

MCMC → Markov Chain Monte Carlo

① Monte Carlo Algo ← Guarantee by $\begin{cases} \text{SLLN} \rightarrow \text{convergence guarantee} \\ \text{CLT} \rightarrow \text{convergence rate} \end{cases}$

a) SLLN X_1, \dots, X_n i.i.d distributed

$$\Rightarrow \frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{\text{a.s.}} \mathbb{E}[X]$$

⇒ If we want to calculate $\int_0^1 f(x) dx$

1. $X_i \sim \text{Uniform}(0,1)$

$$\text{then } \frac{1}{n} \sum_{i=1}^n f(X_i) \xrightarrow{\text{a.s.}} \mathbb{E}[f(X)] = \int_0^1 f(x) \cdot 1 dx$$

2. $X_i \sim \text{Some distribution } p(x)$

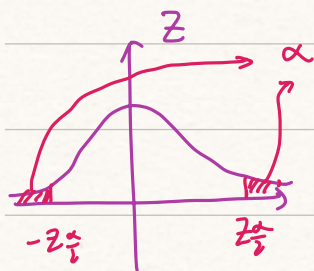
$$\text{then } \frac{1}{n} \sum_{i=1}^n \frac{f(X_i)}{p(X_i)} \xrightarrow{\text{a.s.}} \mathbb{E}\left[\frac{f(X)}{p(X)}\right] = \int_0^1 \frac{f(x)}{p(x)} dP(X \in \cdot) = \int_0^1 f(x) dx$$

b) CLT

denote

$$\boxed{f(x_i) \begin{cases} \mu \\ \sigma^2 \end{cases}}$$

$$\text{then } \frac{\sum_{i=1}^n f(x_i) - n\mu}{\sqrt{n\sigma^2}} \sim Z(0,1)$$



$$\frac{S_n - \mu}{\sqrt{\frac{\sigma^2}{n}}} \approx Z(0,1)$$

$$\Rightarrow \underline{P\left(S_n - \sqrt{\frac{\sigma^2}{n}} \cdot Z_{\frac{\alpha}{2}} \leq \mu \leq S_n + \sqrt{\frac{\sigma^2}{n}} \cdot Z_{\frac{\alpha}{2}}\right) = 1 - \alpha}$$

$$\Rightarrow \frac{\sum_{i=1}^n f(x_i)}{n} - \mu \approx \sqrt{\frac{\sigma^2}{n}} Z(0,1)$$

$\boxed{S_n}$

⇒ $\frac{1}{n} \sum f(x_i)$ converges to $\mathbb{E}[f(x)]$

with rate $\sqrt{\frac{1}{n}}$

⇒ interval length = $2\sqrt{\frac{\sigma^2}{n}} \cdot Z_{\frac{\alpha}{2}}$ will decrease at rate $\sqrt{\frac{1}{n}}$ for fixed confidence α

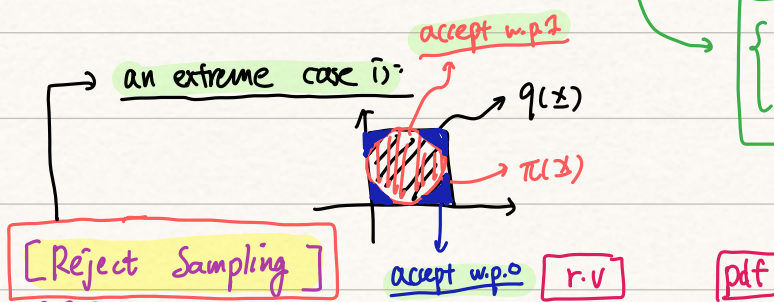
② Question: How to generate SAMPLE for a given $p(x)$?



a) inverse method b) reject sampling c) Box-Muller

Answer: for simple distribution $p(x)$, we can generate sampling!

