



Power-Aware Training for Energy-Efficient Printed Neuromorphic Circuits

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Outline

- Printed Electronics
- Printed Neuromorphic Circuit
- Power-Aware Training
- Experiment
- Conclusions

The Cliché vs Computational Deserts



high performance
resource-intensive
general purpose



simple tasks
resource-limited
tailored functionality
disposable,
flexible,
degradable...

Cost Wall

Electronics



Java Card: €0.20



Microcontroller: €0.35



RFID Tag: €0.15



Applications

Milk Carton: €0.01



Adhesive Bandage: €0.02

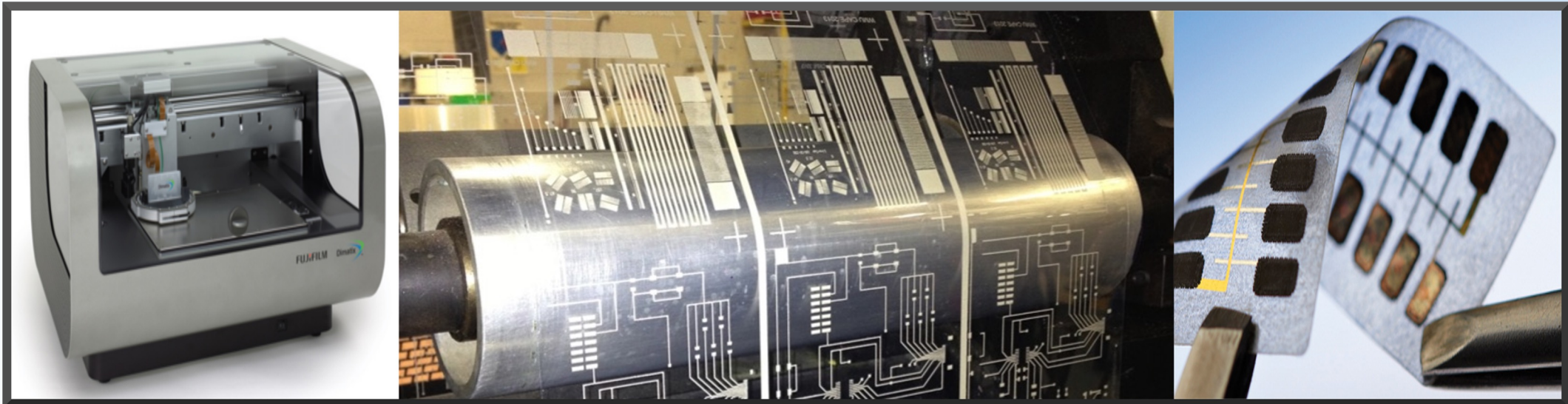


Packaging Label: €0.02

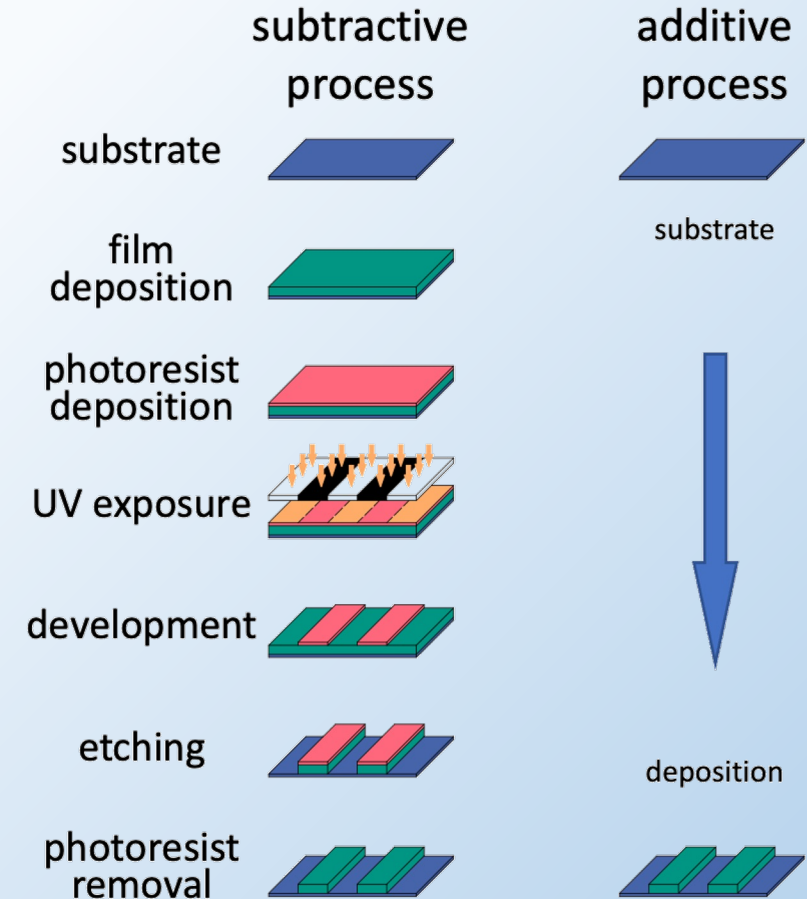
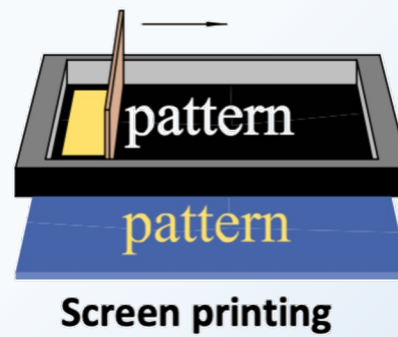
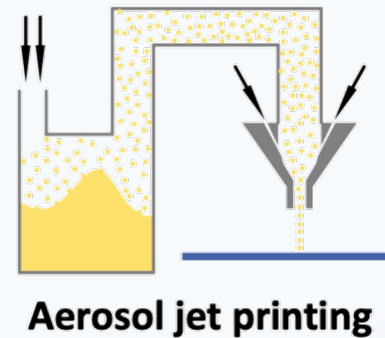
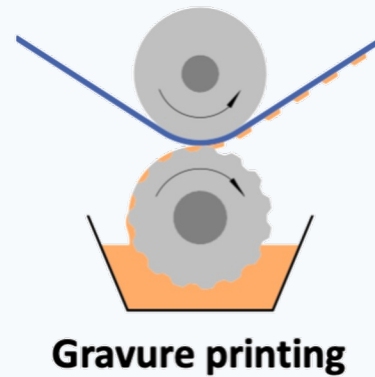
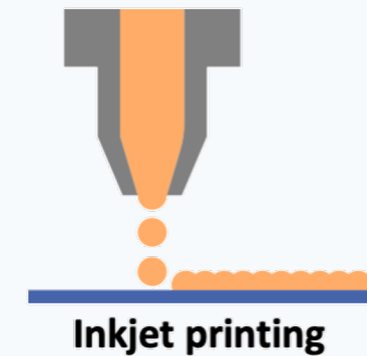


Additive Printed Technologies

- Maskless, fully additive processes
- Flexible, stretchable, and porous substrates
- Non-toxic, bio-compatible inks and substrates

