



UAV-SIRMS: Seismic Infrastructure Risk Management System with Unmanned Aerial Vehicles

MEET THE TEAM



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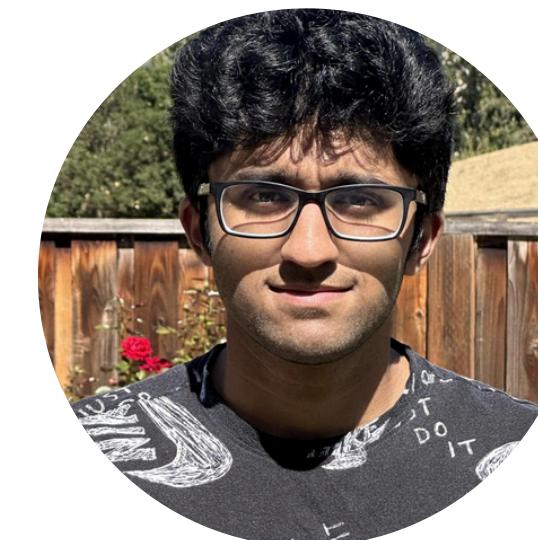
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AGENDA

01 Overview

02 Business + Marketing

03 Software Specifications

04 UAV Drone Prototype

05 Drone Components + Cost

06 Physics Analysis

07 Q&A





01 OVERVIEW



THE PROBLEM



1989 - *The Bay Bridge collapses during the Loma Prieta earthquake*

Current Inspection Methods are Limited:

Human Inspection

Manual inspections involving personnel scaling structures are dangerous, incur significant costs, and require considerable time.

Manual Drone Inspection

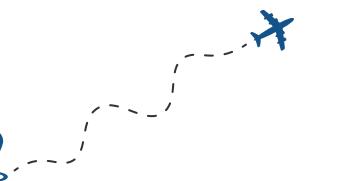
Piloted drones still bear substantial costs and demand extensive pilot training to navigate safely.

OUR SOLUTION

Last Semester, we developed a CONOPs document for a **UAV Seismic Infrastructure Risk Management System.**

UAV-SIRMs provides detailed assessments of infrastructure using autonomous drones and algorithms for both pre-earthquake maintenance and post-earthquake response.

Pre-flight Planning + Analysis



Autonomous Drone(s) Deployment



Pre and Long-Term Post + Short-Term Post Earthquake Data Aquisition



Real-Time Data Transmission and Risk Analysis



MOVING FORWARD...

This Semester, we dove into the Business + Development End.



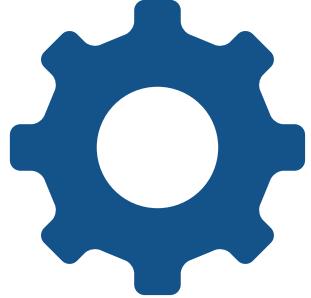
SOFTWARE SPECIFICATION

Prototype Data/Reasoning Services



BUSINESS + MARKETING

*Market Research
Total Addressable Market
Value Proposition
Marketing Plan*



HARDWARE

*CAD Prototype
Material Components + Cost
Physics*



02 BUSINESS + MARKETING



OUR VALUE PROPOSITION

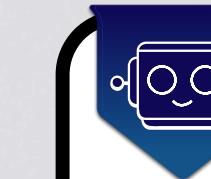
With ***increasing government focus*** and ***rising infrastructure age***, we offer an innovative solution.



Faster and Instant Detection of Faults



Higher Detailed Analysis



Less Labor Intensive



Advanced Detection Technologies + Software



Cheaper Maintenance Cost

MARKET RESEARCH



HIGHWAY INSPECTION

*Serviced by CA Dept. of
Transportation*

ROAD CHARGE PROGRAM

*On track to be implemented in
2027 - Citizens pay for
maintenance + inspection based on
drive activity*

