Getting Python To Learn From

Only Parts Of Your Data

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PyConTW 2013

Outline



- Introduction
- Model Selection And Cross Validation
- Model Assessment And The Bootstrap
- Conclusions

Prevalence Of Computing & Python -Two Implications

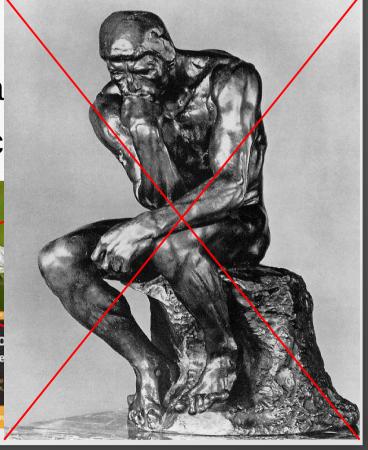
General computing:

- Tasks & calculations unlimited by human limitations

Python (& high-level languages):

 As time goes by...
 Low bar for new-area experimenta





Low Bar For Experimentation & Model Selection



Revenues seem inverse to clicks-to-purchase & page load time.

Cop we questify using CoiDy

Computing Power & Model Assessment

- (Another web devolunar avample)
- "The XYZ frame msec"



ts in under 2.5

1.71	2.55	12.23	3.42	2.58	0.03	2.46	0.01
2.56	1.17	1.46	1.22	1.51	3.6	1.9	23.99
1.12	2.73	2.21	1.81	2.22	2.73	2.63	8.13
2.23	0.00	2.0	2.34	3.2	1.9	3.4	

Without compute

tatistics

- With
$$4.63\bar{x}=\frac{1}{N}\sum_{i=1}^{N}[x_i], \quad \rho=\sqrt{\frac{1}{N}\sum_{i=1}^{N}[x_i-\bar{x}]}$$
n 1.89 and No nee

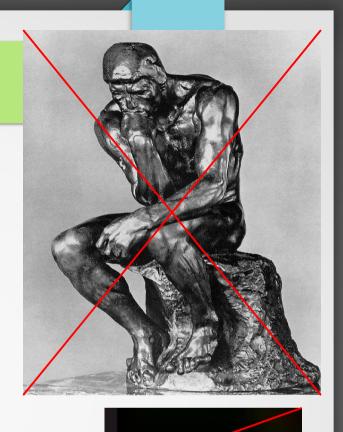
We can, e.g., assess the median and its confidence.

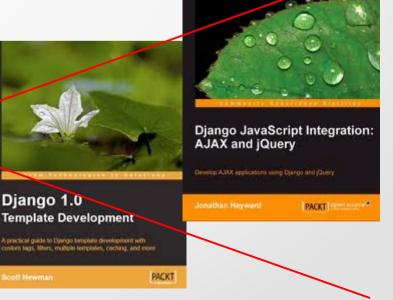
This Talk

Two problems, common solution:
 Getting Python To Learn From
 Only Parts Of Your Data

Talk will use:







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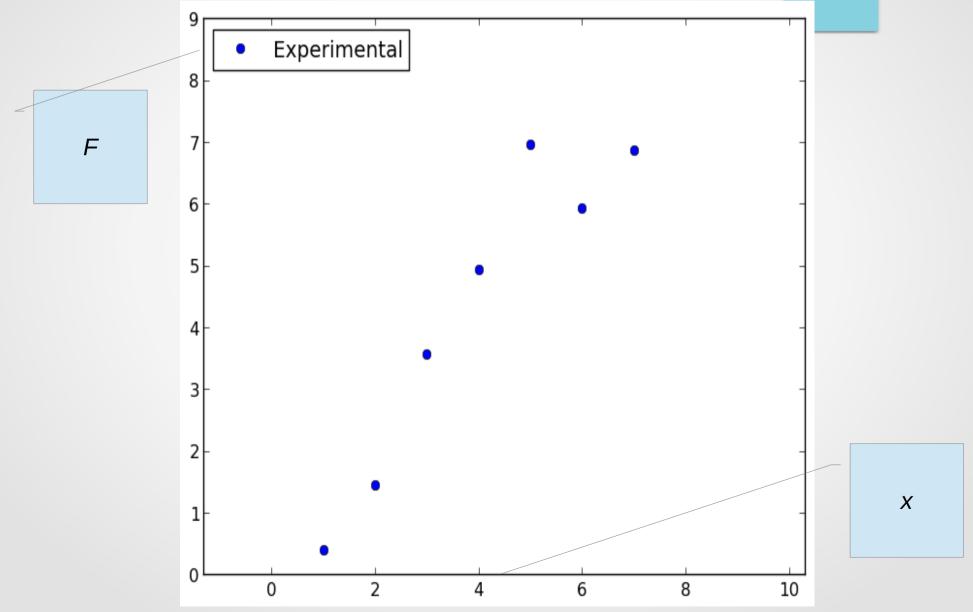


Example Domain – Hooke's Law

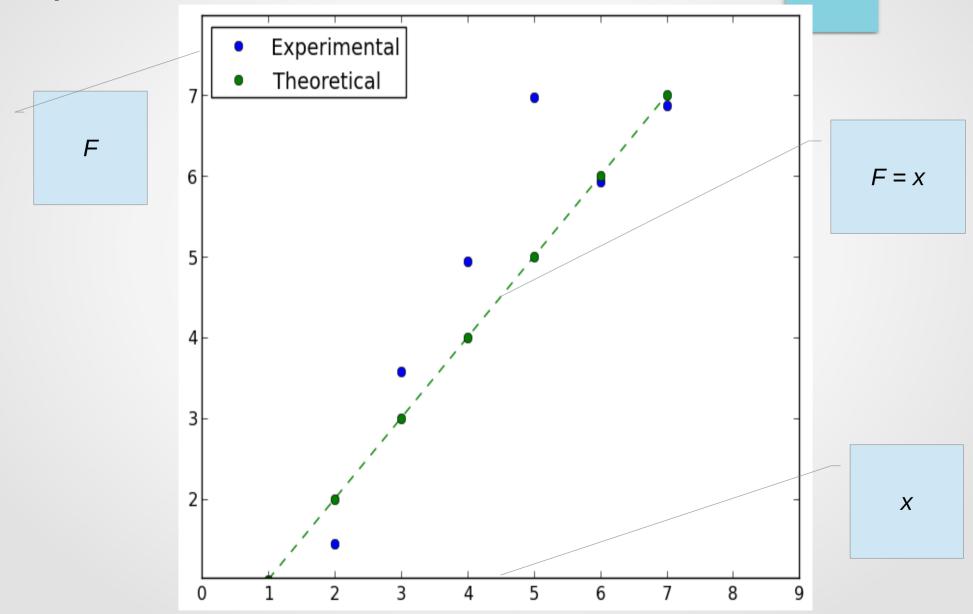
- Basic experiment with springs.
- Hooke's Law (Force proportional to displacement)

```
-F \sim x (F = force, x = displa ent
>>> from numpy import
>>> from sci py i mport *
>>> from mat plot lib. pyplot import
>>> # measure 8 displacements
>> x = arange(1, 8)
>>> # note measurement errors
>>> \overline{\Gamma} = x + 3 random randn(8)
                                    2x
>>>
>>> plot(x, F, 'bo', label = 'Experimental')
[<mat plot lib. lines. Line2D object at ♠x31c5f 90>]
>>> SIIOW )
```