(Example) Uniform \xrightarrow{a} Any distribution with closed form (computationally expensive)
 \xrightarrow{b} Any distribution with closed form (waste)
 \xrightarrow{c} Gaussian (directly from uniform sampling)



chi-square
t
F

☆

流程

- ① sample y_i from $q(\cdot)$
- ② sample u_i from $\text{Unif}(0,1)$
- ③ accept y_i
 $\Leftrightarrow u_i \leq \frac{\pi(y_i)}{M q(y_i)}$

we want to show: $p(x | \text{accept}) = \pi(x)$

$$① \quad p(x | \text{accept}) = \frac{p(x, \text{accept})}{\int p(x, \text{accept}) dx}$$

$$② \quad p(x, \text{accept}) = \int p(\text{accept} | x, u) \cdot p(u | x) \cdot q(x) du$$

$$= q(x) \cdot \int p(\text{accept} | x, u) p(u) du$$

$$p(\text{accept} | x, u) = \begin{cases} 1, & u \leq \frac{\pi(x)}{M q(x)} \\ 0, & \text{otherwise} \end{cases}$$

$$= q(x) \cdot \int_0^{\frac{\pi(x)}{M q(x)}} 1 du$$

$$= \frac{\pi(x)}{M}$$

$$③ \quad p(x | \text{accept}) = \frac{\frac{\pi(x)}{M}}{\frac{1}{M} \int \pi(x) dx} = \pi(x)$$

③ MCMC

1) Reject Sampling limits:

- for some high-dimension distribution, it is difficult to achieve $q(x)$ & M
 - waste samples which are rejected
 - but compared with Numerical Integration, Monte Carlo Integration works well in high-dimension cases
- ↑
need to solve

2) MC result

- recurrent MC, stationary measure uniquely exists [e.g.]
→ asymmetric random walk on \mathbb{Z}
 - transient MC, stationary measure is not unique
- * for irreducible, positive recurrent MC $\pi^n(x, y) \rightarrow P(X_n = y) \forall x$
 $P(X_n = y) \rightarrow \mu(y)$
- ** for irreducible, transient, null recurrent MC $\pi^n(x, y) \rightarrow 0$
 $P(X_n = y) \rightarrow 0$
- *** [Reversible Measure] (detailed balance condition)
- $$\mu(x) \pi(x, y) = \mu(y) \pi(y, x) \quad \text{if } \mu(\cdot), \pi(\cdot, \cdot) \text{ satisfy}$$

★ then $\mu(\cdot)$ must be a stationary measure

→ Our aim is to construct a MC with long-term probability $\mu(\cdot)$

- 1) irreducible, recurrent
- 2) $\pi(\cdot, \cdot)$ satisfy detailed balance condition for the given $\mu(\cdot)$.

⇒ then sample $X_1, \dots, X_N, \dots, X_{N+n}$ from MC

can be used as the sampling from $\mu(\cdot)$

3) M-H Algorithm (Metropolis-Hastings Algorithm)

irreducible ← origin trans accept → aperiodic

a) Construction: $\pi(x, y) = Q(x, y) \alpha(x, y)$

$$\mu(x) \pi(x, y) = \mu(y) \pi(y, x)$$

$$\Leftrightarrow \mu(x) Q(x, y) \alpha(x, y) = \mu(y) Q(y, x) \alpha(y, x)$$

$$\Leftrightarrow \begin{cases} \alpha(x, y) = Q(y, x) \cdot \mu(y) \cdot C \\ \alpha(y, x) = Q(x, y) \cdot \mu(x) \cdot C \end{cases} \quad (\text{natural choice}) \quad \forall C.$$

$$\Rightarrow \begin{cases} \alpha^*(x, y) = \min \left\{ 1, \frac{Q(y, x) \cdot \mu(y)}{Q(x, y) \cdot \mu(x)} \right\} \\ \alpha^*(y, x) = \min \left\{ \frac{Q(x, y) \cdot \mu(x)}{Q(y, x) \cdot \mu(y)}, 1 \right\} \end{cases} \quad (\text{maximize } \alpha(\cdot, \cdot))$$

b) limitation:

