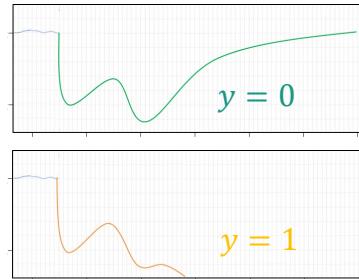
insecure

$$y = 1$$

Machine learning model to predict security



Time-domain simulation



How to train
and use f ?

Challenges for reliability management

- More extreme weather events
- Higher grid load in the system
- Higher uncertainty
- Highly complex problem

Opportunities for reliability management with AI

- Availability of better models and data (weather, grid data, etc)
- New AI techniques
- Once trained, models are quick in ‘predicting’, but challenges also exist

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Supervised Learning for Surrogate Models

Federica
Bellizio

Olayiwola
Arowolo

Notation: Power system s , model m , parameter x

Objective: assess $m(x) \rightarrow y$ very fast and often

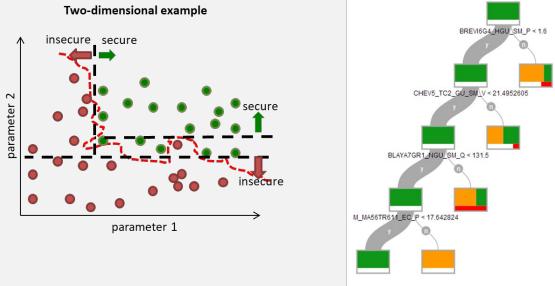
Surrogate approach

1. Generate a training dataset $\Omega^T = \{(x_i, y_i)\}_{i=1}^N$ where $y_i = m(x_i)$ from the full simulator
2. Train surrogate $f(x) \rightarrow \hat{y}$ with supervised loss $\sum_{i \in \Omega^T} \|y_i - \hat{y}_i\|$
3. Use $f(x_j)$ for new $j \notin \Omega^T$

Benefit: speed at inference

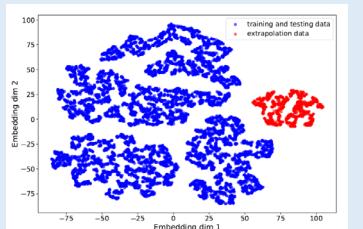
Applications

- Real-time dynamic security assessment ([8,9] and many others)



Challenges

- What if s and m changes? e.g., topology changes
- What if the model is inaccurate $s \neq m$? e.g., inverter-based controls
- Need large, representative training data



Physics-Informed Learning

Objective: surrogate learning enhanced with physics knowledge from model m

Idea: Incorporate physics residual (e.g. from a PDE or simulator) to guide learning and improve generalization

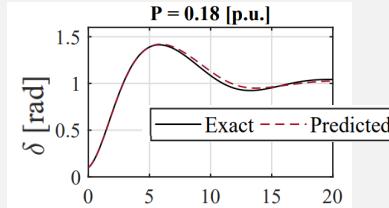
Physics-informed approach

1. Generate offline training dataset $\Omega^T = \{(x_i, y_i)\}_{i=1}^N$ with $y_i = m(x_i)$
2. Train surrogate $f(x) \rightarrow \hat{y}$ on composite loss $\sum_{i \in \Omega^T} \|y_i - \hat{y}_i\| + \mathcal{L}_{phys}(f(x_i), m)$
3. Use $f(x_j)$ for new $j \notin \Omega^T$

Benefits: Better generalisation performance with **fewer training samples**

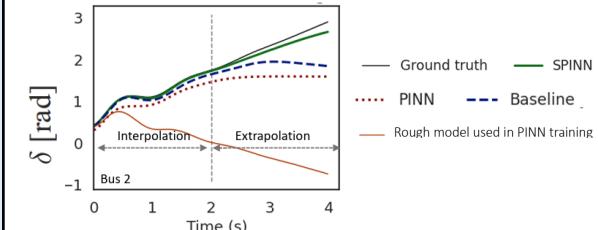
Applications

- Extrapolation in time-domain for dynamic analysis in power systems



Challenges

- Model inaccuracy $s \neq m$
- **Changes in s or m**
- Data sparsity
- Multi-loss scaling causes training instability
- Scaling issues to many physical loss terms in power systems



Weakly-Supervised (E2E) Learning

Objective: learn models $f(x)$ for downstream task even when exact labels $y_i = m(x_i)$ from the simulator m are unavailable, uncertain, or only indirectly defined.

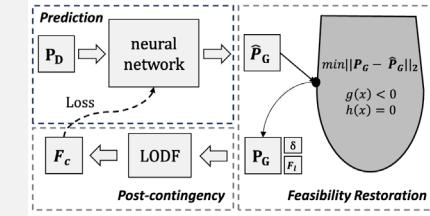
Approach

1. Generate many inputs $\Omega^T = \{(x_i)\}_{i=1}^N$
2. Model task loss $\sum_{i \in \Omega^T} \mathcal{L}(m(f(x_i)))$
3. Use $f(x_j)$ for new $j \notin \Omega^T$

Benefits: learning for computationally expensive or ill-defined problems

Applications

- Learn to predict effective inputs to OPF [13]
- Replace conventional solvers with NN [14]
- Distribution system state estimation [15]
- N-k security-constrained OPF [16]



Challenges

- Inexact supervision $s \neq m$ not so important as success defined by task-loss
- **System shift in s or m**
- Data coverage. Diverse samples are needed for generalization

[13] Donati, P., Amos, B., & Kolter, J. Z. (2017). Task-based end-to-end model learning in stochastic optimization. *Advances in neural information processing systems*, 30.
[14] Donon, B., Liu, Z., Liu, W., Guyon, I., Marot, A., & Schoenauer, M. (2020). Deep statistical solvers. *Advances in Neural Information Processing Systems*, 33, 7910-7921.
[15] Habib, B., Isufi, E., van Breda, W., Jongepier, A., & Cremer, J. L. (2023). Deep statistical solver for distribution system state estimation. *IEEE Transactions on Power Systems*, 39(2), 4039-4050.
[16] Giraud, B. N., Rajaei, A., & Cremer, J. L. (2024). Constraint-driven deep learning for n-k security constrained optimal power flow. *Electric Power Systems Research*, 235, 110692.

Self-Supervised Learning

Objective: Learn a **useful internal representation** from unlabeled data by solving a **pretext task** — no human-labeled or simulator-labeled outputs required.

Idea: instead of training on (x_i, y_i) train on auto-generated pseudo-labels or tasks constructed from structure x_i

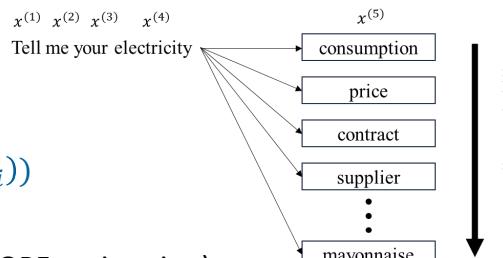
Approach

1. Generate many inputs $\Omega^T = \{(x_i)\}_{i=1}^N$
2. Define self-supervised pretext loss $\mathcal{L}_{\text{pretext}}(f(x_i))$
3. Train encoder $\sum_{i \in \Omega^T} \mathcal{L}_{\text{pretext}}(f(x_i))$
4. Use $f(x)$ for downstream task (e.g. forecasting, OPF, estimation)

Benefits: Good initialization when little data, good transfer to downstream tasks

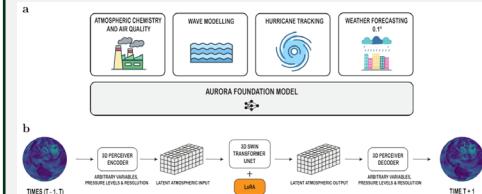
Challenges

- Design pretext loss and model architectures with broad set of tasks, grid conditions, topologies
- Generate large data sets
- ...

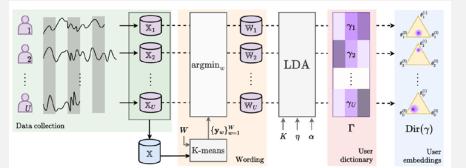


Applications

- Natural Language Processing
- Weather foundational models
- Earth system foundational models [17]



Load forecasting of users [18]



Grid foundation models (GFM) [19]

[17] Bodnar, C., Bruinsma, W. P., Lucic, A., Stanley, M., Vaughan, A., Brandstetter, J., ... & Perdikaris, P. (2024). A foundation model for the earth system. *arXiv preprint arXiv:2405.13063*.

[18] Böllat, Kutay, and Simon Tindemans. "GUIDE-VAE: Advancing Data Generation with User Information and Pattern Dictionaries." *arXiv preprint arXiv:2411.03936* (2024).

[19] Hamann, H. F., Gjorgiev, B., Brunschwiler, T., Martins, L. S., Puech, A., ... & Sobolevsky, S. (2024). Foundation models for the electric power grid. *Joule*, 8(12), 3245-3258.

Graph Neural Networks

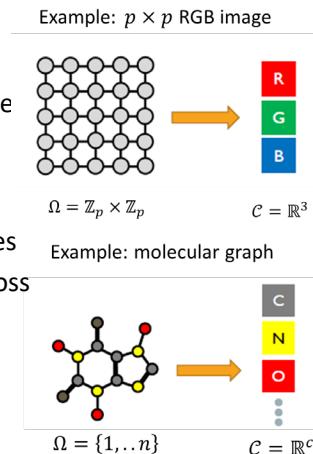
Objective: Improve generalization performance in learning tasks on network-structured systems (like power grids)

Idea: embedding graph topology directly into the model architecture as bias

Approach

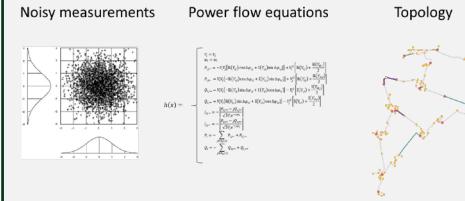
1. Construct graph $G = (V, \mathcal{E})$ with features on nodes and edges
2. Define f_{GNN} and learn with message passing on supervised loss
$$\sum_{i \in \Omega^T} \|y_i - \hat{y}_i\|$$
3. Use $f(x_j)$ for new $j \notin \Omega^T$ or on unseen graphs G'

Benefits: Data efficient, generalisation to changes in topologies



Applications

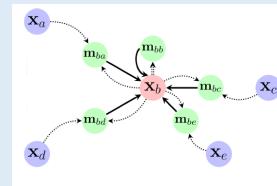
- Graph neural solvers [20] for ACOPF [21]
- Distribution system state estimation [22]



Challenges

- Model inaccuracy $s \neq m$
- Long-range dependencies are difficult to learn. *Power system topology is sparse*
- Challenging to learn for *global* problems (e.g. ACOPF)

Good to learn local relationships



[20] Donon, B., Donnot, B., Guyon, I., & Marot, A. (2019, July). Graph neural solver for power systems. In *2019 International joint conference on neural networks (ijcnn)* (pp. 1-8). IEEE.

[21] Pilotto, L., Liguori, S., Madjihoubem, S., Zgubic, M., Lovett, S., Tomlinson, H., ... & Witherspoon, S. (2024). Canos: A fast and scalable neural ac-opf solver robust to n-1 perturbations. *arXiv preprint arXiv:2403.17660*.

[22] B. Habib, E. Isufi, W. van Breda, A. Jongepier and J. L. Cremer, "Deep Statistical Solver for Distribution System State Estimation," in *IEEE Transactions on Power Systems*, vol. 39, no. 2, pp. 4039-4050, March 2024, doi: 10.1109/TPWRS.2023.3290358.

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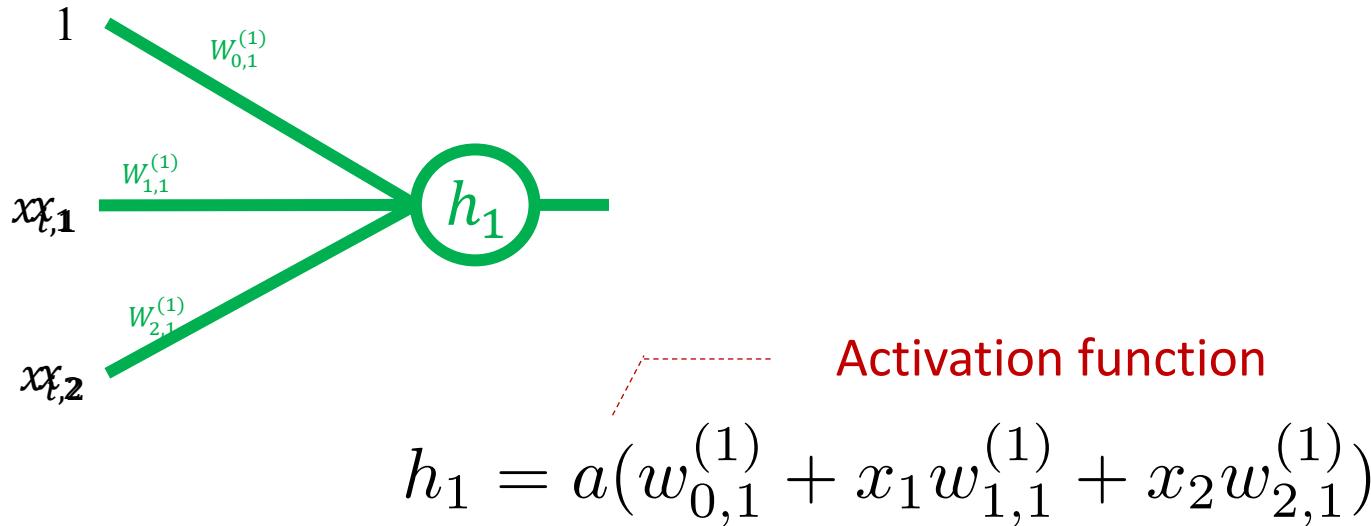
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Neural networks

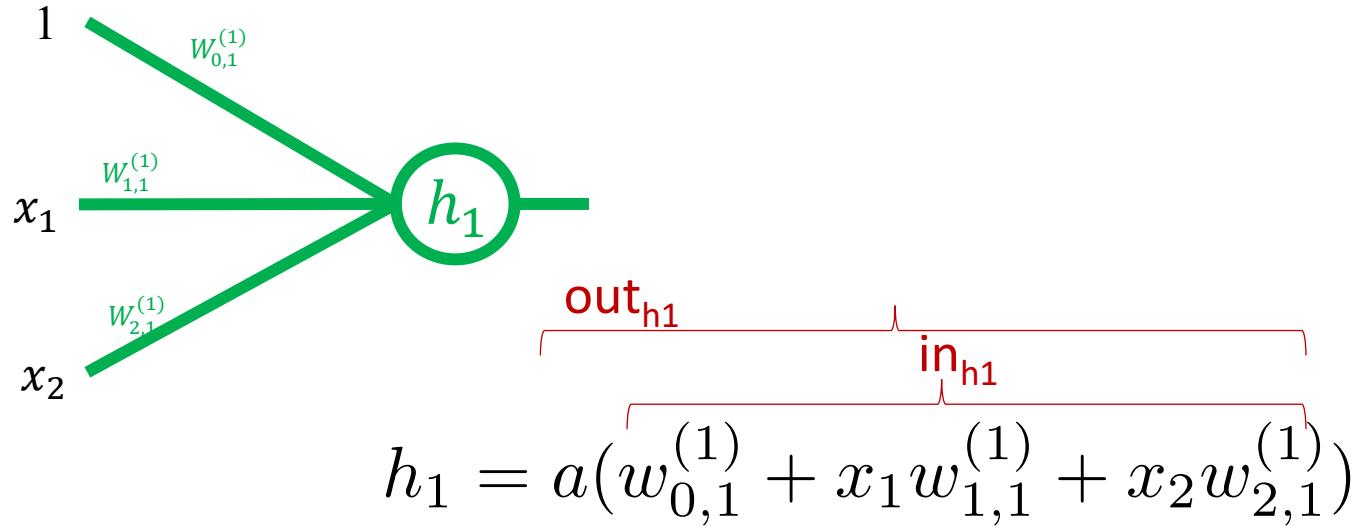
One neuron

Here simplified notation
 $x_{i,1}$ to x_1

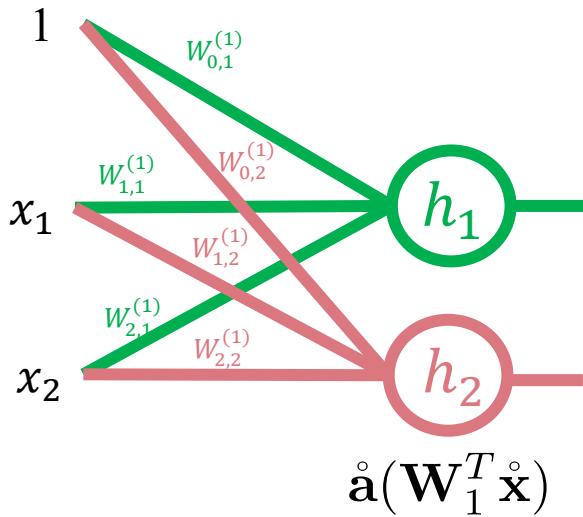


Neural networks

One neuron

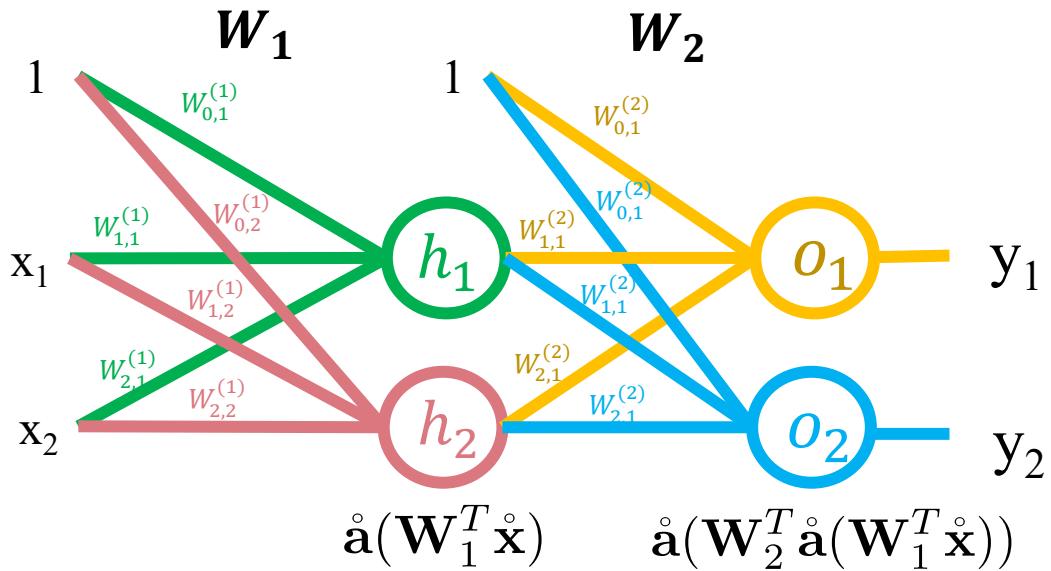


Compact model



$$\mathbf{W}_1 = \begin{bmatrix} W_{0,1}^{(1)} & W_{0,2}^{(1)} \\ W_{1,1}^{(1)} & W_{1,2}^{(1)} \\ W_{2,1}^{(1)} & W_{2,2}^{(1)} \end{bmatrix} \quad (N+1) \times u_1$$