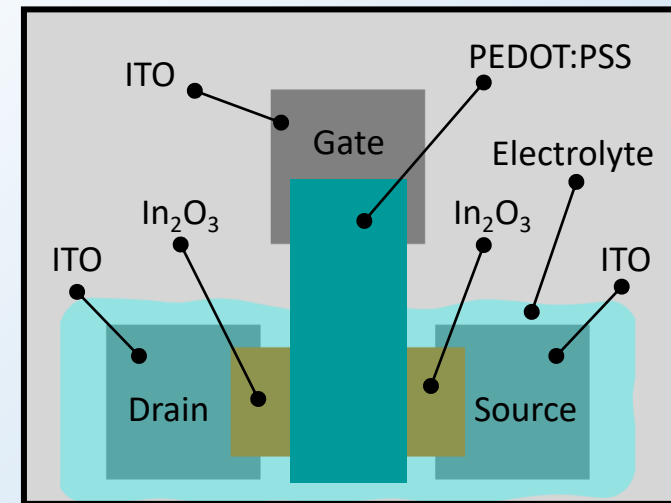


Printed Electronics Technology

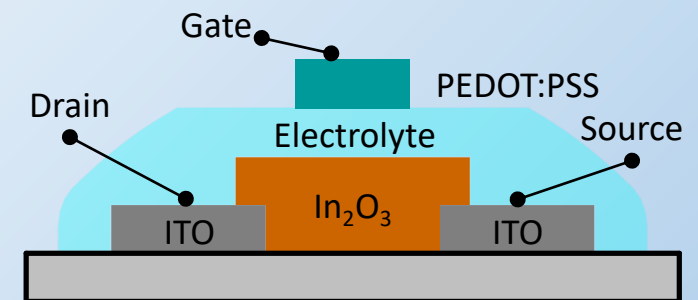


Electrolyte-Gated Transistor (EGT)

- Thin-film transistor
 - Signal routing: indium tin oxide (ITO)
 - Semiconductor: indium oxide (In_2O_3)
 - Gate insulator: composite solid polymer electrolyte
 - Top gate: PEDOT:PSS
- Voltage levels: $\leq 1.5 \text{ V}$, $\approx 100 \mu\text{A} - 1 \text{ mA}$
- Frequency range: $100 \text{ Hz} - 1 \text{ kHz}$

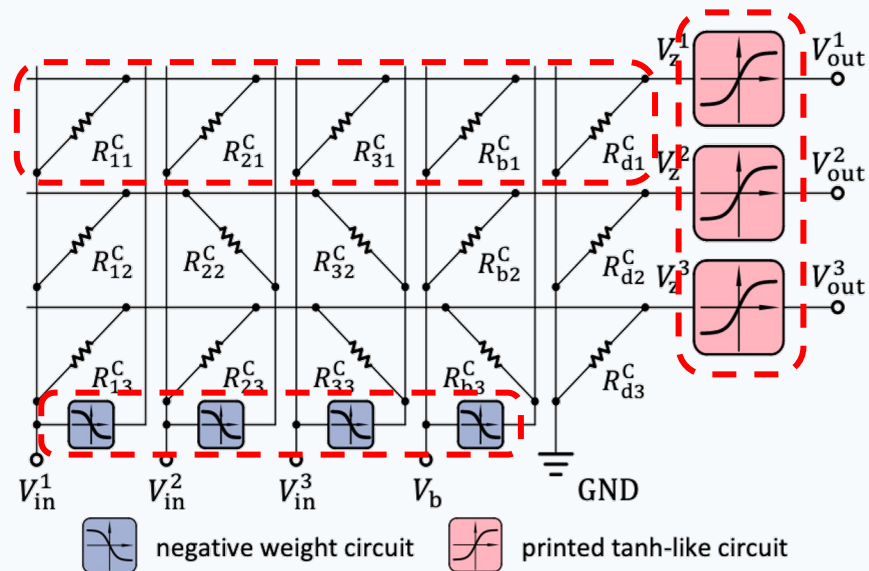


(a) top view of nEGT



(b) front view of nEGT

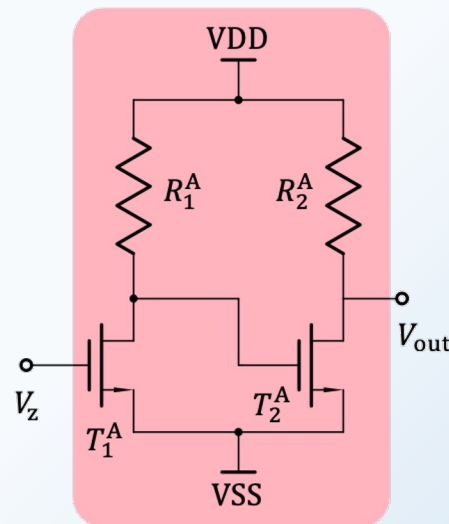
Printed Neuromorphic Circuit



(a) Exemplary printed neuron

$$V_z^1 = \frac{g_{11}}{G_1} V_{in}^1 + \frac{g_{21}}{G_1} V_{in}^2 + \frac{g_{31}}{G_1} V_{in}^3 + \frac{g_{b1}}{G_1} V_b$$

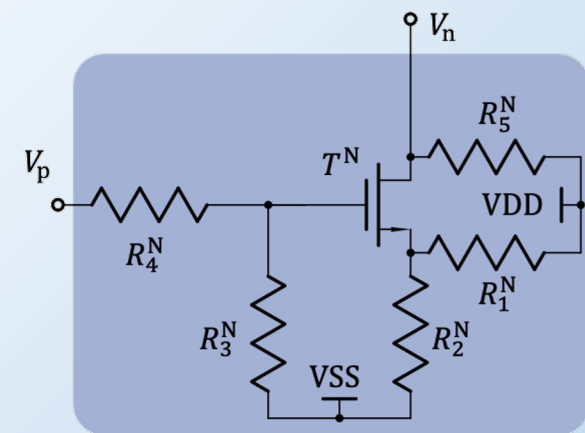
where $g_{ij} = \frac{1}{R_{ij}^C}$, G_i is the sum of g_{ij} , $V_b \equiv 1V$.



(b) Printed tanh-like circuit

$$V_{out} = \text{ptanh}(V_{in}) \\ = \eta_1^A + \eta_2^A \cdot \tanh\left((V_{in} - \eta_3^A) \cdot \eta_4^A\right)$$

where η_i^A is auxiliary parameter determined by physical quantities $\mathbf{q}^A = [R_1^A, R_2^A, T_1^A, T_2^A]$