1) difficult to compute

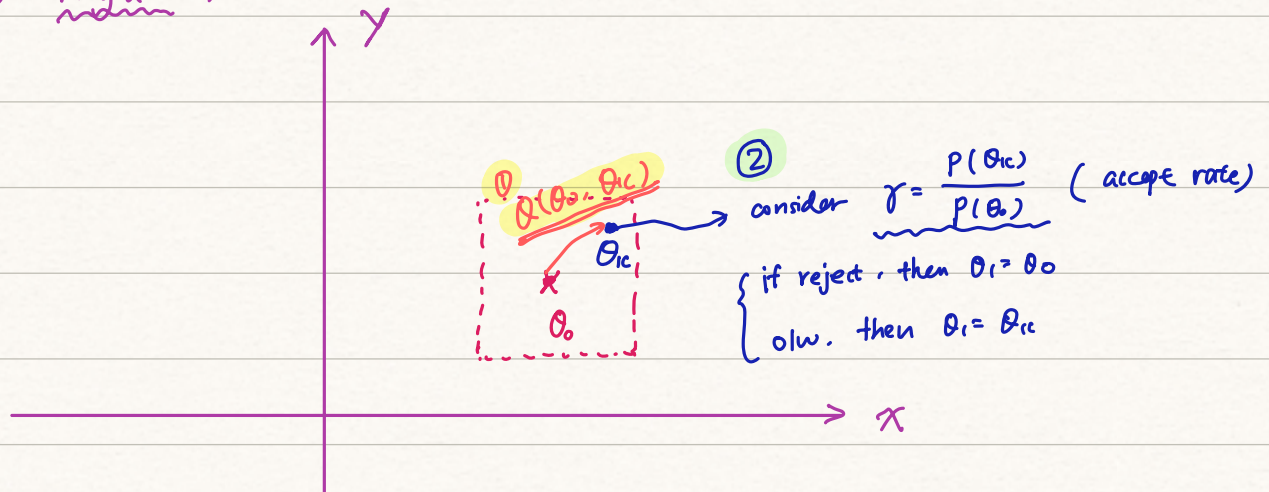
$$\frac{Q(y, x) \mu(y)}{Q(x, y) \mu(x)}$$

term when $\underline{x} \in \mathbb{R}^d$ d big

2) our interest may have good form of $\underline{p}(X_t | X_{-t})$

conditional probability given other coordinates

c) Diagram:



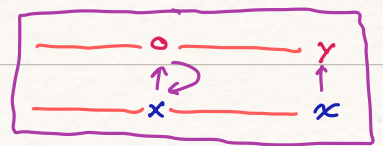
focus on high-dimension case

4) Gibbs Sampling

① idea: a) conditional probability can be easier to deal with

b) still use $\mu(x) \pi(x, y) = \mu(y) \pi(y, x)$

$$Q(x, y) \propto \alpha(x, y)$$



② Formulation

$$\underline{x} = (x^1, \dots, x^d)$$

$$\underline{x}_n = (x_n^1, \dots, x_n^d)$$

choose $\pi(\underline{x}, \underline{y}) = \frac{1}{d} \mu_{\underline{x}^i | \underline{x}^{-i}}(y^i | \underline{x}^{-i})$

$$\underline{x} = (x^1, \dots, x^d)$$

$$\underline{y} = (y^1, \dots, y^d)$$

where there exists $i \in [d]$ st

$x^i \neq y^i$, and others all the same

$$\frac{\mu(y)}{\sum_{x' \in \mathcal{X}} \mu(x')}$$

obviously, $\mu(x) \pi(x, y) = \mu(y) \pi(y, x)$

Note this can be viewed as the special case of M-H Algo:

Recall: M-H Algo: $\pi(x, y) = Q(x, y) \alpha(x, y)$

$$\alpha(x, y) = \min \left\{ \frac{\mu(y) Q(y, x)}{\mu(x) Q(x, y)}, 1 \right\}$$

Here, $Q(x, y) = \frac{1}{d} \mu_{\underline{x}^i | \underline{x}^{-i}}(y^i | \underline{x}^{-i})$

and $\mu(y) Q(y, x) = \mu(x) Q(x, y) \Rightarrow \alpha(x, y) \equiv 1 \quad \forall x, y$

③ Diagram