Example Domain – Hooke's Law – Experiment Results



Example Domain – Hooke's Law – Experiment & Theoretical Results



Example Predictor – Polynomial Fitting

Polynomial fit (scipy.polyfit)

```
>>> help(polyfit)
polyfit(x, y, deg)
    Least squares polynomial fit.

Fit a polynomial ``p(x) = p[0] * x**deg + ... + p[deg]``
of degree `deg`
    to points `(x, y)`. Returns a vector of coefficients `p`
that minimises
    the squared error.
```

Example Predictor – Polynomial Fitting Applied

Polynomial fit (scipy.polyfit)

```
>>> x = arange(1, 8)

>>> F - x + 3 * random randn(8)

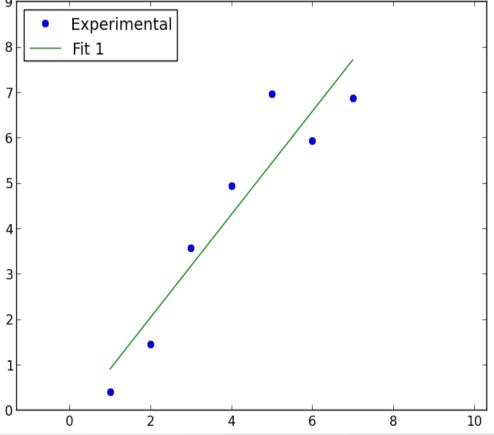
>>> # Fit the data to a

straight line.

>>> print polyfit(x, F, 1)

>>> [ 1.13 -0.23]

>>> # F ~ 1.13 * x - 0.23
```



The Problem – Which Model?

Polynomial fit (scipy.polyfit)

```
>>> x = arange(1, 8)

>>> F = x + 3 * random randn(8)

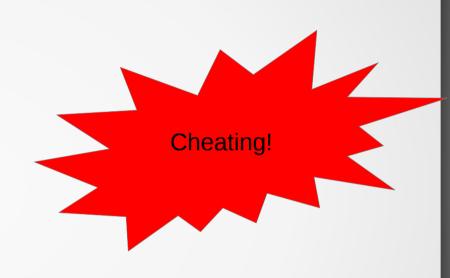
>>> # Fit the data to a

straight line

>>> print polyfit(x, F, 1)

>>> [ 1.13 -0.23]

>>> # F ~ 1.13 * x - 0.23
```



What Types Of Problems Are We Considering?

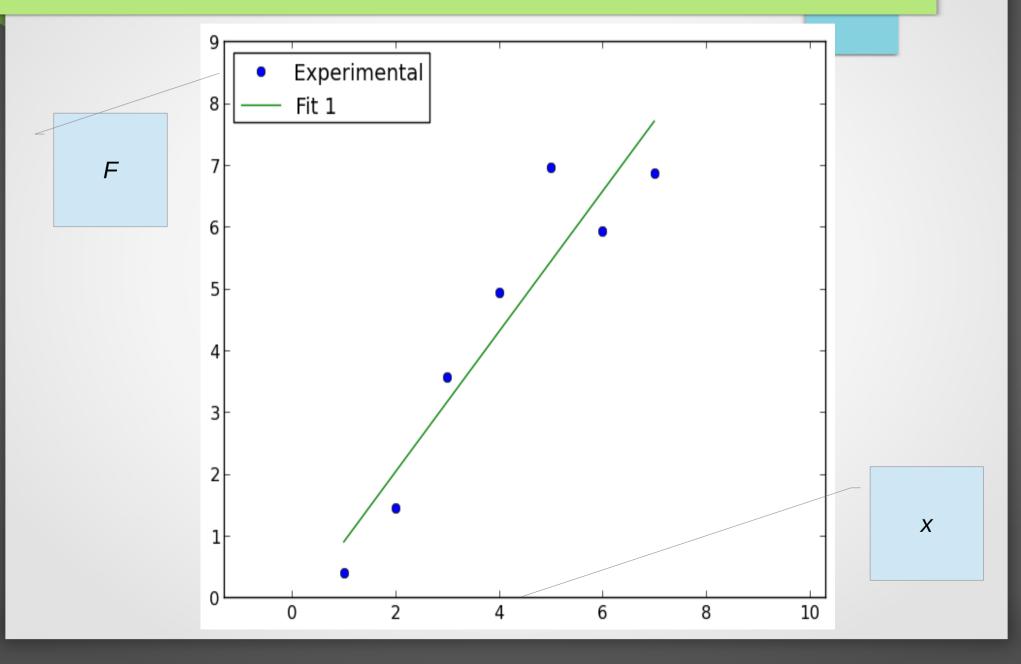
Find model relating # clicks + load time / revenue

The Problem – Alternatives?

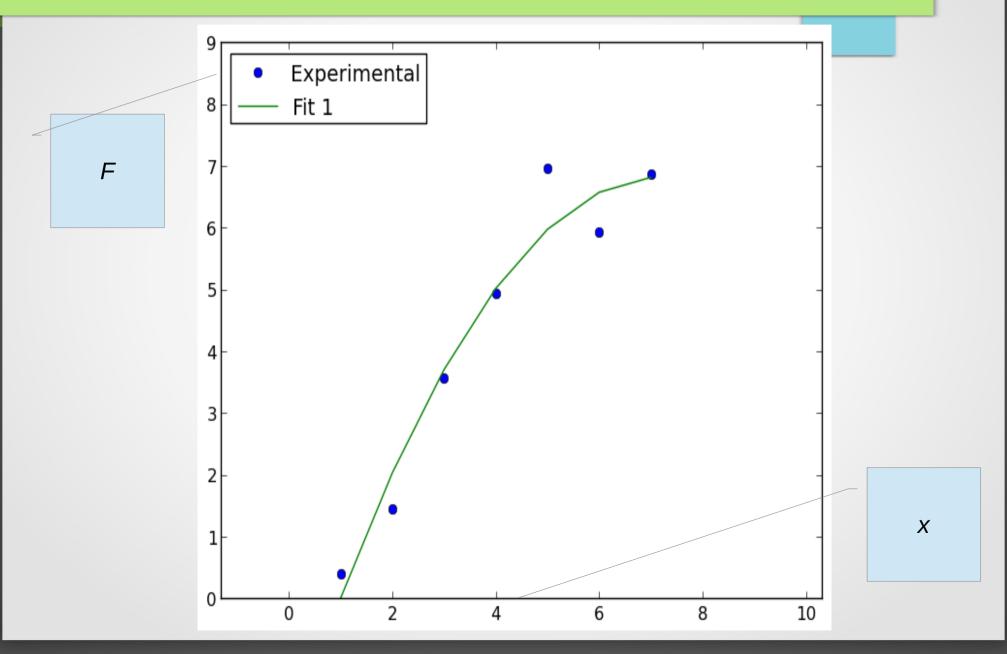
Polynomial fit (scipy.polyfit)

```
>>> x = arange(1, 8)
>>> F - y + 3 * random randn(8)
>>> # Fit the data to a
straight line
>>> print polyfit(x, F, 1)
>>> [ 1. 13 -0. 23]
>>> # F ~ 1. 13 * x - 0. 23 >>> x = arange(1, 8)
                            >>> F - x + 3 * random randn(8)
                            >>> # Fit the data to a parabola.
                            \Rightarrow print polyfit(x, F, 2)
                            >>> [ -0. 18 2. 56 -2. 38]
                            >> # F \sim -0 18 * \times 2 + 2 56 *
                           2.38 * x
```