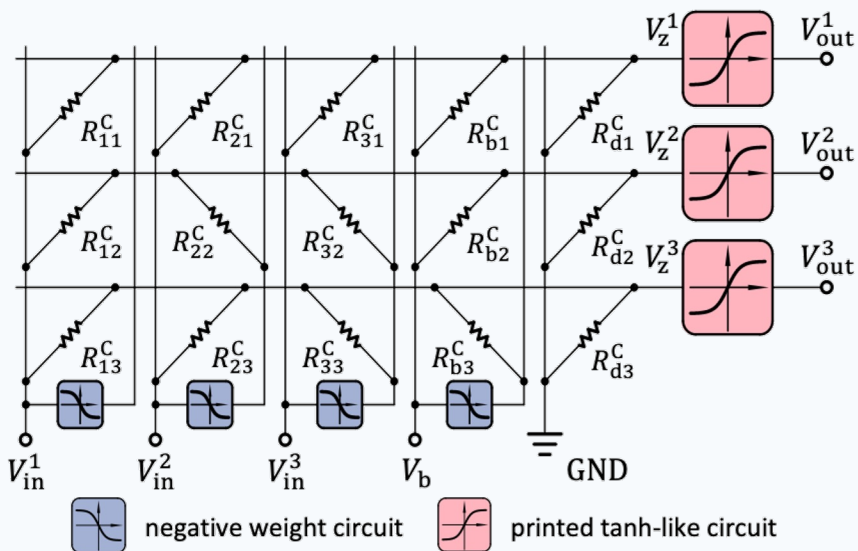


(c) Negative weight circuit

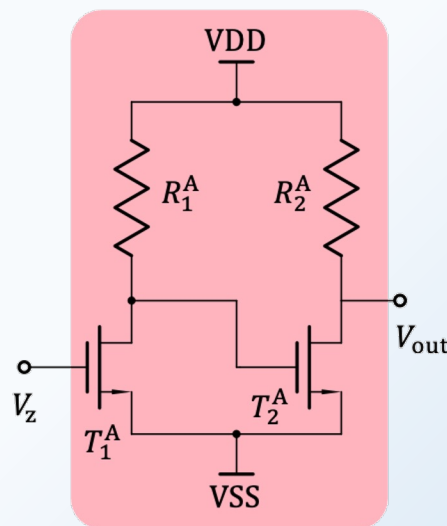
$$V_n = \text{neg}(V_p) \\ = -\left(\eta_1^N + \eta_2^N \cdot \tanh\left((V_p - \eta_3^N) \cdot \eta_4^N\right)\right)$$

where η_i^N is auxiliary parameter determined by physical quantities $\mathbf{q}^N = [R_1^N, \dots, T^N]$

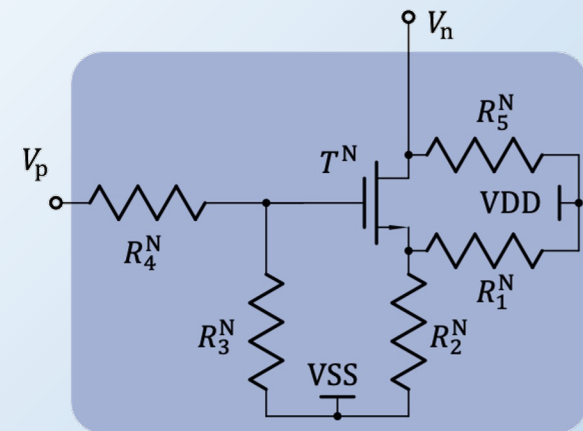
ML-based Circuit Optimization



(a) Exemplary printed neuron



(b) Printed tanh-like circuit



(c) Negative weight circuit

$$V_{\text{out}} = \text{ptanh}_{q^A} \left(V_{\text{in}} \cdot (W \odot \mathbb{I}_{\{\Theta \geq 0\}}) + \text{neg}_{q^N}(V_{\text{in}}) \cdot (W \odot \mathbb{I}_{\{\Theta < 0\}}) \right)$$

$$\text{with } W = |\Theta| \cdot \text{diag}(\Theta^T \cdot \mathbf{1})^{-1}$$

Θ learnable surrogate conductance, $|\Theta|$ printable conductance, $\text{sign}(\Theta)$ requirement of negative weight circuit

ML-based Circuit Optimization

$$V_{\text{out}} = \text{ptanh}_{q^A} \left(V_{\text{in}} \cdot (W \odot \mathbb{I}_{\{\Theta \geq 0\}}) + \text{neg}_{q^N}(V_{\text{in}}) \cdot (W \odot \mathbb{I}_{\{\Theta < 0\}}) \right)$$

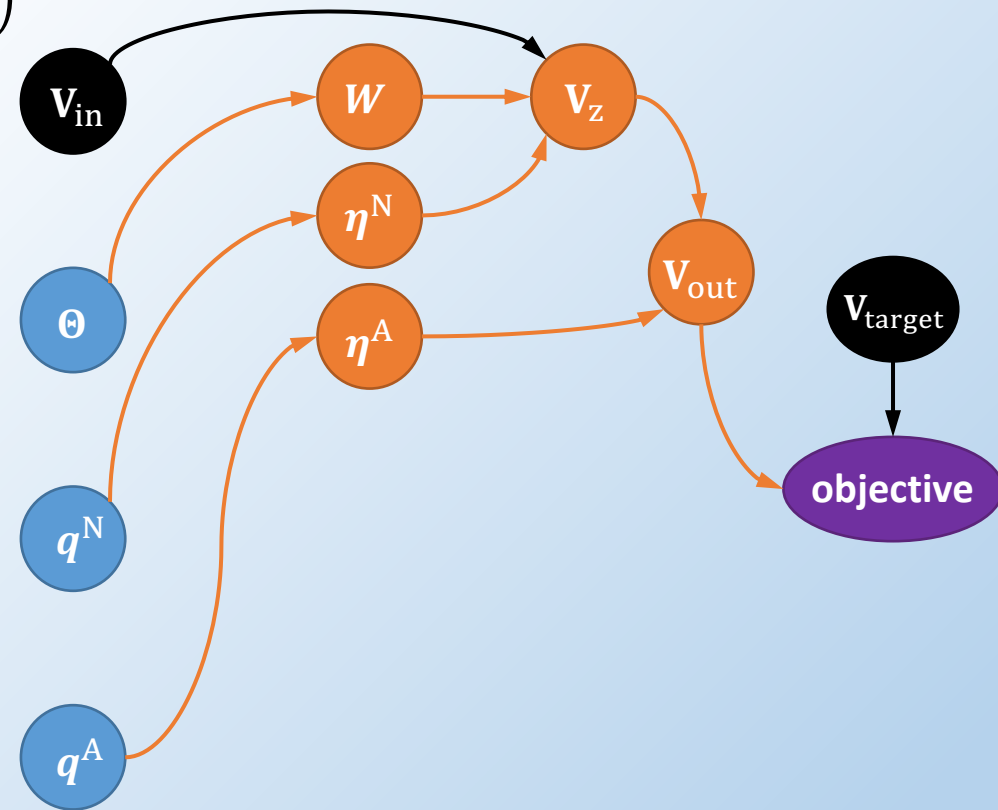
Θ learnable surrogate conductance,

$|\Theta|$ printable conductance,

$\text{sign}(\Theta)$ requirement of negative weight circuit

η_i^A in $\text{ptanh}(\cdot)$ can be determined by physical quantities q^A through a surrogate nonlinear circuit model [1]

η_i^N in $\text{neg}(\cdot)$ can be determined by physical quantities q^N through a surrogate nonlinear circuit model [1]