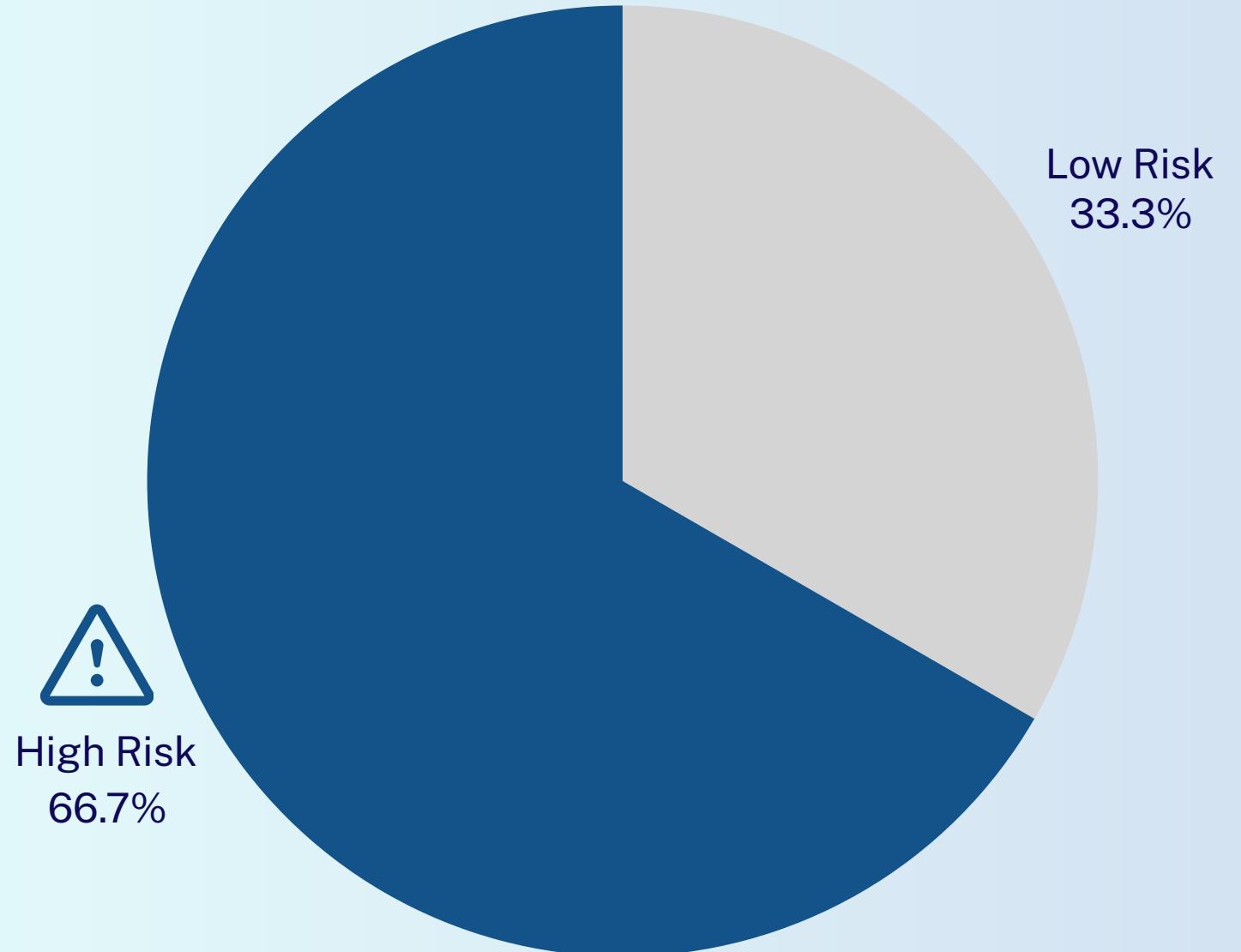
Could Fund UAV-SIRMS

ZERO THREATS

Zero Private Sector Competition

TOTAL ADDRESSABLE MARKET

2/3 of California lives in High Risk Earthquake Areas



MARKET APPROACH

Direct and personalized sales intensive strategy - 1 on 1 engagements to tailor solutions effectively

PRIMARY MARKET LOCAL + REGIONAL GOVERNMENTS



Routine + Emergency Monitoring of Earthquake Prone Infrastructure

Continual Assessment

Emergency Response + Monitoring Capabilities in Disaster Scenarios

SECONDARY MARKET CONSTRUCTION + UNIVERSITIES



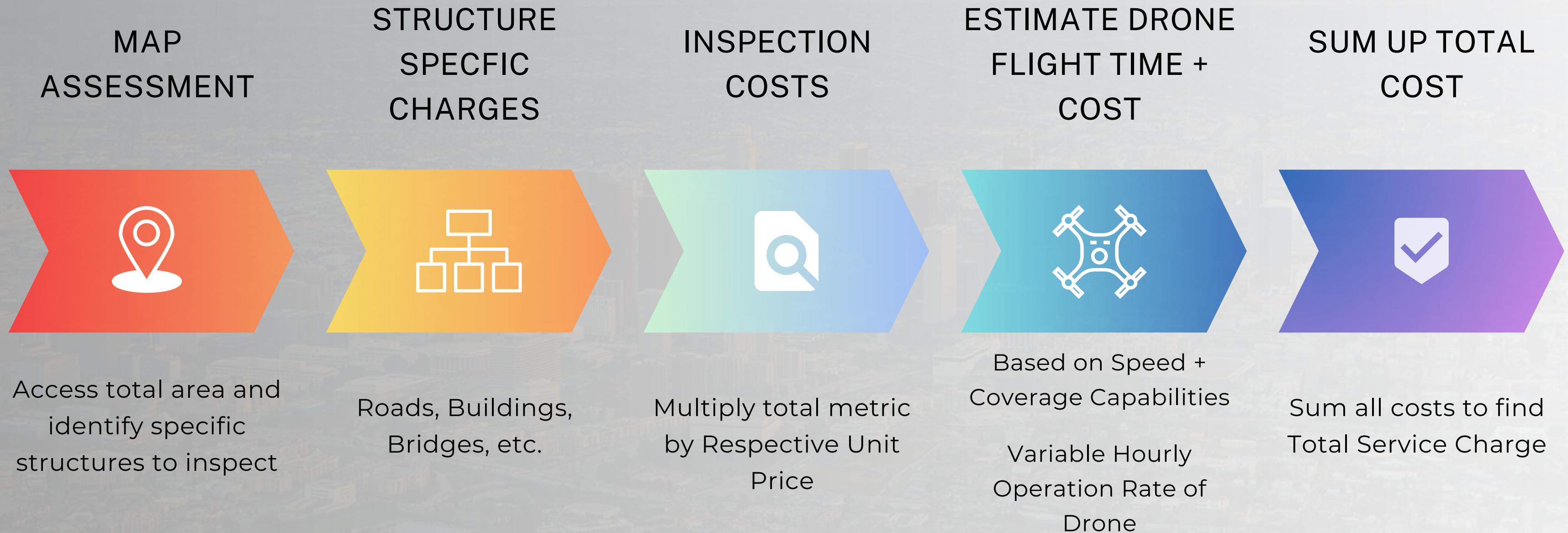
Maintain facility compliance with safety standards

Routine Maintenance

Upgrade Evolving Facilities

CASE: REGULAR MONITORING

LA Greater Area





03 SOFTWARE SPECIFICATIONS

OBJECTIVES

PRIMARY OBJECTIVE

To Efficiently Take and Transmit Data from Drone Inspection

SECONDARY OBJECTIVE

To use Artificial Intelligence to Analyze Data from Drones

Pre-flight Planning

Determine the best path for drone

Test Case Considerations

Ground communication will likely not stay intact after earthquake

Other Considerations

Size of upload, cloud service provider, privacy of data

Data Analysis

Requires high accuracy + precision

High Automation

Elimination of manual labor

Data Presentation

User-friendly format

PRIMARY OBJECTIVES

ROUTE PLANNING

Determining optimal data collection route with flight and distance limitations

OUR SOLUTION

Utilizing Clarke-Wright Savings Algorithm

Graphing intersections of roads into “nodes”; drone depot as start & end

Optimize based on time

Utilizing Google Maps API

Can iteratively improve and add conditions

DATA TRANSFER

Transferring data from drones to secured storage with emergency bandwidth limitations