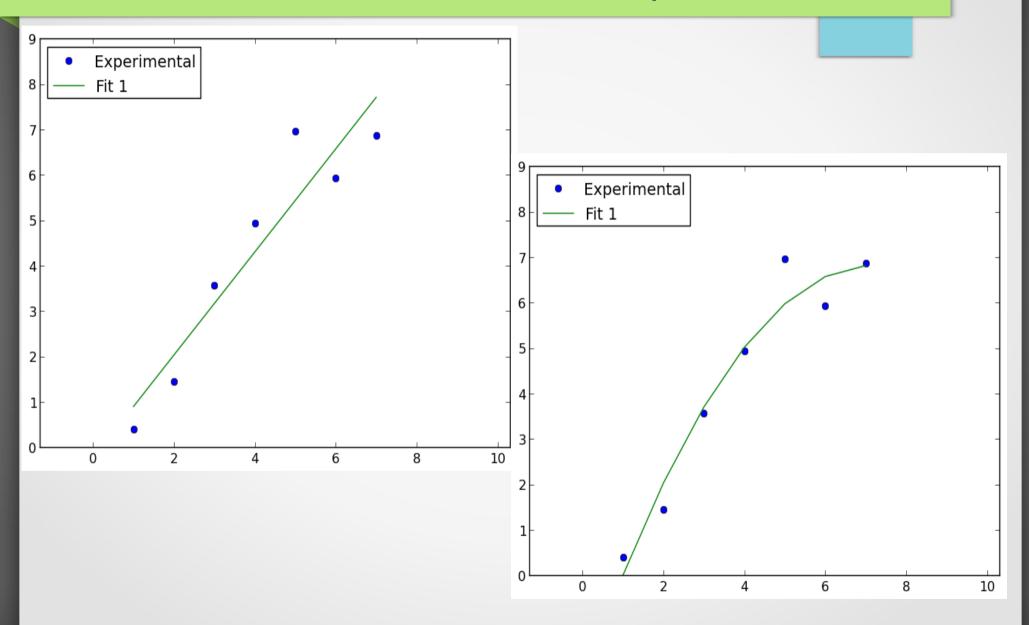
The Problem – Alternatives In Depth – Straight Line



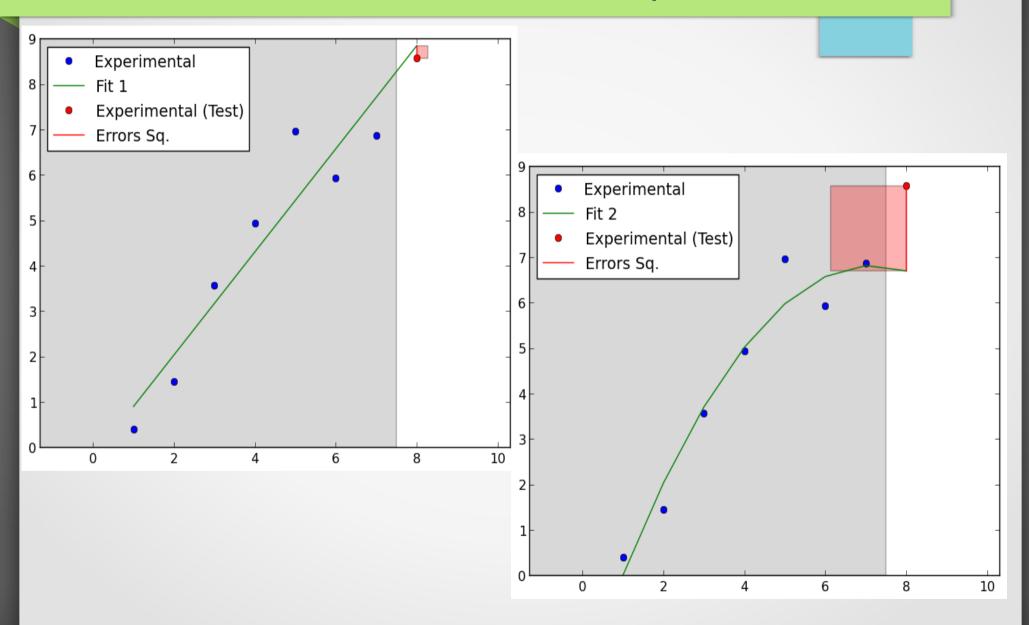
The Problem – Alternatives In Depth – Parabola