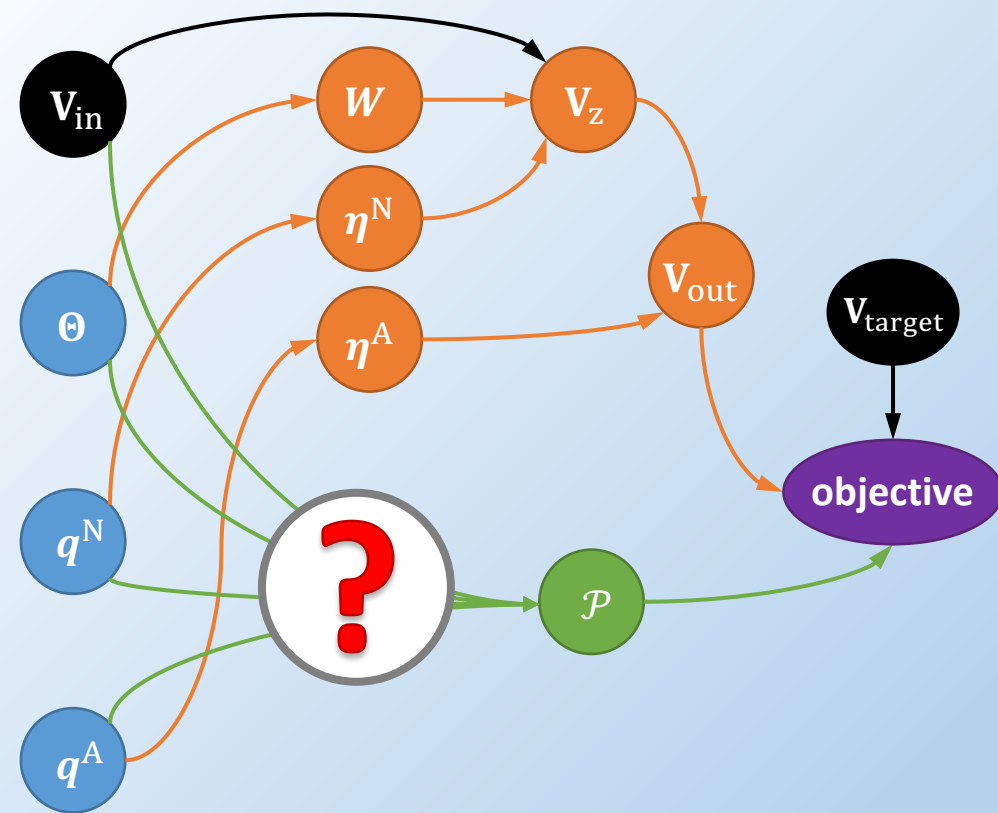
[1] Zhao, et al. "Highly-bespoke robust printed neuromorphic circuits." 2023 Design, Automation & Test in Europe Conference & Exhibition (DATE). IEEE, 2023.

Power-Aware Training

- Target applications of pNCs



- Printed batteries with limited power
- Supplied by energy harvesters
- Low-power design
 - Develop differentiable power model of pNCs
 - Integrate power model into training objective



Power-Aware Training

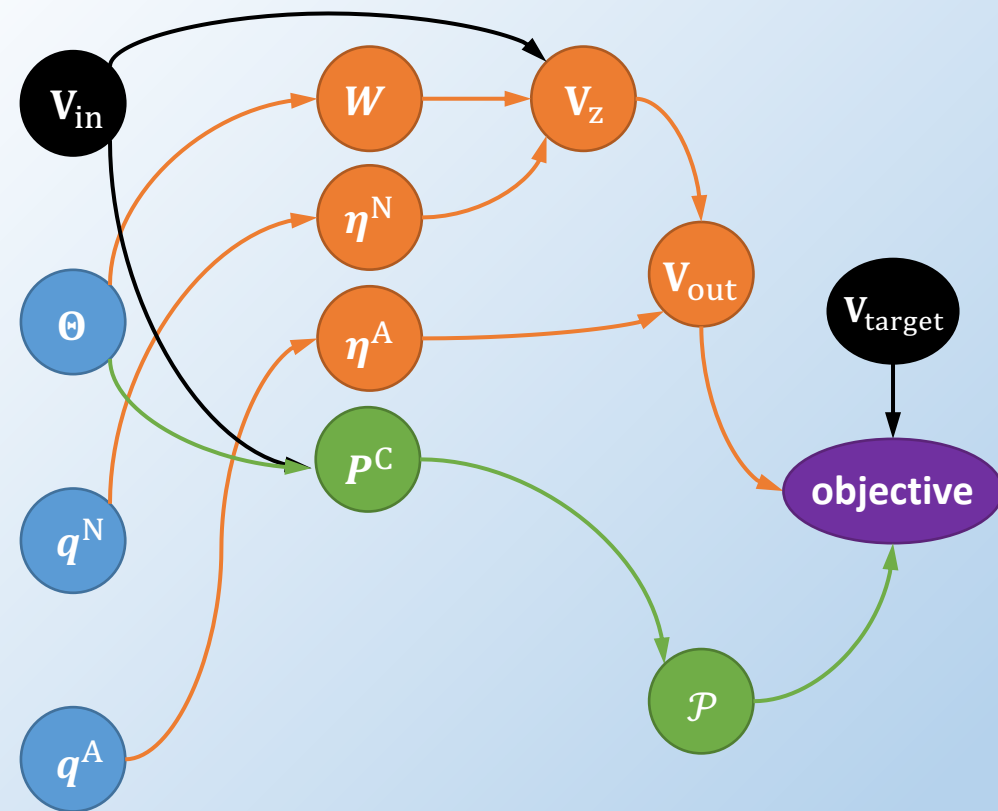
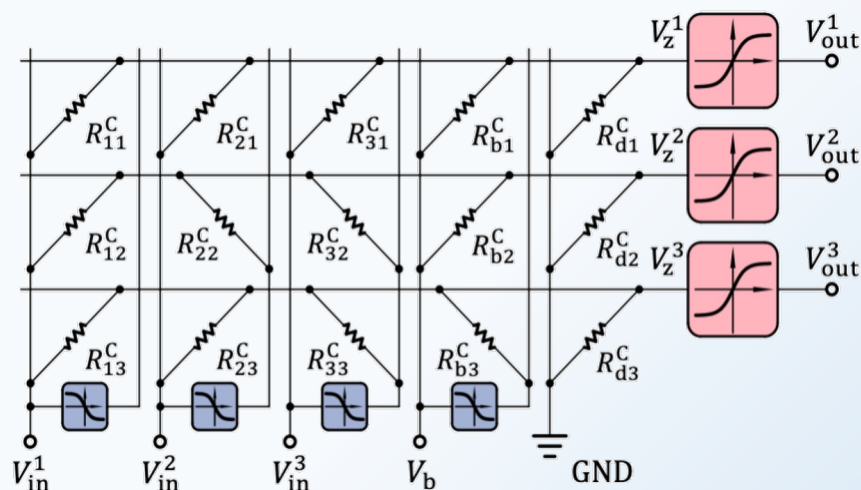
- Power Model

- Power of a single resistor

$$P = (V_{\text{in}} - V_{\text{out}})^2 \cdot g$$

- Power of the crossbar

$$P^C = \left((V_{\text{in}} \odot \mathbb{I}_{\{\Theta \geq 0\}} + V_{\text{in}} \odot \mathbb{I}_{\{\Theta < 0\}}) - V_z \right)^2 \odot \Theta$$



