MAT 4381

Bayesian Inference

Study Guide

Winter 2024

$$P(AB) = \frac{P(BA)P(A)}{P(B)}$$

Bayesian vs. Frequentist

Frequentist: The parameter is not a random variable

Bayesian: The parameter is a random variable

Bayes Theorem

De the sample space

E., E.,... sequence of exhaustive events $A \subset D$ another event $P(E_k|A) = \frac{P(A|E_k)P(E_k)}{\sum_k P(A|E_k)P(E_k)}$

X takes value 1 if event occurs and 0 if event do not occur

Bernoulli Distribution: Ber(0)

$$P(X=1)=0$$

$$P(\chi=0)=1-\theta$$

$$P(\chi=x) = f(x|\theta) = \theta^{x}(1-\theta)^{1-x} I(x \in \{0,1\})$$

$$E[X] = \sum_{x=0}^{1} x f(x|\theta) = \theta$$

Binomial Distribution

$$X_1,...,X_n \stackrel{iid}{\sim} Ber(\theta)$$

$$Y = \sum_{i=1}^{n} X_i \in \{0,1,2,...,n\} \sim Bin(n,\theta)$$

$$P(Y=y) = {n \choose y} \theta^{y} (i-\theta)^{n-y} I(y \in \{0,1,...,n\})$$

$$E[Y] = n\theta \quad Var(Y) = n\theta(1-\theta)$$

Bayes Formula for Distributions

$$f(\theta|y) = \frac{f(y|\theta)g(\theta)}{f_i(y)}$$

If θ is discrete with ρ, m, f , $g(\theta)$ $f(\theta|y) = \frac{f(y|\theta)g(\theta)}{f_1(y)} = \frac{f(y|\theta)g(\theta)}{\sum_i f(y|\theta_i)g(\theta_i)}$

If $\theta \sim g(\theta)$ is continuous

$$f(\theta | y) = \frac{f(y|\theta)g(\theta)}{f_1(y)} = \frac{f(y|\theta)g(\theta)}{\int f(y|\theta)g(\theta)d\theta}$$

The denominator is sometimes called the proportionality constant

$$f(\theta|y) = Cf(y|\theta)g(\theta)$$

or f(Oly) af(ylo)g(O)=likelihood >prior

C some constant and a means "proportional to"

 $g(\theta)$: prior distribution for θ

f(Oly): posterior distribution

Conjugate Prior

 A conjugate prior is also a convenient prior, since it allows one to easily calculate the posterior distribution

Beta Distribution

$$g(\theta) = \frac{T(\alpha + \beta)}{T(\alpha)} \theta^{\alpha + 1} (1 - \theta)^{\beta - 1} I(\theta c \theta c 1)$$

The distribution is the $Beta(\alpha,\beta)$ distribution

We use the fact that $\frac{\Pi(\alpha)}{n^{\alpha}} = \int_{0}^{\infty} x^{\alpha-1} e^{-\beta x} dx, \alpha, \beta > 0$



The Beta distribution is a conjugate prior for binomial distribution

If $(\gamma | \theta = \theta) \sim f(y | \theta)$ $f(y | \theta) = \binom{n}{y} \theta^{g} (1 - \theta)^{n-g} I(y \in \{0, 1, ..., n\})$

and $(\theta(\alpha, \beta) \sim \text{Beba}(\alpha, \beta)$

we have

f(014) or f(10)2(0)

In other words, $f(\theta|y) \propto \theta^{3} (1-\theta)^{6-1} \theta^{4-1} (1-\theta)^{6-1}$

The posterior is: $f(\theta|g) = \frac{T(\alpha+\theta)}{T(\alpha)T(\theta)}\theta^{\alpha+g-1}(1-\theta)^{\beta+m-g-1}$

If the prior is Beta(a,p), then the posterior is Beta(a49,p4m-y)

If $\Theta \sim \text{Beta}(\alpha, \beta)$, then

 $E[\theta] = \frac{\alpha + \beta}{\alpha}$

$$Var(\theta) = \frac{\alpha \beta}{(\alpha + \beta)^2 (\alpha + \beta + 1)}$$

Mode:
$$\hat{\theta} = \frac{\alpha - 1}{\alpha + \beta - 2}$$

- i) For large values of α and β mode and mean are roughly the same .
- ii) Median for Bete(α,β) cannot be written in a closed form
- iii) Peak of mode of beta density gets sharper as off increases
- iv) We need to use numerical methods to calculate the med for different values of a and B