OUR SOLUTION

Prioritize Important Data

Need to identify what data is most important for decision making

Usage of Satellite Communication

Much more reliable in areas where it is remote or disaster-affected

SECONDARY OBJECTIVES

NEED

To accurately analyze the road condition, and present it in a user-friendly format

CURRENT SOLUTION

Department staff needs to drive each road and carefully identify cracks or distresses of roads, if any

Uses **Pavement Condition Index (PCI)** to assess road quality

Scaled from 0 to 100

Categorized roads into “Poor” to “Excellent” condition

Determine strategy of treatment

Some agencies use Pavement management system to systematically quantify PCI

OUR PROPOSED SOLUTION

Using **AI** to speed-up and optimize process in inspection

Need to **pre-process road images** to reduce noise

Using computer vision to detect crack, potholes, etc.

Continue usage of PCI (Proven method)

After AI detects the amount of suspected damages, Calculate that road section’s PCI, Categorize the road’s condition, and provide strategy of treatment

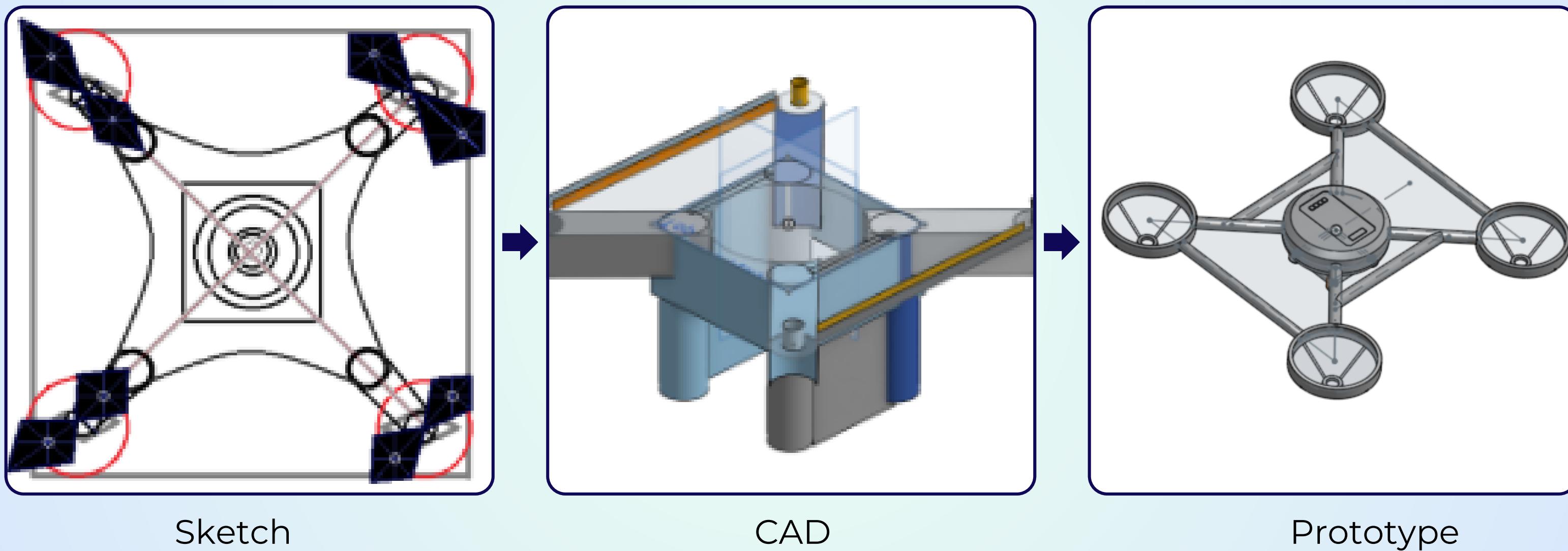
Prioritize highly important/heavy traffic roads