Multiple layers

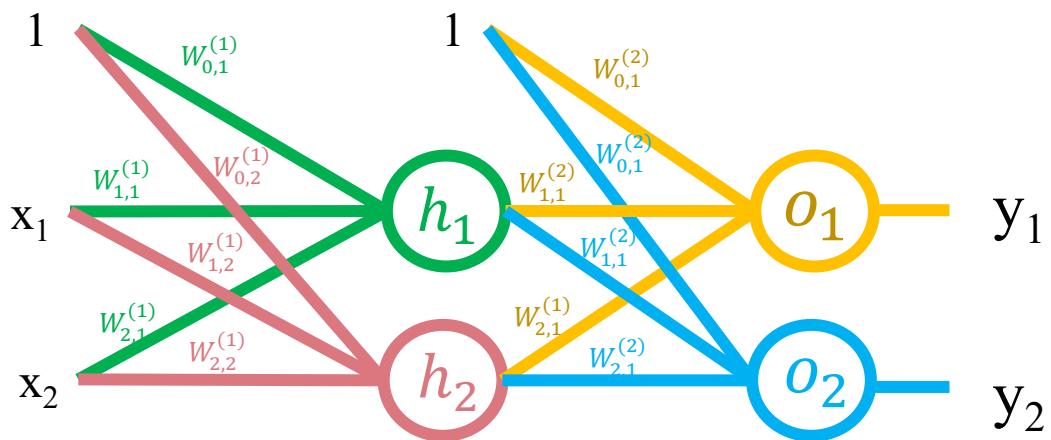


$$\mathbf{W}_1 = \begin{bmatrix} W_{0,1}^{(1)} & W_{0,2}^{(1)} \\ W_{1,1}^{(1)} & W_{1,2}^{(1)} \\ W_{2,1}^{(1)} & W_{2,2}^{(1)} \end{bmatrix}_{(N+1) \times u1}$$

$$\mathbf{W}_2 = \begin{bmatrix} W_{0,1}^{(2)} & W_{0,2}^{(2)} \\ W_{1,1}^{(2)} & W_{1,2}^{(2)} \\ W_{2,1}^{(2)} & W_{2,2}^{(2)} \end{bmatrix}_{(u1+1) \times u2}$$

$$f(x) = \hat{a}(\mathbf{W}_2^T \hat{a}(\mathbf{W}_1^T \hat{\mathbf{x}}))$$

Loss function



Gradient Descent Algorithm

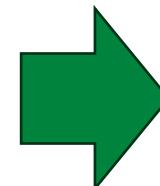
$$\mathbf{w}^k = \mathbf{w}^{k-1} - \alpha \nabla g(\mathbf{w}^{k-1})$$



System operation

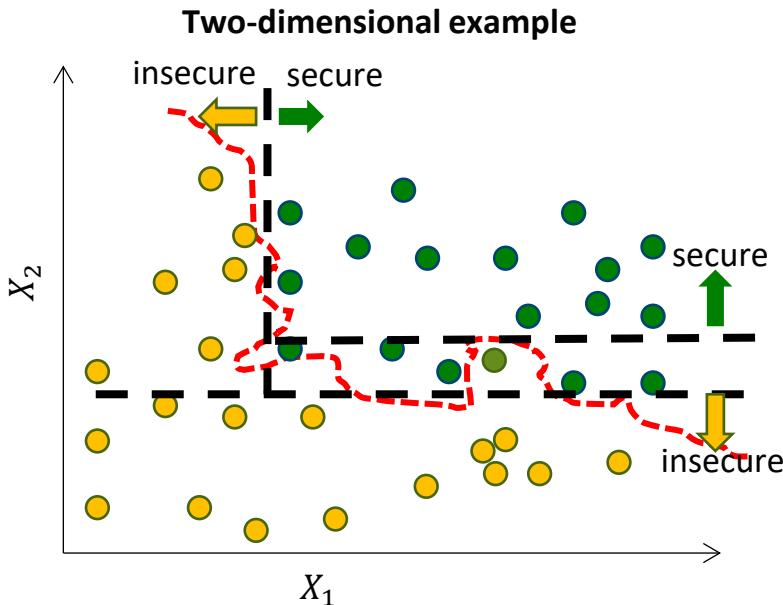


Experts are in charge to manually operate the power system based on experience and with the support of tools



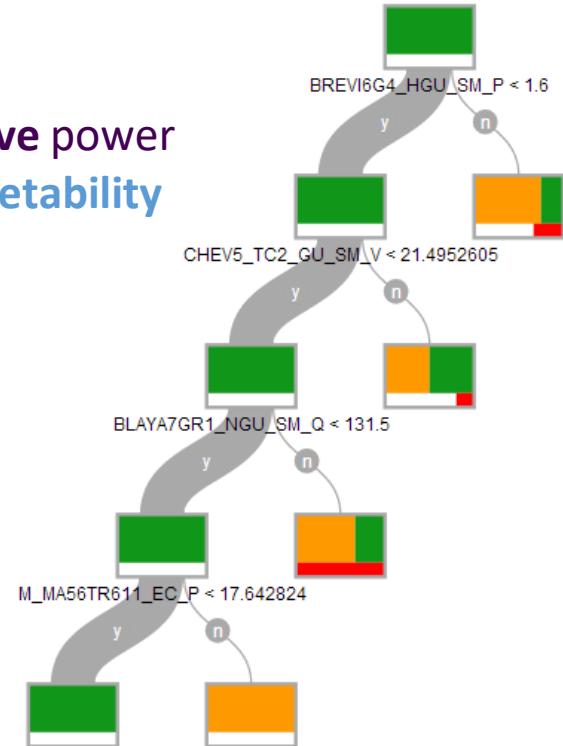
Interpretable models

Decision Trees as a model?

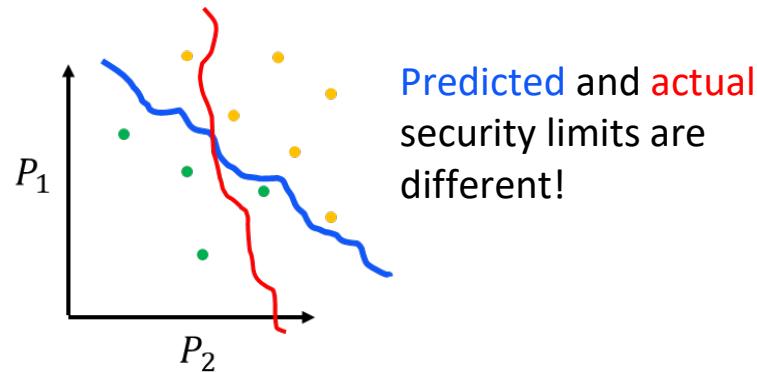


Decision trees:

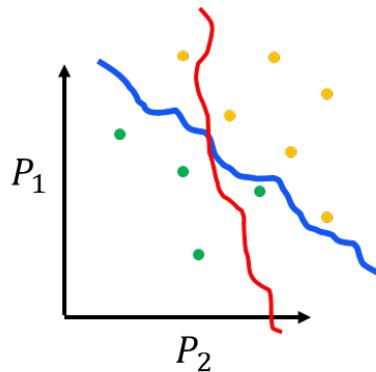
- Limited **expressive power**
- **Fantastic interpretability**



Metrics for classification



Metrics for classification



Predicted and **actual**
security limits are
different!

Predicted Class

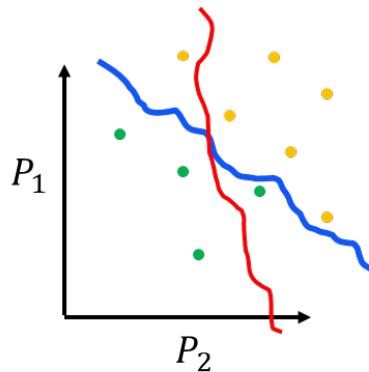
		Positive	Negative
True Class	Positive	TP	FN
	Negative	FP	TN

Confusion Matrix

True Class

Predicted Class

Metrics for classification



Predicted Class

	Predicted Class	
True Class	Positive	Negative
	TP	FN
Positive	FP	TN
Negative		

Confusion Matrix

True Class

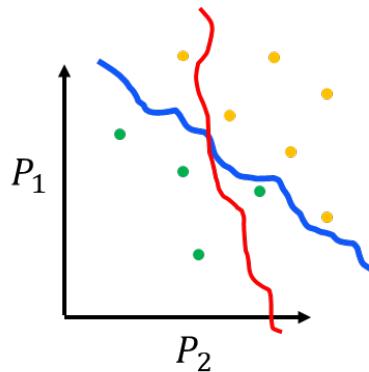
Predicted Class

Two types of accurate predictions:

TN: Is secure and we think it is secure (**GOOD**)

TP: Is insecure and we think it is insecure (**VERY GOOD!**)

Metrics for classification



Predicted and actual
security limits are
different!

True Class

Predicted Class

		Predicted Class	
		Positive	Negative
True Class	Positive	TP	FN
	Negative	FP	TN

Confusion Matrix

Two types of accurate predictions:

TN: Is secure and we think it is secure (**GOOD**)

TP: Is insecure and we think it is insecure (**VERY GOOD!**)

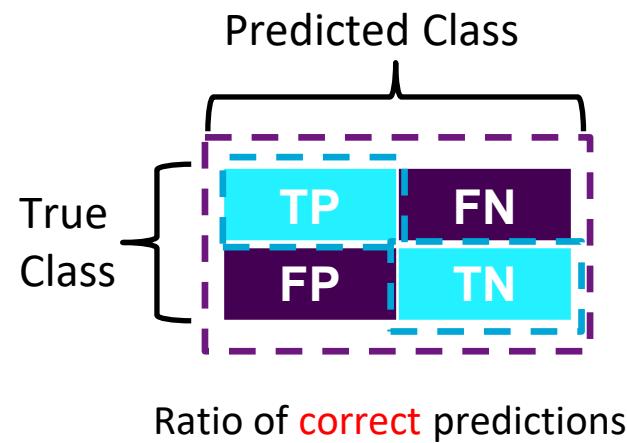
Two types of wrong predictions:

FP: Is secure but we think it is insecure (**BAD**)

FN: Is insecure but we think it is secure (**VERY BAD!**)

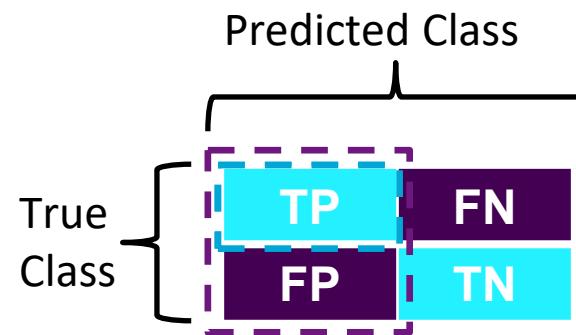
This can have a severe effect!

Metrics for classification



$$\text{Accuracy} = \frac{N_{TP} + N_{TN}}{N_{FP} + N_{TP} + N_{FN} + N_{TN}}$$

Metrics for classification

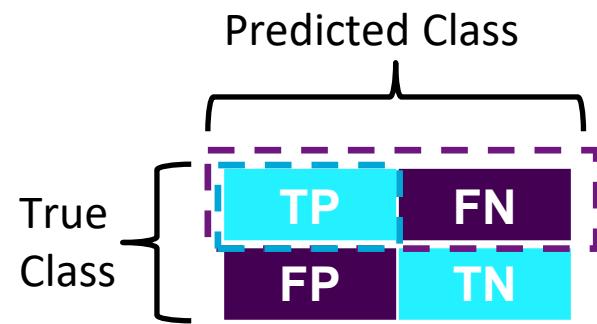


Ratio of correctly found **insecure** cases to
predicted insecure predictions

$$\text{Accuracy} = \frac{N_{TP} + N_{TN}}{N_{FP} + N_{TP} + N_{FN} + N_{TN}}$$

$$\text{Precision} = \frac{N_{TP}}{N_{TP} + N_{FP}}$$

Metrics for classification



Ratio of correctly found **insecure** cases to **all insecure** cases

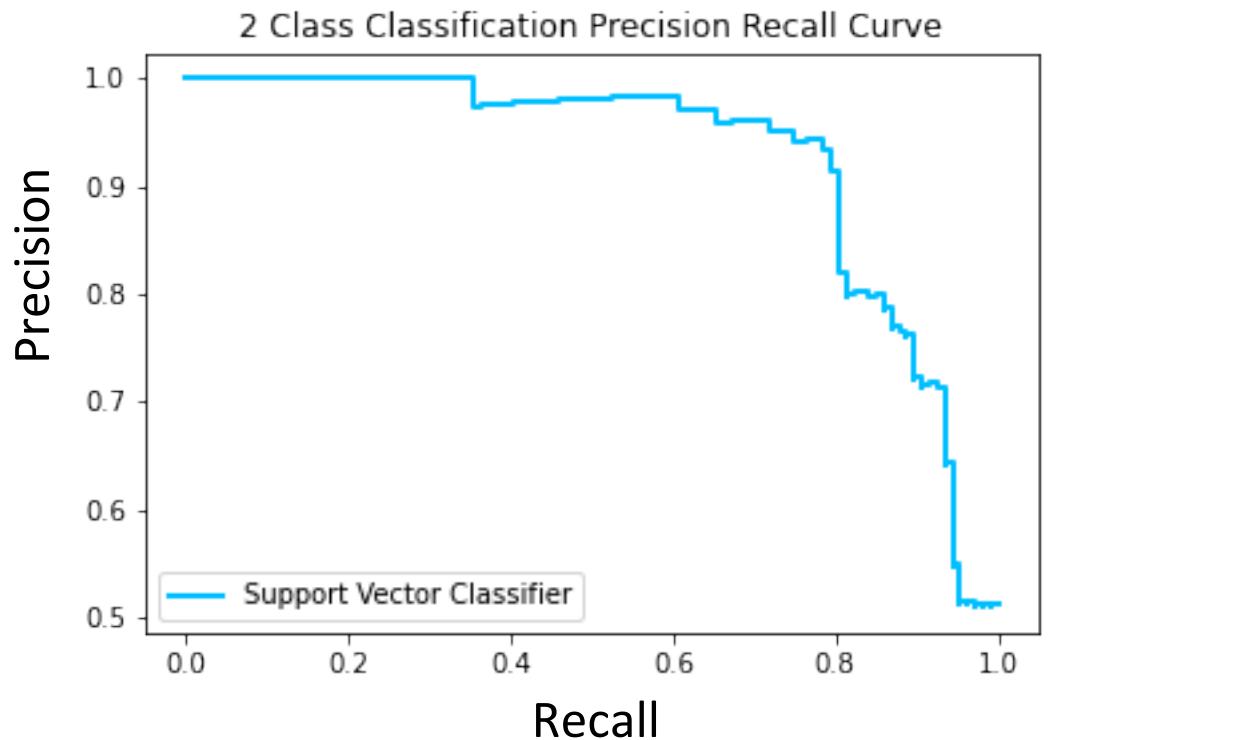
$$\text{Accuracy} = \frac{N_{TP} + N_{TN}}{N_{FP} + N_{TP} + N_{FN} + N_{TN}}$$

$$\text{Precision} = \frac{N_{TP}}{N_{TP} + N_{FP}}$$

$$\text{Recall} = \frac{N_{TP}}{N_{TP} + N_{FN}}$$

Precision vs Recall

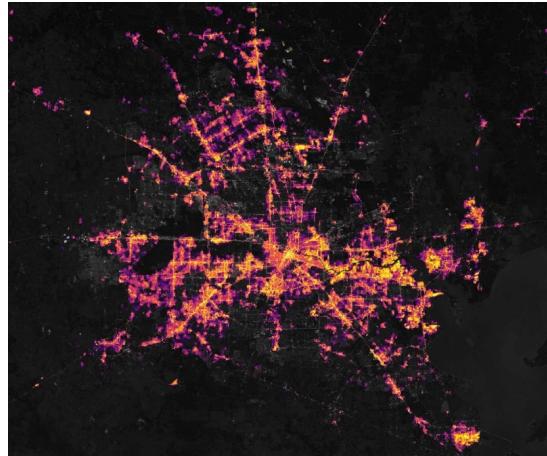
When do we observe the highest performance?



Blackout predictions: Precision or Recall?



Houston, Texas 07 Feb 2021



Houston, Texas 16 Feb 2021

$$\text{Precision} = \frac{N_{TP}}{N_{TP} + N_{FP}}$$

$$\text{Recall} = \frac{N_{TP}}{N_{TP} + N_{FN}}$$

Cost skewness: $C_{FN} \gg C_{FP}$

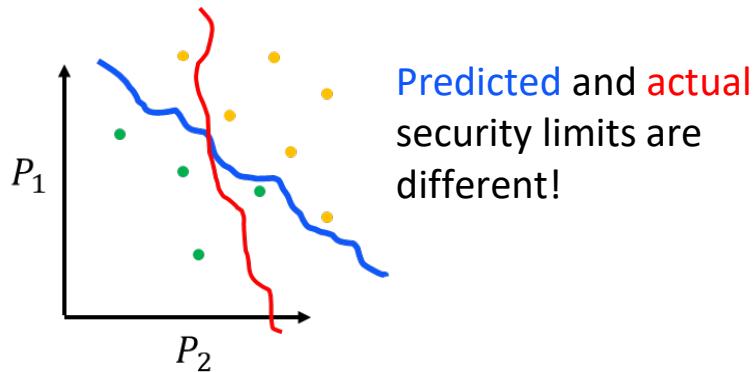
Problem

- The two different false predictions have different costs.



- Damages from the blackouts were estimated at \$195 billion
- Seconds away from a total power blackout in Texas

Metrics for classification



		Predicted Class	
		Positive	Negative
True Class	Positive	0	C_{FN}
	Negative	C_{FP}	0

Two types of accurate predictions:

TN: Is secure and we think it is secure (**GOOD**)

TP: Is insecure and we think it is insecure (**VERY GOOD!**)

Two types of wrong predictions:

FP: Is secure but we think it is insecure (**BAD**)

FN: Is insecure but we think it is secure (**VERY BAD!**)

Two issues

- Cost-skewness: $C_{FN} \gg C_{FP}$
- Class imbalance: $\pi_+ \ll \pi_-$

What a classifier can do

Classify points

- is x positive?

Rank points

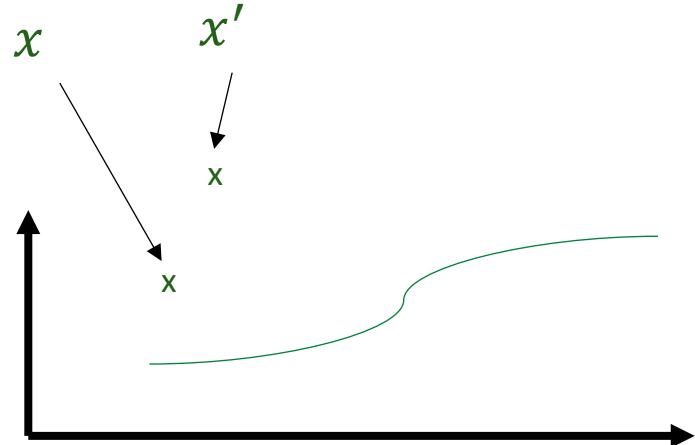
- Is x ‘more positive’ than x' ?

Output a score $s(x)$

- ‘How positive’ is x ?

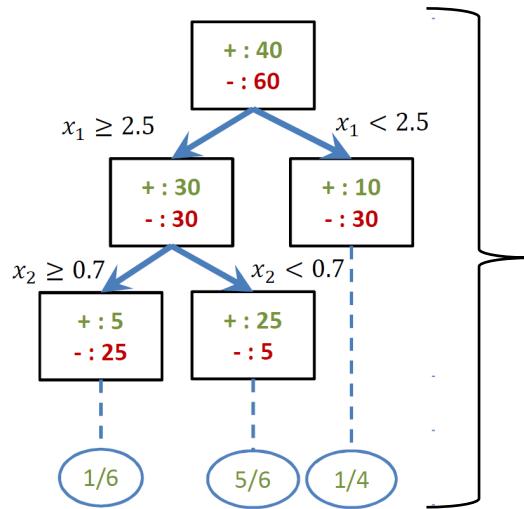
Output a probability estimate $\hat{p}(x)$

- What is the (estimated) probability that x is positive?