Credible Region

• We want to find I s.t. $P(\theta \in I) = 1 - \alpha$, where $1 - \alpha$ is the confidence level

·We can also use simulation method

Choosing Beta Function

First, consider priors that Jones express a strong opinion. Later, consider priors which incorporate a strong prior belief. If there are no preferences on the value for 0, then one might consider using a "flat prior". That is, the uniform distribution between 0 and 1 (Beta(1,1))

·In some sense, this implies that each value of 0 as equally likely

Since the prior is flat, the posterior distribution has the same shape as the likelihad multiplied by a constant C h(0|x) = Cf(x|0)g(0)a f(x|0)

Since the uniform distribution is Beta (1,1), then the posterior is Beta (4+1, n-4+1)

Making Bayesian Inference

The posterior contains the results of the analysis

To communicate the result, we can either present be entire Posterior distribution, or give summany statistics of the Posterior

For credible regions, there are 2 common types:

- Smallest Interval
- · Equal tail area

Jeffreys Prior

Jeffreys proposed that an acceptable "non-informative prior finding principle" should be invariant under monotone transformations of the parameter.

The Jeffrey's prior satisfying this invariance is proportional to

invariance is proportional $\sqrt{J(\theta)}$, where $I(\theta)$ is the Fisher information on θ . Can be generalized when θ is k-dimensional to $\sqrt{J_{\theta}t(J(\theta))}$

$$I(\theta) = - E \left[\frac{3\theta_3}{3_3 (\text{ln} L(x|\theta))} \right]$$

For k-dimensional, we have $I(\theta) = \left[\left(\frac{\partial^{2} \ln f(x|\theta)}{\partial \theta_{1} \theta_{2}} \right)_{(i,j)} \right]$

Multinomial Distribution

 $(X_1,...,X_k) \sim Multinonial (n,p,...,p_k)$ $P_k = 1-p_1-p_2-...-p_{k-1}$

Models probability of counts for each side of an experiment with kexhaustive outcomes

 $\hat{T}\Big(X_{i,j}X_{k_1,\ldots,j}X_{k_i}\Big) = \begin{pmatrix} n \\ X_{j,X_{k_1,\ldots,j}X_{k+1}} \end{pmatrix} P_i^{X_i} P_k^{X_{k_1}} \cdots P_{k+1}^{X_{k+1}} \big(1-\beta-\beta_k-\ldots-\beta_{k+1}\big)^{X_{k+1}}$

where $x_1y_2 = 0, 1, 2, ..., n, x_1 + x_{n+1} + x_{n+1} \le n$

Simple Case: Trinomial Distribution
(X, Y)~ Multinomial (NP, B)

 $f(x,y) = {n \choose x,y} P_1^x P_2^y (-\rho_1 - \rho_2)^{n-x-y}$

K,y=0,1,2,...,n, x4y&n
We can also get that

 $X \sim Bin(n, p_1)$

Y~Bin(n, p_s) $1 \times A = x \sim Bin(n-x, \frac{p_s}{(-p_s)})$

$$\begin{split} & E[\Upsilon | X = x] = (n \rightarrow x) \frac{\rho_n}{(-\rho_n)} \\ & V_{OM}[\Upsilon | X = x] = (n \rightarrow x) \left(\frac{\rho_n}{(-\rho_n)} \left(1 - \frac{\rho_n}{(-\rho_n)}\right) \right) \\ & E[XY] = \frac{\rho_n}{(-\rho_n)} E[X(n \rightarrow x)] = -n\rho_1 \rho_n \end{split}$$

 $\rho(\chi,\chi) = \frac{-n(n+1) \, P_1 P_2}{\sqrt{n \, P_1 \, (l-P_1) n \, P_2 \, (l-P_2)}} = \frac{-(n+1) \, P_1 P_2}{\sqrt{P_1 P_2 \, (l-P_1) \, (l-P_2)}}$

