

## A1: The Boussinesq equations

The governing equations for a nonrotating, inviscid, adiabatic, fluid are:

$$\begin{aligned}\rho \frac{d\mathbf{u}}{dt} &= -\nabla p - g\rho\hat{\mathbf{z}} \\ \frac{\partial\rho}{\partial t} + \nabla \cdot (\rho\mathbf{u}) &= 0 \\ \frac{d\rho}{dt} &= 0 .\end{aligned}$$

(Here  $\hat{\mathbf{z}}$  is the upward unit normal.) In the *Boussinesq* approximation, which is appropriate for an almost-incompressible fluid, it is assumed that variations of density are small, so that in the inertial terms, and in the continuity equation, we may substitute  $\rho \rightarrow \rho_0$ , a constant. However, even weak density variations are important in *buoyancy*, and so we retain variations in  $\rho$  in the buoyancy term in the vertical equation of motion. We define the buoyancy as

$$b = g(\rho_0 - \rho)/\rho_0 ,$$

and also define a reference pressure,  $p_0 = -g\rho_0 z + \text{const.}$ , in hydrostatic balance with the reference density, and then introduce  $\tilde{p} = p - p_0(z)$ . Then we have

$$-\nabla p - g\rho\hat{\mathbf{z}} = \begin{pmatrix} -\frac{\partial p}{\partial x} \\ -\frac{\partial p}{\partial y} \\ -\frac{\partial p}{\partial z} - g\rho \end{pmatrix} = \begin{pmatrix} -\frac{\partial \tilde{p}}{\partial x} \\ -\frac{\partial \tilde{p}}{\partial y} \\ -\frac{\partial \tilde{p}}{\partial z} + g\rho_0 - g\rho \end{pmatrix} = -\nabla \tilde{p} + \rho_0 b\hat{\mathbf{z}} ,$$

Writing  $\Phi = \tilde{p}/\rho_0$  (analogous to geopotential in pressure coordinates), the resulting set of Boussinesq equations for a nonrotating system are

$$\begin{aligned}\frac{d\mathbf{u}}{dt} &= -\nabla\Phi + b\hat{\mathbf{z}} \\ \nabla \cdot \mathbf{u} &= 0 \\ \frac{db}{dt} &= 0\end{aligned}\tag{1}$$

Note that hydrostatic balance is just

$$\frac{\partial\Phi}{\partial z} = b .$$

We will add rotational terms to these equations as the context requires.