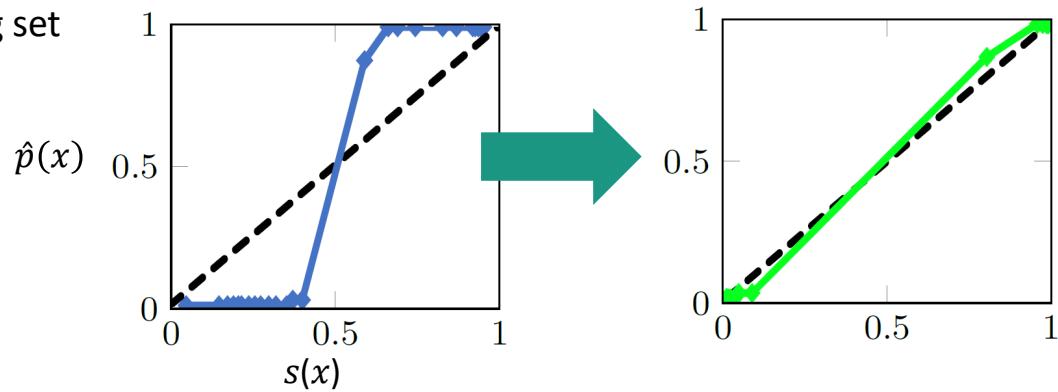
Probability estimation is not easy

- Scores $s(x) \in [0,1]$ as probability estimates $\hat{p}(x)$? **No!**

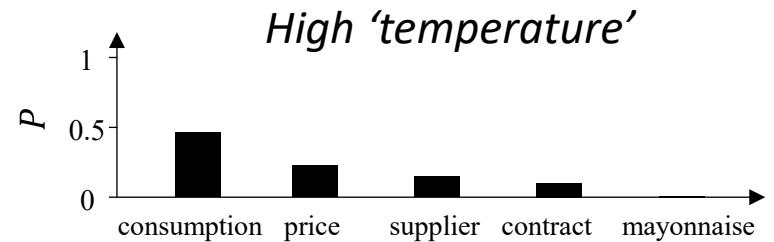
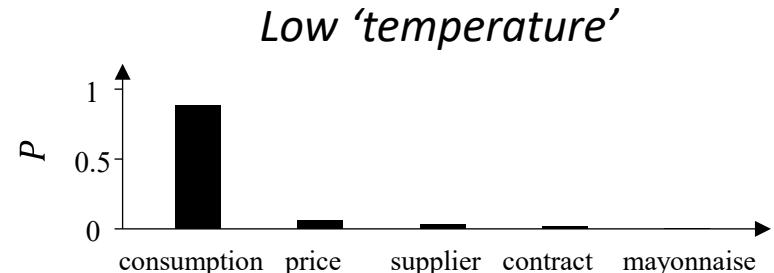
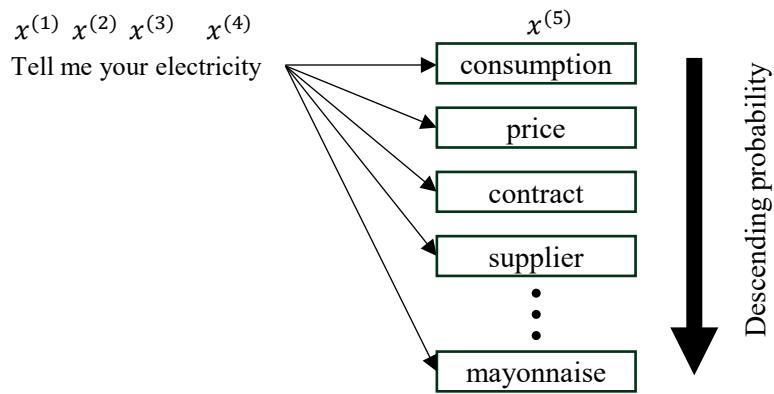


Based on
training set

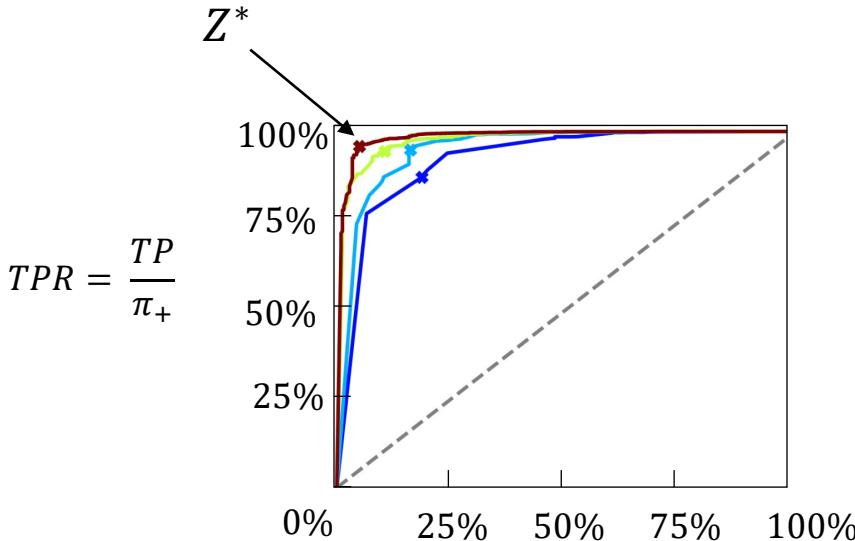
Platt scaling: Find $\hat{p}(x) = \frac{1}{1+e^{As(x)+B}}$



Calibration in Large Language Models



Cost-sensitive learning



$$FPR = \frac{FP}{\pi_+}$$

$$Z^* = \frac{\Pi_- C_{FP}}{\Pi_- C_{FP} + \Pi_+ C_{FN}}$$

Probability of contingency 'Impact' of contingency

- $\hat{p}(x) \geq Z^*$ predict secure
- $\hat{p}(x) < Z^*$ predict insecure

The risk of relying on machine learning

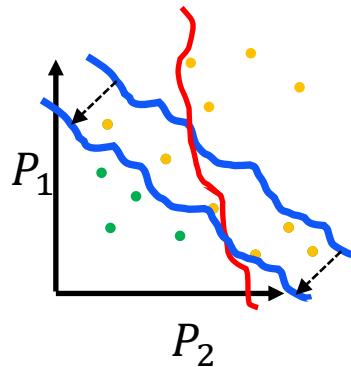
Step 1: Compute risks when predicting x_i as secure $\hat{y}_i = 1$ and insecure $\hat{y}_i = 0$

$$R_{\text{secure}} = p_i p_c \hat{p}(x_i) C_{FN}$$

$$R_{\text{insecure}} = p_i (1 - p_c) (1 - \hat{p}(x_i)) C_{FP}$$

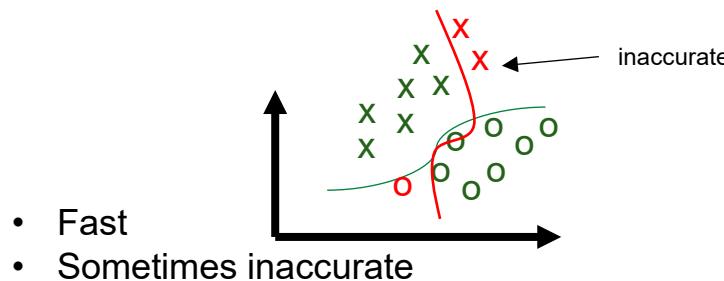
Step 2: Predict with lowest residual risk

$$R_{\text{secure}} \vee R_{\text{insecure}}$$

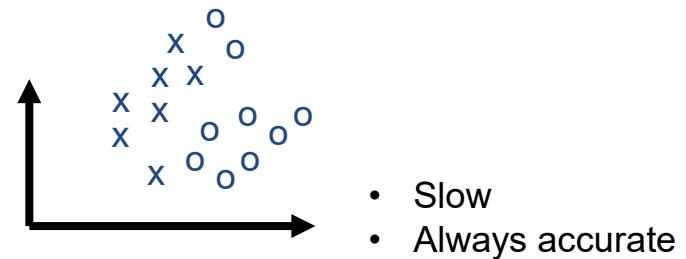


Minimize risks by hybrid approach

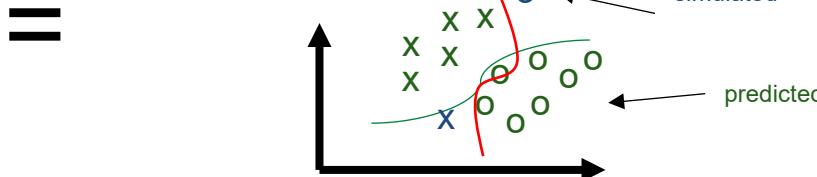
Machine Learning



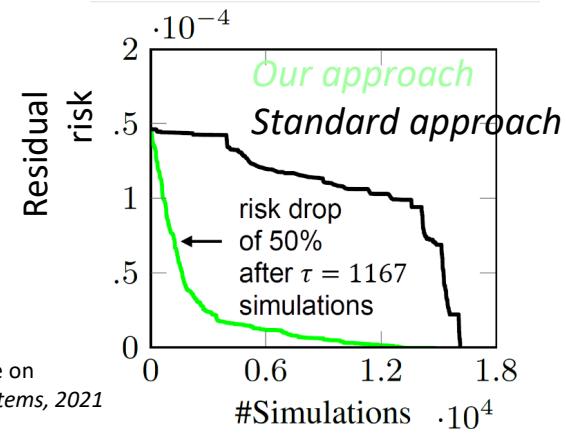
Simulator



Probabilistic approach



Case study: French system



[24] Jochen Cremer, Goran Strbac, "A Machine-learning based Probabilistic Perspective on Dynamic Security Assessment, *International Journal of Electrical Power and Energy Systems*, 2021

Outline

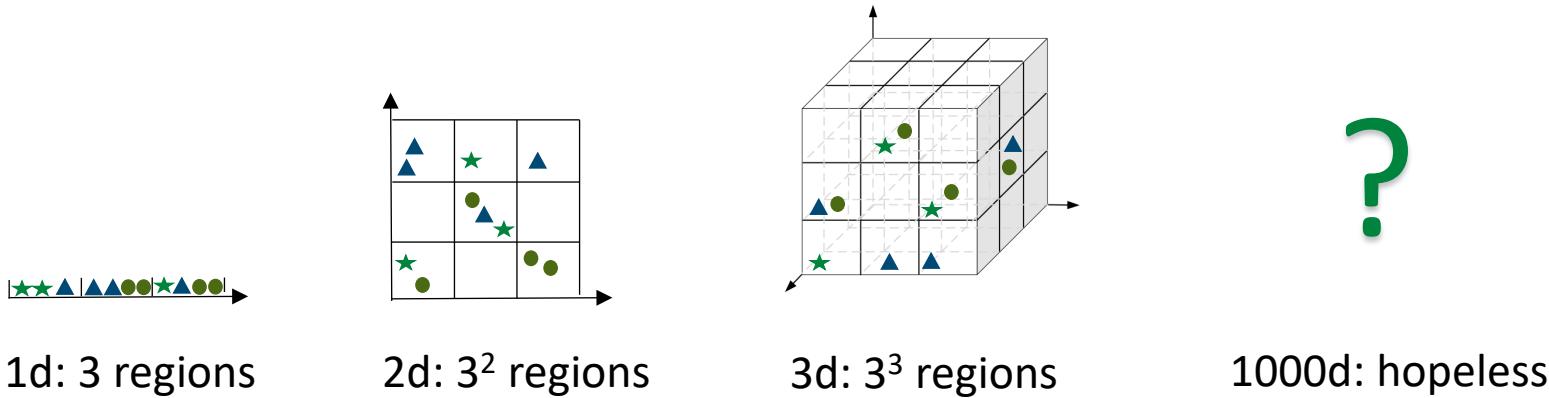
Reliability management and data in control rooms

1. Introduction to reliability management
2. Machine learning approaches
3. Security assessment with cost-sensitive supervised learning

Learning models for secure system operation

4. Learning with domain knowledge
5. State estimation with graph neural networks
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7. Challenges applying ML to reliability

How to address curse of dimensionality?



1d: 3 regions

2d: 3^2 regions

3d: 3^3 regions

1000d: hopeless

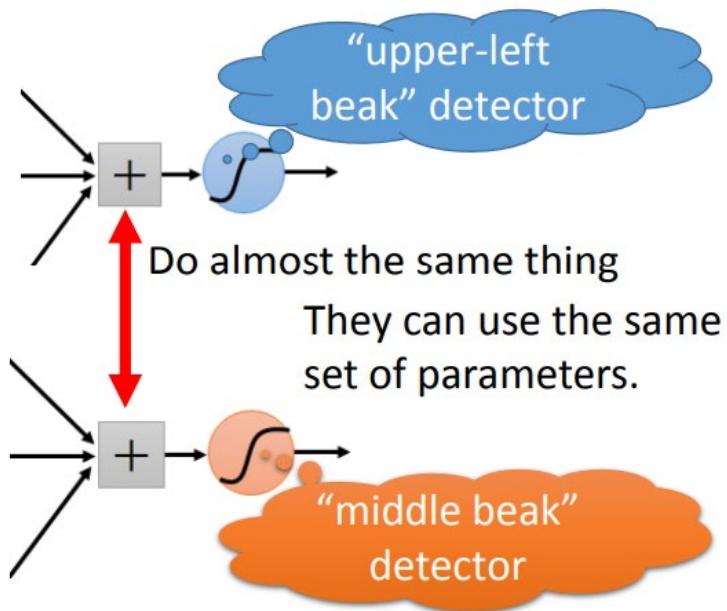
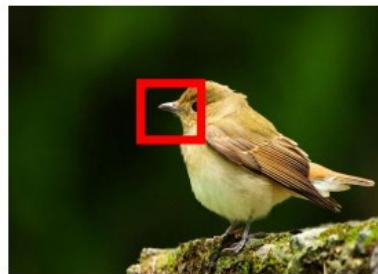
As dimensionality grows: fewer samples per region.

AI can well predict with images

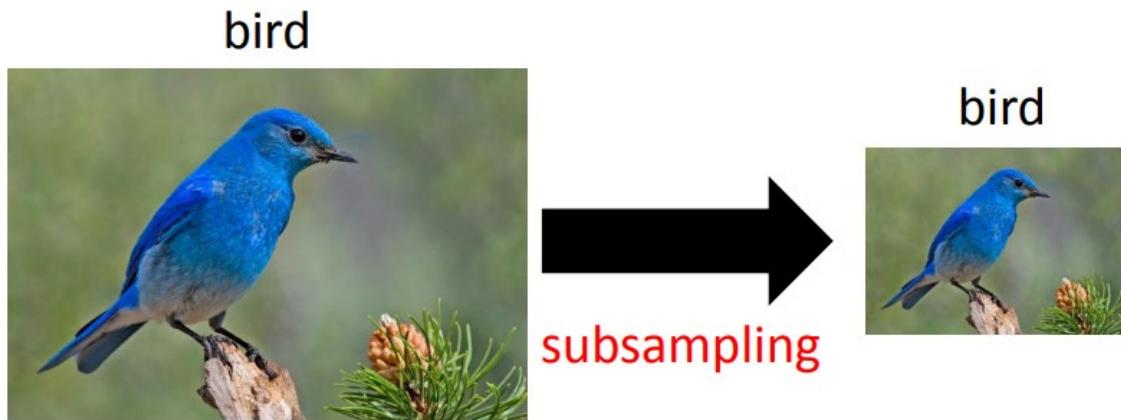
Property 1: Some patterns are much smaller than the whole image. A neuron does not have to see the whole image to discover the pattern.



Property 2: The same patterns appear in different regions. (translated invariance)



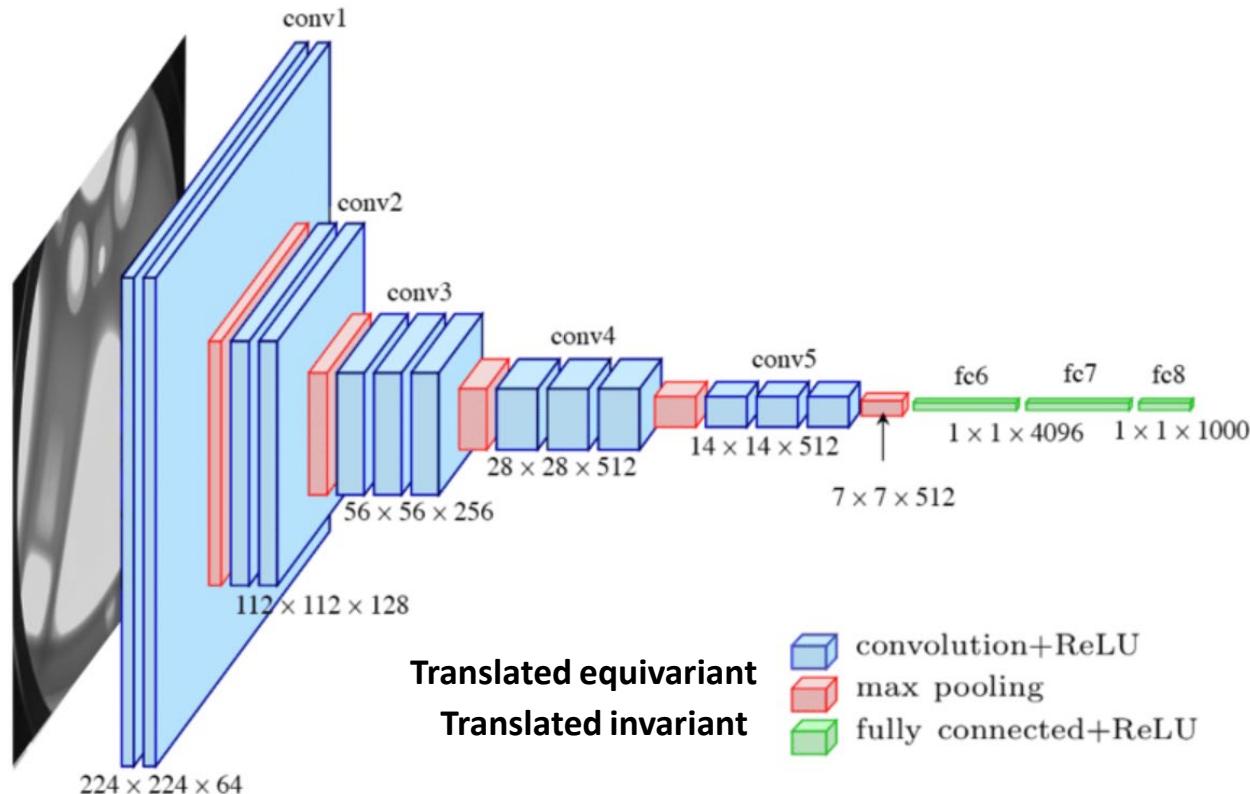
Property 3: Subsampling the pixels will not change the object. (Subsampling invariance)



We can subsample the pixels to make image smaller

Less parameters for the network to process the image

How can CNN make this happen?



How can CNN make this happen?

Property 1

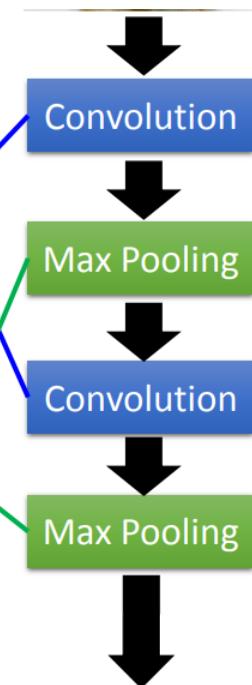
- Some patterns are much smaller than the whole image

Property 2

- The same patterns appear in different regions.

Property 3

- Subsampling the pixels will not change the object



Can repeat
many times

CNN— Convolution layer

Stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
0	0	0	0	1	0
1	1	1	0	1	0
0	0	0	0	1	0

6×6 image

Those are the network parameters to be learned.

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1
Matrix

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2
Matrix

3	-1	-3	-1
-2	2	-1	-3
-2	-4	0	1
-1	0	-2	-1

CNN— Convolution layer

Stride=1

0	1	0	0	0	1
0	1	0	0	1	0
0	0	0	1	0	0
0	0	0	1	0	0
1	1	1	0	1	0
0	0	0	0	0	1

6×6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1
Matrix



0	1	-2	-1
-1	1	-1	-3
-1	-4	0	-1
-1	-1	-3	3

Property 2

The same patterns appear in different regions can be detected.