Power-Aware Training

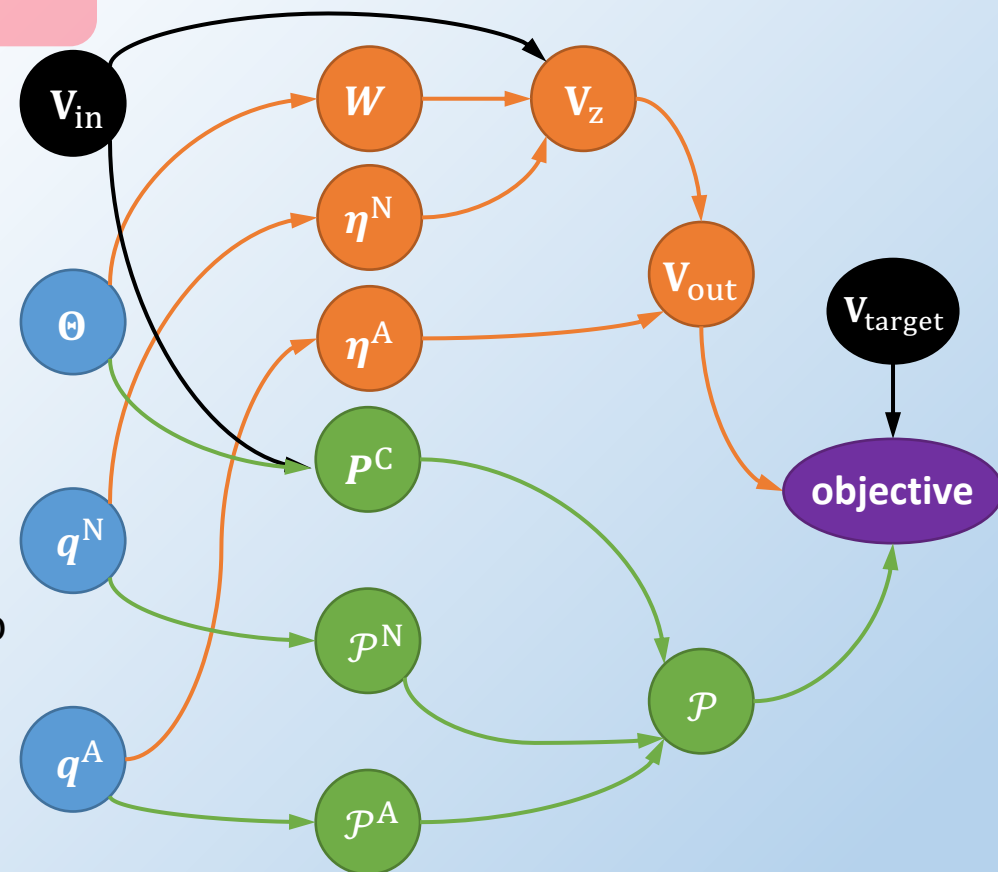
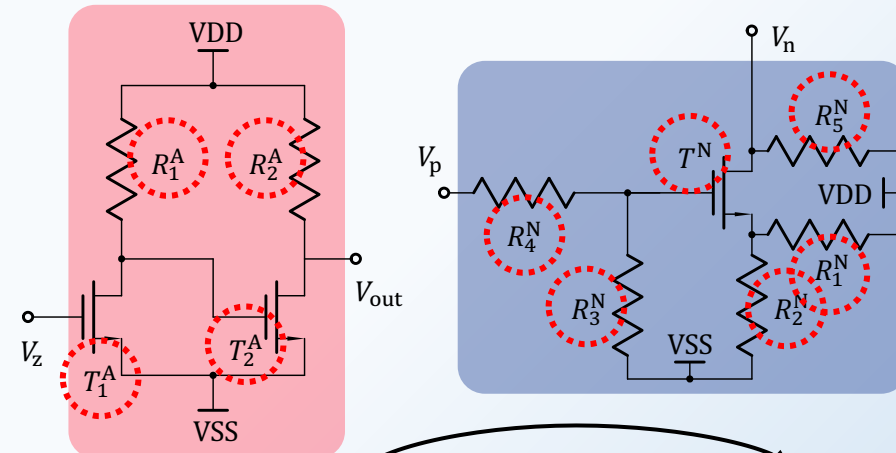
• Power Model

- Power of the crossbar

$$P^C = \left((V_{in} \odot \mathbb{I}_{\{\Theta \geq 0\}} + V_{in} \odot \mathbb{I}_{\{\Theta < 0\}}) - V_z \right)^2 \odot \Theta$$

- Power of the nonlinear circuits

- Estimating power consumptions P^A and P^N from physical quantities q^A and q^N is complicated
- Employ NN-based models as *surrogate power consumption models*, denoted by $SP(\cdot)$
 - Sampled 10000 q_i^A and q_i^N with Quasi-Monte Carlo
 - Simulated their power P_i^A and P_i^N based on SPICE with pPDK [2]
 - Trained NN to estimate P_i by q_i , i.e., $SP(\cdot): q_i \mapsto P_i$



[2] Rasheed, et al. "Variability modeling for printed inorganic electrolyte-gated transistors and circuits." *IEEE transactions on electron devices* 66.1 (2018): 146-152.

Power-Aware Training

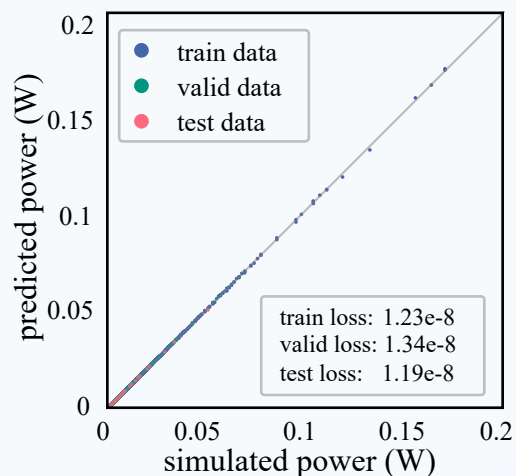
• Power Model

- Power of the crossbar

$$P^C = \left((V_{in} \odot \mathbb{I}_{\{\Theta \geq 0\}} + V_{in} \odot \mathbb{I}_{\{\Theta < 0\}}) - V_z \right)^2 \odot \Theta$$