Jeffreys Prior for Trinomial Distributions $9(P_1, P_2) \propto \frac{1}{\sqrt{P_1 P_2 (1-P_1-P_2)}}$

Special case of Dirichlet distribution Dir(k, k, k)

Dirichlet Distribution

 $Cov(X,Y) = -n(nH) \rho_1 P_2$

$$f(x_{i_1,...,j} X_{k-i_1}) = \int_{\substack{i=1 \ i \neq i}} X_i \int_{\substack{i=1 \ i$$

Defined on $S = \{(x_1,...,x_{k-1}): \sum_{i=1}^{k-1} x_i < l, x_i > 0, i=1,...,k \}$

Posterior for Trinomial

 $(\theta_1,...,\theta_{k-1}|X_1=x_1,...,X_{k-1}=x_{k-1}) \sim Dir(\alpha_1+x_1,...,\alpha_{k-1}+x_{k-1}) - \Sigma_{k+k}$

 $E[\Theta|X_{i}=X_{i_{1},...,i_{n}}X_{k-i}=X_{k-i}]=\left[\frac{\alpha_{i}+X_{i}}{2\alpha_{i}+n_{i_{1},...,i_{n}}}\frac{\alpha_{k}+X_{k}}{2\alpha_{i}+n_{i_{n}}}\right]$ $\theta=\left[\theta_{i}\;\;\theta_{2}\;\ldots\;\theta_{k-i}\;\theta_{k}\;\right]^{T}$

 $\theta_k = [-\theta_1 - \dots - \theta_{k-1} \quad X_k = n - x_1 - \dots - X_{k-1}]$

Notice: $(\theta_1, \theta_2) \sim \text{Dir}(\alpha_1, \alpha_2, \alpha_3 + ... + \alpha_k)$

Basic Properties of Dirichlet Distribution $(Y_1, ..., Y_{k-1}) \sim \text{Dir}(\alpha_1, ..., \alpha_k) \qquad \alpha_0 = \sum_{i=1}^k \alpha_i$ $E[Y_i] = \frac{\alpha_i}{\alpha_0} \qquad \text{Var}[Y_i] = \frac{\alpha_i(\alpha_0 - \alpha_i)}{\alpha_0^2(\alpha_0 + 1)}$

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$$C_{\text{ov}}(X_i, X_j) = -\frac{\alpha_i \alpha_j}{\alpha_o^2(\alpha_o + 1)}$$

Conjugate Prior and Posterior for Poisson

$$\chi_{i_1,...,j_n} \chi_{i_n} \stackrel{\text{iid}}{\sim} f(x|\theta) = \frac{exp(-\theta)\theta^x}{x!} 1(x=o,i,...)$$

Likelihood: $\prod_{i=1}^{n} f(x_i|\theta) = \prod_{i=1}^{n} \frac{x_i!}{x_i!} \propto \exp(-n\theta)\theta^{\frac{1}{2}}$

Conjugate Prior: $g(\theta) = \frac{\beta^{\alpha}}{\Gamma(\alpha)} \theta^{\alpha-1} \exp(-\beta \theta) I(\theta > 0)$

Posterior: h(Oly) & Ofta+1exp(-(D+n)O) I(O>0)

 $h(\theta|y) = \frac{(\beta+n)^{9+\alpha}}{\prod (y+\alpha)} \theta^{y+\alpha+1} \exp(-(\beta+n)\theta) I(\theta>0)$

 $E[\Theta|Y=y] = \frac{y+\alpha}{n+\beta}$

 $Var[\theta|Y=y] = \frac{y+\alpha}{(n+\beta)^2}$

Mode (BIY=y) = y+a-1

Jeffrey's Prior for Poisson

$$f(x|y) = \frac{\sum_{i=1}^{n} x_i i}{\sum_{i=1}^{n} x_i}$$

$$- \left[\frac{3\theta_3}{3} \log f(x|\theta) \right] = \frac{y}{y}$$

Jeffrey's prior: g(h) a 1/h

This leads to an improper Prior since we have

$$\int_{\infty}^{0} \frac{\gamma y}{4y} = \infty$$

No normalizing constant will turn it into a prior p.d.f.

