

# Meta-Reinforcement Learning and Causality for Multi-tasking in Robots with Redundant Kinematics

## 1st Year Update

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# Focus

## Meta-Reinforcement Learning and Causality for Multi-tasking in Robots with Redundant Kinematics

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Meta-Reinforcement Learning and Causality for Multi-tasking in Robots with Redundant Kinematics

Translation: Explore different methodologies to create intelligent agents that can control robots in difficult tasks

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