CNN— Max Pooling

6×6 image



3	-1	-3	-1
-2	2	-1	-3
-2	-4	0	1
-1	0	-2	-1



3	-1
0	1

New images but smaller

0	1	-2	-1
-1	1	-1	-3
-1	-4	0	-1
-1	-1	-3	3

1	-1
-1	3

Property 3

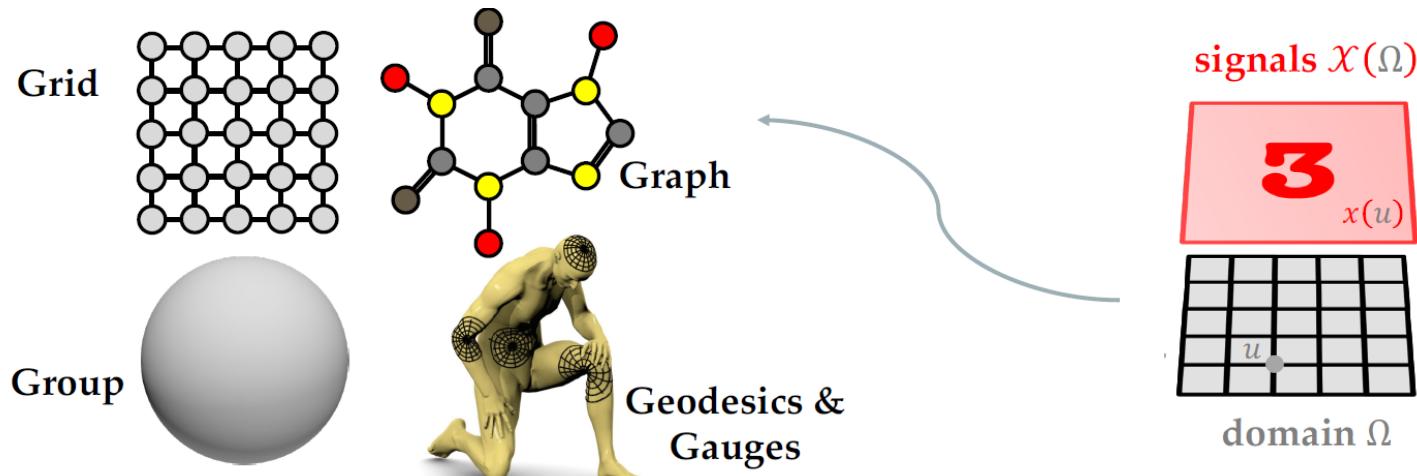
Subsampling the pixels will not change the object

**Not much image-like data in power system
operation and planning...**

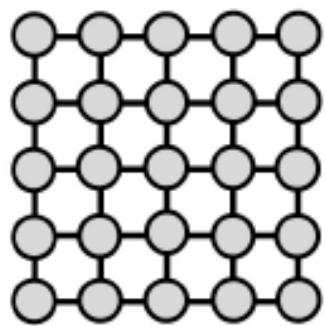
Geometric deep learning (GDL)

In GDL, data are **signals** x on **geometric domains** Ω

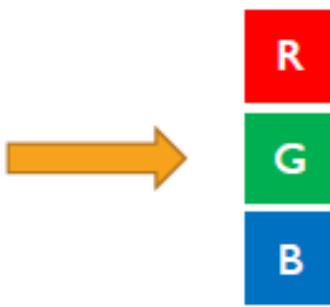
- The domain Ω is a set, possibly with additional structure
- A signal x on Ω is a function $\chi(\Omega, C) = \{x: \Omega \rightarrow C\}$
- C is a vector space whose dimensions are called channels



Graph Neural Networks (GNNs)

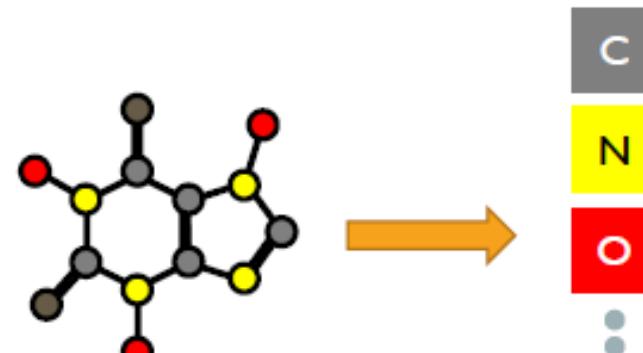


$$\Omega = \mathbb{Z}_n \times \mathbb{Z}_n$$



$$\mathcal{C} = \mathbb{R}^3$$

Example: $n \times n$ RGB image

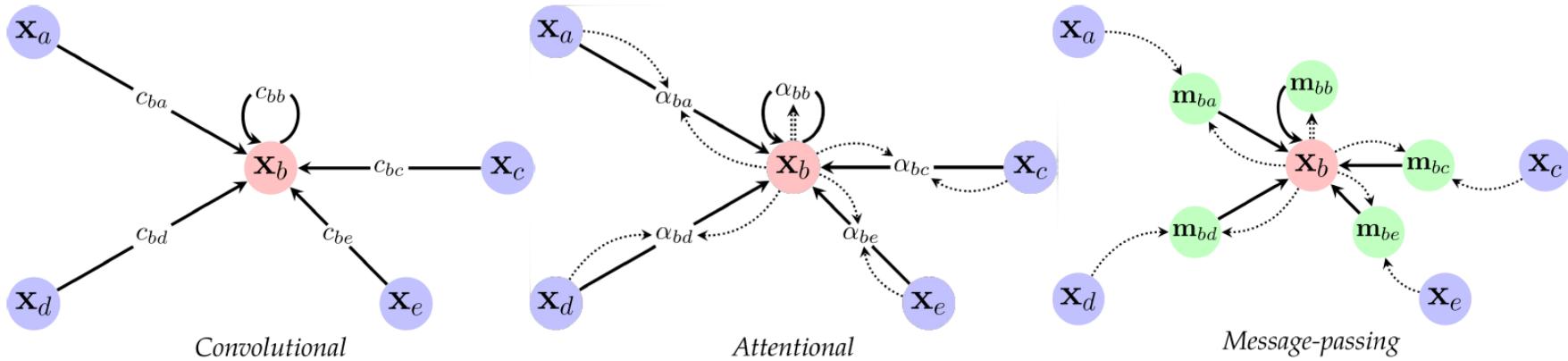


$$\Omega = \{1, \dots, n\}$$

$$\mathcal{C} = \mathbb{R}^m$$

Example: molecular graph

The three ‘flavours’ of GNN layers



$$\mathbf{h}_i = \phi \left(\mathbf{x}_i, \bigoplus_{j \in \mathcal{N}_i} c_{ij} \psi(\mathbf{x}_j) \right)$$

$$\mathbf{h}_i = \phi \left(\mathbf{x}_i, \bigoplus_{j \in \mathcal{N}_i} a(\mathbf{x}_i, \mathbf{x}_j) \psi(\mathbf{x}_j) \right)$$

$$\mathbf{h}_i = \phi \left(\mathbf{x}_i, \bigoplus_{j \in \mathcal{N}_i} \psi(\mathbf{x}_i, \mathbf{x}_j) \right)$$

Increasing order of generality: *convolutional* \subseteq *attentional* \subseteq *message – passing* 66

Outline

Reliability management and data in control rooms

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Learning models for secure system operation

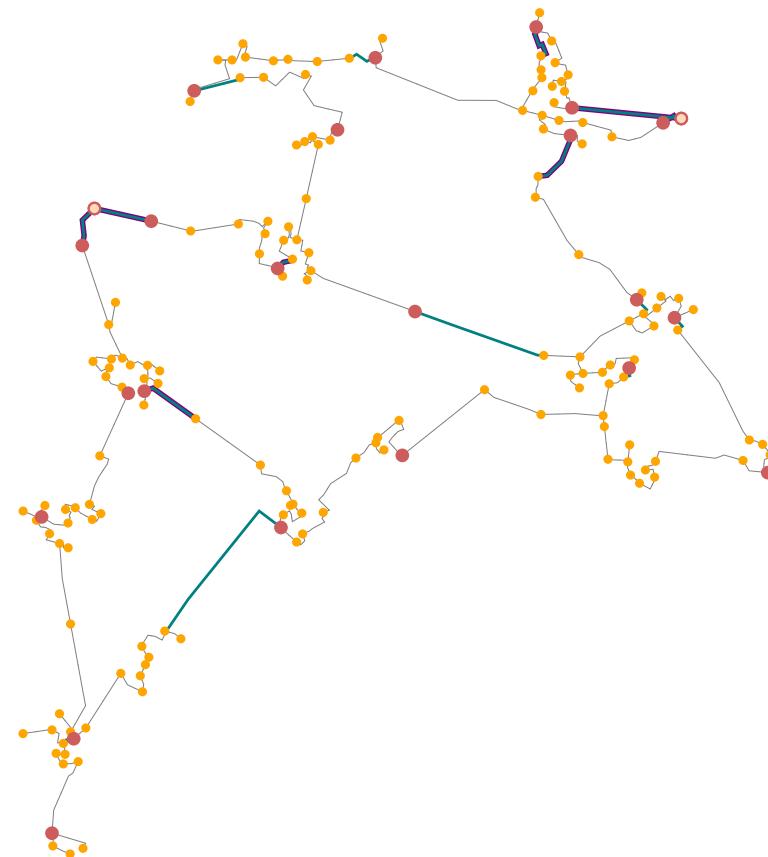
4. Learning with domain knowledge
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Distribution system state estimation

- Measurements $z \in \mathbb{R}^m$ with noise $\varepsilon \in \mathbb{R}^m$
- System state $x \in \mathbb{R}^{2n}$
- State estimation $f(z) \rightarrow x$
- Challenge: partial observable, scarce measurements $m \ll n$

Distribution system (MV)

- Trafo
- Lines
- MV/LV buses
- HV buses
- Power flow measurement
- Voltage measurements

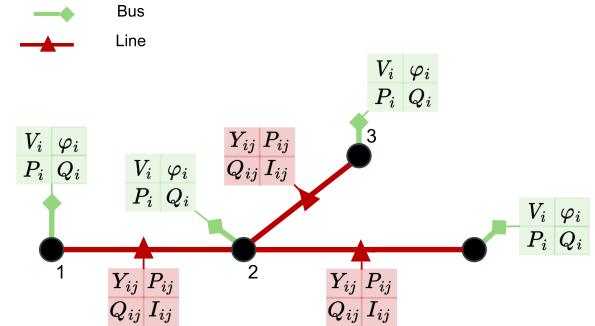


Model of the power flow

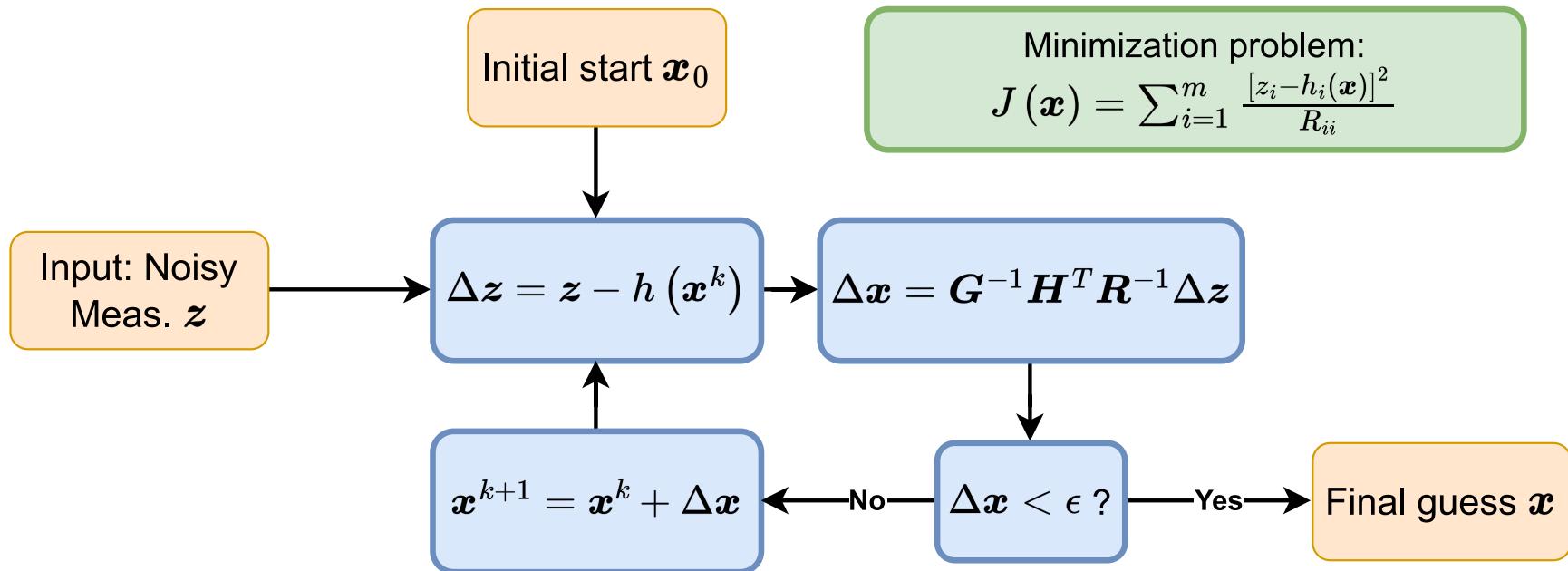
$$x = [V, \varphi]$$

$$z = h(x) + \varepsilon$$

$$h(x) = \left\{ \begin{array}{l} V_i = V_i \\ \varphi_i = \varphi_i \\ P_{ij \rightarrow} = -V_i V_j \left[\Re(Y_{ij}) \cos \Delta\varphi_{ij} + \Im(Y_{ij}) \sin \Delta\varphi_{ij} \right] + V_i^2 \left[\Re(Y_{ij}) + \frac{\Re(Y_{sij})}{2} \right] \\ P_{ij \leftarrow} = V_i V_j \left[-\Re(Y_{ij}) \cos \Delta\varphi_{ij} + \Im(Y_{ij}) \sin \Delta\varphi_{ij} \right] + V_j^2 \left[\Re(Y_{ij}) + \frac{\Re(Y_{sij})}{2} \right] \\ Q_{ij \rightarrow} = V_i V_j \left[-\Re(Y_{ij}) \sin \Delta\varphi_{ij} + \Im(Y_{ij}) \cos \Delta\varphi_{ij} \right] - V_i^2 \left[\Im(Y_{ij}) + \frac{\Im(Y_{sij})}{2} \right] \\ Q_{ij \leftarrow} = V_i V_j \left[\Re(Y_{ij}) \sin \Delta\varphi_{ij} + \Im(Y_{ij}) \cos \Delta\varphi_{ij} \right] - V_j^2 \left[\Im(Y_{ij}) + \frac{\Im(Y_{sij})}{2} \right] \\ I_{ij \rightarrow} = - \left| \frac{P_{ij \rightarrow} - j Q_{ij \rightarrow}}{\sqrt{3} V_i e^{-j \varphi_i}} \right| \\ I_{ij \leftarrow} = - \left| \frac{P_{ij \leftarrow} - j Q_{ij \leftarrow}}{\sqrt{3} V_j e^{-j \varphi_j}} \right| \\ P_i = - \sum_{j \in N_X(i)} P_{ij \leftarrow} + P_{ij \rightarrow} \\ Q_i = - \sum_{j \in N_X(i)} Q_{ij \leftarrow} + Q_{ij \rightarrow} \end{array} \right.$$



Weighted least squares method

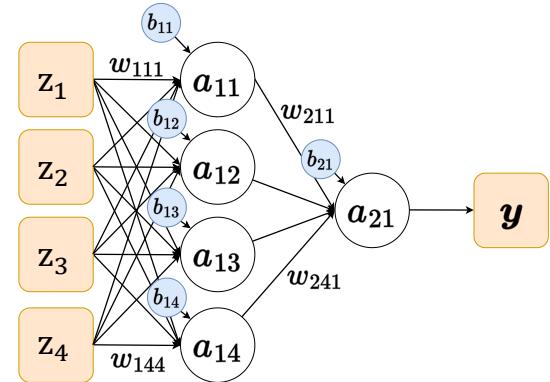


How accurate is x ?
Convergence?

Statistical learning

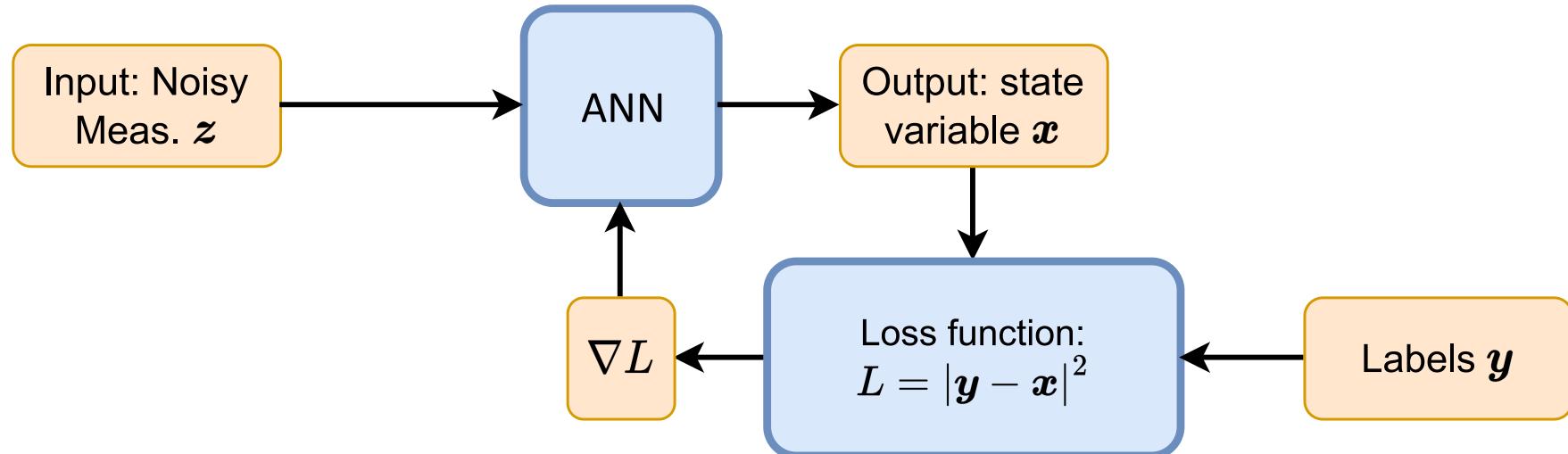
- Training set $\Omega^T = \{(z_1, y_1), (z_2, y_2) \dots (z_t, y_t)\}$ with t samples
- Inference problem is to find a function $f: Z \rightarrow Y$ such that $f(z) \sim y$
- Common loss function $L(f(z), y)$ for regression is the square loss

Artificial Neural Network (ANN)



$$f_\theta: Z \rightarrow Y$$

Supervised learning for state estimation



Labels are not known

Newton's method generates label with "errors" $\hat{\mathbf{y}} = \mathbf{y} + \gamma^N$