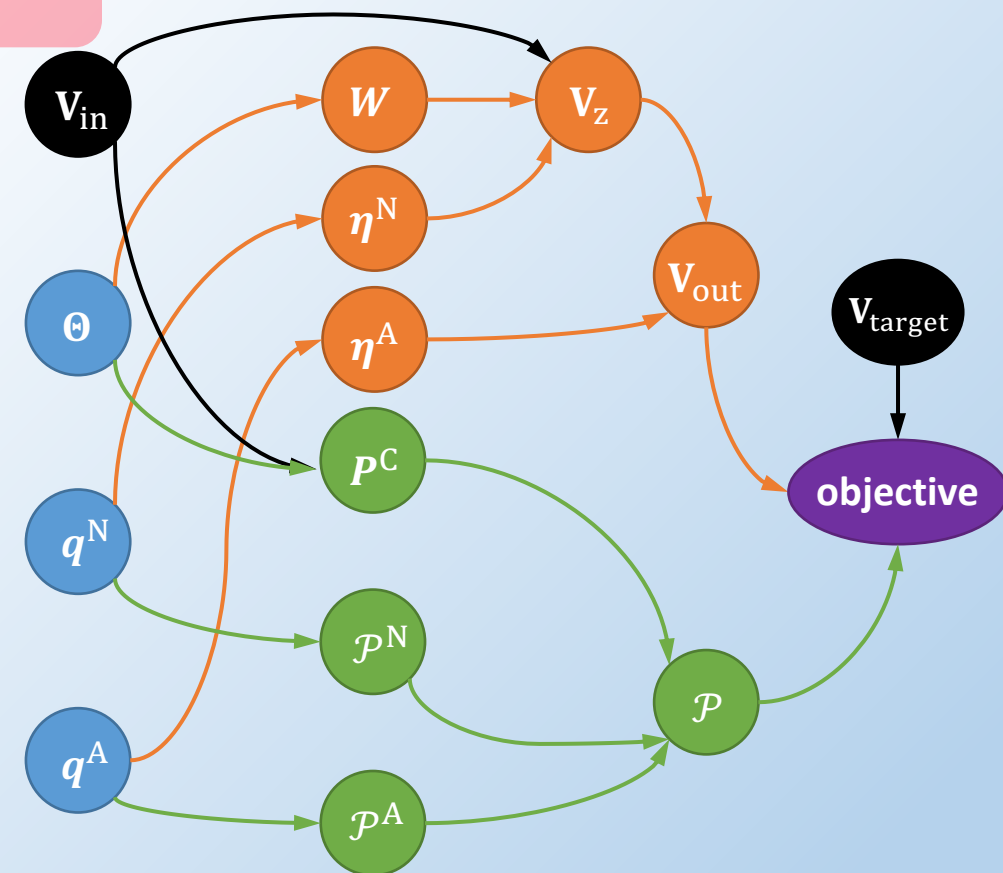
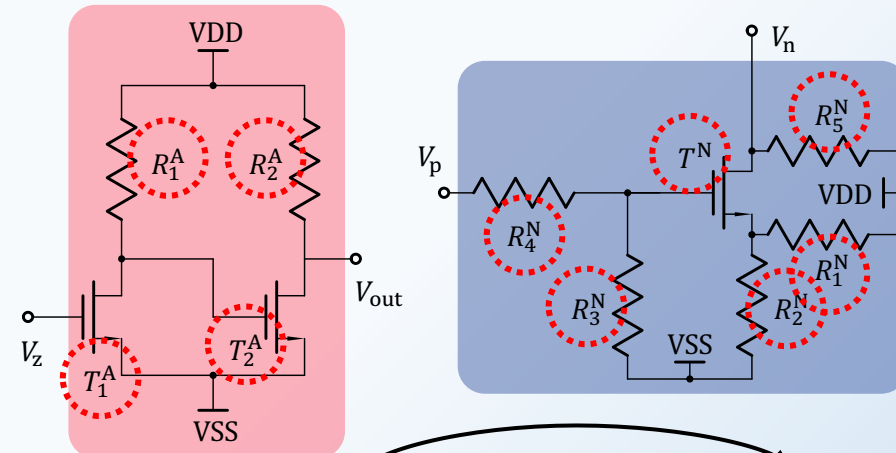
- Power of the nonlinear circuits

- Employ NN-based models as *surrogate power consumption models*, denoted by $SP(\cdot)$



$$P^A = SP^A(q^A)$$

$$P^N = SP^N(q^N)$$



Power-Aware Training

- Power Model

- Power of the crossbar

$$P^C = \left((V_{in} \odot \mathbb{I}_{\{\Theta \geq 0\}} + V_{in} \odot \mathbb{I}_{\{\Theta < 0\}}) - V_z \right)^2 \odot \Theta$$

- Power of the nonlinear circuits

- Employ NN-based models as *surrogate power consumption models*, denoted by $SP(\cdot)$

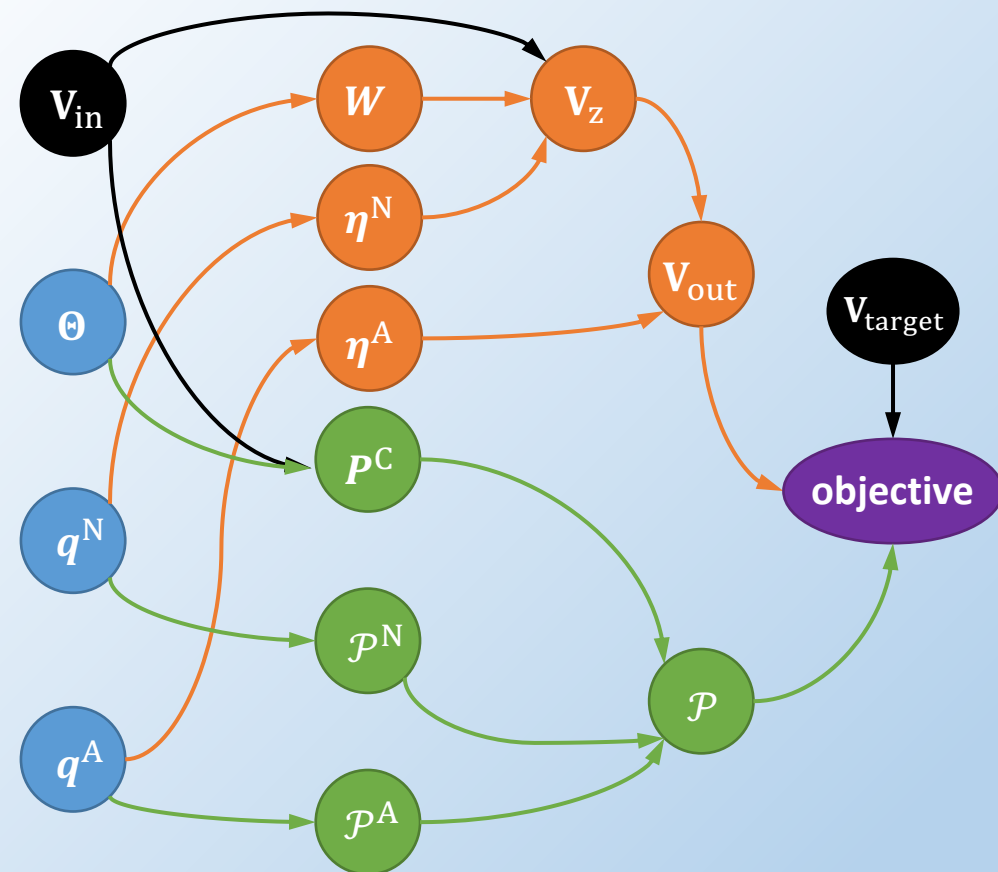
$$P^A = SP^A(q^A)$$

$$P^N = SP^N(q^N)$$

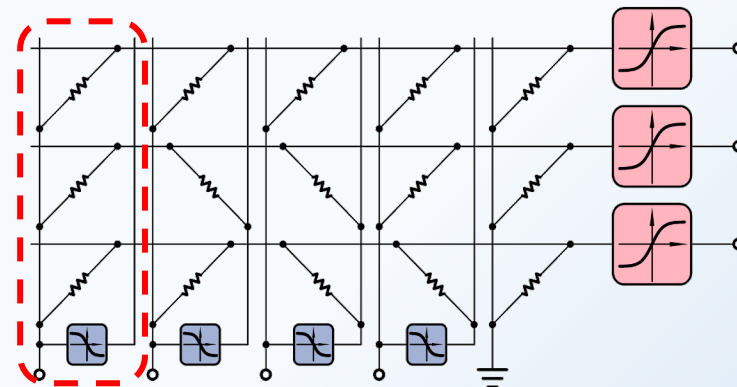
- Power overhead

$$\mathcal{P}^A = N^A \cdot SP^A(q^A)$$

$$\mathcal{P}^N = N^N \cdot SP^N(q^N)$$



Power-Aware Training



• Power Model

- Power of the crossbar

$$P^C = \left((V_{in} \odot \mathbb{I}_{\{\Theta \geq 0\}} + V_{in} \odot \mathbb{I}_{\{\Theta < 0\}}) - V_z \right)^2 \odot \Theta$$

