

Lecture 21 Structural stability + Bifurcations of vector fields

⊛ $f \in C^1(E)$, $E \subset \mathbb{R}^n$ open

the C^1 -norm of $f = \|f\|_{C^1} = \sup_{x \in E} |f(x)| + \sup_{x \in E} \|Df(x)\|$

definition the vector field f given in ⊛ is structurally stable

iff $\exists \epsilon > 0$ s.t. $\forall g \in C^1(E)$,

$\|f - g\|_{C^1} < \epsilon \Rightarrow$ the vector fields are equivalent
orientation-preserving

i.e. \exists Homeomorphism $H: E \rightarrow E$ which maps

trajectories of $\dot{x} = f(x)$ onto trajectories of $\dot{x} = g(x)$

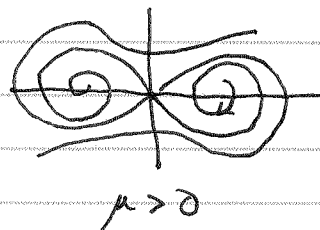
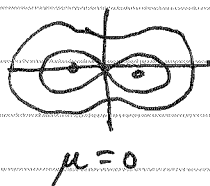
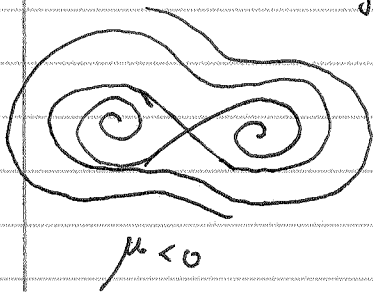
may restrict this definition to say vector field is locally structurally stable
stable on some compact $K \subset E$

Now assume $f = f(x, \mu)$

saw 2 examples last time

example $\dot{x} = y$

$$\dot{y} = x - x^3 + \mu y$$



See that the only structurally stable feature of the $\mu = 0$ system is the ~~ps~~ hyperbolic fixed pt

Periodic orbits and homoclinic connections destroyed

note on any small compact set ~~not~~ $N_\delta(x_0)$ s.t. $x_0 \neq (\pm 1, 0)$

Note that \forall pts ~~not~~ $(\pm 1, 0)$, $\overrightarrow{N_\delta(x_0)}$

$\exists \epsilon > 0$ s.t. the vector field is structurally stable on some ~~set~~

$N_\delta(x_0)$ for all ~~lot~~ $0 < \delta < \epsilon$

Thm if $f \in C^1(E)$, has a hyperbolic critical pt x_0 then $\forall \epsilon > 0 \exists \delta > 0$
 st $\forall g \in C^1(E)$ s.t. $\|f - g\|_{C^1} < \delta \Rightarrow \exists y_0 \in N_\epsilon(x_0)$ hyperbolic
 critical pt w/ same # of +ve & -ve eigenvalues

~~fact~~ SIMILARLY FOR hyperbolic periodic orbits of f

Why? implicit function thm, $f(x_0, \mu_0) = 0$ $D_x f(x_0, \mu_0) \neq 0 \Rightarrow x = X(\mu)$ near x_0, μ_0

Bifurcations - $\dot{x} = f(x, \mu)$ how does structure of solutions depend on μ ?

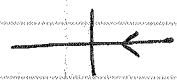
Simplest examples: 1d

$$\dot{x} = \mu - x^2$$

$\mu < 0$ no fixed pts

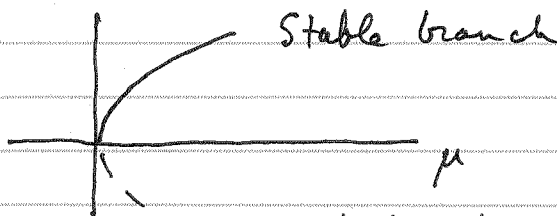
$\mu > 0$ 2 fixed pts $x_{\pm} = \pm \sqrt{\mu}$