Visualize **condition** of roads on map; provide **ease of use** in system



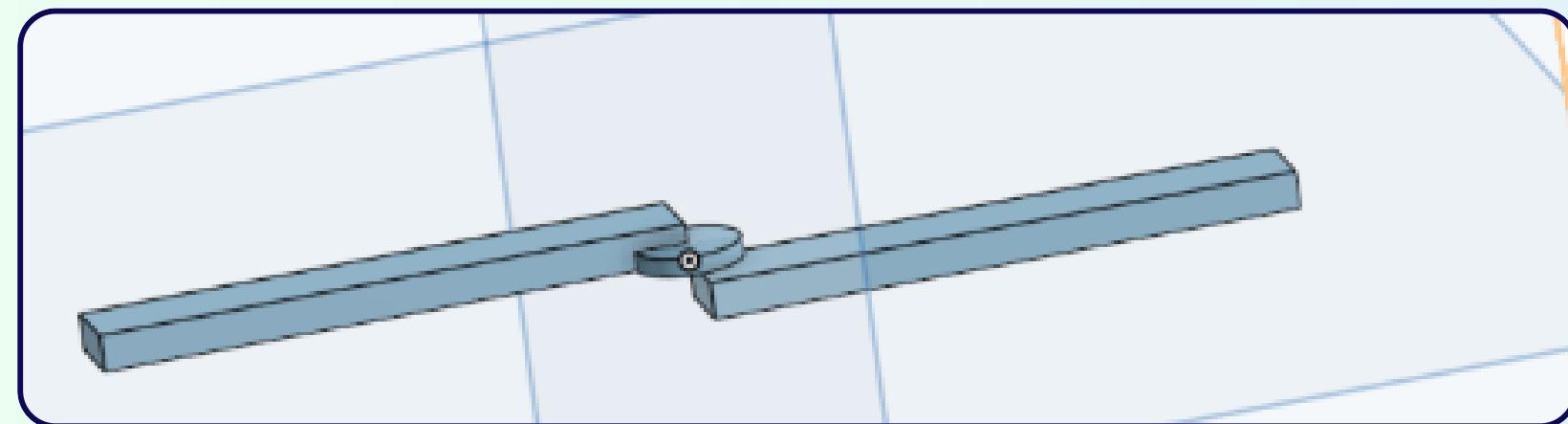
04 UAV DRONE PROTOTYPE

2D TO 3D: DRONE MODEL

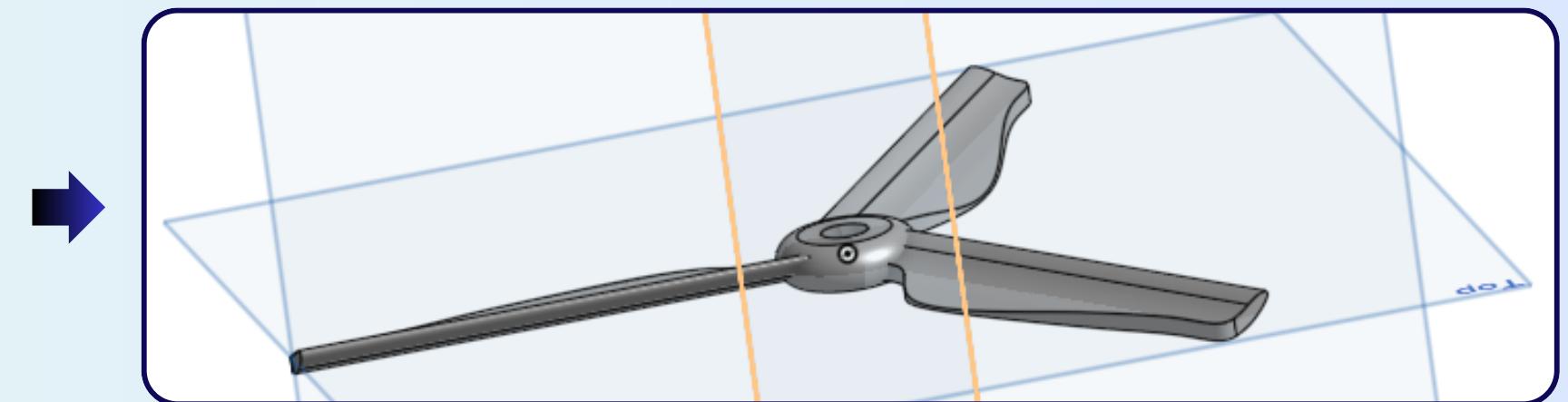


Inspired by DJI's Phantom 3 and Matrice 300 RTK Drone
Adapted for Increased Aerodynamics, Added Component Drag, and Maneuver in Flight

PROPELLERS



Two-Blade CAD



Three-Blade Prototype

Adapted from the Lightweight CAD

Two-Bladed Wing transformed to Three-Bladed Wing for Added Stability, Clearance, and Horsepower for Added Durability



05 DRONE COMPONENTS + COST



COST

Component	Price
Accelerometer	\$129
Battery	\$865
Frame	\$304
Infrared Sensor	\$370
Motherboard	\$73
Parachute	\$151
ShortRange LiDAR Sensor	\$8,544
Wiring	\$40
Total Cost Per Unit	\$10,476



06 PHYSICS ANALYSIS

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DRONE MASS ANALYSIS



Component:

Mass

Battery - 4.2 kg

LiDAR Sensor - 0.94 kg

Infrared Sensor - 0.26 kg

Parachute - 0.05 kg

Industrial Drone (accounts for mass of other components) - ~3.6 kg

Total - ~9 kg



Example Industrial Drone:

Matrice 300 RTK by DJI

This drone provides the specs of an industrial drone. As its specifications show that it can take off with 9 kg, we can be assured that a drone with all of our sensors and components is viable.

SERVICE RANGE ANALYSIS



Specs for Matrice 300 RTK

(Our Example Drone)

Maximum Flight Time - ~1 hour

Maximum Flight Speed - 23 m/s (~50 mph)

Maximum Covered Distance in One Flight - 50 miles



Range of Service - 25 mi

By looking at the abilities of our example drome, we can conclude that our drones will be able to survey locations within 25 miles of their starting location, or slightly less if more time is needed to survey.



Thank you | Questions?



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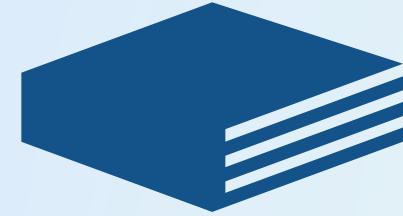
APPENDIX



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IDENTIFIED STAKEHOLDERS



ACADEMIC

Conducts relevant research, hosts testbed implementations, and contributes to research funding through grants and as a potential customer.



COMMERCIAL

Requires consistent monitoring and regular inspections to uphold safety standards in commercial buildings and other real estate.



GOVERNMENT

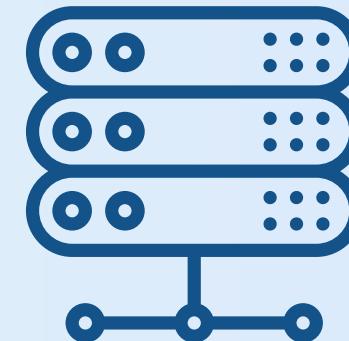
Demands widespread deployment for routine infrastructure assessments and action in emergency situations.

WHY NOW?



Increasing Focus From the
Government to Focus on
Infrastructure

The Infrastructure Investment & Jobs Act (2021)
allocated \$110B specifically towards roads and
bridge maintenance



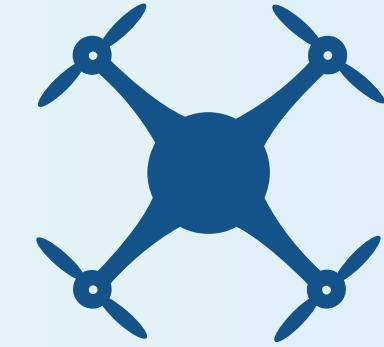
Infrastructure is Showing Age
and Requires Proper
Maintenance or Replacement

36% of U.S's bridges need major work
68% of California roads are in “poor” or
“mediocre” condition

OUR ADVANTAGE

AUTONOMY

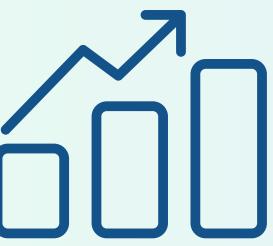
Drones operate autonomously, reducing the risk to human operators during aftershocks.



