

Lecture 4

Linear stability of parallel flows I

AE209 Hydrodynamic stability

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- 1. Concept of parallel flows**
- 2. Linearised equation for inviscid parallel shear flows**
- 3. Normal mode solution**
- 4. When does an instability occur?**

1. Concept of parallel flows

1. $\vec{u} = u_1 \vec{e}_1 + u_2 \vec{e}_2 + u_3 \vec{e}_3$ and $\vec{v} = v_1 \vec{e}_1 + v_2 \vec{e}_2 + v_3 \vec{e}_3$ are parallel if and only if $\vec{u} = \lambda \vec{v}$ for some scalar λ .
2. $\vec{u} = \lambda \vec{v}$ if and only if $\frac{u_1}{v_1} = \frac{u_2}{v_2} = \frac{u_3}{v_3}$ (provided $v_1, v_2, v_3 \neq 0$).

2.

Parallel shear flows

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Parallel shear flows

The flow configuration, the base flow of which is given by

$$\mathbf{U} = (U(y), 0, 0)$$

Examples

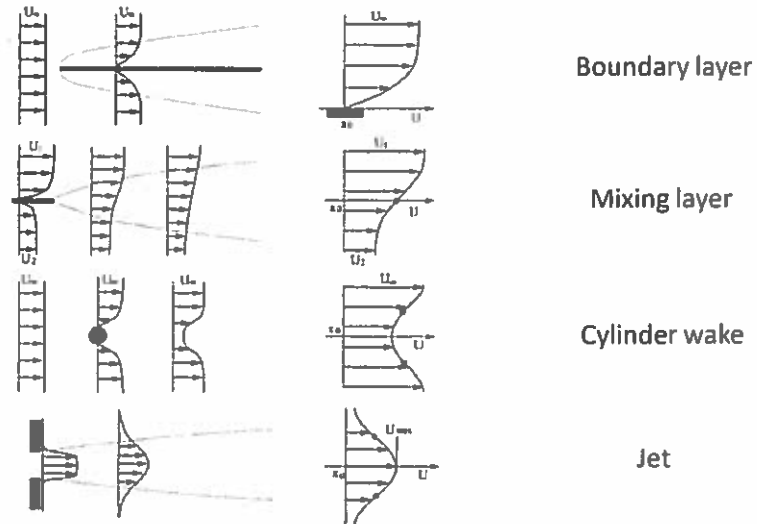
Plane Couette flow, Poiseuille flow, Pipe flow, and etc.

$$U(y)$$

$$U(y) = 1 - y^2$$

$$U(r) = 1 - r^2.$$

Weakly non-parallel flows (or spatially developing flows)



2. Linearised equation for inviscid parallel shear flows

Linearised Euler equation around parallel base flow

$$\begin{aligned}
 \frac{\partial}{\partial x} \left[\frac{\partial u'}{\partial t} + U \frac{\partial u'}{\partial x} + v' \frac{dU}{dy} \right] &= - \frac{\partial p'}{\partial x} \\
 \frac{\partial}{\partial y} \left[\frac{\partial v'}{\partial t} + U \frac{\partial v'}{\partial x} \right] &= - \frac{\partial p'}{\partial y} \\
 \frac{\partial}{\partial z} \left[\frac{\partial w'}{\partial t} + U \frac{\partial w'}{\partial x} \right] &= - \frac{\partial p'}{\partial z}
 \end{aligned}
 \Rightarrow \nabla^2 p = -2 \frac{dU}{dy} \frac{\partial v}{\partial x}$$

Poisson equation for pressure.

$$\frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} + \frac{\partial w'}{\partial z} = 0$$

Euler equation

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\nabla p$$

$$\nabla \cdot \mathbf{u} = 0$$

Consider $\mathbf{u}(x, y, z, t) = \underline{U(y, 0, 0)} + \varepsilon \mathbf{u}'(x, y, z, t),$

$p(x, y, z, t) = P(x, y) + \varepsilon p'(x, y, z, t)$

and neglect the terms at $O(\varepsilon^2)$. Then,

$$\frac{\partial \underline{u}'}{\partial t} + (\underline{U} \cdot \nabla) \underline{u}' + (\underline{u}' \cdot \nabla) \underline{U} = -\nabla p'$$

$$\nabla \cdot \underline{u}' = 0$$

1) Equation for wall-normal velocity

$$\nabla^2 \cdot \left[\frac{\partial v'}{\partial t} + U \frac{\partial v'}{\partial x} = - \frac{\partial p'}{\partial y} \right] \quad \frac{\partial}{\partial y} \left[\nabla^2 p = -2 \frac{dU}{dy} \frac{\partial v}{\partial x} \right]$$

$$\left[\left(\frac{\partial}{\partial t} + U \frac{\partial}{\partial x} \right) \nabla^2 - \frac{d^2 U}{dy^2} \frac{\partial}{\partial x} \right] v' = 0$$