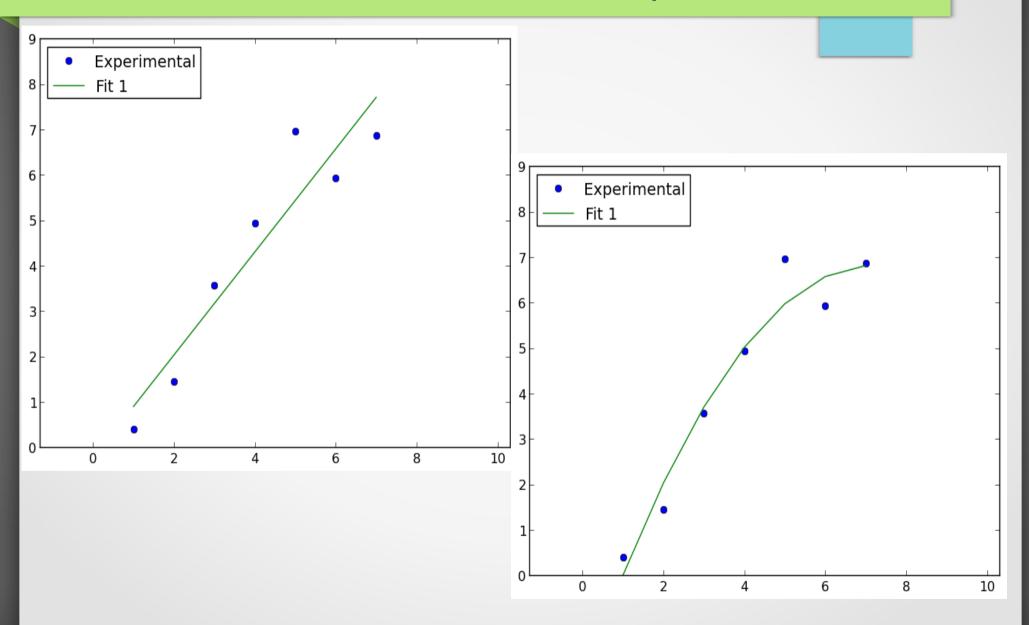
The Problem – Alternatives Comparison



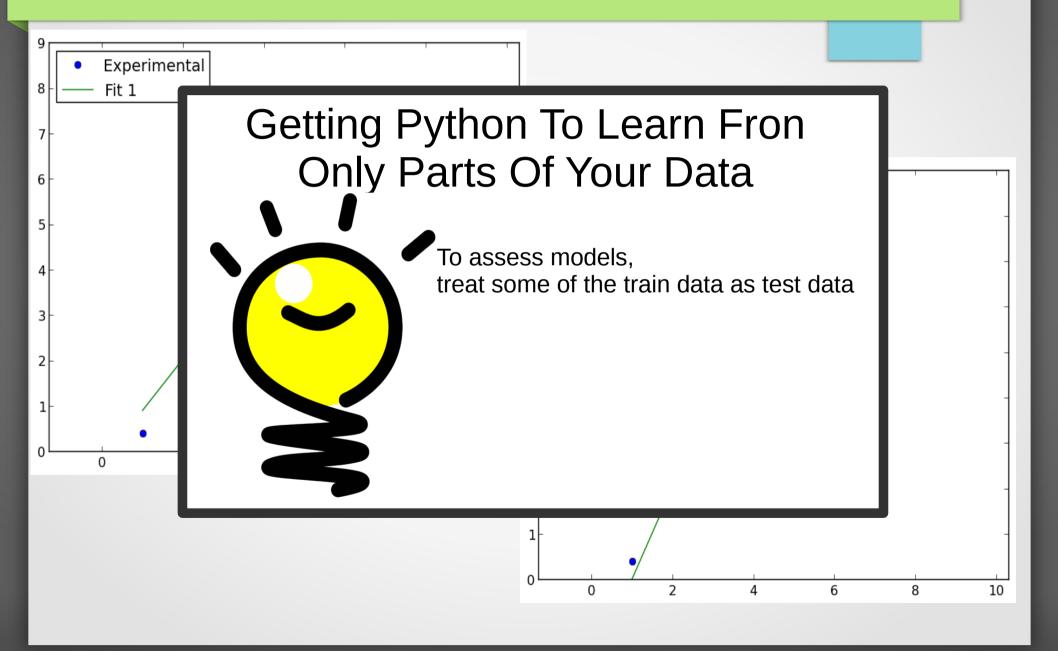
The Problem – Alternatives Comparison

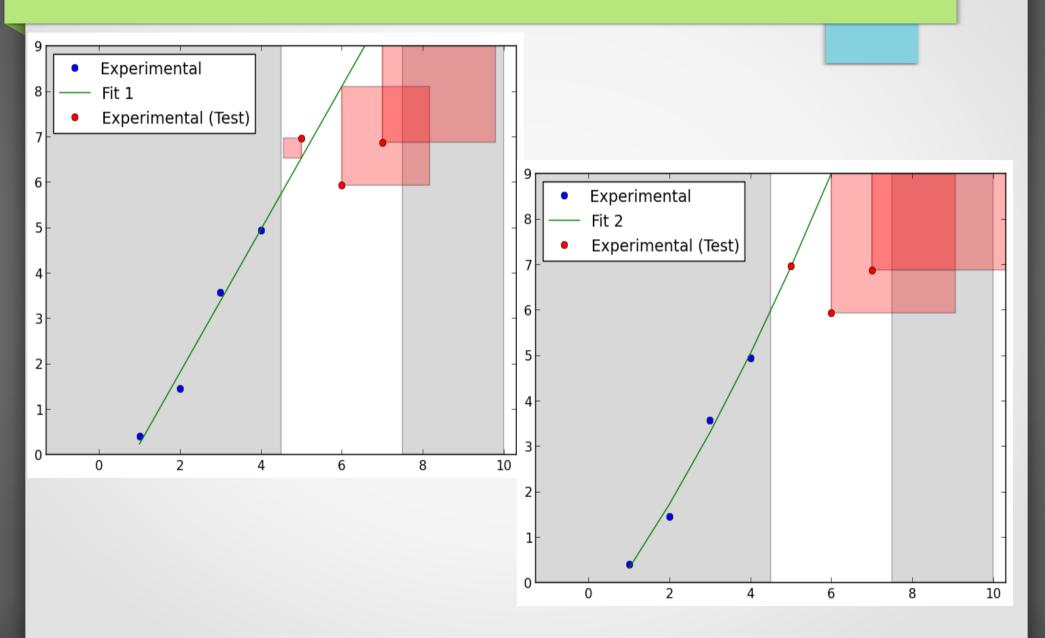


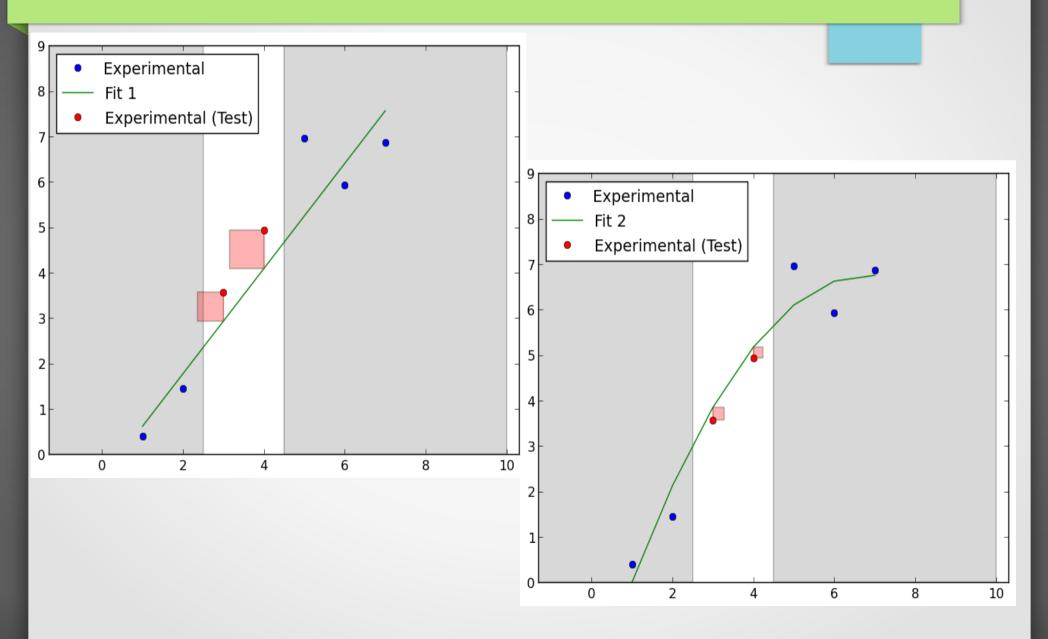
The Problem – Alternatives Comparison

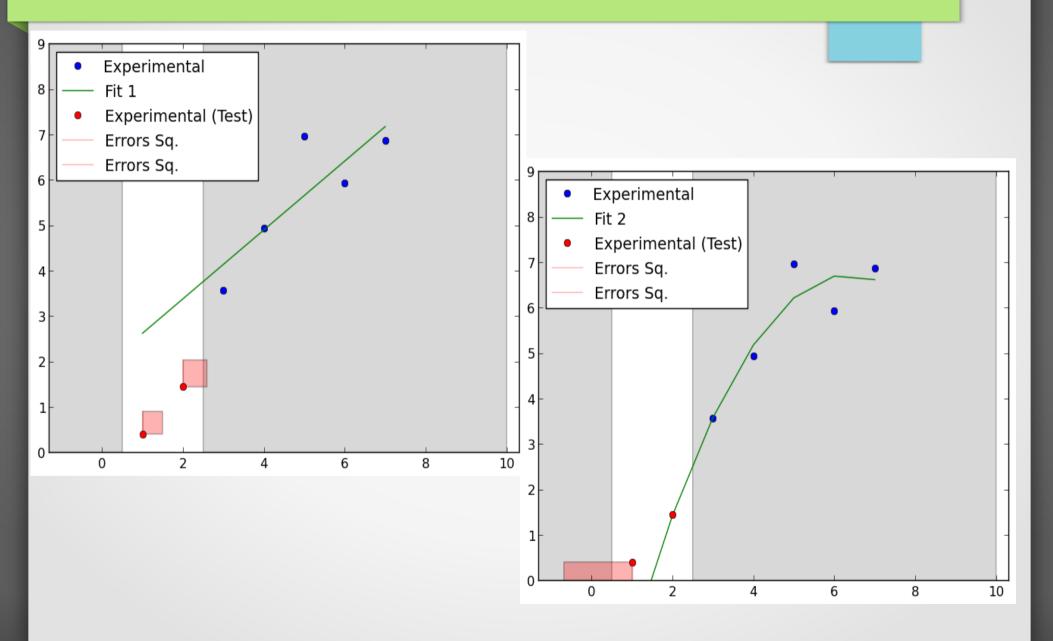