MANEUVERABILITY

Drones can traverse and inspect over larger cracks and more severely damaged road sections, areas where traditional vehicles may fail to reach.

PRICING

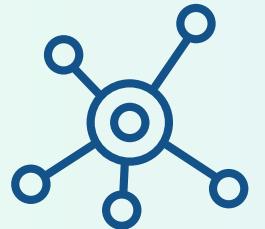


VARIABLE METRICS

Roads: Miles

Buildings: Surface Area

Bridges: Length

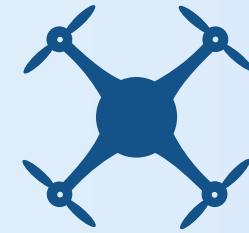


DATA DELIVERABLES

Detailed Imagery

Comprehensive Report

Risk Categorization



ADDITIONAL INPUTS

Drone Flight Time

Geographic Area Covered



EMERGENCY SERVICES

Additional Charges

On-Demand Deployment +

Monitoring

CASE 02: EMERGENCY

STRUCTURE
SPECIFIC
CHARGES



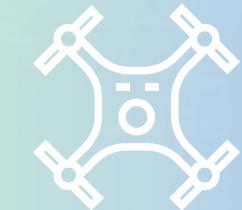
Apply Higher
Emergency Rate

ROAD INSPECTION
COSTS



Variable Emergency
Rate for Mileage

ESTIMATE DRONE
FLIGHT TIME +
COST



Calculate Expected
Drone Time, Considering
Aftershocks + Hazards

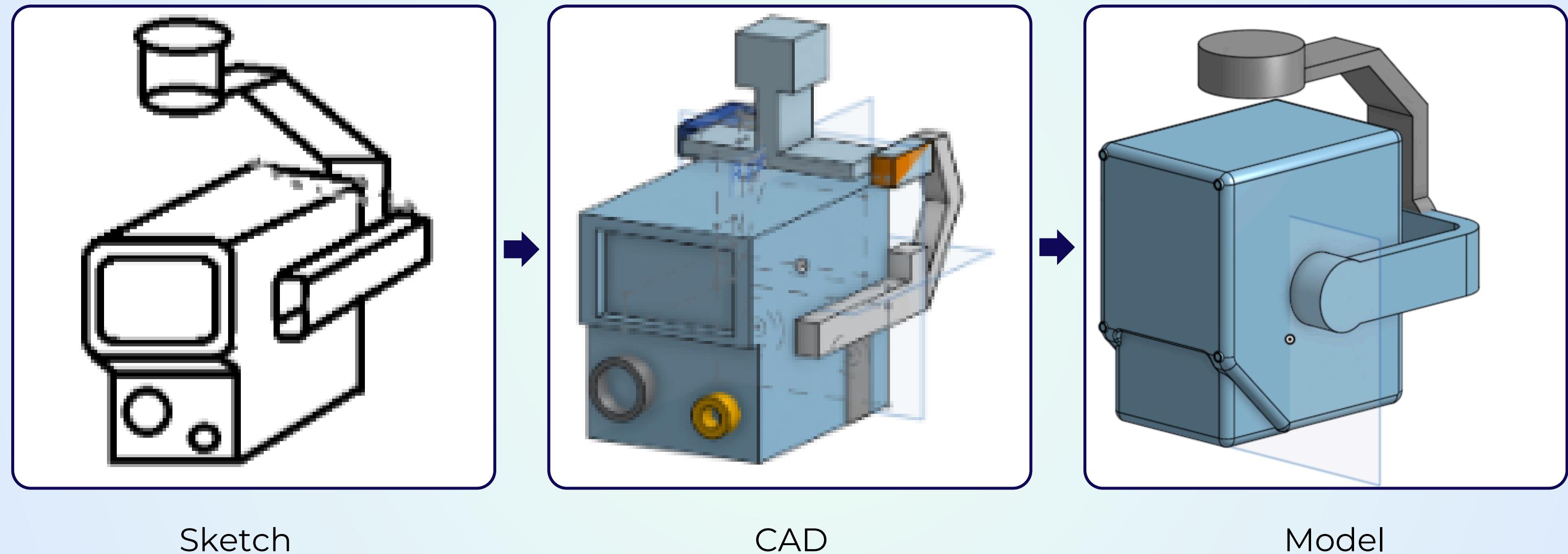
Variable Operation Rate
+ Risk Premium Charge