~~to~~



Stability given by sign $f'(x_{\pm}) = -2x_{\pm} = \mp \sqrt{\mu}$
 $\Rightarrow x_+$ stable, x_- unstable

draw ~~for~~ bifurcation diagram



- - - unstable branch

this is called a saddle-node bifurcation

example 2

$$\dot{x} = \mu x - x^2 = x(\mu - x)$$

$$f'(x) = \mu - 2x$$

$$f'(0) = \mu$$

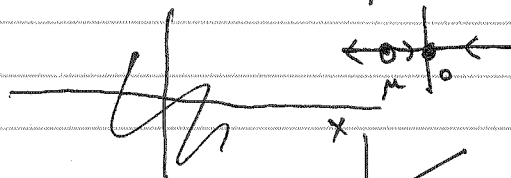
$$f'(\mu) = -\mu$$

stable when $\mu < 0$

stable when $\mu > 0$

$\mu < 0$

$\mu > 0$



TRANSITICAL BIFURCATION

LEC 21-3

$$\dot{x} = \mu x - x^3$$

(System with symmetry, no even terms)

$$\mu < 0$$



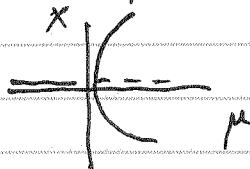
$$\mu > 0$$



$$f' = \mu - 3x^2$$

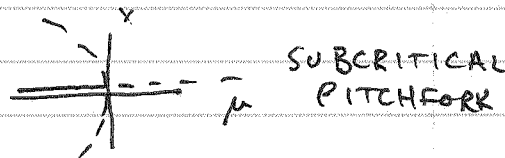
$$f'(0) = \mu \Rightarrow \text{stable if } \mu < 0$$

$$f'(\pm\sqrt{\mu}) = -2\mu \text{ stable when } \mu > 0 \text{ i.e. when } \pm\sqrt{\mu} \text{ is a fixed pt}$$



PITCHFORK BIFURCATION

SIMILAR $\dot{x} = \mu x + x^3$ find



SUBCRITICAL PITCHFORK

note that in all 3 examples

$$\left. \frac{\partial}{\partial x} f(x, \mu) \right|_{x=0, \mu=0} = 0$$

~~pitch~~ Saddle-node + transcritical $f_{xx}(0,0) \neq 0$
pitchfork $f_{xx}(0,0) = 0$ but $f_{xxx}(0,0) \neq 0$

so there is a center subspace associated to the linearization about fixed pt $x=0$ at the parameter value $\mu=0$

In general $f(x_0, \mu_0) = Df(x_0, \mu_0) = 0$ then x_0 is a ~~th~~ nonhyperbolic critical pt. The type of bifurcation depends on which derivative $\frac{\partial^m f(x_0, \mu_0)}{\partial x^j \partial \mu^k}$ is nonzero

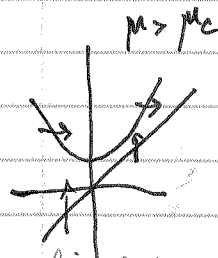
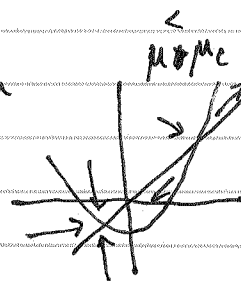
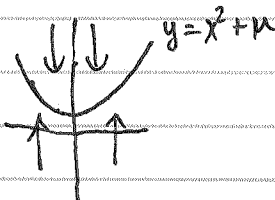
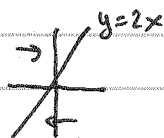
Note there exist in higher dimension

eg trivial $\dot{x} = \mu - x^2$
 $\dot{y} = -y$

non-trivial

$$\dot{x} = y - 2x$$

$$\dot{y} = \mu + x^2 - y^2$$



$$\mu = \mu_c$$



$$x^2 + \mu = 2x$$


and

$$2x = 2 \Rightarrow x=1 \Rightarrow \mu=1$$

Can solve for fixed pts since quadratic

LEC 21-4

Now there exist theorems that tell us if the Taylor series of $\dot{x} = f(x, \mu)$ takes a certain form, then near a non-hyperbolic fixed pt x_0 at parameter-value μ_0 takes a certain form, then the bifurcation is of a given type

$\dot{x} = \pm \mu \pm x^2$ the normal form for the saddle-node bifurcation depending on signs, get 

theorems can tell us "which way parabola opens" + "which branch is stable" but usually easier to just work it out by hand