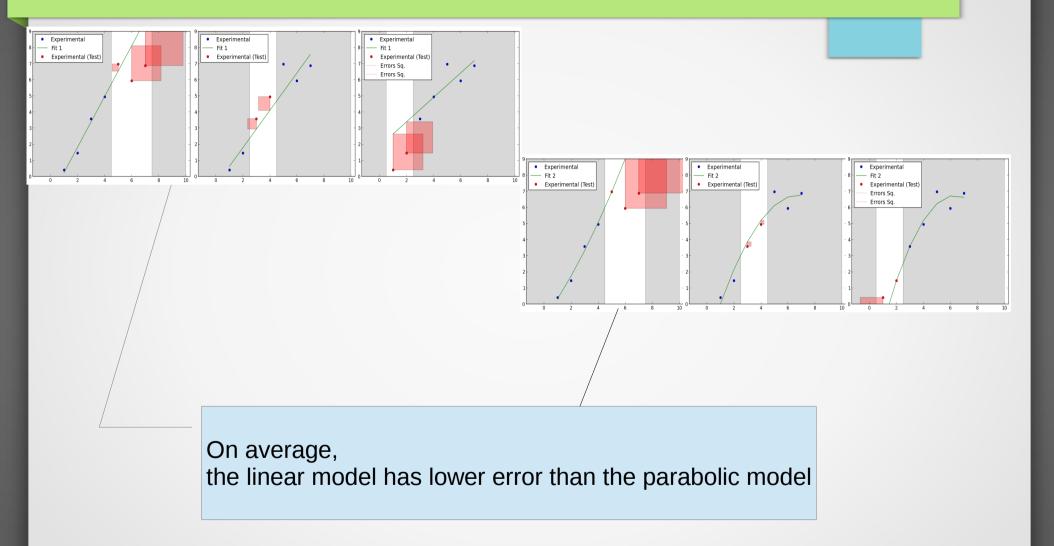
The Solution – Observation

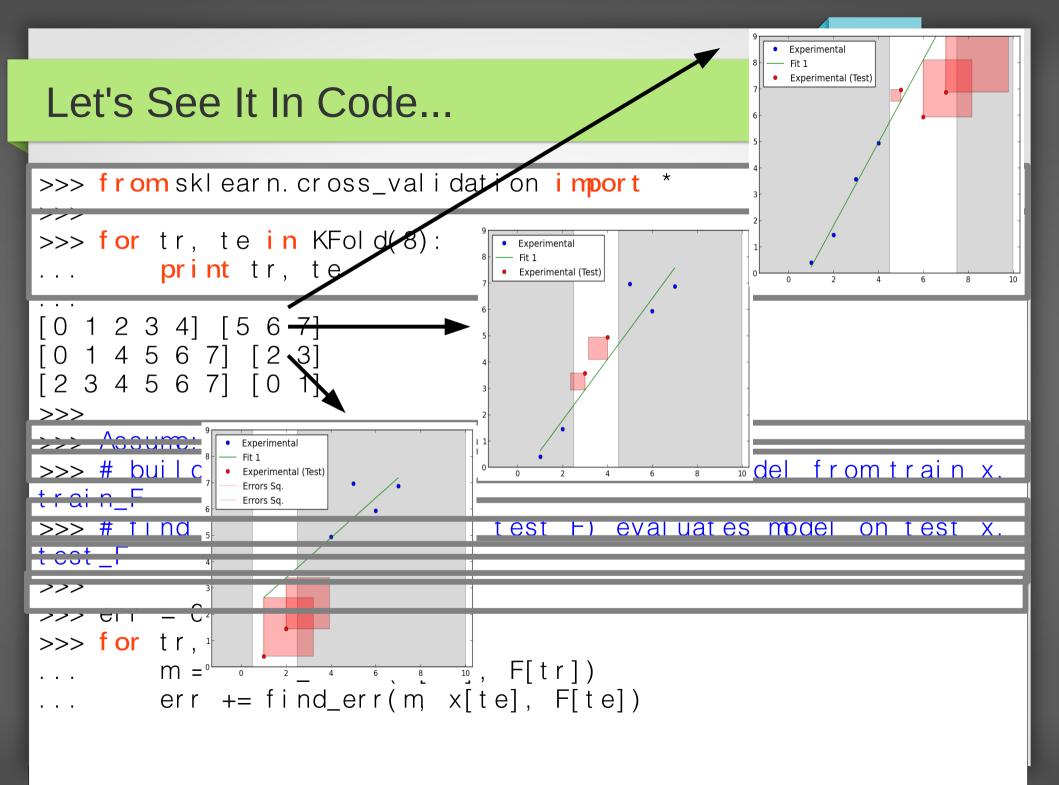










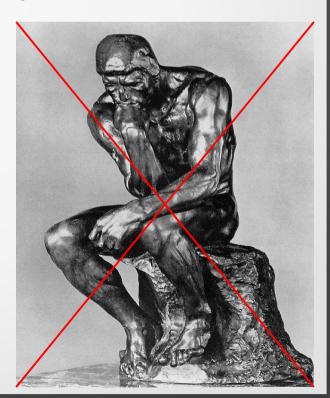


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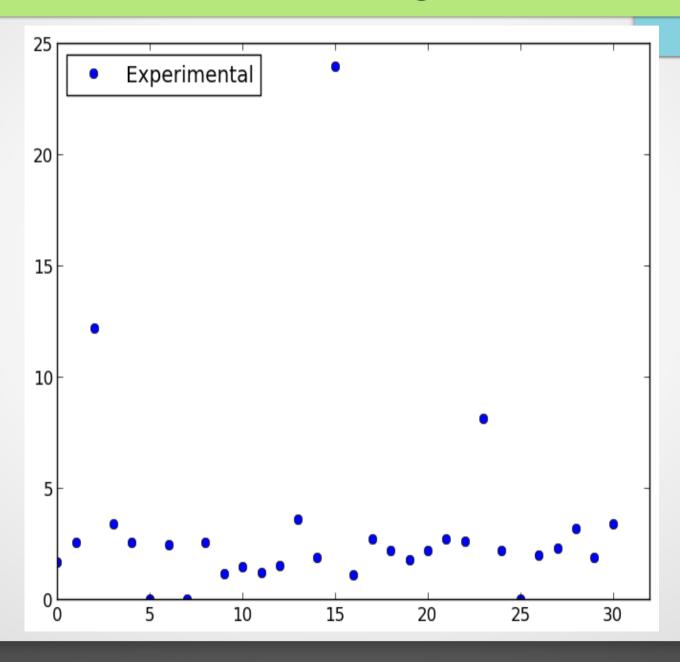
Example Domain – Processing Time