SUM UP TOTAL
COST



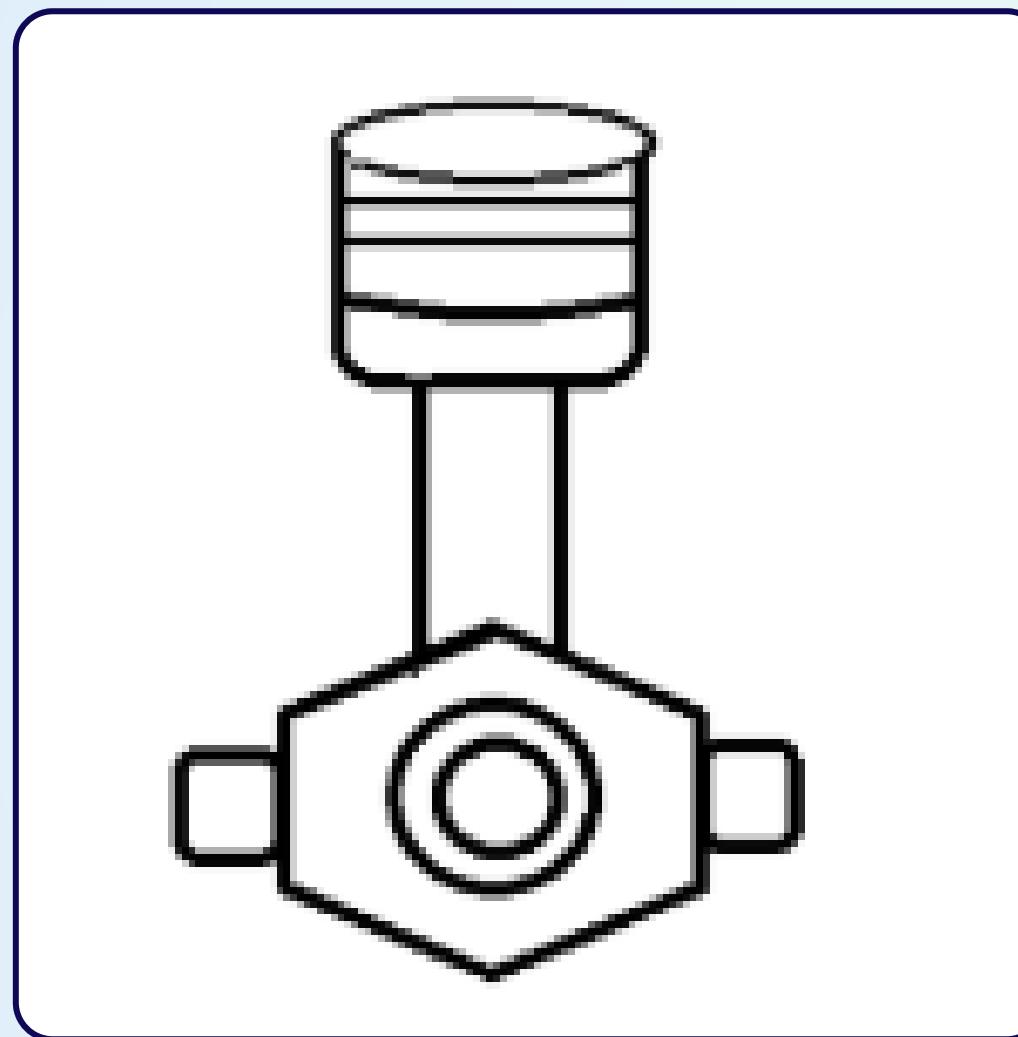
Inspection + Operation
Costs

Short Range LiDAR Camera Gimbal

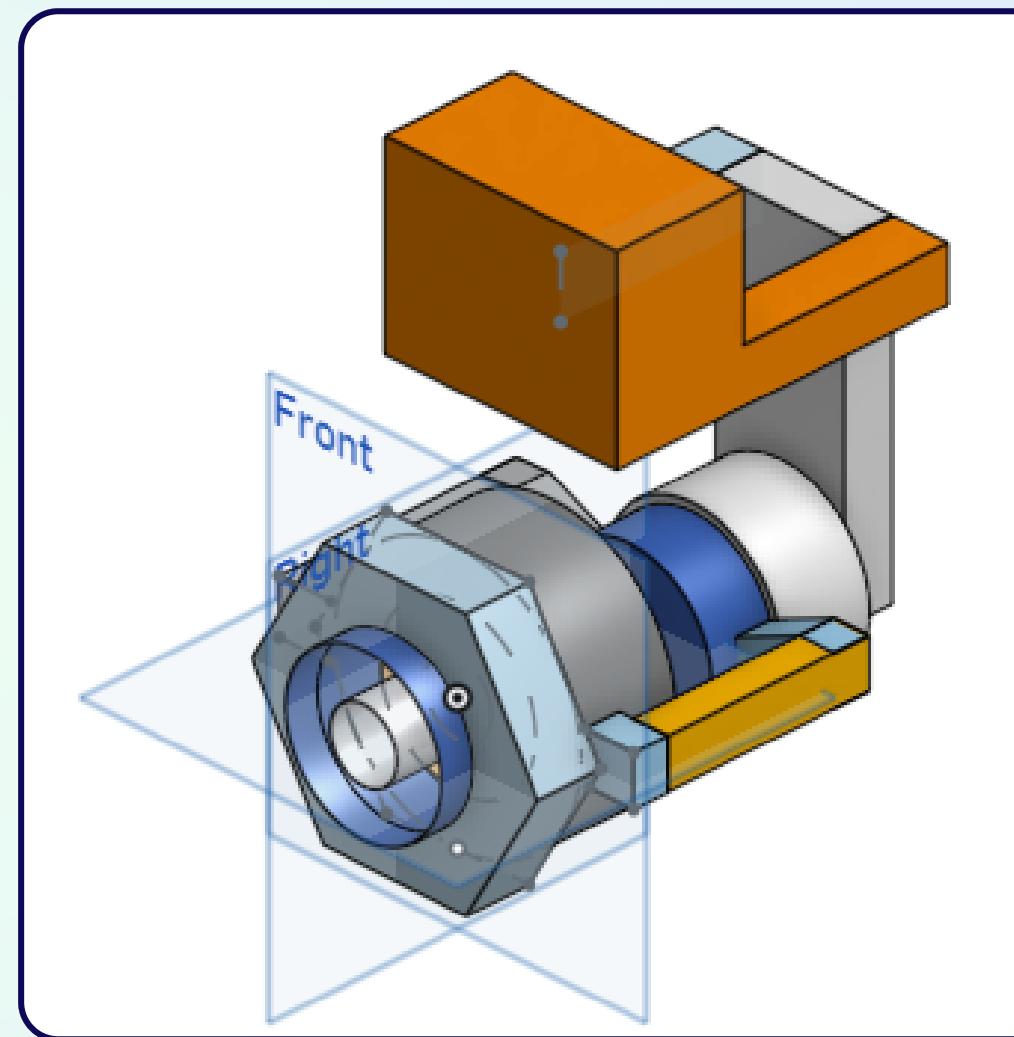
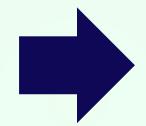


Increases the Short Range Gimbal Visibility Range, Terrain Input, and Calculation of Flight Accuracy