Theorem (Simplification of §4.2 Thm 1) to 1 dimension
 $\dot{x} = f(x, \mu)$, $f, \mu \in C^\infty(\mathbb{R})$

We want to talk about the fact that the saddle-node bifurcation is "generic" while the transcritical & pitchfork bifurcations are not, i.e. structurally stable. If you change equations slightly get same bifurcation behavior

In general, $\dot{x} = f(x, \mu)$ has a bifurcation at $x = x_0, \mu = \mu_0$ if

$f(x_0, \mu_0) = 0$ and $\partial_x f(x_0, \mu_0) = 0$ because then x_0 a multiple root
 $\dot{x} = f(x, \mu_0) + \partial_x f(x_0, \mu_0)(x - x_0) + \frac{1}{2} \partial_{xx}^2 f(x_0, \mu_0)(x - x_0)^2 + \dots$ + implicit function thm inapplicable

Saddle-node: $\partial_\mu f(x_0, \mu_0) \neq 0$ and $\partial_{xx}^2 f(x_0, \mu_0) \neq 0$

Expand in Taylor series

$$\dot{x} = f(x_0, \mu_0) + \partial_x f(x_0, \mu_0)(x - x_0) + \partial_\mu f(x_0, \mu_0)(\mu - \mu_0) + \frac{1}{2} \partial_{xx}^2 f(x_0, \mu_0)(x - x_0)^2 + \partial_{x\mu} f(x_0, \mu_0)(x - x_0)(\mu - \mu_0) + \dots$$

Saddle node: $\partial_\mu f(x_0, \mu_0) \neq 0$, $\partial_{xx}^2 f(x_0, \mu_0) \neq 0$

Transcritical: $\partial_\mu f(x_0, \mu_0) = 0$, $\partial_{x\mu} f(x_0, \mu_0) \neq 0$, $\partial_{xx}^2 f(x_0, \mu_0) \neq 0$

pitchfork: $\partial_\mu f = 0$, $\partial_{x\mu} f \neq 0$, $\partial_{xx}^2 f = 0$, $\partial_{xxx}^3 f \neq 0$

LEC 21-5

Now we'll let μ be a vector of parameters
but we'll keep $x \in \mathbb{R}$

Then we'll go dip into chapter 2 for center manifold theory which
we'll need to extend this to $x \in \mathbb{R}^n$

assume that $f_0(x)$ defines a structurally unstable vector field (locally)

eg $f_0(x) = x^2$

now we embed f_0 in an m -parameter family of vector fields ~~s.t~~
 $f(x, \mu) = f(x, \mu)$, $\mu \in \mathbb{R}^m$, s.t $f_0(x) = f(x, \mu_0)$

this family is called an unfolding of the vector field $f_0(x)$

it is called the universal unfolding of $f_0(x)$ at a nonhyperbolic
fixed point if it is an unfolding and if every other unfolding
of $f_0(x)$ is topologically equivalent to $f(x, \mu)$ in a nbhd of x_0
the codimension of a bifurcation is the minimum # of parameters to describe a universal unfolding

The normal form of the saddle node bifurcation is

$$f_0(x) = ax^2, \text{ scaling } x \text{ and } t, \text{ we can reset } a = -1 \text{ WLOG}$$

So set $f_0(x) = -x^2$

if we add higher ~~deg~~ degree terms, then behavior near $x=0$
unaffected i.e if $f(x, \mu) = -x^2 + \mu_3 x^3 + \dots$

then if $\mu_3 \ll 1$ this just adds another fixed pt at $x \approx \frac{1}{\mu_3} \gg 1$
so this doesn't change behavior near 0

so a universal unfolding is

$$f(x, \mu) = \mu_1 + \mu_2 x - x^2$$

complete the square $y = x - \frac{\mu_2}{2}$

$$f(y, \mu) = (\mu_1 + \mu_2^2/4) - y^2 \quad \text{define } \mu = \mu_1 + \mu_2^2/4$$

$$f(x, \mu) = \mu - x^2$$

Thus all possible types of behavior for systems that can occur in an unfolding
of $\dot{x} = -x^2$ are given by the saddle-node normal form
it is a codimension 1 bifurcation since it is described by $\mu \in \mathbb{R}^1$