

Lecture 4: Continuous Dependence on Init Cond + Parameters

⊕ $\begin{cases} \dot{x} = f(x) \\ x(0) = y \end{cases}$ think of the initial condition as a parameter
 a family of solutions ^{Φ} is given by $x(t) = u(t; y)$
 use semicolon to emphasize y a parameter

if we assume f is C^1 we can define the linearization

$$\text{let } \Phi = D_y u = \frac{\partial u}{\partial y} \quad (\text{a matrix})$$

$$\text{note since } u(0, y) = y \text{ we have } \Phi(0, y) = \frac{\partial y}{\partial y} = I$$

What ODE does Φ solve?

$$\frac{d\Phi}{dt} = \frac{d}{dt} \frac{\partial}{\partial y} (u(t, y)) = \frac{\partial}{\partial y} \dot{u}(t, y) = \frac{\partial}{\partial y} f(u(t, y))$$

$$= Df(u(t, y)) \frac{\partial u}{\partial y} = Df(u(t, y)) \Phi$$

$$\begin{cases} \frac{d\Phi}{dt} = Df(u(t, y)) \Phi \\ \Phi(0) = I \end{cases} \quad \text{the linearized eqn}$$

first we need to show it makes sense to write $u(t) = u(t, y)$

Lemma 1 Neighborhood existence

suppose for some $x_0 \in \mathbb{R}^n$, $\exists b > 0$ s.t. $f: B_b(x_0) \rightarrow \mathbb{R}^n$ is Lipschitz w/ const K

and that let $M = \max_{x \in B_b(x_0)} |f(x)|$

Then a family of solutions ^{$u(t, y)$} exist $\forall y \in B_{b/2}(x_0)$

and is unique $\forall t \in [a, a] = I$ where $a < \min[\frac{1}{K}, \frac{b}{2M}]$

Proof define $T_y(u) \in C(I, \mathbb{R}^n)$

the closed set of functions $V = C^0(I, B_b(x_0))$

label the operator T by its initial condition

$$T_y(u) = y + \int_0^t f(u(\tau)) d\tau \quad \text{for all } y \in B_{b/2}(x_0)$$

~~then~~

$$|T_y(u) - x_0| \leq |y - x_0| + \int_0^t |f(u(\tau))| d\tau$$

$$\leq \frac{b}{2} + Ma \leq \frac{b}{2} + \frac{b}{2} \quad \text{provided } a \leq \frac{b}{2M}$$

Lecture 4-2

Further $T_{\mathbf{u}}$ is a contraction if $a < \frac{1}{K}$ (can relax w/ weighted norm)
 Contraction mapping thm $\Rightarrow \exists!$ soln $u(t, y) \quad \forall t \in J$ \square

note we had to vary initial condns over ball half the size, could take a larger ball, but would need to take a smaller

$$\text{eg } B_{\frac{3b}{4}}, \quad a < \frac{1}{4} \frac{b}{M}$$

Recall from last time

GRONWALL LEMMA

$$\text{if } g(t) \leq C + \int_0^t k(s)g(s)ds, \quad g(t), k(t), C \geq 0$$

$$\text{then } g \leq Ce^{\int_0^t k(s)ds}$$

~~Lemma 2~~

Theorem 1 Lipschitz dependence on Initial Conditions

let $x_0 \in \mathbb{R}^n$, suppose $\exists b > 0$ st $f: B_b(x_0) \rightarrow \mathbb{R}^n$ Lipschitz w/ const. K

and $J = [-a, a]$ is the common interval of existence for solutions

$$u(t, y) \text{ of } (*) : J \times B_{b/2}(x_0) \rightarrow B_b(x_0)$$

then $u(t, y)$ is uniformly Lipschitz in y w/ Lipschitz const e^{Ka}
 \uparrow
 w.r.t. t

$$\text{Pf } |u(t, y) - u(t, z)| \leq |y - z| + \int_0^t |f(u(\tau, y)) - f(u(\tau, z))| d\tau$$

$$\leq |y - z| + K \int_0^t |u(\tau, y) - u(\tau, z)| d\tau$$

by gronwall w/ $k(t) = K, \quad C = |y - z|$

$$|u(t, y) - u(t, z)| \leq |y - z| e^{Kt} \leq |y - z| e^{Ka}$$

lecture 4-4

Suppose $|h| < b/2$ and define

$$g(t) = |u(t, y+h) - u(t, y) - \Phi(t, y)h|$$

$$= |u(t, y+h) -$$

$$= |y+h + \int_0^t f(u(\tau, y+h)) d\tau - (y + \int_0^t f(u(\tau, y)) d\tau)$$

$$- (\Phi(t, 0)h + \int_0^t Df(u(\tau, y))\Phi(\tau, y)h d\tau)|$$

$$= \left| \int_0^t [f(u(\tau, y+h)) - f(u(\tau, y)) - Df(u(\tau, y))\Phi(\tau, y)h] d\tau \right|$$

we need to show $\lim_{h \rightarrow 0} g(t) \rightarrow 0$ faster than $|h|$ as $h \rightarrow 0$

which would imply $\Phi = \frac{\partial u}{\partial y}$

Since f is C^1

we can write $f(w) = f(u) + Df(u)(w-u) + R(u, w)$

where $R(u, w)$ is small in the sense that

$$\forall \epsilon > 0, \exists \delta = \delta(\epsilon, u) > 0 \text{ s.t. } |w-u| < \delta \Rightarrow |R(u, w)| < \epsilon |w-u| \quad (3)$$

