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Simple case that:

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- 3. Consider the fixed design nonparametric regression set up with observations $(x_1, Y_1), \ldots, (x_n, Y_n)$. Suppose further that the noise has constant variance, i.e. $\operatorname{Var}\{\epsilon_i\} = \sigma^2$. Both regressograms and Nadaraya-Watson kernel estimators are examples of *linear smoothers*. This means that the vector of predicted values $\hat{\mathbf{r}} = (\hat{r}_n(x_1), \ldots \hat{r}_n(x_n))$ is given by $\hat{\mathbf{r}} = \mathbf{L}\mathbf{y}$ where $\mathbf{y} = (Y_1, \ldots, Y_n)$. The training error can therefore be written as $\frac{1}{n} \|\mathbf{L}\mathbf{y} \mathbf{y}\|_2^2$. What is the expected training error (your answer may contain Trace(\mathbf{L}))? What is the average predictive risk, i.e. $\mathbb{E}\left\{\frac{1}{n} \|\mathbf{L}\mathbf{y} \mathbf{y}^*\|_2^2\right\}$ where $\mathbf{y}^* = (Y_1^*, \ldots, Y_n^*)$ are new observations at each x_i (your answer may contain Trace(\mathbf{L}))? The difference in the two values should be $2\sigma^2 \operatorname{Trace}(\mathbf{L})/n$. In other words, this is the amount by which the training error is overly optimistic. *Hint:* If M is any matrix, and ϵ a vector of independent random variables each with mean 0 and variance σ^2 , then $\mathbb{E}\{\epsilon^T M \epsilon\} = \operatorname{Trace}(M)\sigma^2$.

Model:
$$\widehat{y}_i = \widehat{\Gamma}(x_i) + \epsilon_i$$

expected training error,
$$\mathbb{E}_{\varepsilon} \left[\frac{1}{n} \| \left(\lfloor (\hat{r} + \varepsilon) - (\hat{r} + \varepsilon) \|_{2}^{2} \right) \right]$$

expected testing error, $\mathbb{E}_{\xi,\xi^*}\left[\frac{1}{n} \| L \cdot (\hat{\Gamma} + \xi) - (\hat{\Gamma} + \xi^*) \|_2^1\right]$