We can still use it to calculate the posterior

$$\lambda | \chi \propto \exp(-n\lambda) \lambda^{9+k-1}$$

The use of improper prior leads to Gamma posterior $\frac{1}{|Y|} = \frac{1}{|Y|} \left(\frac{2}{|X|} \frac{x_1 + \frac{1}{|X|}}{|X|} \right)^{\frac{2}{|X|}} \exp(-\eta_0)$

$$E[\lambda|x_{1,...,x_{n}}] = \frac{\sum_{i=1}^{n} x_{i} + o.s}{h}$$

$$V_{i}[\lambda|x_{i},...,x_{n}] = \sum_{i=1}^{n} x_{i} + o.s$$

$$\sqrt{\alpha_k[y|x^{1^{2}},x^{p}]} = \frac{1}{\sum_{i=1}^{n} x^{i} + o \cdot s}$$

Distribution Normal

 $(Y_1, ..., Y_n | \mu) \sim f(y_1, ..., y_n | \mu) \propto \exp\left(-\sum_{i=1}^{n} \frac{(y_i - \mu)^2}{2\sigma^2}\right)$ 02 known

$$f(y_1,...,y_n|A) \propto \exp\left(-\frac{A^3-2Ab\overline{y}}{2\sigma^3/n}\right)$$

The Jeffrey's prior is $g(u) \propto 1$

This constitutes an improper prior

However, we can still calculate the posterior

$$(u|Y_i, y_i, ..., Y_n = y_n) \sim N(\bar{y}, \frac{\sigma^2}{n})$$

The normal prior

 σ^2 known

Prior: $g(\theta) \propto \exp(-(\theta-\mu)^2/\gamma^2)$

Likelihood · in f(4,..., 4, la) ocf(yla)

Posterior for 0

$$\begin{split} h(\theta|q_i,q_{a_i,...,y}q_n) & \propto \exp\left[-(\theta-M)^2/\gamma^4\right) \cdot \exp\left[-\frac{(\vec{q}-M)^2}{2\sigma\gamma_h}\right] \\ & \ll \exp\left[\frac{(\vec{q}-\theta)^4}{2\sigma\gamma_h} - \frac{(\theta-M)^4}{2\gamma^2}\right] \\ & \ll \exp\left[-\frac{\theta^2-2\theta\overline{q}}{2\sigma\gamma_h} - \frac{(\theta-M)^4}{2\gamma^2}\right] \\ & \ll \exp\left[-\frac{\theta^2-2\theta\overline{q}}{2\sigma\gamma_h} - \frac{\theta^2-2\theta}{2\gamma^2}\right] \\ & \ll \exp\left[-\frac{\theta^2(\Upsilon^4+\sigma\gamma_h) - 2\theta(\Upsilon^2\overline{q} + M\sigma^2\gamma_h)}{2\gamma^2\gamma^2\gamma_h}\right] \end{split}$$

 $\begin{aligned} & \underset{\text{cerp}}{\sim} \left(- \frac{\theta^2 - 2\theta(\gamma_n^2 + k_0 \gamma_n)/(\gamma^2 + \gamma_n^2 n)}{2\gamma^2 n} \right) \\ & (\theta | y_1, ..., y_n) \sim N \left(\frac{\gamma^2 + k_0 \gamma_n^2 n}{\gamma^2 + \sigma^2 \gamma_n}, \frac{\gamma^2 \sigma^2 n}{\gamma^2 + \sigma^2 \gamma_n} \right) \\ & E[\theta | \gamma = y] = \frac{\gamma^2 y}{\gamma^2 + \sigma^2 \gamma_n} \\ & MAP = E[\theta | y_1, ..., y_n] = Median \left(\theta | \gamma = y \right) \end{aligned}$

Posterior precision is equal to prior proper plus observation precision

Since $E[\theta|y_1,...,y_n] = \frac{\sigma^2/n}{\tau^2 + \sigma_N^2}M + \frac{\tau^2}{\tau^2 + \sigma_N^2}$ the posterior mean is the weighter average of the prior mean and the mean of observations, where the weights are the proportions of the precision to the posterior