Weakly-supervised learning

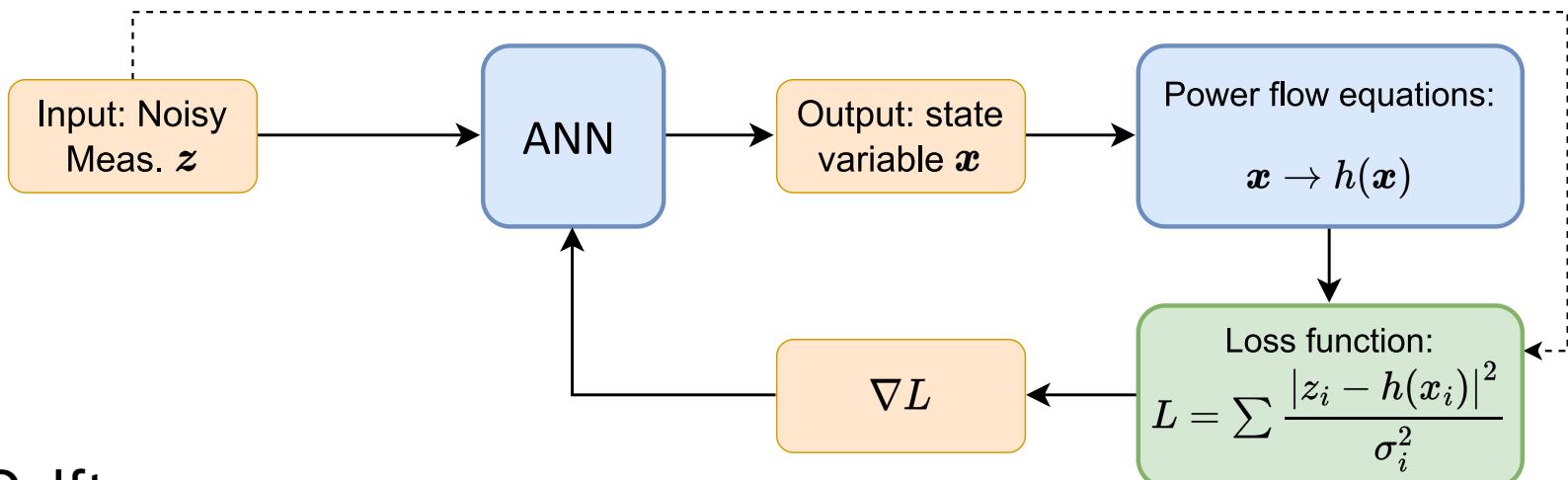
- Inaccurate input and **output**
- Learn with inaccurate labels $\Omega^T = \{(z_1, \hat{y}_1), (z_2, \hat{y}_2) \dots (z_t, \hat{y}_t)\}$
- Design a loss function $L(f(z), \hat{y})$
- Objective: learning $f: Z \rightarrow Y$ such that $f(z) \sim y$



Benjamin Habib

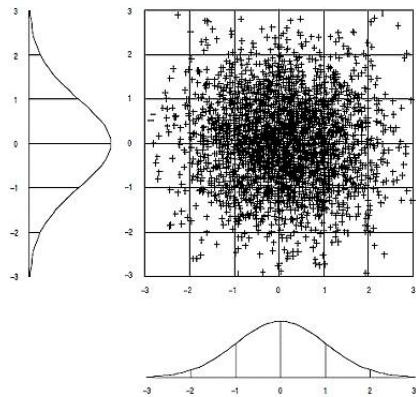
Weakly-supervised learning for state estimation

- ANN $f(z) \rightarrow x$
- Measurement function using power flow equations $h(x) \rightarrow \hat{z}$



Respect the structure of the domain

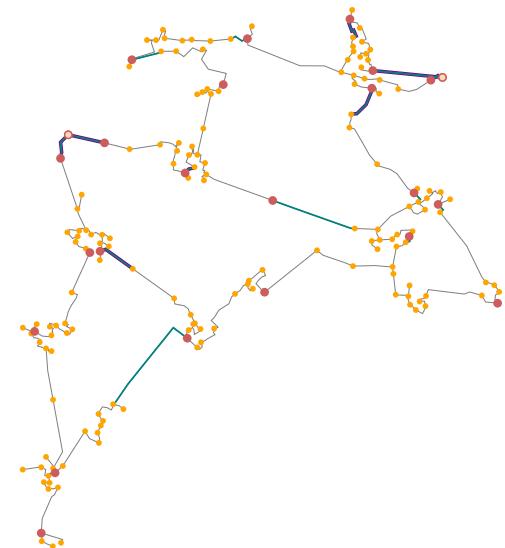
Noisy measurements



Power flow equations

$$h(x) = \begin{cases} V_i = V_i \\ \varphi_i = \varphi_i \\ P_{ij \rightarrow} = -V_i V_j [\Re(Y_{ij}) \cos \Delta\varphi_{ij} + \Im(Y_{ij}) \sin \Delta\varphi_{ij}] + V_i^2 \left[\Re(Y_{ij}) + \frac{\Re(Y_{sij})}{2} \right] \\ P_{ij \leftarrow} = V_i V_j [-\Re(Y_{ij}) \cos \Delta\varphi_{ij} + \Im(Y_{ij}) \sin \Delta\varphi_{ij}] + V_j^2 \left[\Re(Y_{ij}) + \frac{\Re(Y_{sij})}{2} \right] \\ Q_{ij \rightarrow} = V_i V_j [\Re(Y_{ij}) \sin \Delta\varphi_{ij} + \Im(Y_{ij}) \cos \Delta\varphi_{ij}] - V_i^2 \left[\Im(Y_{ij}) + \frac{\Im(Y_{sij})}{2} \right] \\ Q_{ij \leftarrow} = V_i V_j [\Re(Y_{ij}) \sin \Delta\varphi_{ij} + \Im(Y_{ij}) \cos \Delta\varphi_{ij}] - V_j^2 \left[\Im(Y_{ij}) + \frac{\Im(Y_{sij})}{2} \right] \\ I_{ij \rightarrow} = -\frac{|P_{ij \rightarrow} - jQ_{ij \rightarrow}|}{\sqrt{3}V_i e^{-j\varphi_i}} \\ I_{ij \leftarrow} = -\frac{|P_{ij \leftarrow} - jQ_{ij \leftarrow}|}{\sqrt{3}V_j e^{-j\varphi_j}} \\ P_i = -\sum_{j \in N_x(i)} P_{ij \leftarrow} + P_{ij \rightarrow} \\ Q_i = -\sum_{j \in N_x(i)} Q_{ij \leftarrow} + Q_{ij \rightarrow} \end{cases}$$

Topology



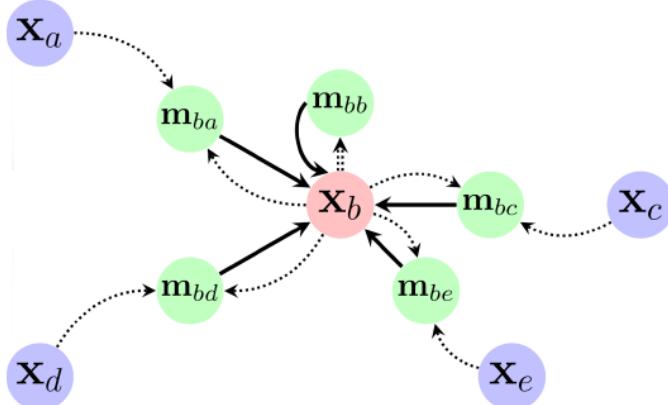
Locality on graphs: Neighbourhoods

- Consider graph $G = (V, E)$ where $E \subseteq V \times V$
- Adjacency matrix A with

$$a_{ij} = \begin{cases} 1, & (i, j) \in E \\ 0, & (i, j) \notin E \end{cases}$$

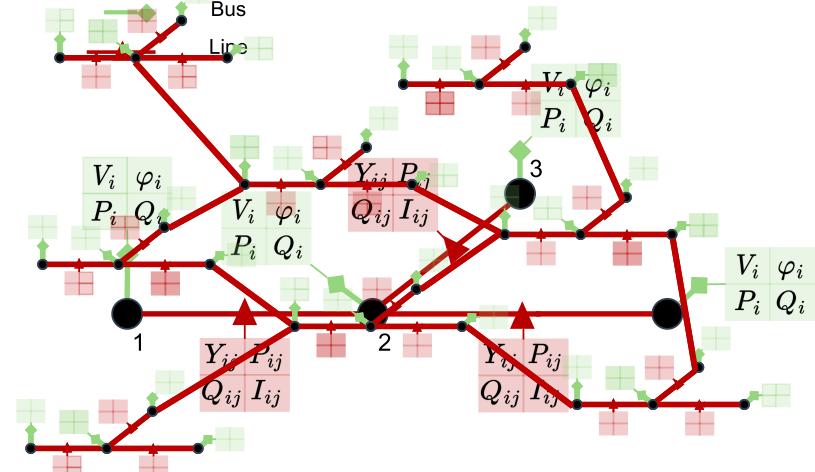
- (1-hop) neighbourhood $N_i = \{j: (i, j) \in E \cup (j, i) \in E\}$ for a node i
- Neighbourhood features $X_{N_i} = \{\{x_j: j \in N_i\}\}$
- Local function, $\phi(x_i, X_{N_i})$, operating over them.

Convolutional layers & message passing

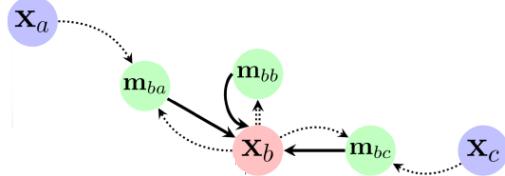


$$\eta_i = \phi \left(x_i, \bigoplus_{j \in N_i} \psi(x_i, x_j) \right)$$

State estimation

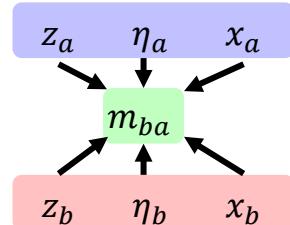


Deep statistical solver



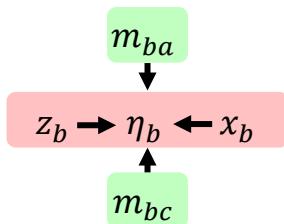
0. Initialize $x = x^0, \eta = \eta^0$

1. update edges



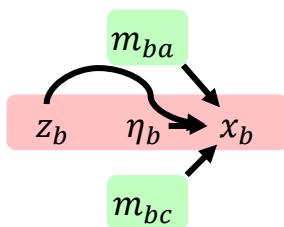
$$m_{ba} \leftarrow m_{ba} + \Delta t \times [\phi_\theta^{ba}(t, z_a, \eta_a, x_a) + \phi_\theta^{ba}(t, z_b, \eta_b, x_b)]$$

2. update vertices



$$\eta_b \leftarrow \eta_b + \Delta t \times \phi_\theta^b(t, z_b, \eta_b, x_b, m_{ba}, m_{bc}, m_{bb})$$

3. update label



$$x_b \leftarrow x_b + \Delta t \times \phi_\theta^{bx}(t, z_b, \eta_b, x_b, m_{ba}, m_{bc}, m_{bb})$$

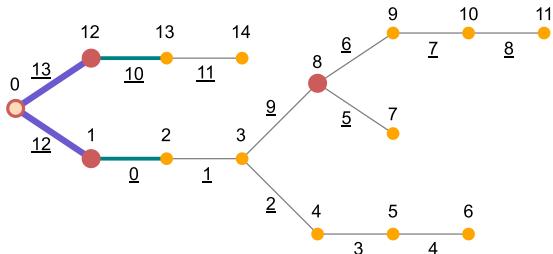
Perform $t = 1, \dots, T$



Benjamin Habib

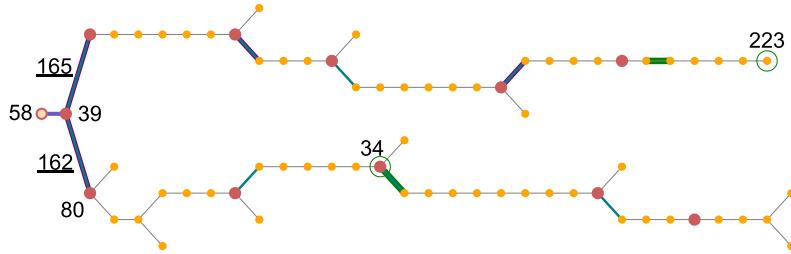
Case study: power systems

14-bus CIGRE MV grid from

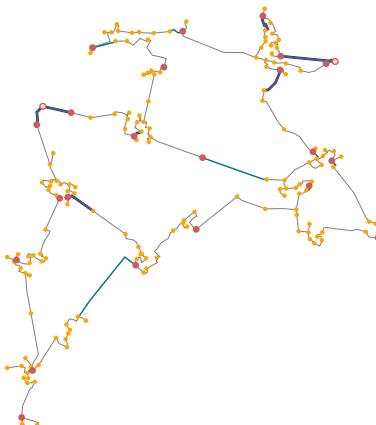


- Trafo
- Lines
- MV/LV buses
- HV buses
- Power flow measurement
- Voltage measurements
- Focus bus

70-bus Oberrhein MV sub-grid from



179-bus Oberrhein MV grid from



Case study settings

Data generation

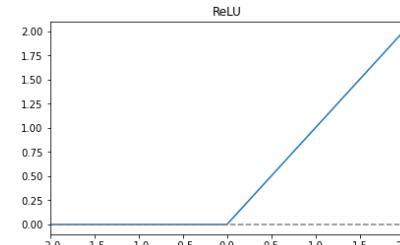
- 8640 days, with each 24 hours, +/- 15% around Gaussian on loads
- Balanced system, pandapower, AC power flow
- Measurement noise
 - 0.5% – 2% for the voltage and current measurement
 - 1% – 5% for the active and reactive power measurement
 - Pseudomeasurement were generic load profiles
- Baselines
 - Weighted least square (WLS)
 - Feedforward Neural Network (FFNN)
 - supervised DSS²

Model & hyperparameters

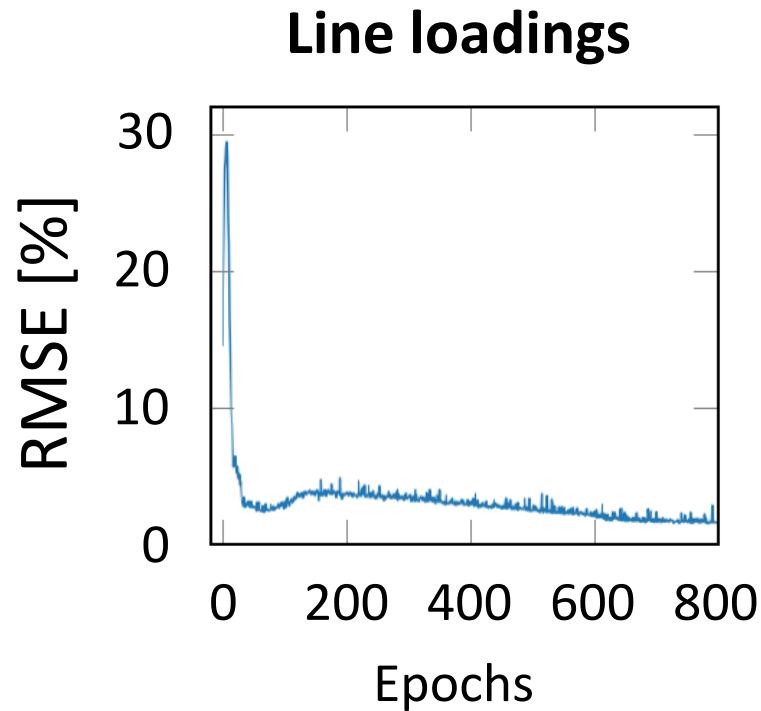
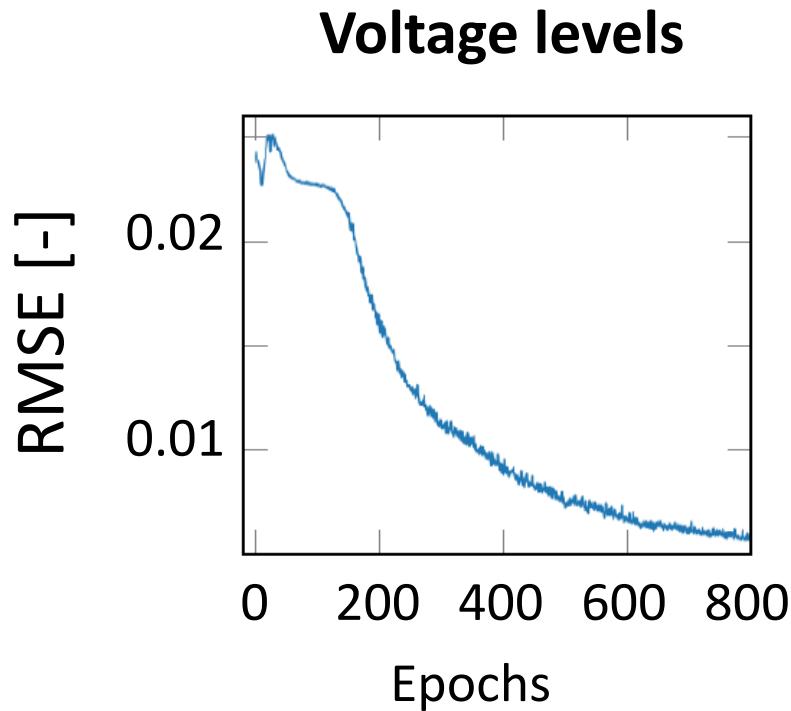
- Hyper-Heterogeneous Multi GNN
- Training 80%, validation 10%, testing 10%
- Grid search on learning rate λ , layer dimensions d , and layer numbers

Assume stable system

$$L(\mathbf{z}, \mathbf{x}) = \sum_{i \in m} \frac{|z_i - h_i(\mathbf{x})|^2}{R_{ii}} + \lambda [\text{ReLU}(V - 1.05) + \text{ReLU}(0.95 - V) \\ + \text{ReLU}(\text{loading} - 100) + \text{ReLU}(\varphi - 0.25) + \text{ReLU}(-0.25 - \varphi)]$$

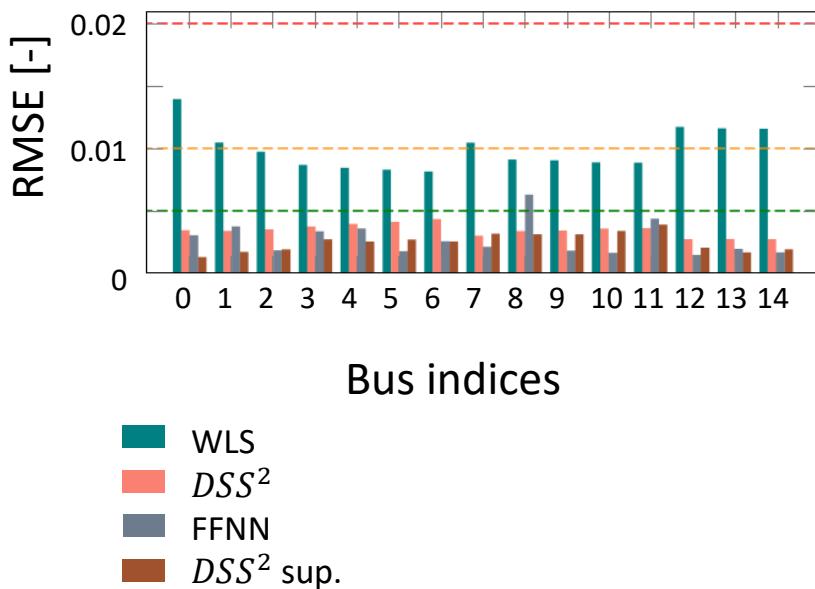


Training performance 14-bus system

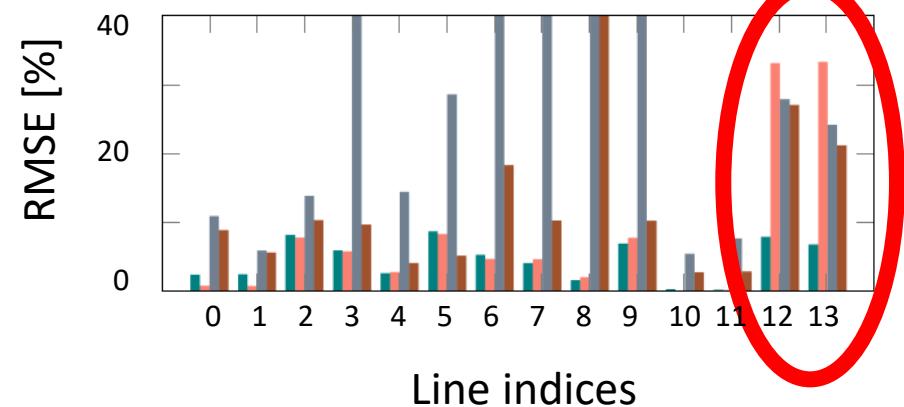


State estimation 14-bus system

Voltage levels



Line loadings



Model inaccuracies: assumed transformer = lines!