INFRARED CAMERA



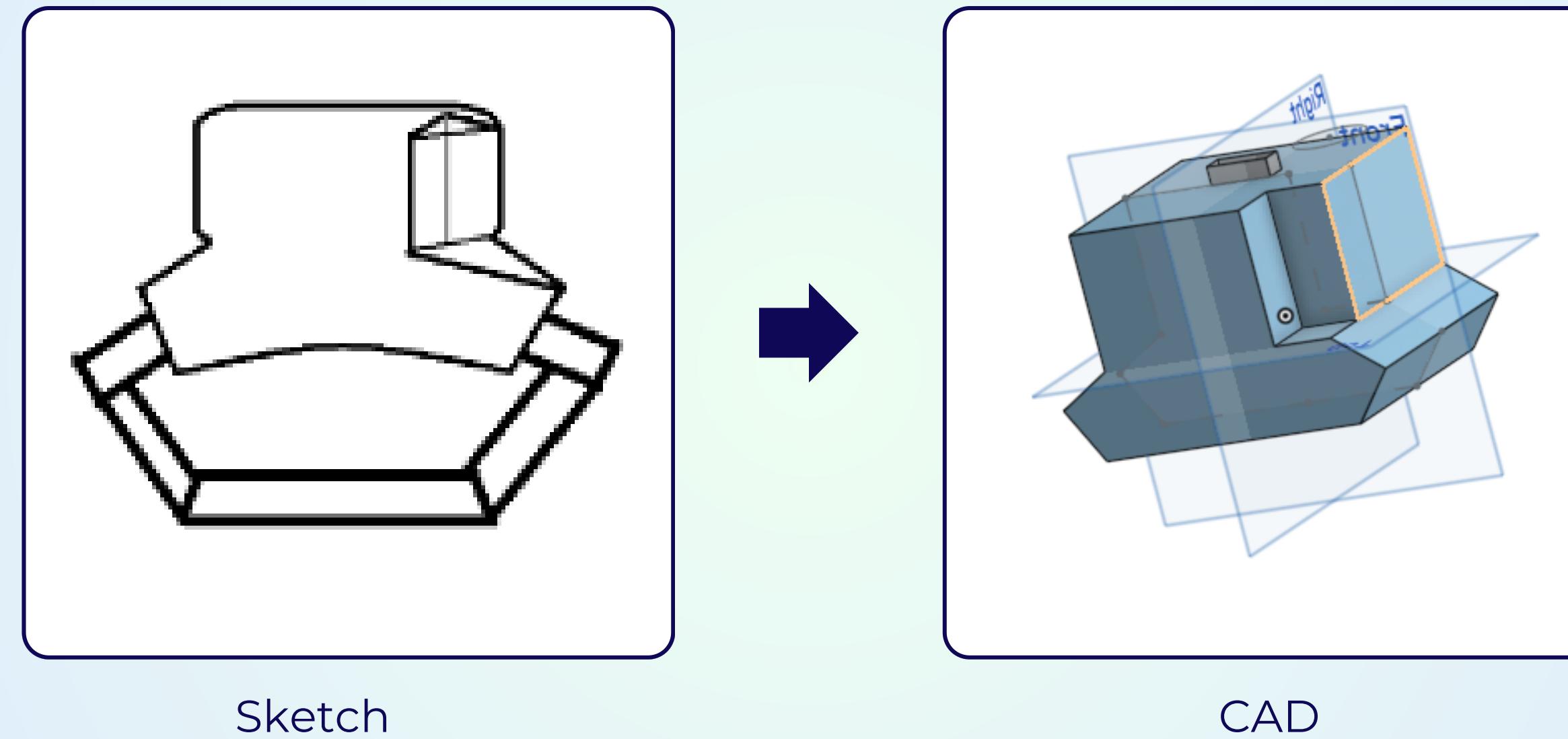
Sketch



CAD

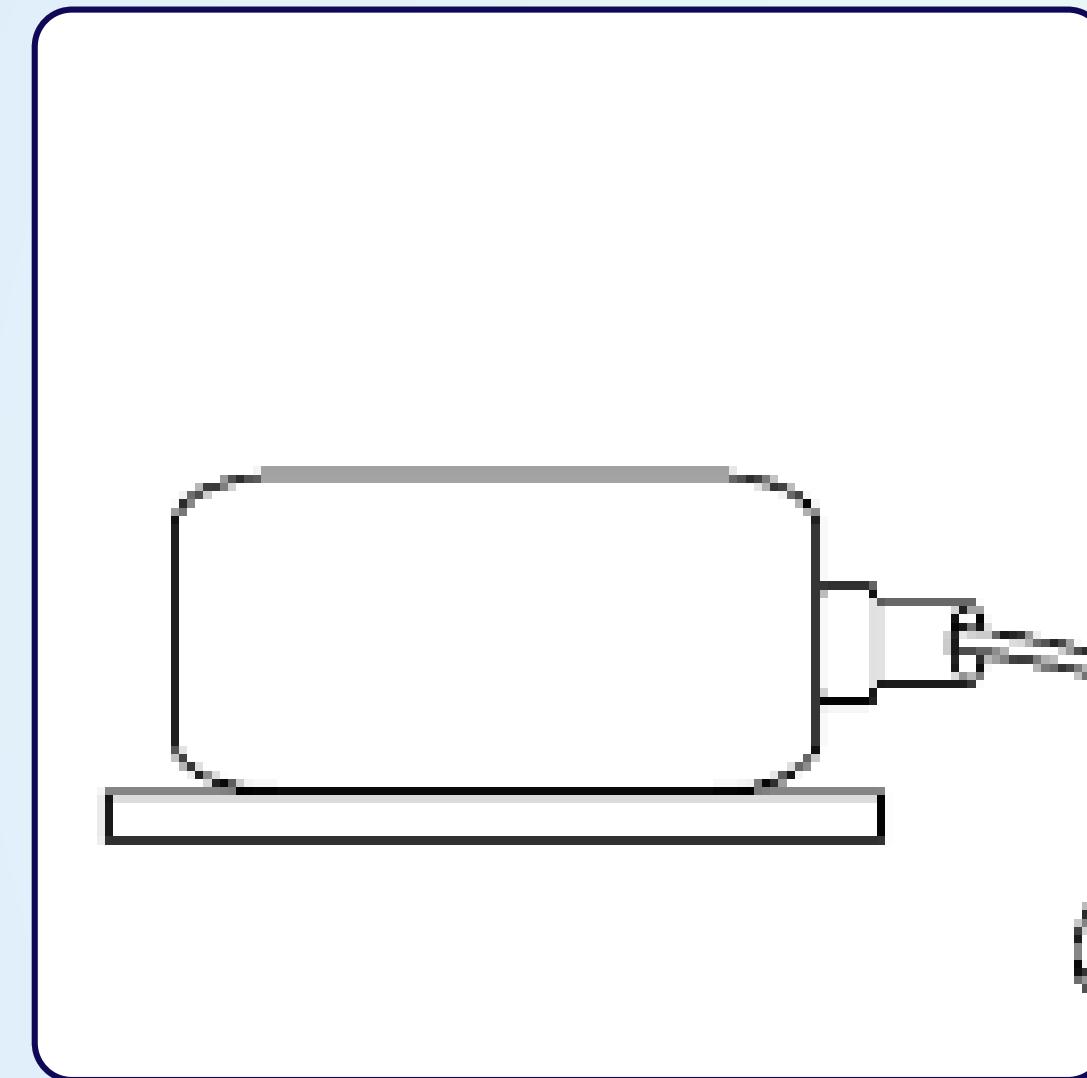
Scans Surrounding Shapes and Temperature Gauge for Greater Input and Calculation of Dangers, Increasing Safety for Drone Operation and Report Strategies.