Transaction processing time (msecs.) of XYZ:

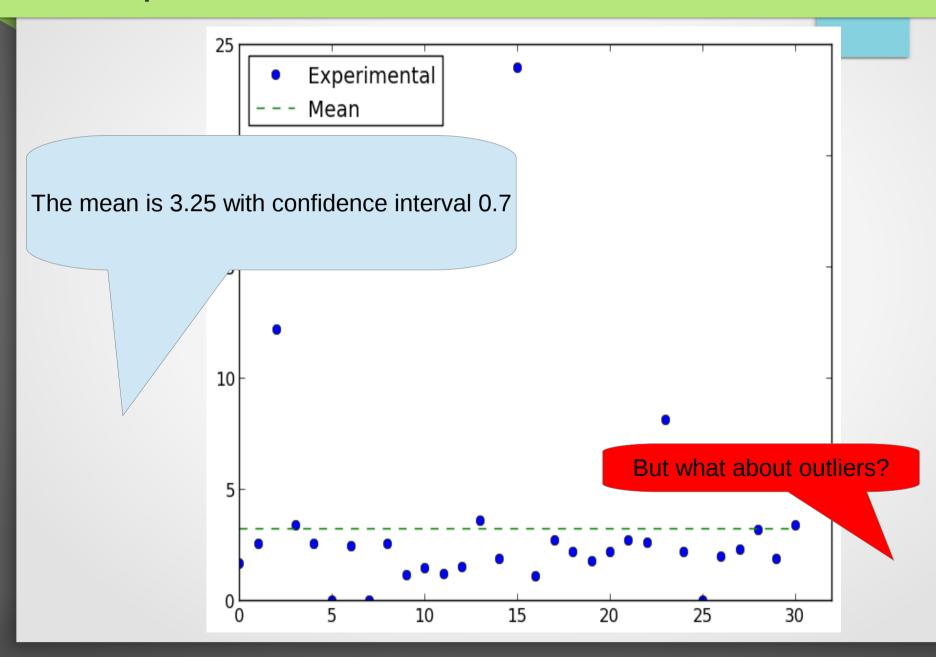
```
>>> t = [1.71, 2.55, 12.23, 3.42, 2.58, 0.03, 2.46, 0.01, 2.56, 1.17, 1.46, 1.22, 1.51, 3.6, 1.9, 23.99, 1.12, 2.73, 2.21, 1.81, 2.22, 2.73, 2.63, 8.13, 2.23, 0.00, 2.0, 2.34, 3.2, 1.9, 3.4]
```

What is the "typical" processing time?