- Power of the nonlinear circuits

- Employ NN-based models as *surrogate power consumption models*, denoted by $SP(\cdot)$
- Power overhead

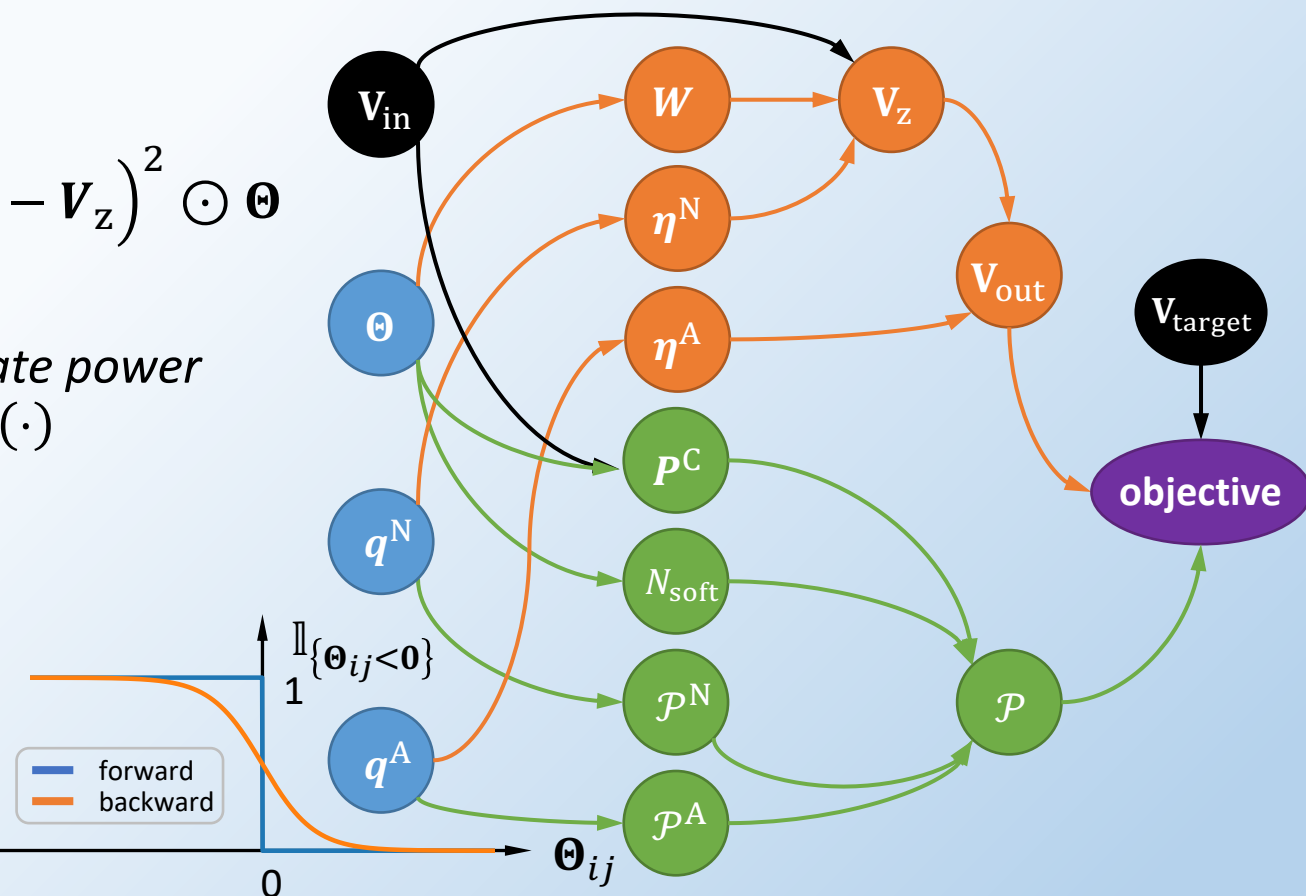
$$\mathcal{P}^A = N^A \cdot SP^A(q^A)$$

$$\mathcal{P}^N = \cancel{N^N} \cdot SP^N(q^N)$$

- Soft-Count

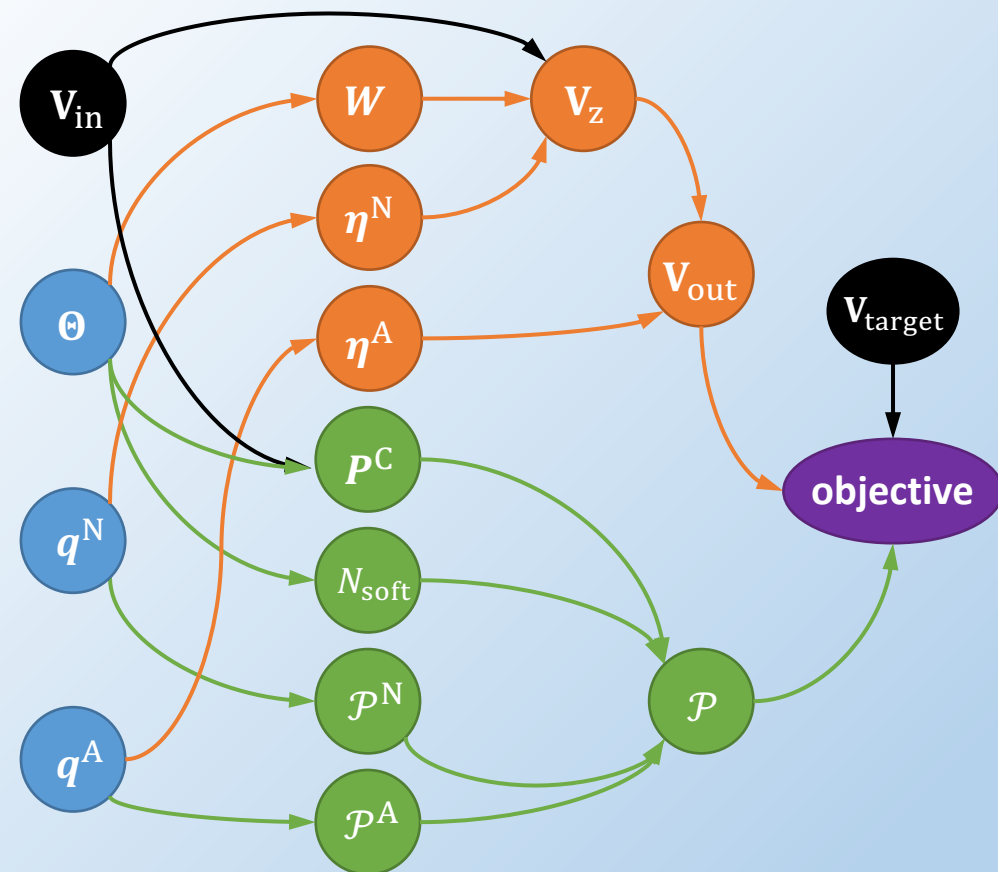
$$N^N = \sum \text{column max} \{ \mathbb{I}_{\{\Theta < 0\}} \}$$

$$\frac{\partial N_{\text{soft}}^N}{\partial \Theta} = \frac{\partial \sum \text{column max} \{ 1 - \text{sigmoid}(\Theta) \}}{\partial \Theta}$$