PARACHUTE

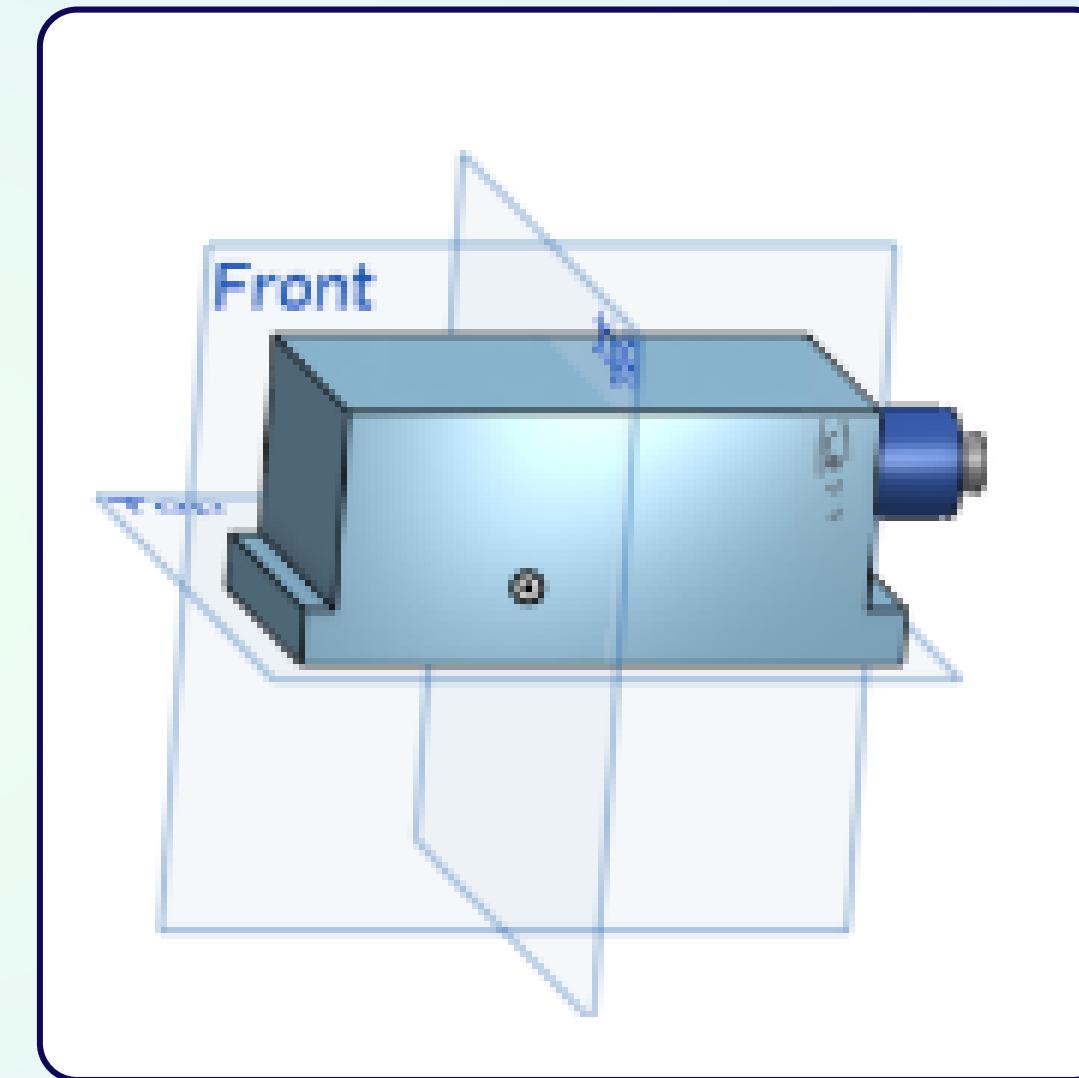
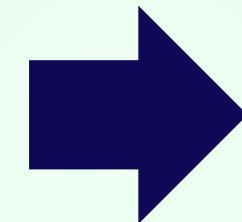


Aids Drone in Entry, Descent, Landing Protocols (EDL) to Increase Safety for Failure of Main Landing Components and Control

ACCELEROMETER



Sketch



CAD Prototype

Aids in Measurement of Real-Time Speed to Time for Greater Understanding of Remote Control and AI Assist