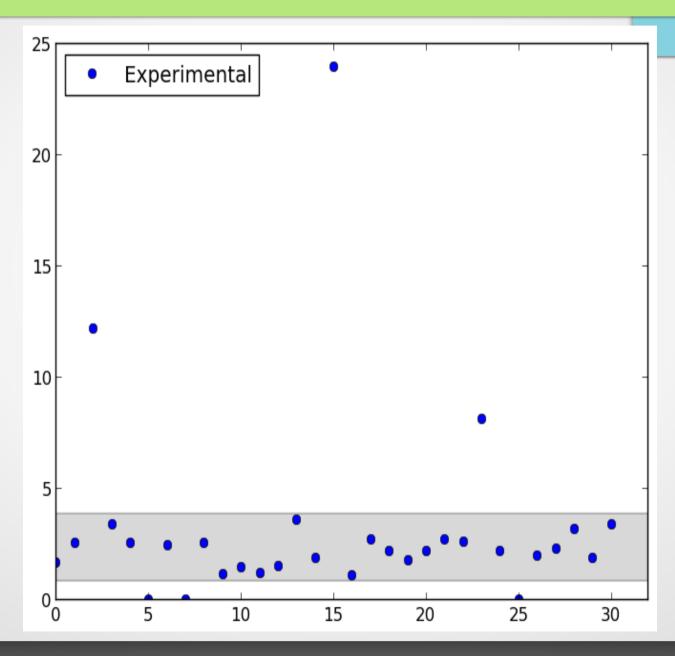
Example Domain – Processing Time



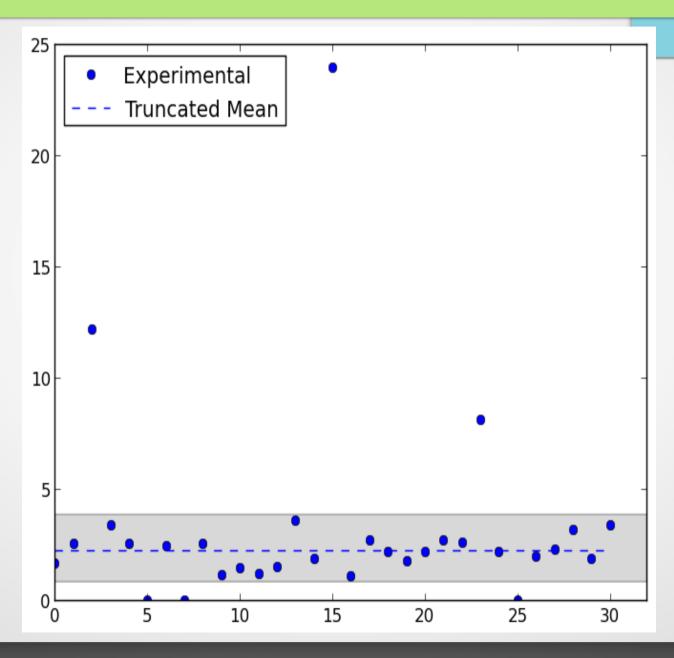
Example Domain And Model - Mean



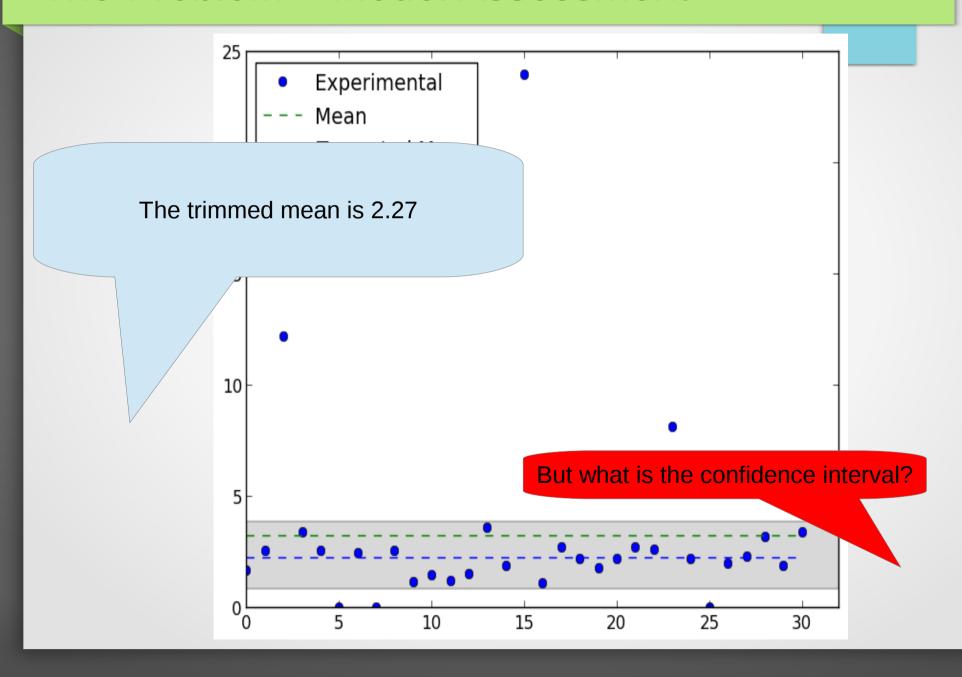
Example Domain And Model – Trimmed Mean



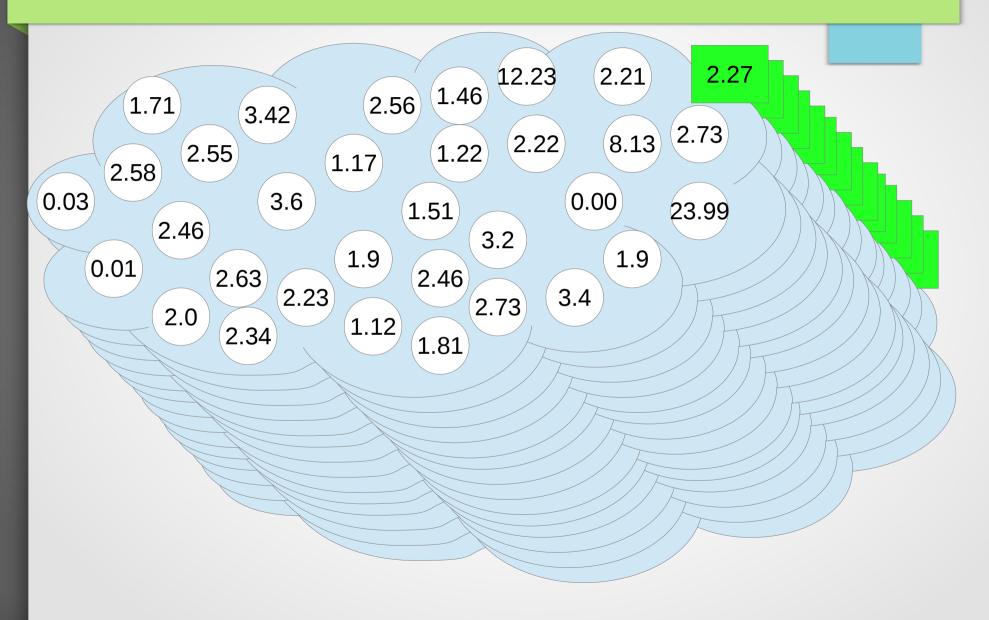
Example Domain And Model – Trimmed Mean



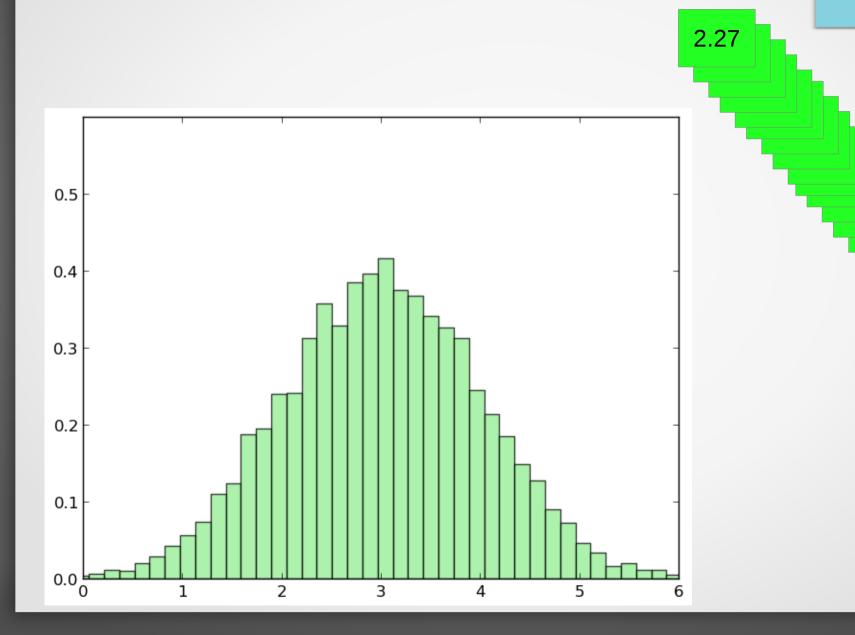
The Problem – Model Assessment



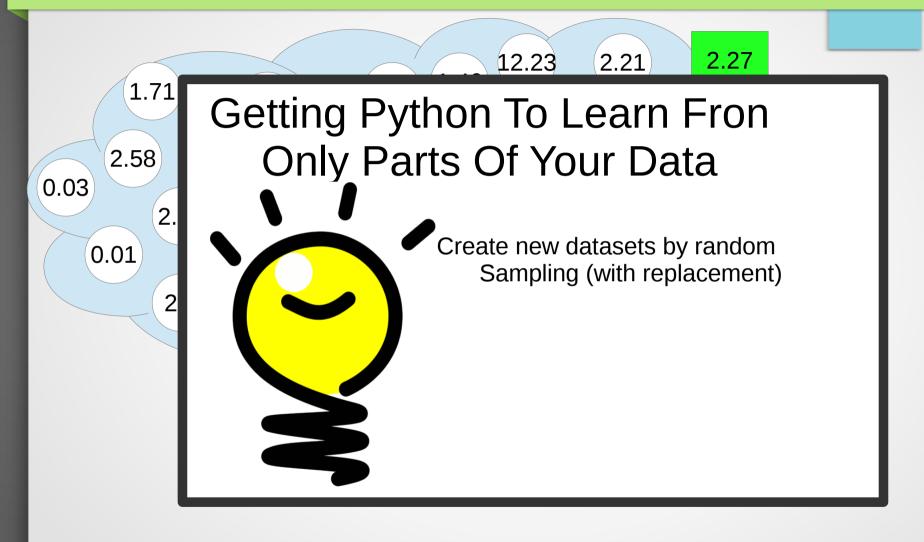
The Problem – Model Assessment



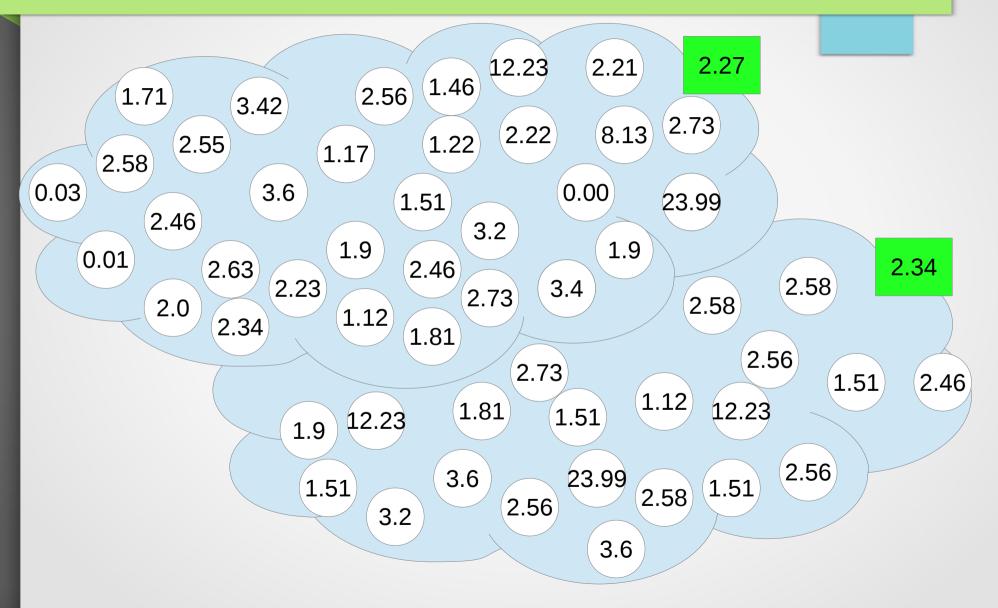
The Problem – Model Assessment



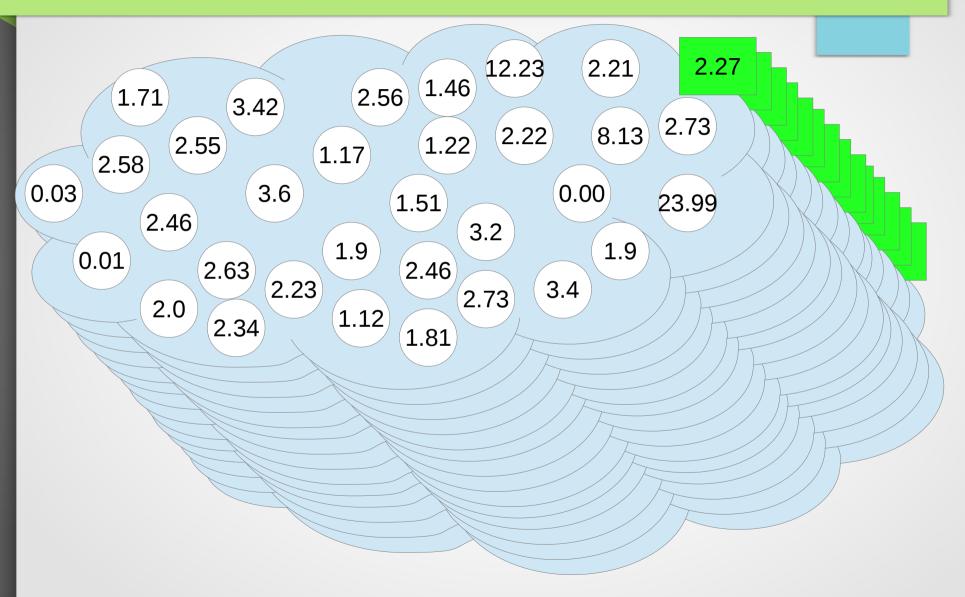
The Solution – Observation



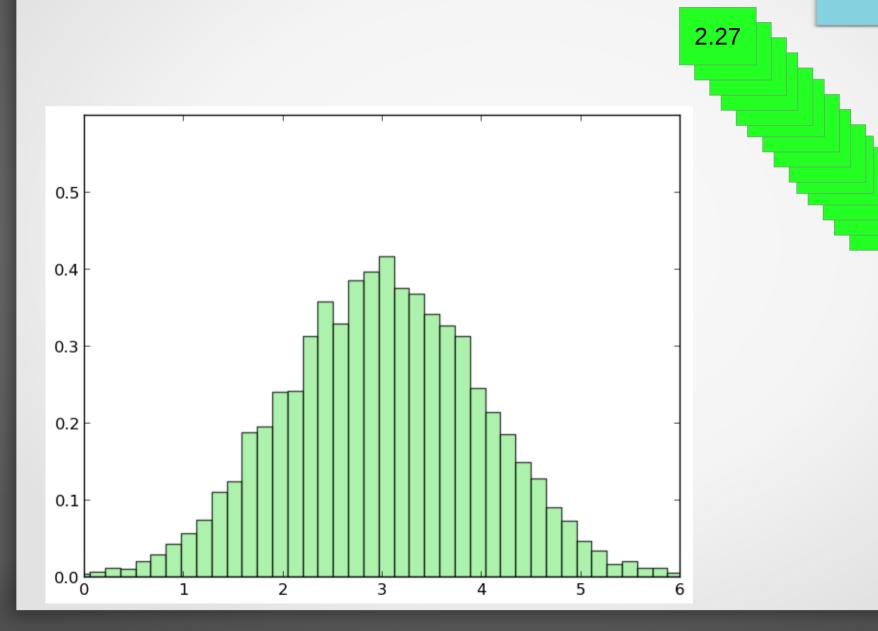
The Solution – Bootstrapping



The Solution – Bootstrapping



The Solution – Bootstrapping



Let's See It In Code...

```
>>> from sci py. stats. mstats i mport *
>>> from sci kits. bootstrap. bootstrap i mport *
>>> t = [1.71, 2.55, 12.23, 3.42, 2.58, 0.03, 2.46, 0.01, 2.56, 1.17, 1.46, 1.22, 1.51, 3.6, 1.9, 23.99, 1.12, 2.73, 2.21, 1.81, 2.22, 2.70, 2.63, 8.13, 2.20, 0.00, 2.0, 2.34, 3.2, 1.0, 3.4]
>>> print mean(t), trimmed_mean(t)
2.25067741025 2.2664
>>> print ci(t, trimmed_mean)
[ 1.7604 3.2816]
```

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Conclusions

Conclusions

- Computers & Python availability implies that:
 - We are faced with varied, configurable prediction techniques
 - We are unconstrained by pen-and-paper-only statistical methods

We can use Python's scientific libraries to ad



Thanks!

Thank you for your time!

