view_frames Result Recorded at time: 46.346 map Broadcaster: /amcl Average rate: 5.208 Hz Most recent transform: 46.649 (-0.303 sec old) Buffer length: 4.800 sec odom Broadcaster: /gazebo Average rate: 30.205 Hz Most recent transform: 46.345 (0.001 sec old) Buffer length: 4.966 sec base_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (46.346 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 30.199 Hz Average rate: 30.199 Hz Most recent transform: 0.000 (46.346 sec old) Most recent transform: 0.000 (46.346 sec old) Most recent transform: 0.000 (46.346 sec old) Most recent transform: 46.346 (0.000 sec old) Most recent transform: 46.346 (0.000 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.967 sec Buffer length: 4.967 sec wheel_right_link caster_back_link imu_link wheel_left_link base_scan