Accuracy

Metric \ approach	14-bus system			
	WLS	ANN	sup DSS^2	DSS^2
Voltage RMSE [10^{-3}]	10	3	3	3
Line loading RMSE [%]	3	42	13	4
Trafos loading RMSE [%]	5	39	14	8

Convergence

Metric \ approach	14-bus system				70-bus Oberrhein			179-bus Oberrhein	
	WLS	ANN	sup	DSS ²	WLS	WLS*	DSS ²	WLS**	DSS ²
Voltage RMSE [10^{-3}]	10	3	3	3	31	6	2	10	2
Line loading RMSE [%]	3	42	13	4	17	15	2	6	3
Trafos loading RMSE [%]	5	39	14	8	39	24	3	4	4
Convergence [%]	100	100	100	100	25	100	100	53	100

- WLS did not converge in some instances (25%-50%)
- DSS^2 always ‘converges’ (produces a label)

* with increased convergence rate

** with higher tolerance and more iterations

[22] B. Habib, E. Isufi, W. v. Breda, A. Jongepier and Jochen L. Cremer, "Deep Statistical Solver for Distribution System State Estimation," *IEEE Transactions on Power Systems*, 2023, doi: 10.1109/TPWRS.2023.3290358.

Computational ‘prediction’ time [ms]

Metric \ approach	14-bus system				70-bus Oberrhein			179-bus Oberrhein	
	WLS	ANN	sup DSS ²	DSS ²	WLS	WLS*	DSS ²	WLS**	DSS ²
Voltage RMSE [10^{-3}]	10	3	3	3	31	6	2	10	2
Line loading RMSE [%]	3	42	13	4	17	15	2	6	3
Trafos loading RMSE [%]	5	39	14	8	39	24	3	4	4
Convergence [%]	100	100	100	100	25	100	100	53	100
Computational time [ms]	86	4	5	6	123	161	26	1212	58

~ 10

~ 2

- WLS increases significantly with system size
- DSS^2 increases moderately with system size

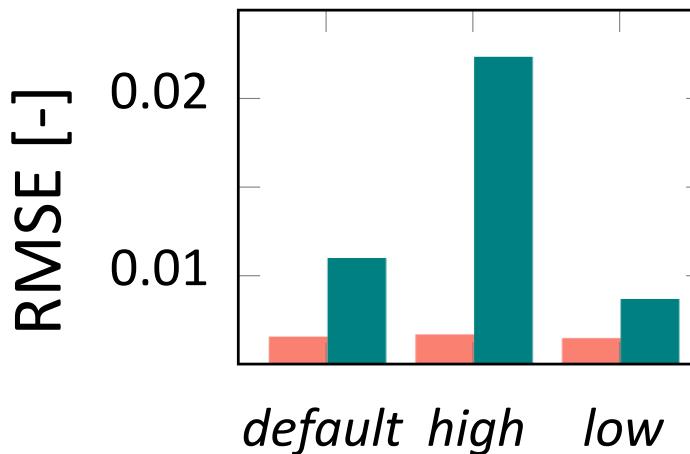
* with increased convergence rate

** with higher tolerance and more iterations

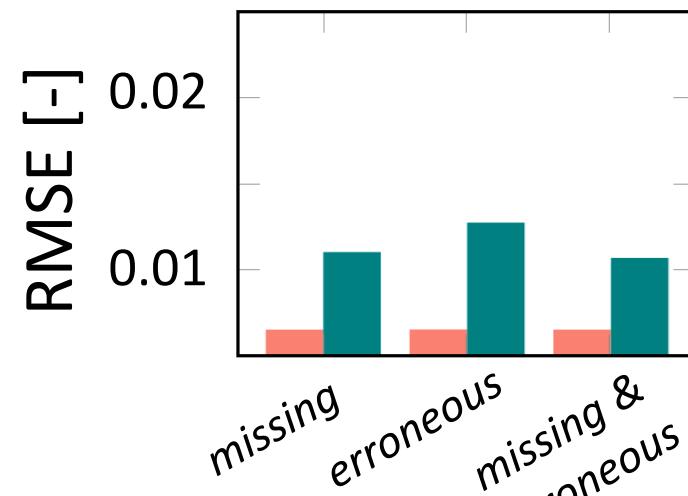
[22] B. Habib, E. Isufi, W. v. Breda, A. Jongepier and Jochen L. Cremer, "Deep Statistical Solver for Distribution System State Estimation," *IEEE Transactions on Power Systems*, 2023, doi: 10.1109/TPWRS.2023.3290358.

Noise and missing, erroneous data

Voltage levels



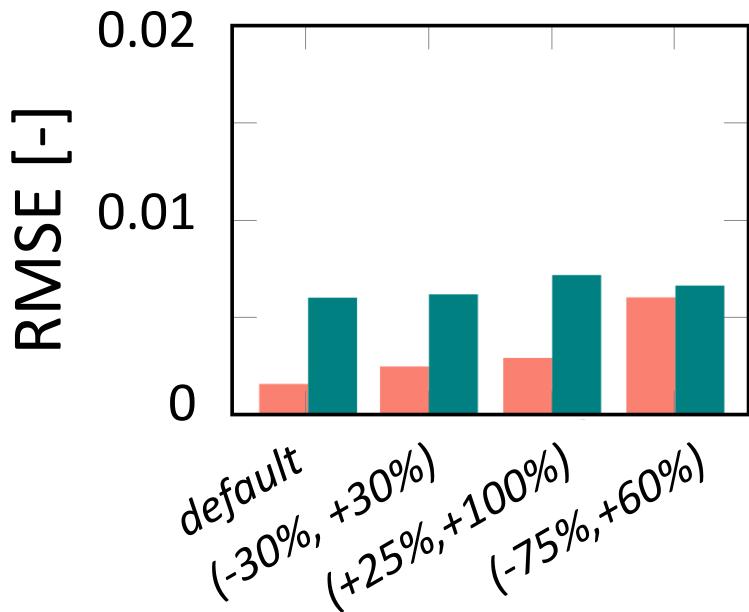
Voltage levels



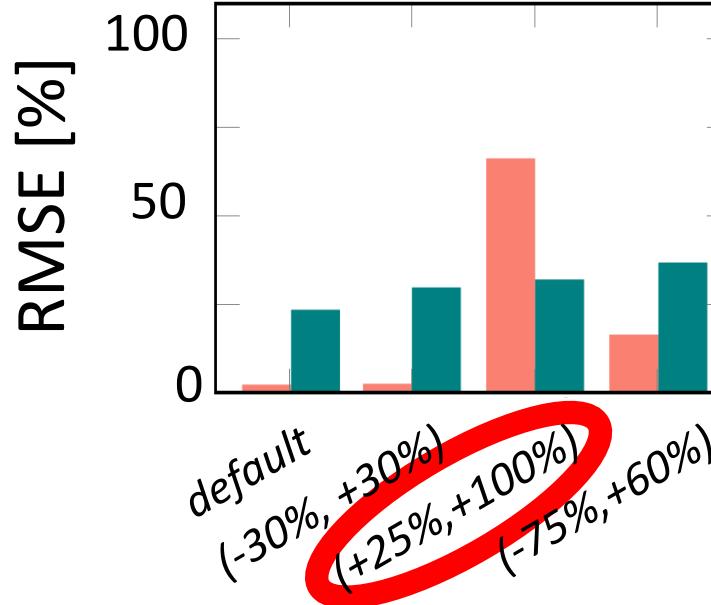
- DSS^2 successfully cancelled noise
- DSS^2 was not trained to handle such events
- GNN architecture increased the interpolation capabilities by incorporating the data symmetries w.r.t. the underlying graph

Increase in (generation, load)

Voltage levels



Line loadings



Limitation: high load levels

Outline

Reliability management and data in control rooms

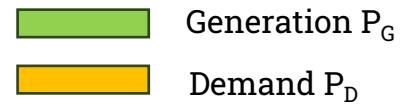
1. Introduction to reliability management
2. Machine learning approaches
3. Security assessment with cost-sensitive supervised learning

Learning models for secure system operation

4. Learning with domain knowledge
5. State estimation with graph neural networks
6. Weakly-supervised learning for secure operation
7. Challenges applying ML to reliability

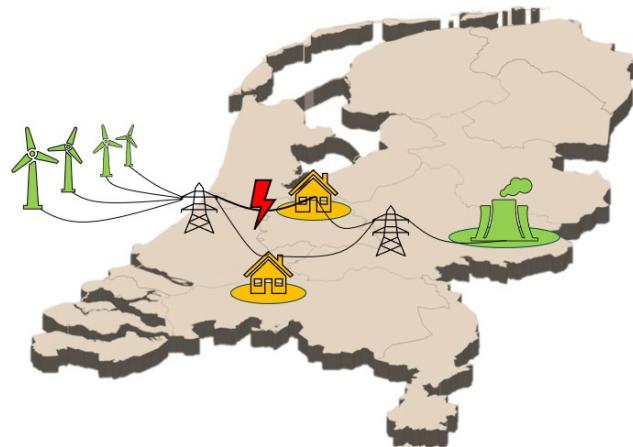


Bastien Giraud



Problem overview

- Growing grid complexity
 - Challenging to maintain N-1 security
- Increasing number of unforeseen weather events
- Need for N-k considerations to increase reliability
- **Problem:** Conventional approaches don't scale well with the number of simultaneous outages k



Security constrained optimal power flow (SCOPF)

Objective: minimize cost

Constraints: In = out

Generator limits

Line flow limits

Contingency
Constraints: Line flow limits

$$\min_{n \in \Omega^G} \sum c_n P_{G_n}$$

$$B \cdot \delta = P_G - P_D$$

$$P_{G_n}^{min} < P_{G_n} < P_{G_n}^{max} \forall n \in \Omega^G$$

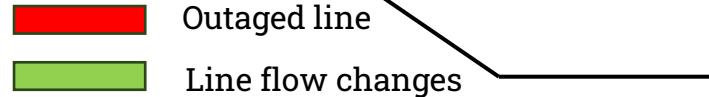
$$F_l^{min} < F_l < F_l^{max} \forall l \in \Omega^L$$

$$F_l^{min} < F_l^c < F_l^{max} \forall l \in \Omega^L, \forall c \in \Omega^C$$



Combinatorial
complexity

Conventional approaches



Solving a **large optimization** problem can be slow

- Benders decomposition
- Column and constraint generation algorithm with robust optimization
- Line outage distribution factors (**LODF**)

Machine learning approaches often rely on **labeled** training data

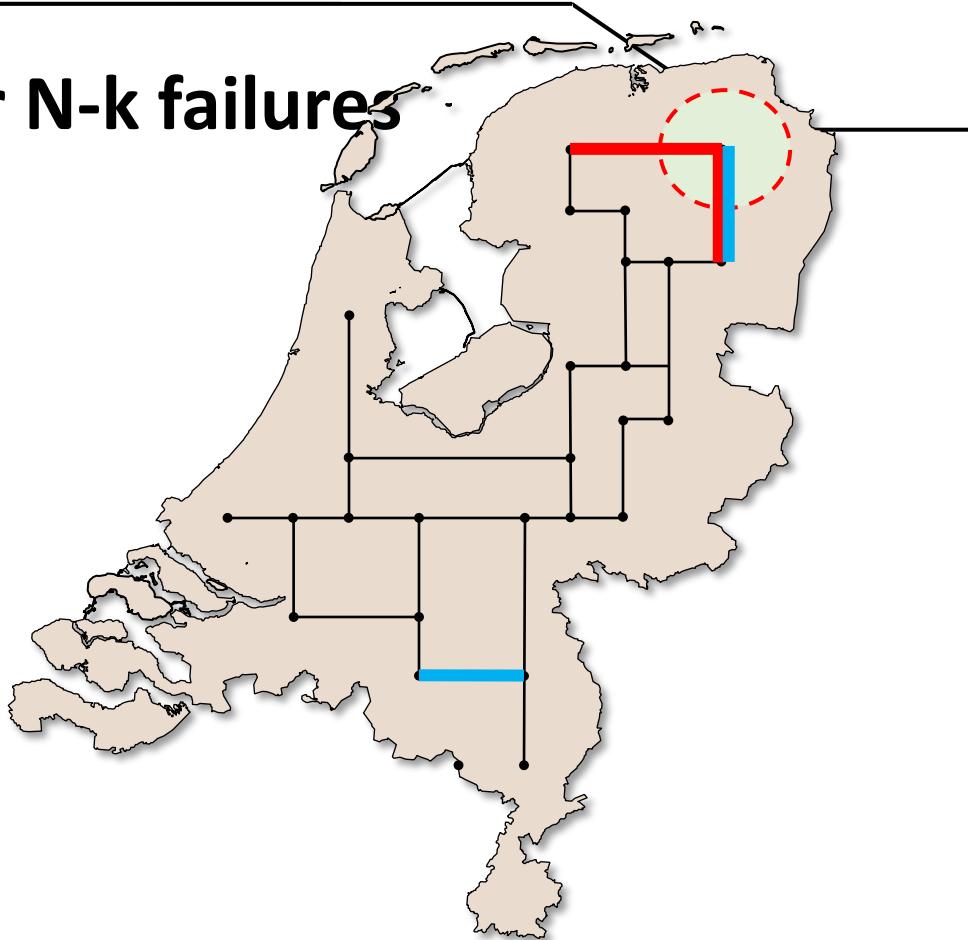
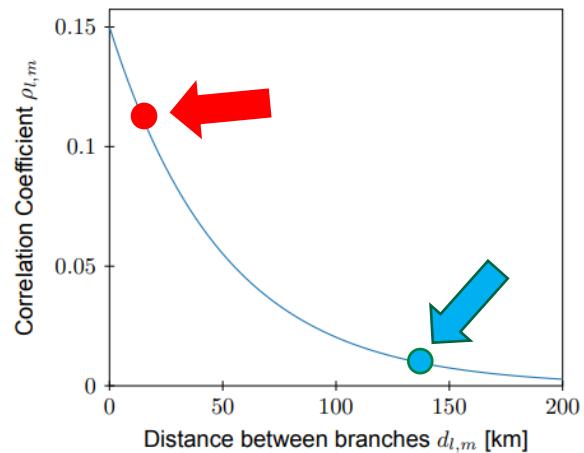
- Intractable for increasing k



$$F^c = F^0 + LODF_{N-k} \times F^0$$

Probabilistic security for N-k failures

- Compute probabilities of all contingencies
- Spatial correlation between line outages
- Compute joint probabilities using a copula analysis



Proposed constraint-driven approach

Main advantages

- Weakly-supervised -> so **no labeled data** needed
- Never actually solve an SCOPF

Contributions

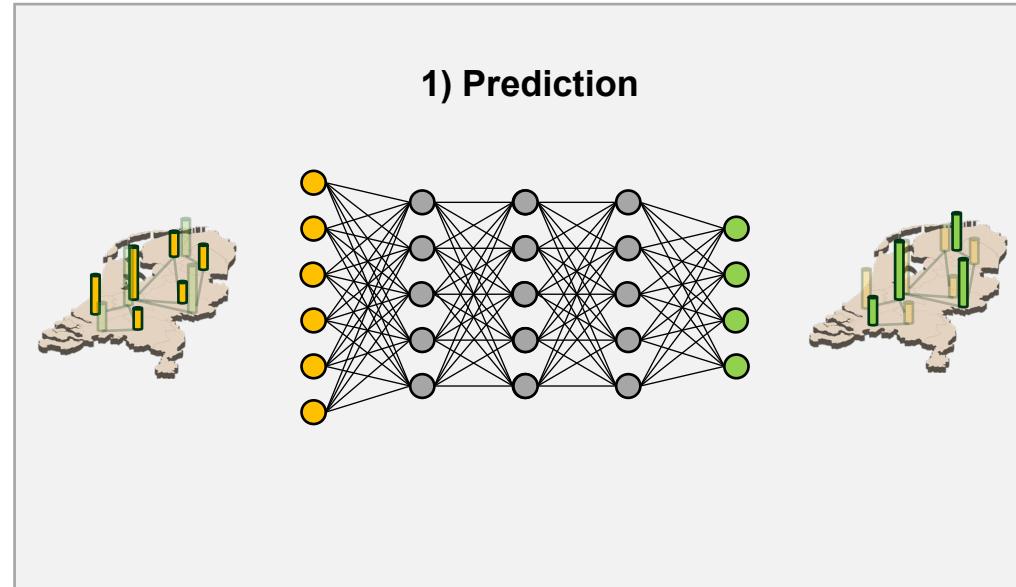
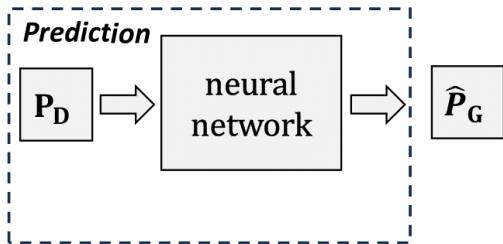
- The deterministic constraint-driven approach to approximate N-k SCOPFs, considering all line contingencies using LODFs.
- The computational graph memory reduction for fast and efficient implementation.
- The probabilistic security assessment to formulate a N-k risk-based security criterion, providing an alternative to the current deterministic N-1 security criterion.