thus, using $w = u(\tau, y+h)$, $u = u(\tau, y)$, get

$$g(t) \leq \int_0^t |Df(u(\tau, y))(u(\tau, y+h) - u(\tau, y)) + R(u, w) - Df(u(\tau, y))\Phi(\tau, y)h| d\tau$$

$$\leq \int_0^t |Df(u(\tau, y))(u(\tau, y+h) - u(\tau, y) - \Phi(\tau, y)h)| d\tau + \underbrace{\int_0^t |R(u, w)| d\tau}_{\int_0^t |R(u(\tau, y+h), u(\tau, y))| d\tau}$$

$$\leq \int_0^t |Df(u(\tau, y))| |u(\tau, y+h) - u(\tau, y) - \Phi(\tau, y)h| d\tau + \int_0^t |R(u(\tau, y+h), u(\tau, y))| d\tau$$

so if u is C^1 , but using (3) and we have

so if u is C^1

define $r = \int_0^t |R(u(\tau, y+h), u(\tau, y))| d\tau$

Lecture 4-3

Review: What is a derivative in \mathbb{R}^n ?

def $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is differentiable at x_0 if there is a linear transformation (a matrix) denoted $Df(x_0)$ satisfying

$$\lim_{|h| \rightarrow 0} \frac{|f(x_0+h) - f(x_0) - Df(x_0)h|}{|h|} = 0$$

Theorem 1 f is differentiable at $x_0 \iff$ all the mixed partials $\frac{\partial^2 f_i}{\partial x_j \partial x_k}$ are well-defined
in which case $(Df(x_0))_{ij} = \frac{\partial f_i}{\partial x_j}$

Theorem 2 (Smooth dependence on initial conditions)

suppose $f: E \rightarrow \mathbb{R}^n$ is C^1 on an open set E

then $\exists a > 0$ s.t. $u(t, y)$ solving \oplus is a C^1 function of y for $t \in [-a, a]$

Proof - since f is C^1 then f locally Lipschitz

For each $x_0 \in E$, $\exists b > 0$ w/ $B_b(x_0) \subset E$ and f Lipschitz on $B_b(x_0)$ w/ const $K(x_0, b)$

- by lemma 1, Unique sol'n $u(t, y) \oplus \forall y \in B_{b/2}(x_0)$ on a common interval J

- since $f \in C^1$, can define Φ as above by

$$(*) \quad \begin{cases} \frac{d}{dt} \Phi = Df(u(t, y)) \Phi \\ \Phi(0, y) = I \end{cases}$$

let $A(t) = Df(u(t, y))$

since $u \in C^1$ and Df continuous, A is a continuous function of t
thus for each column i of $**$ solves

$$\begin{cases} \dot{x} = A(t)x \\ x(0) = \hat{e}_i \end{cases} \text{ has a unique solution on } J$$

these solutions define the columns of J

Lecture 4-5

$$g(t) \leq r + \int_0^t K g(s) ds$$

$$\Rightarrow g(t) \leq r e^{Kt} \leq r e^{Ka}$$

need to show $\frac{r}{h} \rightarrow 0$ as $h \rightarrow 0$

we have by (2) $|R(u(\tau, y+h), u(\tau, y))| \leq$

by (3) $|R(u(\tau, y+h), u(\tau, y))| \leq \varepsilon |u(\tau, y+h) - u(\tau, y)|$

if $|u(\tau, y+h) - u(\tau, y)| \leq |h| e^{Ka} < \delta(\varepsilon, b)$
i.e. if $|h| < \delta e^{-Ka}$

in which case $\int |R(u(\tau, y+h), u(\tau, y))| d\tau \leq \varepsilon \int_0^t |u(\tau, y+h) - u(\tau, y)| d\tau$

$$r \leq \varepsilon \int_0^t |h| e^{Ka} d\tau$$

$$r \leq \varepsilon a |h| e^{Ka}$$

So we end up with $g(t) \leq r e^{Ka} \leq \varepsilon a |h| e^{Ka} e^{Ka} = \varepsilon a |h| e^{2Ka}$

since this is true for all $\varepsilon > 0$

we have $\frac{g(t)}{|h|} \rightarrow 0$ as $h \rightarrow 0 \Rightarrow u \in C^1$

Theorem Suppose $\begin{cases} \dot{x} = f(x, \mu) \\ x(0) = x_0 \end{cases}$, $f: B_b(x_0) \times B_r(\mu_0) \rightarrow \mathbb{R}^n$
has uniformly Lipschitz dependence on $x \in B_b(x_0)$
(Lipschitz K independent of μ)
and f is uniformly continuous function of parameters
then (i) has unique solution $u(t; y, \mu)$ for $y \in B_{b/2}(x_0)$
that is a uniformly continuous function of μ on some
time interval J

Lecture 4-6

Theorem 3 if $\frac{dx}{dt} = f(x, \mu)$, $x \in \mathbb{R}^n$, $\mu \in \mathbb{R}^m$ $x|_{t=0} = y$
then the solution

$x(t) = u(t; y, \mu)$ depends continuously on
both y & μ

proof let $Z = \begin{bmatrix} x \\ \mu \end{bmatrix} \in \mathbb{R}^{n+m}$

$$g(Z) = \begin{bmatrix} f(x) \\ 0 \\ \vdots \\ 0 \end{bmatrix} \begin{matrix} n \text{ coords} \\ m \text{ coords} \end{matrix}$$

apply previous proof to $\dot{Z} = g(Z)$
 $Z|_{t=0} = \begin{pmatrix} y \\ \mu \end{pmatrix}$

Final note: if $f(t)$ is C^k then dependence on initial conds / parameters is also C^k