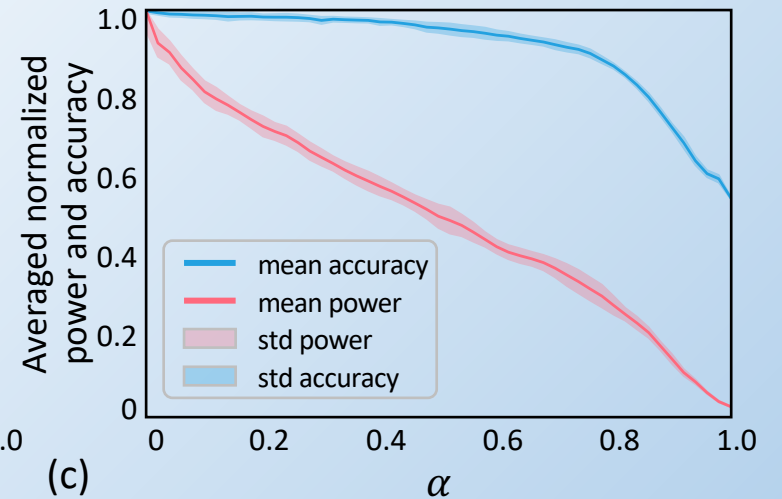
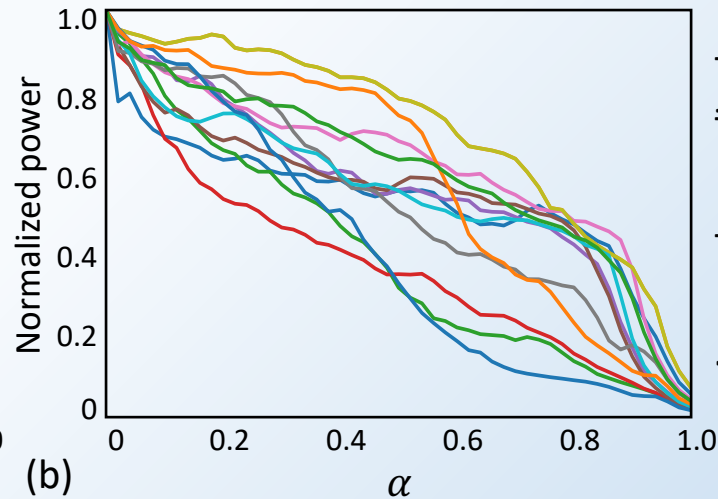
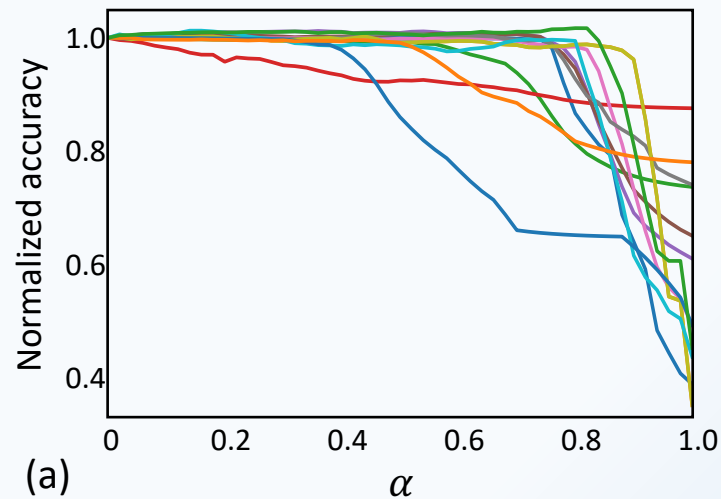
Experiment

- Training objective
 - $\mathcal{L} = (1 - \alpha) \cdot \text{CELoss} + \alpha \cdot \mathcal{P}$
 - CELoss: cross-entropy for classification accuracy
 - \mathcal{P} : overall power consumption of the pNC
- 13 benchmark datasets
- 100 different α values in $[0,1]$
- Baseline: $\alpha = 0$ (power-**un**aware training)
- Evaluation metric
 - Accuracy
 - Normalized accuracy (by baseline)
 - Averaged normalized accuracy (across all datasets)
 - Power
 - normalized power (by baseline)
 - Averaged normalized power (across all datasets)



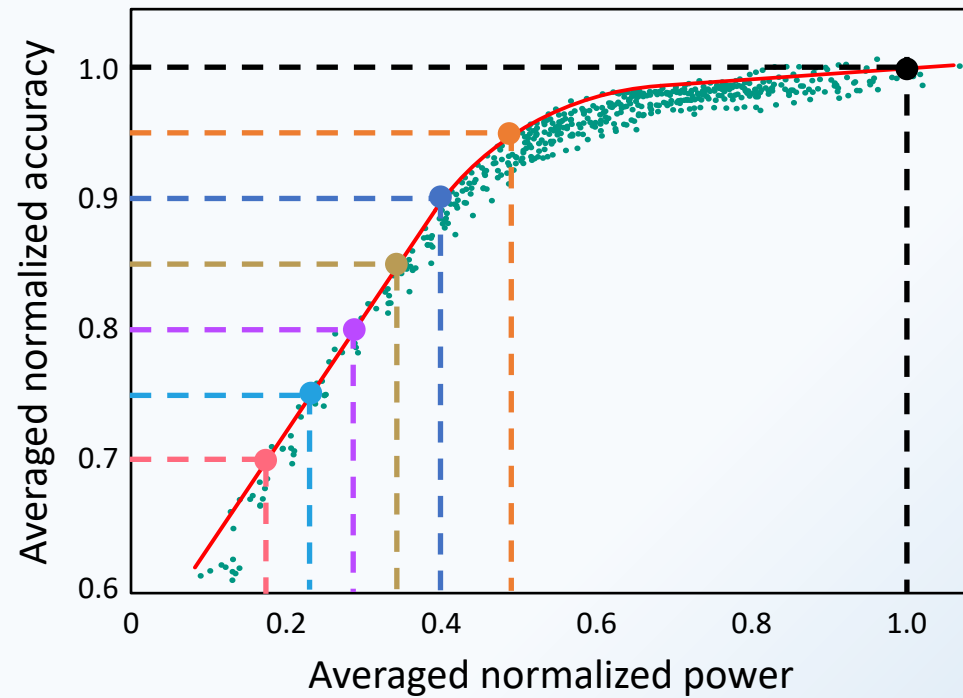
Result

- Normalized Accuracy vs. α
- Normalized Power vs. α
- Averaged normalized accuracy and power vs. α



Result

- Pareto analysis



Accuracy	Power	
100%	100%	1×
95%	50%	2×
90%	40%	2.5×
85%	34%	3×
80%	28%	3.6×
75%	23%	4.4×
70%	18%	5.5×

Conclusion

- Printed electronics provides complementary advantages, i.e.,
 - flexibility, bio-degradability, high customization, ultra-low cost, ...
- Printed neuromorphic circuits (pNCs)
 - implement effective computational functionalities as in ANNs
 - through interconnection of simple-structured circuit primitives
 - favored for circuit design, optimization, and manufacturing
- Power-aware training for pNCs
 - derive analytical power model for the resistor crossbar
 - develop *surrogate power models* to precisely estimate the power of nonlinear circuits
 - propose soft-count to enable the reduce the number of required negative weight circuits
 - achieve $2\times$ power-saving of the whole pNC with only 5% loss in classification accuracy



Thank you for your attention

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