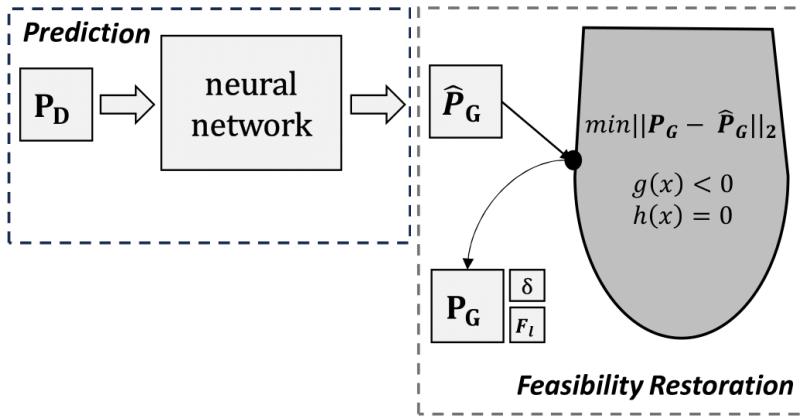
LODF = line outage distribution factor

SCOPF = security constrained optimal power flow

Proposed constraint-driven approach



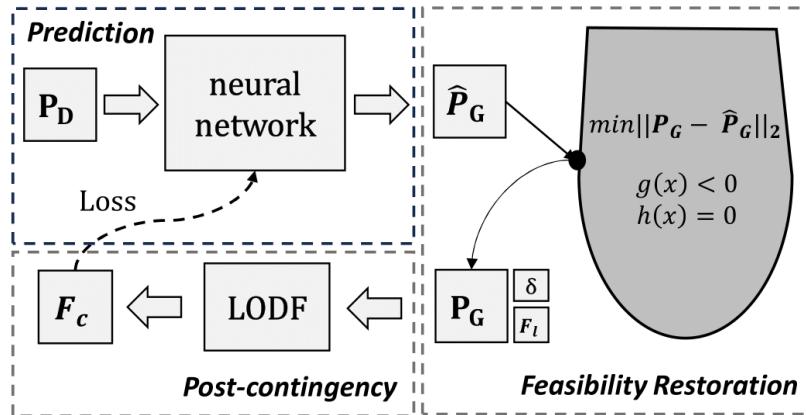
Proposed constraint-driven approach



2) Feasibility Restoration

- With \hat{P}_{G_n} compute predicted line flow \hat{F}_l^0
- Prediction might **violate** DC PF equations
- Map prediction to feasible region constrained by DC PF equations

Proposed constraint-driven approach

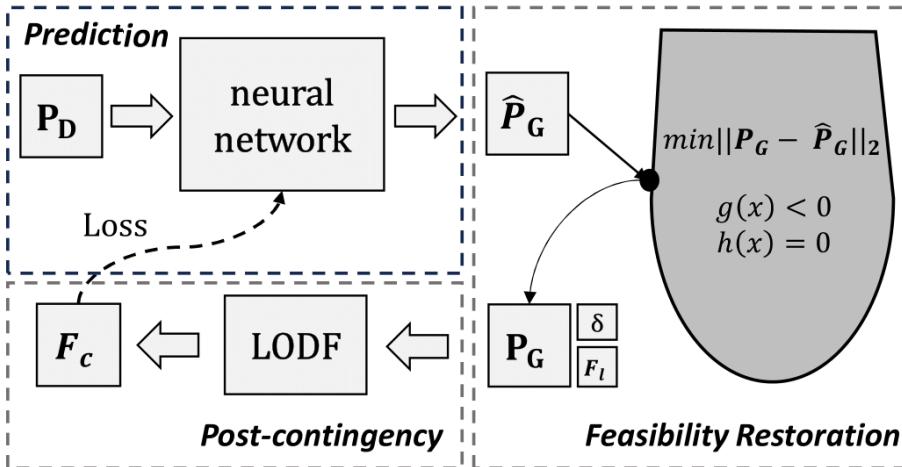


3) Post-contingency

$$\mathbf{F}^c = \mathbf{F}^0 + LODF_{N-k} \times \mathbf{F}^0$$

$$F_l^{min} < F_l^c < F_l^{max} \quad \forall l \in \Omega^L, \forall c \in \Omega^C$$

Proposed constraint-driven approach



1) Dispatch cost

$$\lambda_c \sum \mathbf{P}_G c_G$$

2) Line flow violation pre-contingency

$$\lambda_0 \|ReLU(|\hat{\mathbf{F}}^0| - \mathbf{F}^{max})\|_1$$

3) Line flow violation post-contingency

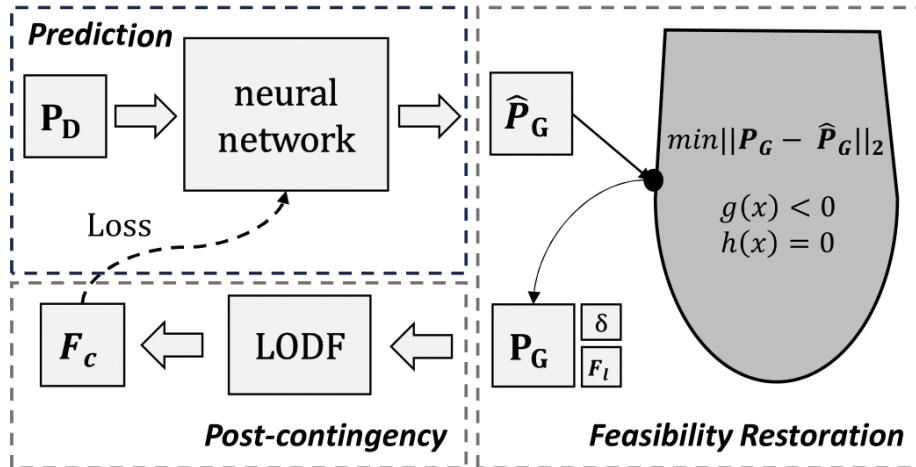
$$\lambda_1 \|ReLU(|\mathbf{F}^c| - \mathbf{F}^{max})\|_1$$

4) Power imbalance

$$\lambda_2 \|\sum \hat{\mathbf{P}}_G - \sum \mathbf{P}_D\|_1$$

$$Loss = \lambda_c \sum \mathbf{P}_G c_G + \lambda_0 \|ReLU(|\hat{\mathbf{F}}^0| - \mathbf{F}^{max})\|_1 + \lambda_1 \|ReLU(|\mathbf{F}^c| - \mathbf{F}^{max})\|_1 + \lambda_2 \|\sum \hat{\mathbf{P}}_G - \sum \mathbf{P}_D\|_1$$

Proposed constraint-driven approach



1) Dispatch cost

$$\lambda_c \sum P_G c_G$$

2) Line flow violation pre-contingency

$$\lambda_0 \| \text{ReLU}(|\hat{F}^0| - F^{max}) \|_1$$

3) Line flow violation post-contingency

$$\lambda_1 \| \pi_{N-k} \cdot \text{ReLU}(|F^c| - F^{max}) \|_1$$

4) Power imbalance

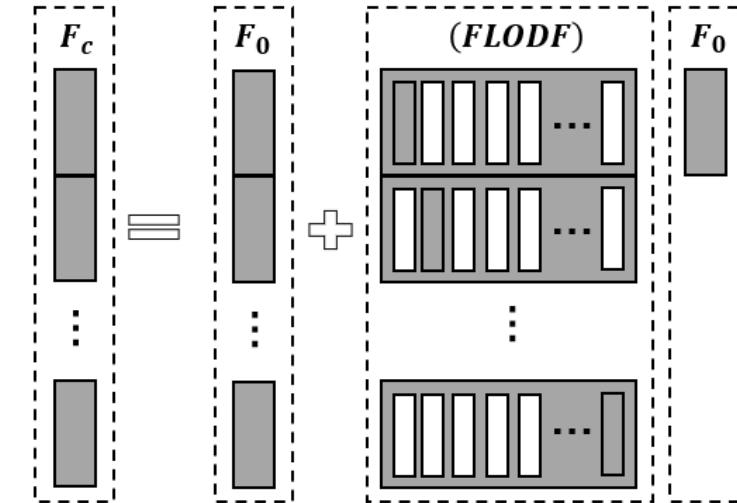
$$\lambda_2 \| \sum \hat{P}_G - \sum P_D \|_1$$

$$\text{Loss} = \lambda_c \sum P_G c_G + \lambda_0 \| \text{ReLU}(|\hat{F}^0| - F^{max}) \|_1 + \lambda_1 \| \pi_{N-k} \cdot \text{ReLU}(|F^c| - F^{max}) \|_1 + \lambda_2 \| \sum \hat{P}_G - \sum P_D \|_1$$

Sparsity LODF matrix

Non-zero values
Zeros

$$F^c = F^0 + LODF_{N-k} \times F^0$$

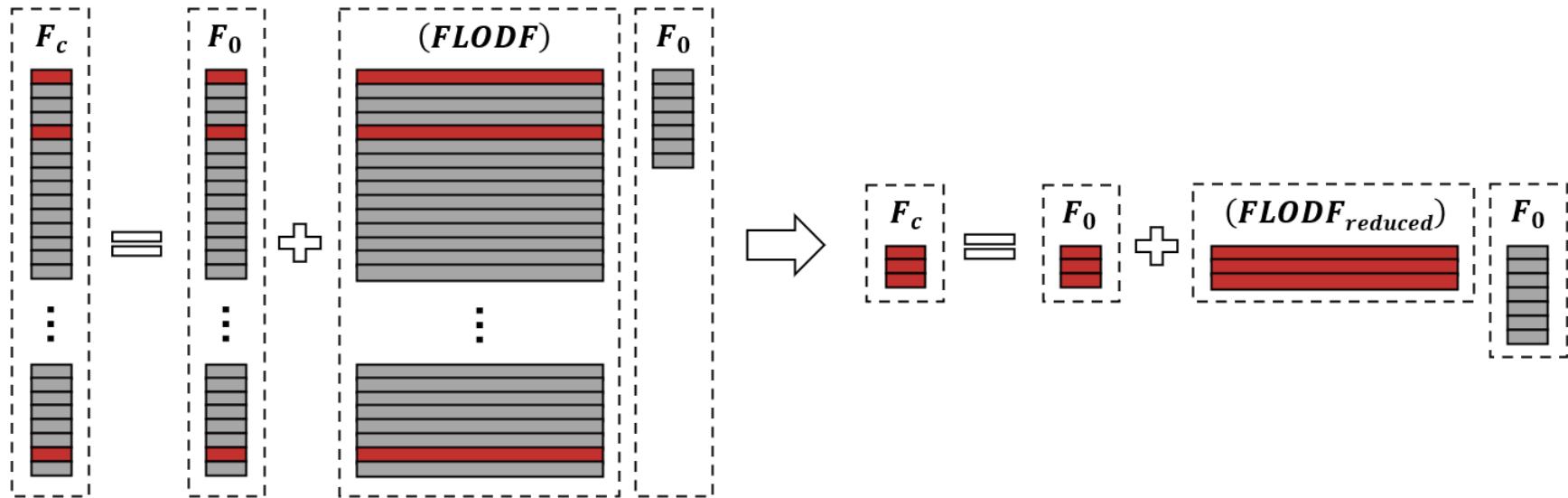


FLODF = 'Full LODF'

	k	1	2	3
39-bus sparsity [%]		98.5	97.6	97.5
118-bus sparsity [%]		99.6	99.3	99.0

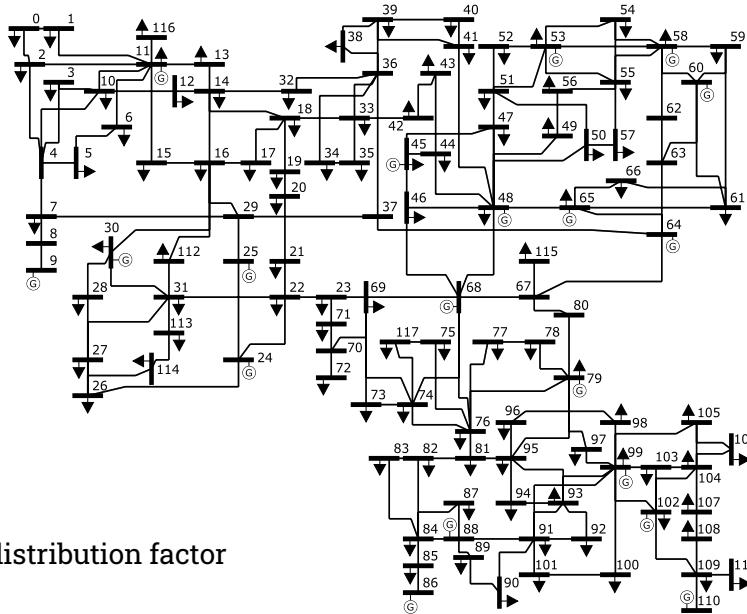
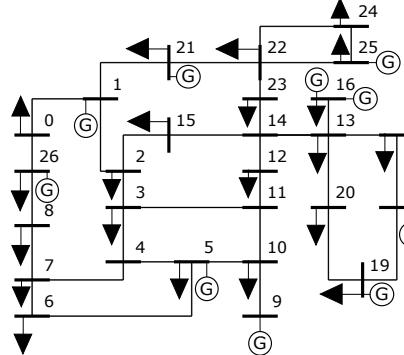
LODF = line outage distribution factor

Reducing the graph



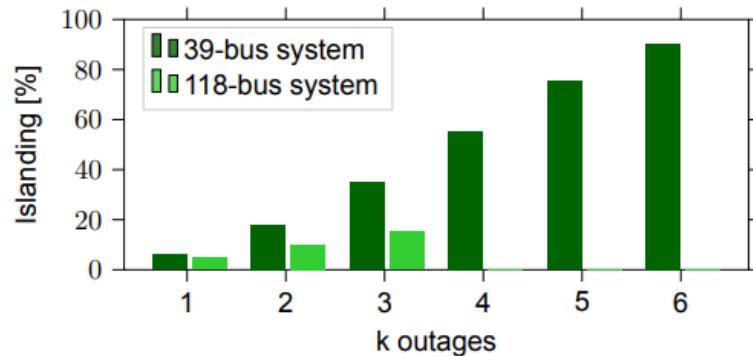
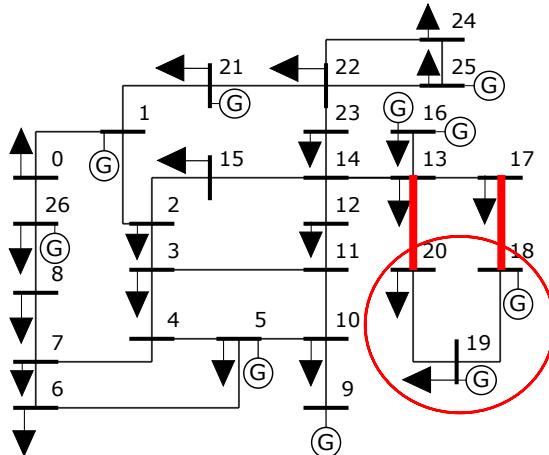
Case studies

- IEEE 39-bus and 118-bus test systems
- $k = \{1, 2, 3\}$
- Baseline: iterative contingency screening with LODFs
- Code: <https://github.com/TU-Delft-AI-Energy-Lab/Constraint-Driven-SCOPF>



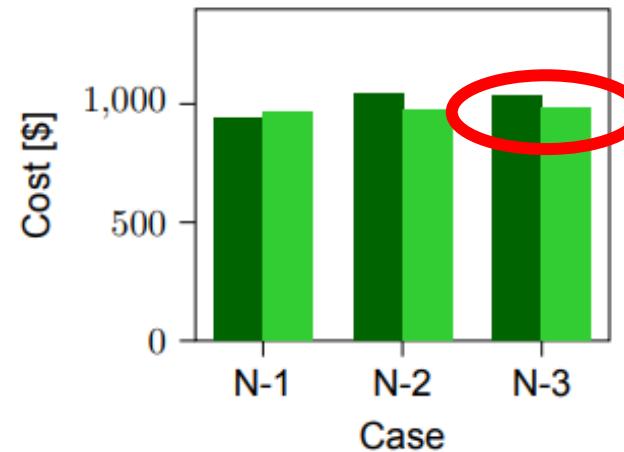
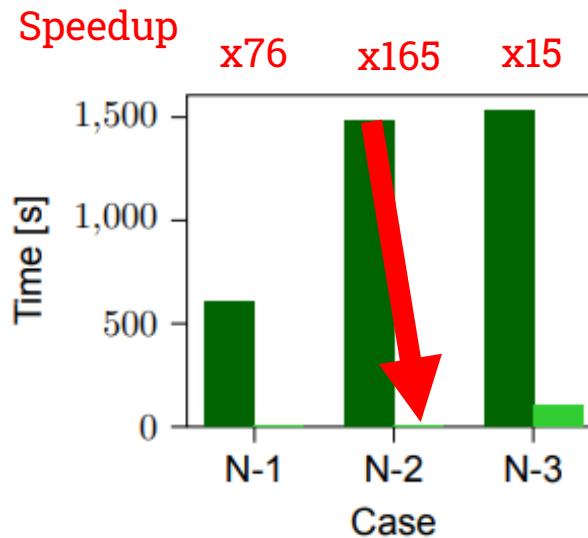
LODF = line outage distribution factor

Islanding

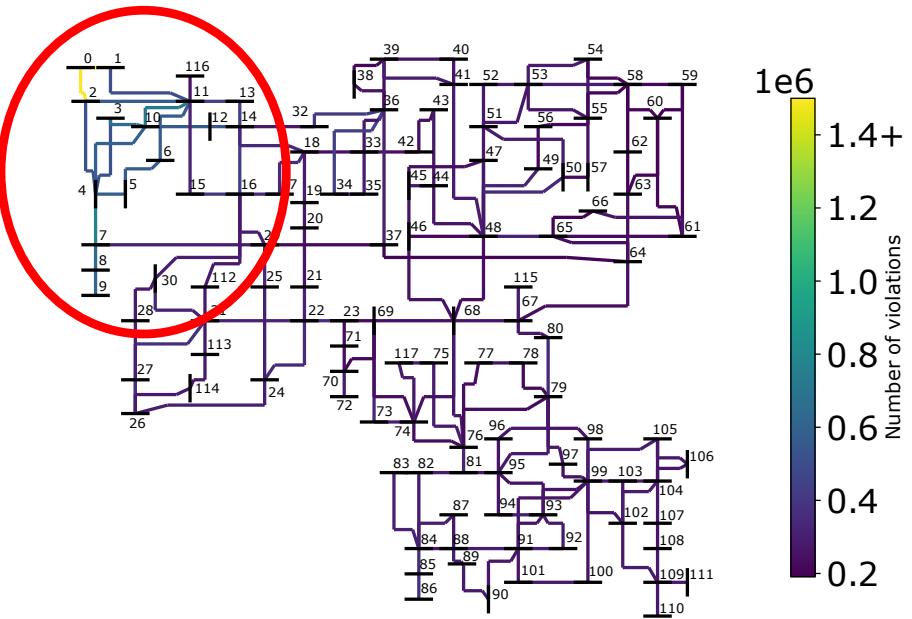


Removing islanding cases

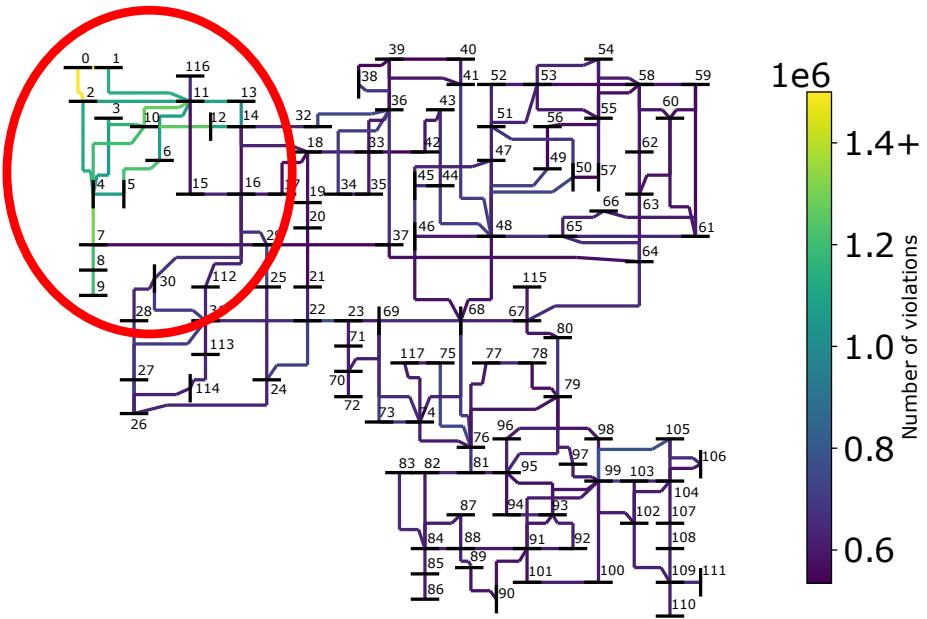
Performance 118-bus system



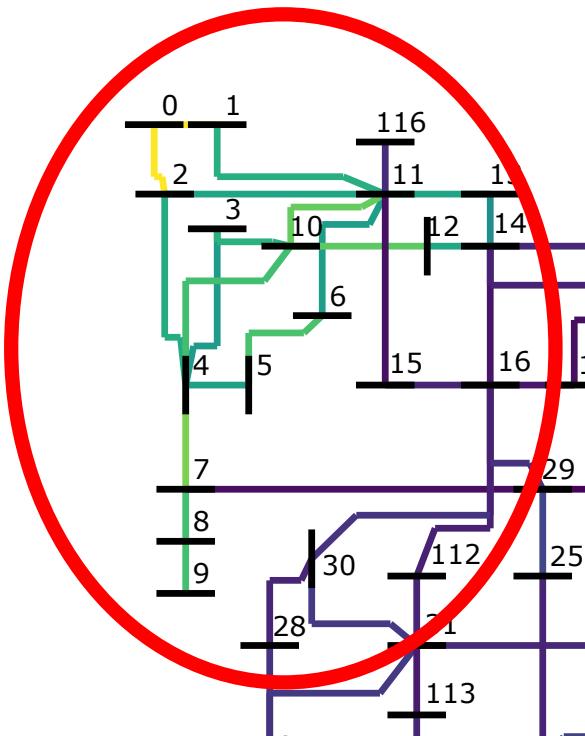
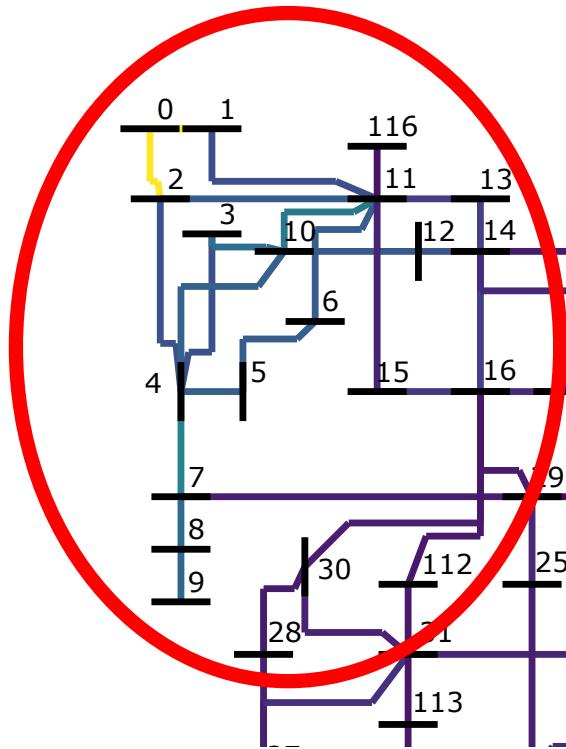
N-3 proposed approach