2) Equation for wall-normal vorticity

$$\frac{\partial}{\partial z} \left[\frac{\partial u'}{\partial t} + U \frac{\partial u'}{\partial x} + v' \frac{dU}{dy} = - \frac{\partial p'}{\partial x} \right]$$

$$\frac{\partial}{\partial z} \left[\frac{\partial w'}{\partial t} + U \frac{\partial w'}{\partial x} = - \frac{\partial p'}{\partial z} \right]$$

Wall-normal vorticity (ω_y)

$$\eta' = \frac{\partial u'}{\partial z} - \frac{\partial w'}{\partial x}$$

$$\left(\frac{\partial}{\partial t} + U \frac{\partial}{\partial x} \right) \eta' = - \frac{dU}{dy} \frac{\partial v'}{\partial z}$$

\Rightarrow Use continuity to retrieve v' .

Velocity and vorticity form of linearised Euler equation

$$\left[\left(\frac{\partial}{\partial t} + U \frac{\partial}{\partial x} \right) \nabla^2 - \frac{d^2 U}{dy^2} \frac{\partial}{\partial x} \right] v' = 0$$

$$\left(\frac{\partial}{\partial t} + U \frac{\partial}{\partial x} \right) \eta' + \frac{dU}{dy} \frac{\partial v'}{\partial z} = 0$$

with the boundary condition,

$$\underline{v' = \eta' = 0} \quad \text{at solid boundary and/or the far field}$$

and the initial condition,

$$v'(x, y, z, t = 0) = v'_0(x, y, z)$$

$$\eta'(x, y, z, t = 0) = \eta'_0(x, y, z)$$



3. Normal mode solution

For example,

$$v' \rightarrow \tilde{v}$$

$$\frac{\partial v'}{\partial t} = \frac{\partial}{\partial t} (\tilde{v} e^{\bar{\imath} \alpha x - \bar{\imath} \omega t}) = -\bar{\imath} \omega \tilde{v} e^{\bar{\imath} \alpha x - \bar{\imath} \omega t}$$

$$\frac{\partial}{\partial t} \rightarrow -\bar{\imath} \omega$$

$$\frac{d^2 U}{dy^2} \frac{\partial v'}{\partial x} = \frac{d^2 U}{dy^2} \frac{\partial}{\partial x} [\tilde{v} e^{\bar{\imath} \alpha x - \bar{\imath} \omega t}] = \bar{\imath} \alpha \frac{d^2 U}{dy^2} \tilde{v} e^{\bar{\imath} \alpha x - \bar{\imath} \omega t}$$

$$\frac{\partial}{\partial x} \rightarrow \bar{\imath} \alpha$$

$$\nabla^2 v' = \left[\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right] (\tilde{v} e^{\bar{\imath} \alpha x - \bar{\imath} \omega t})$$

$$\frac{\partial^2}{\partial x^2} \rightarrow -\alpha^2$$

$$= [-\alpha^2 + \frac{\partial^2}{\partial y^2}] (\tilde{v} e^{\bar{\imath} \alpha x - \bar{\imath} \omega t})$$

Normal mode solution

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Consider two-dimensional case such that

$$\left[\left(\frac{\partial}{\partial t} + U \frac{\partial}{\partial x} \right) \nabla^2 - \frac{d^2 U}{dy^2} \frac{\partial}{\partial x} \right] v' = 0$$

Then, the normal mode solution takes the following form:

$$v'(x, y, t) = \tilde{v}(y) e^{i(\alpha x - \omega t)} + \text{c.c.}$$

Assume

where $\alpha \in \mathbb{R}$ and $\omega \in \mathbb{C}$.

Real.

known.

(Prescribed)

Complex

Unknown.

Complex

Complex conjugate

cf

$$\nabla^2 \chi - a^2 \chi = 0$$

$$\Rightarrow \chi = C e^{\lambda t}$$

Interpretation of normal mode solution

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Normal mode solution

$$\begin{aligned}
 v'(x, y, t) &= \tilde{v}(y) e^{i\alpha(x-ct)} + c.c \\
 &= \text{Real} \left\{ \tilde{v}(y) | e^{i\phi(y)} e^{i\alpha(x - (c_r + ic_i)t)} \right\} \\
 &= |\tilde{v}(y)| e^{ac_i t} \cos[\alpha(x - c_r t) + \phi(y)]
 \end{aligned}$$

c_r : Phase speed

(Speed of wave)

$c_i > 0$ Linearly unstable

$c_i = 0$ Marginally stable (or neutral)

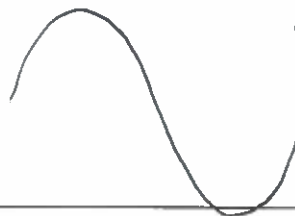
$c_i < 0$ Linearly stable

Wall-normal structure of wave

$c_r \rightarrow$



$$\lambda_x = \frac{2\pi}{\alpha}$$



if $c_i > 0$

$$\begin{aligned}
 z &= r e^{i\theta} \\
 r &= |z|
 \end{aligned}$$

Phase angle.

Rayleigh equation

Let $\omega = \alpha c$ and $D \equiv d/dy$. Then, we get

$$(U - c)(D^2 - \alpha^2)\tilde{v} - D^2 U \tilde{v} = 0$$

\uparrow
eigenvalue

\uparrow
eigenfunction

with the boundary condition,

$$\tilde{v} = 0 \quad \text{at solid boundary and/or the far field}$$

Prescribed by a real number.

Remark

If $\alpha \in \mathbb{R}$ is given, then $c \in \mathbb{C}$ becomes unknown with \tilde{v} , resulting in eigenvalue problem.

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1. Equilibrium and stability
2. Linear stability analysis
3. Non-linear stability analysis

4. When does an instability occur?

When does an instability occur?

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Theorem: Rayleigh inflection point criterion (Inverse is NOT true)

If there exist perturbations with $c_i > 0$, then d^2U/dy^2 must be zero at some $y \in \Omega$ ($\Omega = [a, b]$ is the flow domain in y).

Proof Assume $C\bar{\alpha} > 0$ → complex conjugate of \tilde{v} .

$$\int_a^b \tilde{v}^* (U - c) (D^2 - \alpha^2) \tilde{v} - \frac{D^2 U}{(U - c)} \tilde{v} \tilde{v} dy = 0$$

$$\int_a^b \tilde{v}^* (D^2 - \alpha^2) \tilde{v} dy - \int_a^b \frac{D^2 U}{(U - c)} \tilde{v} \tilde{v} dy = 0$$

$$\int_a^b \tilde{v}^* D^2 \tilde{v} dy = \left[\tilde{v}^* D \tilde{v} \right]_a^b - \int_a^b D \tilde{v}^* D \tilde{v} dy$$

↑
integration by part.

$$= - \int_a^b |D \tilde{v}|^2 dy$$

There is
a linear
instability.

Rayleigh inflection point criterion

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$$\int_a^b |D\tilde{v}|^2 + \alpha^2 |\tilde{v}|^2 dy + \int_a^b \frac{d^2 U / dy^2}{(U - c)} |\tilde{v}|^2 dy = 0$$

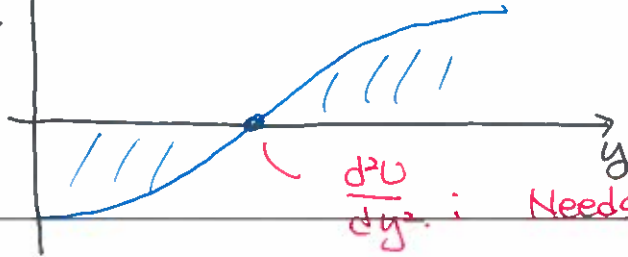
Real Positive

Complex

Imaginary part:

$$\text{Im} \left(\int_a^b \frac{d^2 U / dy^2}{(U - c)} |\tilde{v}|^2 dy \right) = \int_a^b \frac{c_i d^2 U / dy^2}{|U - c|^2} |\tilde{v}|^2 dy = 0$$

$\frac{d^2 U}{dy^2}$



$\frac{d^2 U}{dy^2}$

Needs sign change at some y.

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$$\int_a^b \frac{(U - c)^* d^2 U / dy^2}{(U - c)(U - c)^*} |\tilde{v}|^2 dy$$

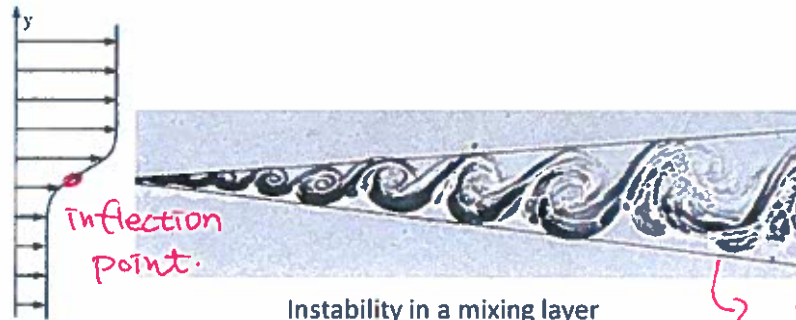
$$\int_a^b \frac{(U - c)^* d^2 U / dy^2}{|U - c|^2} |\tilde{v}|^2 dy$$

Remark 1

The presence of some inflection points is a necessary condition for linear instability.

Remark 2

The presence of an inflection point is often a sign of instability.



Instability in a mixing layer
(Brown & Roshko 1974)

↪ Kelvin
- Helmholtz
Instability

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- 2. Linearised equation for inviscid parallel shear flows**
- 3. Normal mode solution**
- 4. Rayleigh theorem**