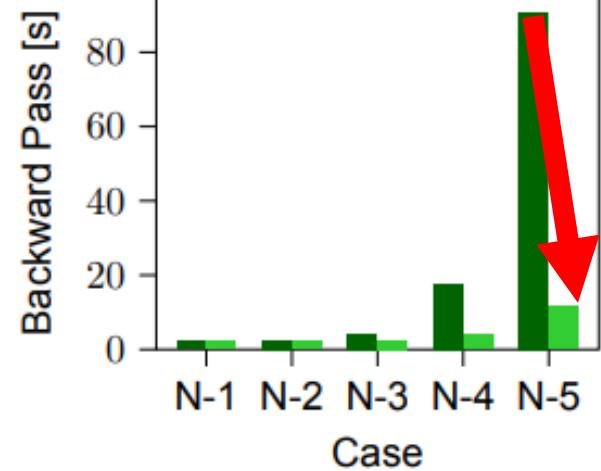
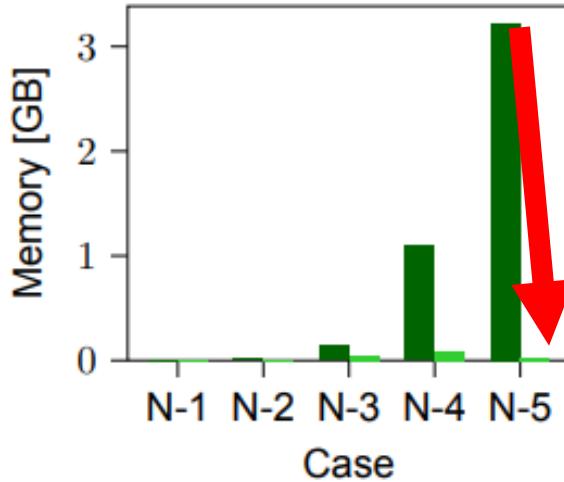
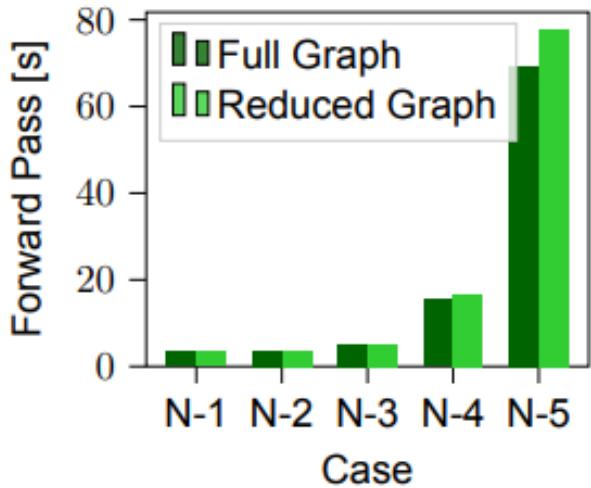
N-3 baseline



N-3 proposed approach



Reducing computational graph



Reduction in memory

Reduction in computation time

Outline

Reliability management and data in control rooms

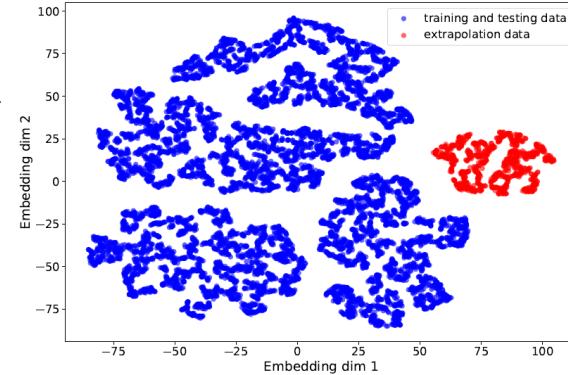
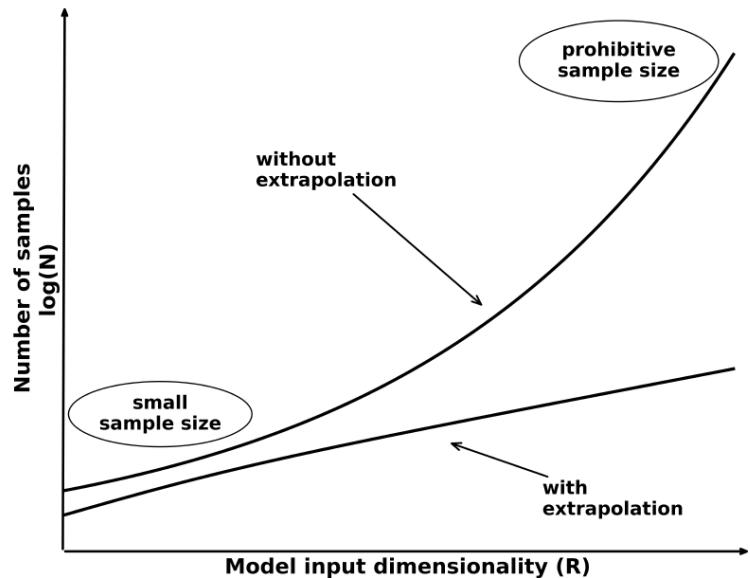
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Learning models for secure system operation

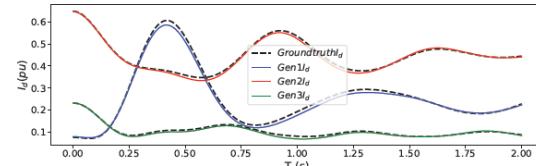
4. Learning with domain knowledge
5. State estimation with graph neural networks
6. Weakly-supervised learning for secure operation
7. Challenges applying ML to reliability

Generalisation to changes in s or m

The model performs well not just on training data, but on **unseen scenarios** – new grid states, topologies, contingencies, or time horizons.

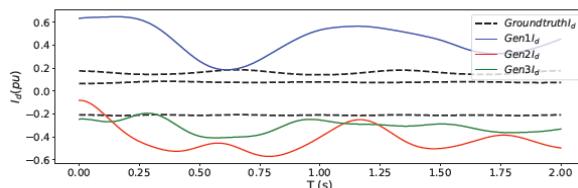


Extrapolation in continuous domain



(a) I_d current trajectory

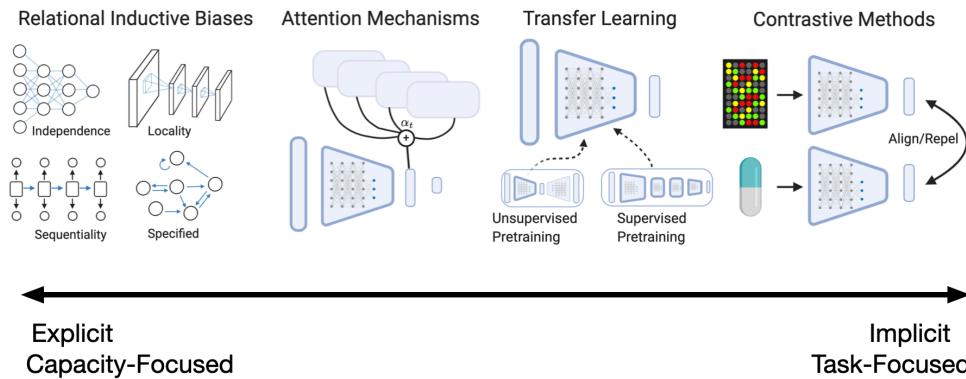
Extrapolation in nonlinear domain (discrete)



(a) I_d current trajectory

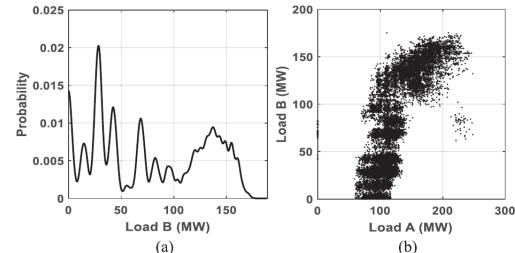
Challenge: Data-efficiency

- **Data efficiency is critical**
- Embedding **inductive bias** and learning **task-aware representations** helps supervised models generalise better — even with limited labels.

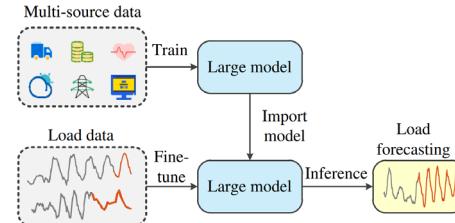


Sampling synthetic data & use real-data

Snapshot sampling



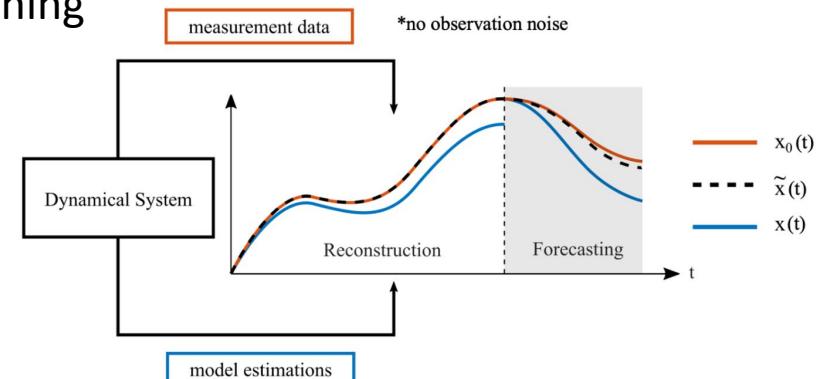
Time-series foundational models



Model inaccuracy $s \neq m$ (data quality issues)

"All models are wrong, but some are useful", George E. P. Box

- Example challenges
 - Distribution: Inaccurate transformer-tap positions
 - Transmission: Converter-based control models are unknown
- Possible techniques: Parameter estimation to develop probabilistic and deterministic models, discrepancy learning



Conclusions

- For many decades, AI has been investigated for power system reliability -> demonstrating promising ideas
- Promising: New techniques, availability of data, models, industry R&D commitments

Open research challenges

- Handling changes in data, and model inaccuracy -> Adaptive GNNs
- Curse of dimensionality -> Self-supervised learning
- Addressing risks, confidence, and trust in ML models
- A large amount of data is needed
- Integrating various concepts

Thank you

Speaker

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Personal www.jochen-cremer.com

Email: j.l.cremer@tudelft.nl

Code: <https://github.com/TU-Delft-AI-Energy-Lab>



References & code

Weakly supervised learning for power systems (Example code: <https://github.com/TU-Delft-AI-Energy-Lab/Deep-Statistical-Solver-for-Distribution-System-State-Estimation>)

- Bastien Giraud, Ali Rajaei, Jochen L. Cremer "Constraint-Driven Deep Learning for N-k Security Constrained Optimal Power Flow", *Electric Power System Research and 2024 IEEE Power System Computation Conference* [Code: <https://github.com/TU-Delft-AI-Energy-Lab/Constraint-Driven-SCOPF>]
- B. Habib, E. Isufi, W. v. Breda, A. Jongepier and Jochen L. Cremer, "Deep Statistical Solver for Distribution System State Estimation," *IEEE Transactions on Power Systems*, 2023, doi: 10.1109/TPWRS.2023.3290358.

Cost-sensitive learning

- Dariush Wahdany, Carlo Schmitt, Jochen L. Cremer, "More than Accuracy: End-To-End Wind Power Forecasting that Optimises the Energy System", *Electric Power System Research*, 2023
- A. Bugaje, J. L. Cremer, M. Sun, G. Strbac, "Selecting DT Models for Security Assessment using ROC- and Cost-Curves", *Energy and AI*, 2021: 100110.
- J. L. Cremer, G. Strbac, "A Machine-learning based Probabilistic Perspective on Dynamic Security Assessment" *International Journal of Electrical Power & Energy System*, 2020

Interpretable models (Example code: <https://github.com/JochenC/From-optimization-based-machine-learning-to-interpretable-security-rules-for-operation>)

- J. L. Cremer, I. Konstantelos, G. Strbac, "From Optimization-based Machine Learning to Interpretable Security Rules for Operation", *IEEE Transactions on Power Systems*, 2019
- J. L. Cremer, I. Konstantelos, S. H. Tindemans, G. Strbac, "Data-driven Power System Operation: Exploring the Balance between Cost and Risk", *IEEE Transactions on Power Systems*, 2018

Fast training of models

- Mert Karaçelebi, Jochen L. Cremer "Online Neural Dynamics Forecasting for Power System Security", *International Journal of Electrical Power & Energy Systems* 2025
- Mert Karaçelebi, Jochen L. Cremer, "Predicting Power System Frequency with Neural Ordinary Differential Equations", *12th Bulk Power System Dynamics and Control Symposium and Sustainable Energy, Grids and Networks Journal*, 2025

Generalisation challenge:

- Olaiyola Arowolo, Jochen Stiasny, Jochen Cremer, "Exploring the Extrapolation Performance of Machine Learning Models for Power System Time Domain Simulations", *12th Bulk Power System Dynamics and Control Symposium and Sustainable Energy, Grids and Networks Journal*, 2025



Thank you for your attention

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Reliability Indicators

Loss of load expectation (LOLE)

- Expected amount of time demand can not be supplied [h/y]
- \sum (Outage duration x probability)

Expected energy not supplied (EENS)

- Amount of energy expected not to be supplied during that period [MWh/y]
- \sum (Energy not supplied x probability)



$$t_1 * \pi_1 = 2 \text{ h/y}$$
$$E_1 * \pi_1 = 3 \text{ MWh/y}$$



$$t_1 * \pi_1 = 0 \text{ h/y}$$
$$E_1 * \pi_1 = 0 \text{ MWh/y}$$



$$t_1 * \pi_1 = 0 \text{ h/y}$$
$$E_1 * \pi_1 = 0 \text{ MWh/y}$$



$$t_1 * \pi_1 = 3 \text{ h/y}$$
$$E_1 * \pi_1 = 4 \text{ MWh/y}$$

+

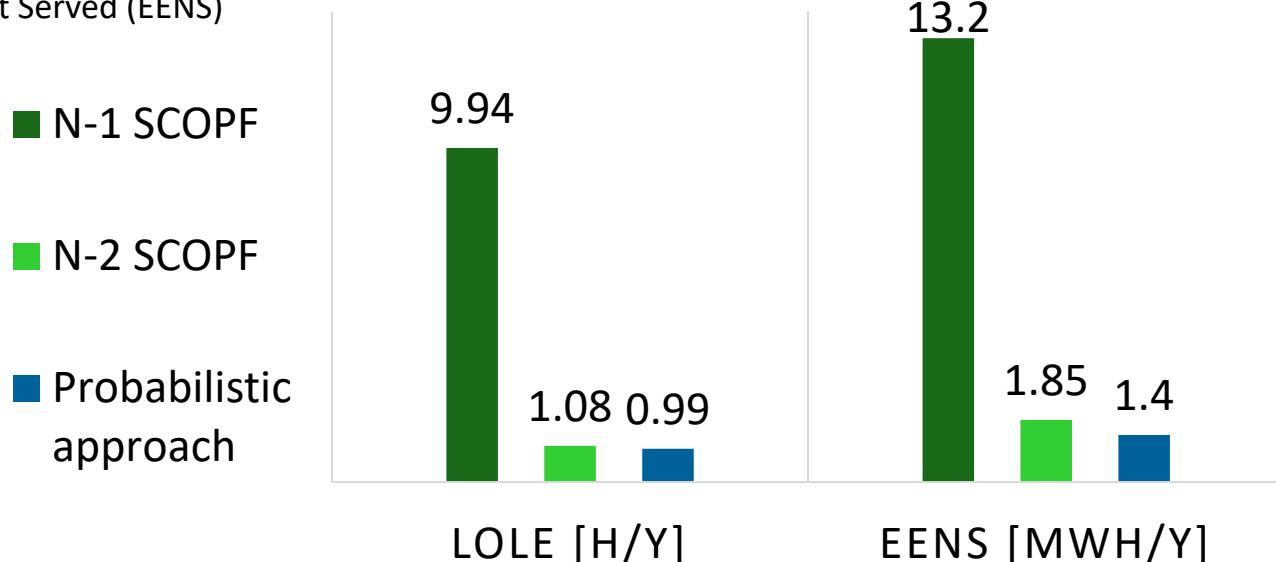
$$\text{LOLE} = 5 \text{ h/y}$$
$$\text{EENS} = 7 \text{ MWh/y}$$

Probabilistic security assessment

Proposed probabilistic security enhances reliability

Compare reliability indices

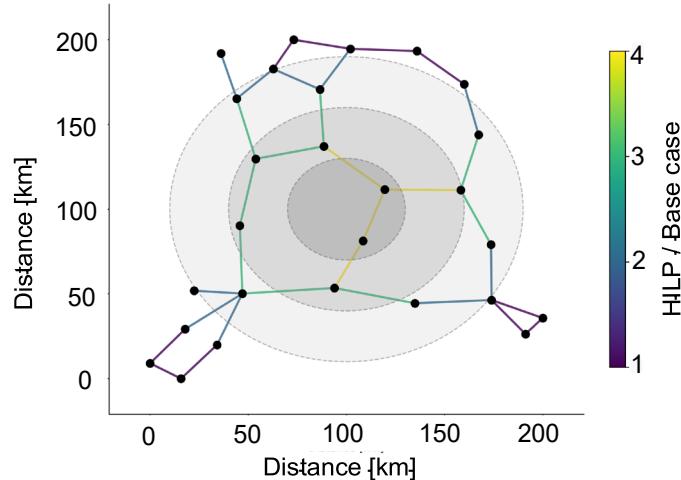
- Loss of Load Expected (LOLE)
- Expected Energy not Served (EENS)



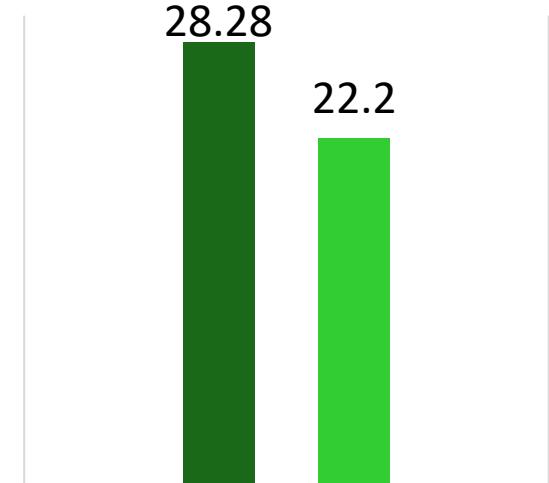
Extreme event

- Individual probabilities change due to an earthquake
- Recompute joint probabilities
- Recompute reliability indices

Potential for increased resiliency



- N-2 SCOPF
- Probabilistic approach



Performance 118-bus system

- Evaluate ability to identify line violations
- **Only** consider single, double or triple line outages
- Post-cont violations [%] indicates the percentage of samples where line violations occur

Proposed approach
Baseline

